Innovation in Motion
TSUBAKI

Expanded Lineup

TSUBAKI
Overload protection and control devices

Safety

**Safety devices for protecting machinery from potentially damaging mechanical and electrical overload.
Both mechanical and electrical types are available.**

Creating device safety and control

From safety mechanisms like Torque Limiter, Shock Guard and Shock Relay, to controlling devices like Torque Keeper and Shock Monitor, SAFCON provides your vital machinery with top-notch safety and control.

Control

Contributing to device automation.

Torque Limiter
Friction type

Shock Guard
Separation type

Axial Guard
Linear actuating type

Shock Relay
Current type

SAFCON

TSUBAKI Safety and Control devices

Torque Keeper
Mechanical type slipping clutch and brake

MINI-KEEPER
Mechanical type slipping clutch and brake

Shock Monitor
Electric type overload protection device and load sensor

Variation

Safety

Overload Protection

Mechanical type

What it detects

- Torque
- Thrust Load

Disconnection (trip) method

- Ball type
- Friction type
- Ball type

Torque adjustment method

- Spring pressure
- Air pressure
- Spring pressure
- Spring pressure

Reset after trip

- Automatic
- Manual
- Automatic/ Manual
- Automatic
- Automatic

Construction

- Open
- Sealed
- Open
- Open
- Open
- Open

One position reset

- YES
- YES
- YES
- YES
- NO
- YES

Backlash

- Small
- NO
- Minimal
- NO
- Small
- Minimal
- NO

Shock Guard

- Wide variety of sizes
- Compact
- Compact
- Large capacity

Shock Guard TGB Series

Set torque:0.294 to 7154Nm
Max. rpm:80 to 1200r/min

P21

Shock Guard TGX Series

Set torque:1.7 to 784Nm
Max. rpm:480 to 1400r/min

P41

Shock Guard TGM Series

Set torque:1.5 to 902Nm
Max. rpm:150 to 600r/min

P63

Shock Guard TGK Series

Set torque:15 to 392Nm
Max. rpm:340 to 430r/min

P79

Axial Guard TGA Series

Set load:147 to 3430N
Trip load repeatability:±15%
Backlash:0

P97

Shock Guard TGE Series

Set torque:1 to 700Nm
Max. rpm:570 to 900r/min

P35

Shock Guard TGF Series

Set torque:5 to 4900Nm
Max. rpm:340 to 900r/min

P51

Shock Guard TGZ Series

Set torque:2.4 to 251Nm
Max. rpm:1800r/min

P71

Torque Limiter TL Series

Set torque:1.0 to 9310Nm
Max. rpm:500 to 1800r/min

P87

Torque Limiter

- Motor current
- Display function
- YES
- Display method
- Digital display
- Analog display
- Manual
- Functions
- Standard functions
- Multi-functions
- Lower limit detection

Select by motor capacity

Shock Relay

Shock Relay ED Series

Motor capacity:
AC200V0.1 to 5.5kW
AC400V0.1 to 11kW

P113

Shock Relay 150 Series

Motor capacity:
AC200V0.2 to 90kW
AC400V0.2 to 90kW

P127

Shock Relay SU Series

Motor capacity:
AC200V0.1 to 11kW
AC400V0.2 to 22kW

P137

Shock Relay SC Series

Motor capacity:
AC200V0.1 to 75kW
AC400V0.2 to 132kW

P124

Shock Relay SS Series

Motor capacity:
AC200V0.1 to 75kW
AC400V0.2 to 132kW

P131

Control

Electrical type

What it detects

- Motor power
  - Load detection level
    - Fixed
      - Function
        - Multi-functions
        - Limited functions
    - Follow
- NO
  - Reset after trip
    - Automatic
      - Functions
        - Standard functions
        - Limited functions

Select by motor capacity

- Shock Relay SA Series
  - Motor capacity: AC200V0.1 to 75kW, AC400V0.2 to 132kW
  -  P134
- Shock Monitor
  - Shock Monitor TSM4000 Type
    - Motor capacity: AC200V0.1 to 110kW, AC400V0.1 to 110kW
    -  P163
  - Shock Monitor TSM4000H2 Type
    - Motor capacity: AC200V0.1 to 110kW, AC400V0.1 to 110kW
    -  P170
  - Shock Relay 50 Series
    - Motor capacity: AC200V0.2 to 3.7kW, AC400V0.2 to 3.7kW
    -  P139
  - Shock Monitor TSM4000H1Type
    - Motor capacity: AC200V0.1 to 110kW, AC400V0.1 to 110kW
    -  P169

Slipping clutch and brake

Mechanical type

What it detects

- Torque
  - Slip torque
    - Large
    - Small

Select by slip torque

- Torque Keeper
  - Torque Keeper TFK Series
    - Set torque: 0.59 to 650N·m
    -  P143
- MINI-KEEPER
  - MINI-KEEPER MK Series
    - Set torque:1.96 to 39.2N·cm
    -  P155

Power sensor

Electrical type

What it detects

- Motor power
  - Purpose of use
    - Contact detection
    - Wear detection
    - Crusher control

Select by motor capacity

- Shock Monitor
  - Shock Monitor TSM4000M1 Type
    - Motor capacity: AC200V0.1 to 110kW, AC400V0.1 to 110kW
    -  P171
  - Shock Monitor TSM4000C1 Type
    - Motor capacity: AC200V0.1 to 110kW, AC400V0.1 to 110kW
    -  P174
  - Shock Monitor TSM4000M2 Type
    - Motor capacity: AC200V0.1 to 110kW, AC400V0.1 to 110kW
    -  P172

SAFCON contributes to the protection and control

Starting with the examples below, SAFCON meets a wide range of industrial equipment safety and control needs.

Selection guide

Safety

Shock Guard

Category	Machine (Safety or Control)		Protection, detection, applications	TGB Series	TGE Series	TGX Series	TGF Series	TGM Series	TGZ Series	TGK Series
	Page			P21	P35	P41	P51	P63	P71	P79
Transport equipment	Crane	S	Overload protection for machine overload, jamming, etc.							
	Hoist	S	Overload protection for machine overload, jamming, etc.							
	Chain block	S	Overload protection for machine overload, jamming, etc.							
	Overhead conveyor	S	Chain breakage protection							
	Overhead conveyor	S	Chain breakage detection							
	Belt conveyor	S	Belt breakage protection	●	●		●	●		
	Belt conveyor	S	Belt breakage detection							
	Chain conveyor	S	Chain breakage protection	●	●		●	●		
	Chain conveyor	S	Chain breakage detection							
	Roller conveyor	S	Roller axis damage protection	●	●		●	●		
	Screw conveyor	S	Screw damage protection							
	Bucket elevator	S	Prevents chain breakage due to bucket jamming							
	Industrial robot	S	Drive portion, pivot portion overload protection			◉				
Environmental equipment	Garbage disposal equipment	S	Overload protection for garbage conveyor							
	Water treatment equipment	S	Prevents chain breakage for scraper and dust collector							
	Water gate	S	Gate and rack damage protection	◉	●					
Pump	Pump	S	Motor protection					●		
	Compressor	S	Motor protection					●		
	Blower	S	Motor protection							
Packaging machine	Bag making and packaging machine	S	Overload protection for film feeding and seal/pillow packaging machine cutter	◉	◉	◉	●	●		●
	Cartoning machine	S	Overload protection for workpiece conveyor and packaging equipment	◉	◉	◉	●			●
	Vacuum packaging machine	S	Overload protection for workpiece conveyor, seal, and cutter	◉	◉	◉	●	●		●
	Filling machine	S	Clutch function and overload protection for intermittent workpiece conveyor							◉
Food processing machine	Flour mill	S	Overload protection for milling, mixing and sifting machine	●	●	◉	●			
	Noodle-making machine	S	Overload protection for mixer and roller/extruder	●		◉	●			●
	Bakery equipment	S	Prevents chain breakage for fermentation oven and cooler	●	●	●	●			
	Beverages	S	Overload protection for bottle/can conveyor and dehydrating press	●	●	●	●			◉
Machine tools	Turning machine	C	Tip breakage detection							
	Machining	C	Drill wear detection							
	Grinding machine	C	Grinding stone contact detection							
	Tapping machine	C	Tap breakage detection							
	Cutter	C	Saw contact detection							
	Chip conveyor	S	Prevents damage due to jammed chips		●					
Metal working machinery	Press	S	Punch and transfer portion protection	●		◉				
	Casting	S	Overload protection for conveyor unit	●	●					
Iron and steel	Rolling machine	S	Overload protection for conveyor unit							
Plastic processing machine	Injection molding machine	S	Screw and mold clamping protection			●		●	●	
	Extruding machine	S	Screw and gear protection			●		●	●	
	Gear pump for extruding machine	S	Gear and axis protection		●		●			
	Extruding machine	S	Heater wire breakage detection							
Textile machine	Spinning machine	C	Winding-off portion tension control							
	Textile weaving loom	C	Winding-off portion tension control					●		
	Winder	S	Protection of rocking arm driving servo motor for carbon fiber winder		●					
Printing machine	Printing machine	C	Printed material tension control							
	Book binder	S	Protects pressure portion and conveyor from overload damage	●	●	●	◉		●	
IT	Printer	C	Printed material tension control							
	Liquid crystal manufacturing device	S	Conveyor unit overload protection	●		●				
	Semiconductor production device	S	Conveyor unit overload protection	●		●				
Others	Crusher	S	Crusher blade protection						●	
	Raw garbage processor	S	Mixing blade damage protection	●						
	Mixer	S	Mixing blade damage protection							
	Kneading machine	S	Mixing blade damage protection							
	Automotive testing machine	S	Damage protection for torque measuring instrument for engine bench test machine				●			
	Can making machine	S	Clutch function and damage protection for aluminum can pressing machine							◉
	Capper	S	Closing torque adjustment for drum can cap							◉
	Feeder	S	Workpiece jamming detection							
	Stage device	S	Floor mechanism overload protection							
	Lighting system	S	Overweight detection for lifting devices							

# of a wide range of industrial equipment

◉:Optimal ●:Recommended

Control

Torque Limiter	Axial Guard	Shock Relay						Torque Keeper	MINI-KEEPER	Shock Monitor		
TL Series	TGA Series	SC Series	ED Series	150 Series	SS Series	SA Series	SU Series	TFK Series	MK Series	TSM4000 Type	TSM4000 H1 Type	TSM4000 H2 Type
												
P87	P97	P113	P124	P127	P131	P134	P137	P143	P155	P163	P169	P170
◉		●	●		●					●	●	
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		◉	◉		●	◉				●	◉	
		◉	◉		●	●				●	●	

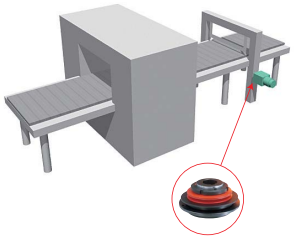
Application Safety

Providing optimal overload protection

TSUBAKI mechanical and electrical safety devices provide overload protection for various applications.

Packaging machine

Cutter drive portion overload protection



Product used

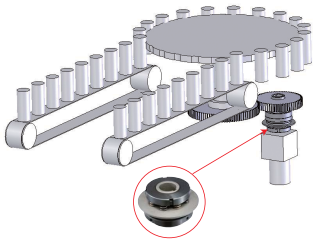
Shock Guard TGB Series P21

Features

- Automatic reset
- Economical

Rotary filling and packaging machine

Protects the machine from intrusion



Product used

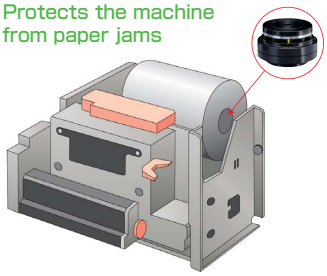
Shock Guard TGE Series P35

Features

- Automatic reset
- Works with wide gears

Small precision printer

Protects the machine from paper jams



Product used

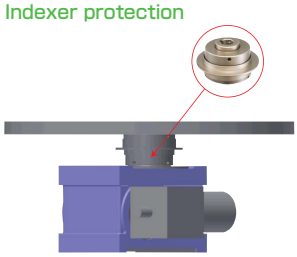
Shock Guard TGX Series P41

Features

- Non-backlash
- Automatic reset
- One position

Index table

Indexer protection



Product used

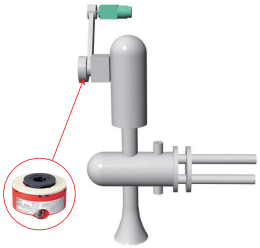
Shock Guard TGF Series P51

Features

- The index table can be installed directly.
- One position
- Automatic reset

Pump

Protects the pump from highly viscous material



Product used

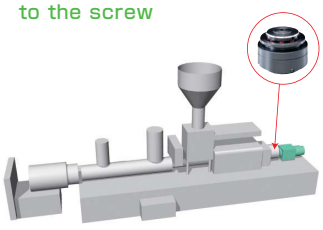
Shock Guard TGM Series P63

Features

- Sealed construction
- One position

Extruding machine

Trips to protect the machine and screw from overload to the screw



Product used

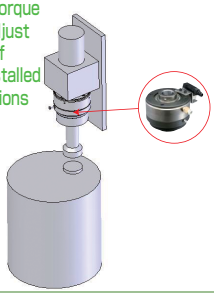
Shock Guard TGZ Series P71

Features

- Works with high rpm
- Rotates freely after trip

Drum can cap closer

Works when closing a cap with the prescribed torque
Remotely adjust the torque of products installed in high positions



Product used

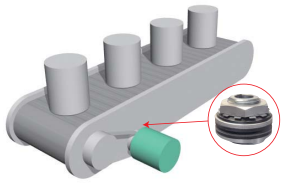
Shock Guard TGK Series P79

Features

- Remote torque adjustment
- Clutch function

Conveyor

Protects the machine from overload due to jamming



Product used

Torque Limiter P87

Features

- Automatic reset
- The sprocket can be directly mounted, making it easy to use

Mechanical type features

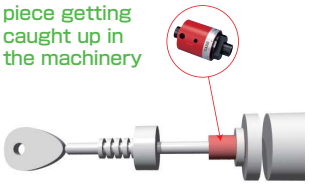
Due to cutting the peak load, overload does not occur.
Excessive power to the loaded axis can be shut off.

Electronic type features

All models are equipped with the start time function.
Price stays same regardless of motor size.

Pusher

Protects the mechanical system from overload due to the work piece getting caught up in the machinery



Product used

Axial Guard P97

Features

- Can protect from overload on the axial direction

Lifting and lowering device

Detects overweight

Product used

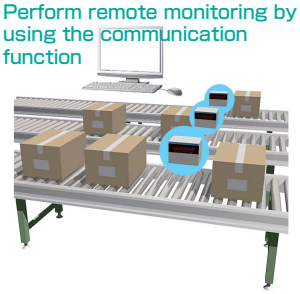
Shock Relay ED Series P124

Features

- While verifying motor current during operation, the load value can be precisely set on the digital display
- Economical

Multiple conveyors

Perform remote monitoring by using the communication function



Product used

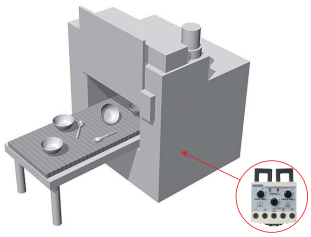
Shock Relay SC Series P113

Features

- Loads on multiple conveyors can be monitored remotely with a PC using the communication function.
- Parameter values can also be changed remotely.

Dishwasher

Stops overload when spoons or other utensils get jammed in the machine.



Product used

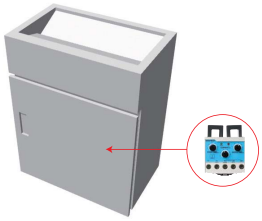
Shock Relay SS Series P131

Features

- Compact and economical

Shredder

Temporarily stops the shredder when the load becomes heavy



Product used

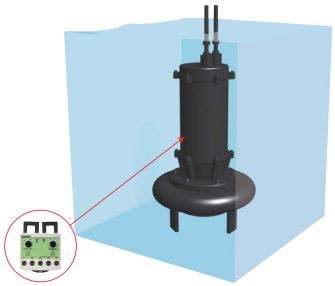
Shock Relay SA Series P134

Features

- Convenient automatic reset for frequent stops
- Compact
- Economical

Submersible pump

Prevents pump motor burnout



Product used

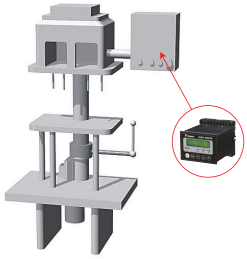
Shock Relay SU Series P137

Features

- Compact
- Economical
- Test functions

Multi-spindle drilling machine

Overload protection and breakage detection for each tool



Product used

Shock Monitor TSM4000 P163

Features

- Detects overload and tool breakage when machining with high precision
- The set value for each tool can be changed (8 types)

Water treatment equipment

Sewage collector chain breakage prevention

Product used

Shock Monitor TSM4000H2 Type P170

Features

- Because of the load following function, the set value can be followed and abnormal load can be detected precisely even if there is a small efficiency change in the high gear ratio reducer

Application Control

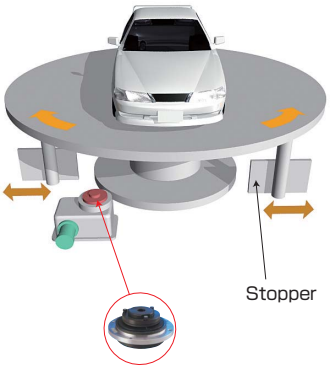
For controlling devices

Slipping clutch and brake

Because it is possible to use even with continuous slipping, it is ideal for braking, accumulation and dragging.

Multistory parking facility

When the table strikes the stopper and stops, the Torque Keeper slips, protecting the drive portion.



Product used

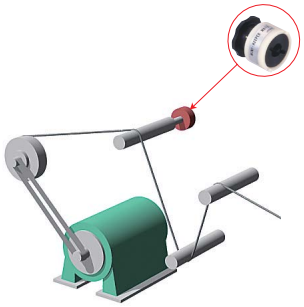
Torque Keeper
TFK Series P143

Features

- Stable slip torque
- Long life
- Simple layout

Wire winding machine

By installing a MINI-KEEPER to the roll, constant tension allows the wire to wind smoothly



Product used

MINI-KEEPER
MK Series P155

Features

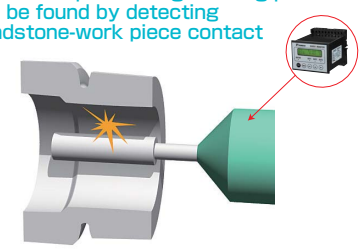
- Continuous slip is possible
- Gives ideal amount of tension for the work piece

Power sensor

Preventitive device maintenance and automation can be realised by detecting minute overload variation for grindstone-work piece contacts, tool wear, crusher automatic operation, etc.

Internal grinding machine

The grinding cycle can be reduced and grindstone processing starting points can be found by detecting grindstone-work piece contact



Product used

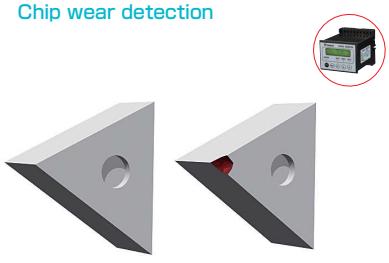
Shock Monitor
TSM4000M1 Type P171

Features

- Can off-set the load ratio at no load operation before contacting the work-piece, can only detect a tiny contact load

Lathe

Chip wear detection



Product used

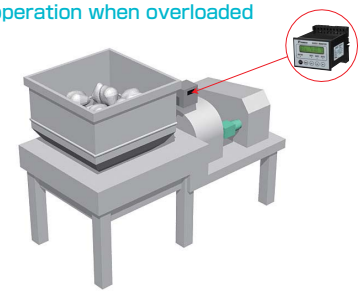
Shock Monitor
TSM4000M2 Type P172

Features

- Intergrates power consumption during working to detect minimal load variations due to wear, thus allowing the user to know the appropriate time to change the chips

Crusher

Automatic forward and reverse operation when overloaded



Product used

Shock Monitor
TSM4000C1 Type P174

Features

- Accurately detects hard foreign objects that get caught up in the crusher, thus protecting expensive crushing blades from damage
- With just one Shock Monitor, complex device control can be achieved

Safety Devices

SAFCON

Mechanical Type

Shock Guard, Torque Limiter, Axial Guard

Features

Mechanical type safety devices

Shock Guard, Torque Limiter, Axial Guard

General use, economical
Shock Guard **TGB Series**

Easy to operate and reasonably priced. Can be used with almost all machines.

General-purpose, wide torque setting range
Shock Guard **TGE Series**

Compact design. Applicable to small-diameter sprockets and wide pulleys.

High precision, high rigidity
Shock Guard **TGX Series**

No backlash and unsurpassed operation rigidity.
Ideal for machines that require precision positioning.

Ideal for indexers
Shock Guard **TGF Series**

Excellentreset position accuracy.

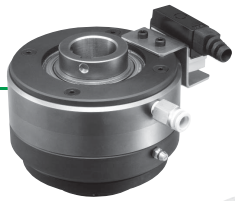
Sealed construction
Shock Guard **TGM Series**

The sealed type possesses unsurpassed precision.
Excels in wet, oily and dusty environments.

ON-OFF, release
Shock Guard **TGZ Series**

As a release type protection device, as well as an ON-OFF clutch,
its simple layout makes it easy to use.

Air clutch structure
Shock Guard **TGK Series**



Enables remote torque adjustment during operation.

Friction type
Torque Limiter

Traditional friction type. Super low price and easy to use.

Linear actuating type
Axial Guard

This is a new type of overload protection device with ball
and groove construction.

Mechanical safety device variation

In order to meet the diverse needs of our customers, we provide a wide range of mechanical safety products. Refer to the chart below to choose the functions and device characteristics that best suit your safety needs.

Product name / Function, capacity	Shock Guard					
	TGB Series				TGE Series	TGF Series
	Compact size (TGB08 to 16)	Medium size (TGB20 to 70)	Large size (TGB90 to 130)	With sprocket (TGB20 to 70)		
Torque range [N・m]	0.294 to 11.76	9.8 to 1080	441 to 7154	9.8 to 1080	1.0 to 700	5.0 to 4900
Bore range [mm]	6 to 16	10 to 70	45 to 130	10 to 70	12 to 50	10 to 90
Repetitive motion torque accuracy	±10%	±10%	±10%	±10%	±5%	±5%
Backlash	None	Small	Small	Small	Small	Minimal
Reset method	Automatic	Automatic	Automatic	Automatic	Automatic	Automatic
Overload detection	TG Sensor	TG Sensor	TG Sensor	TG Sensor	TG Sensor	TG Sensor
Torque indicator	Yes	Yes	Yes	Yes	No	Yes
Exterior						

Product name / Function, capacity	Shock Guard				Torque Limiter	Axial Guard
	TGX Series	TGM Series	TGZ Series	TGK Series	TL	TGA
Torque range [N・m]	1.7 to 784	1.5 to 902	2.4 to 451	15 to 392	1.0 to 9310	147 to 3430 (Load range[N])
Bore range [mm]	8 to 70	10 to 60	10 to 50	10 to 45	8 to 130	—
Repetitive motion torque accuracy	±5%	±5%	±10%	±5%	—	±15% (trip load)
Backlash	None	None	Small	Minimal	None*1	None
Reset method	Automatic	Automatic	External force (manual)	Automatic	Automatic	Automatic
Overload detection	TG Sensor	Limit switch	TG Sensor	Limit switch	Proximity switch, tachometer	TGA Sensor
Torque indicator	Yes	Yes	Yes	No*2	No	Yes
Exterior						

*1 Only for unidirectional operation.
2 Adjust the regulator pressure to adjust the torque.

The right mechanical type safety device for your particular needs is available. Using the chart below, select the device that is most right for your machines.

For machinery like positioning and indexing machines that require preciseness.

One position function	
TGB Series	Yes
TGE Series	Yes
TGX Series	Yes
TGF Series	Yes
TGM Series	Yes
TGZ Series	Yes
TGK Series	Yes

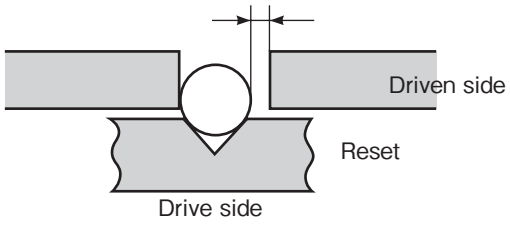
One position

Because of its unique construction, the drive and driven sides only mesh in one position. After tripping the Shock Guard resets and meshes in its original position.

Backlash	
TGB Series	Small
TGE Series	Small
TGX Series	No
TGF Series	Minimal
TGM Series	No
TGZ Series	Small
TGK Series	Minimal

Backlash

Connecting clearance between drive side and driven side at normal operation.



Repetitive motion torque accuracy	
TGB Series	±10%
TGE Series	±5%
TGX Series	±5%
TGF Series	±5%
TGM Series	±5%
TGZ Series	±10%
TGK Series	±5%

Repetitive motion torque accuracy

This represents the deviation caused by repeated trips.

For the machine that you want to automatically reset after removing overload after trip

TGB Series	Automatic reset
TGE Series	
TGX Series	
TGF Series	
TGM Series	
TGK Series	

Automatic reset

After overload is removed, the overload detection function is reset automatically by inching either the drive or driven side.

For the machine that you want to freely rotate after trip

TGZ Series	Complete release
TGK Series	

* In cases where the air pressure is zero for the TGK series

Complete release

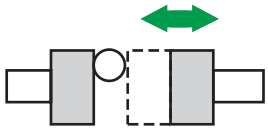
After tripping, this function completely eliminates transmission of the drive side rotation to the driven side. While in the case of an automatic reset mechanism, the overrunning of the drive side after tripping prevents reset shock. This complete release function is best suited for a high speed rotation axis.

Arbitrarily shutoff the rotary power transmission as an ON-OFF clutch

TGZ Series	Reset by external force
TGK Series	In cases where the air pressure is zero

ON-OFF

The ON-OFF function.
Arbitrarily transmit or shutoff torque by external force.

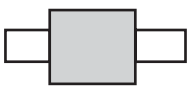


For the machine that is used in a highly humid environment

TGM Series	Sealed construction

Sealed Construction

Sealed construction using O-ring. Under normal usage conditions it is not necessary to refill the grease.



Selection

As a safety device, the Shock Guard will be most effective if it is installed in the place nearest to where overload is thought to most likely occur on the driven machine.
For most situations, avoid using the Shock Guard with human transportation or lifting devices. If you decide to use a Shock Guard with these devices, take the necessary precautions to avoid serious injury or death from falling objects.

1. Setting trip torque

$$T_P = T_L \times S.F = \frac{60000 \times P}{2\pi \cdot n} \times S.F \quad \{T_P = \frac{974 \times P}{n} \times S.F\}$$

T_P = Trip torque N·m{kgf·m}　T_L = Load torque N·m{kgf·m}
P = Transmittance power kW　S.F = Service factor
n = rpm　r/min

(1) From the machine's strength and load, as well as other information, set the trip torque at the point where it should not go any higher.
(2) When the limit value is not clear, calculate the rated torque by using the rpm of the shaft where the Shock Guard is installed and rated output power. Then, depending on the conditions of use, multiply by the service factor in Table 1.

Table1

S.F	Operating conditions
1.25	In the case of normal start up/stop, intermittent operation
1.50	In the case of a heavy shock load or forward-reverse driving

2. When rpm is relatively high

When rpm is relatively high (more than 500r/m), or when load inertia is large, depending on the motor's start up torque, there is a chance the Shock Guard will trip. In this case, determine the inertia ratio and calculate the torque used in the Shock Guard during start up, then multiply it by the service factor and make this the trip torque.

$$K = \frac{I_L + I_t}{I_s} \left\{ K = \frac{GD^2_L + GD^2_t}{GD^2_s} \right\} \quad Tt = \frac{K \cdot T_s + T_L}{1 + K} \quad Tp = SF \cdot Tt$$

K : Inertia ratio
I_s : Drive side moment of inertia(kg·m^2)
$\{GD^2_s$: Drive side GD^2(kgf·m^2)$\}$
I_L : Load side moment of inertia(kg·m^2)
$\{GD^2_L$: Load side GD^2(kgf·m^2)$\}$
I_t : Shock Guard moment of inertia(kg·m^2)
$\{GD^2_t$: Shock Guard GD^2(kgf·m^2)$\}$
T_s : Motor starting torque(N·m){kgf·m}
T_t : Torque in Shock Guard during start up(N·m){kgf·m}
T_L : Load torque(N·m){kgf·m}
T_P : Trip torque(N·m){kgf·m}
S.F : Service factor

Note) Use the equivalent value to the shaft in which the Shock Guard is installed for each moment of inertia, GD^2 and torque value.

3. Precautions when deciding trip torque

Compared with load torque, if the torque used when starting up becomes large, the setting trip torque value also becomes large, causing a problem from the viewpoint of the overload protection device. (Compared with the load torque, the trip torque is too large.) In this case install it as close to the load side as possible.

4. Choosing the model number

Choose a model where the calculated trip torque is within the minimum to maximum setting range.

5. Verifying bore diameter

Verify that the shaft where the Shock Guard will be installed is in the possible range (refer to the dimensions table) of the bore diameter of the Shock Guard model you selected.
If the shaft diameter is larger than the possible bore range, select a model one size larger that uses a weak spring.

6. Confirming rpm

Confirm that the Shock Guard rpm used is within the maximum rpm value in this catalog.

Notes for Design

* When selecting the size based on the torque, ensure that the preset torque is not more than 80% of the upper limit of the torque capacity of the Shock Guard. The reason for this is to allow a margin for readjustment considering the decline in torque attributable to wear after many years of use.
* When using an induction motor or a similar device as the drive motor, consider the starting torque when determining the preset torque. Also, for machines that generate large vibrations, give consideration to these vibrations when setting the torque since the Shock Guard is activated in response to a momentary overload and consequently seems to be activated at a torque less than the calculated torque.
* When using the Shock Guard for an intermittent drive such as an indexer and the difference between the preset torque and the normal peak torque is small, transmission balls oscillate due to load fluctuation during operation, which causes machine vibration and abnormal wear of the inside of the Shock Guard. Therefore, set the torque to the highest value possible that is within a range that does not damage the machine.
* Driving method
  When using the Shock Guard with a V pulley or timing pulley, confirm that the radial load caused by belt tension does not exceed the permissible load. Contact us if the load exceeds the permissible load.
* Coupling
  Select the appropriate type according to your use conditions after checking whether the allowances are satisfied.
* Reset speed
  The reset speed should be as low as possible. The appropriate reset speed depends on factors such as the inertia of the driven machine, elasticity of the drive machine, and selected torque of the Shock Guard, but 50 rpm or less is sufficiently low for the reset speed in most cases. If low speed reset is impossible, perform inching operations.

⚠Do not reset the main unit or shaft of the Shock Guard by turning it by hand. Doing so is dangerous.

Usable sprocket minimum number of teeth

For sprocket machining dimensions, refer to the description pages of each series.

● TGB Series

Model No.	Sprocket minimum number of teeth							
	RS40	RS50	RS60	RS80	RS100	RS120	RS140	RS160
TGB08-L,M,H	14	12	13(10)					
TGB12-L,M,H	16	13	13(11)					
TGB16-L,M,H	18	15	14					
TGB20-H	26	22	19	15	13	13(11)		
TGB30-L,H	32	26	22	18	15	13		
TGB50-L,M,H	45(43)	35	30	24	20	17		
TGB70-H	60(58)	48(47)	40	32(31)	26	24(22)		
TGB90-L,H		62	52	40	33	28	25	22
TGB110-L,H		74	62	48	39	33	29	26
TGB130-L,H		83	70	53	43	37	32	29

* The numbers of teeth in parentheses are not those of standard A-type sprockets. Whenever possible, use sprockets with a larger number of teeth.
* The above are the smallest possible installable sprockets. Sprocket transmissible power is not considered, so refer to TSUBAKI drive chain catalog for more information on sprocket selection and handling.

● TGE Series

〈Type 1〉

Model No.	Sprocket minimum number of teeth				
	RS35	RS40	RS50	RS60	RS80
TGE17-1	18	14	12	—	—
TGE25-1	25	20	17	15	12
TGE35-1	32	25	20	18	14
TGE50-1	—	31	26	22	17

〈Type 3〉

Model No.	Sprocket minimum number of teeth				
	RS35	RS40	RS50	RS60	RS80
TGE17-3	23	18	15	—	—
TGE25-3	32	25	21	18	14
TGE35-3	39	30	25	21	17
TGE50-3	—	40	33	28	22

● TGM Series

Model No.	Sprocket minimum number of teeth							
	RS25	RS35	RS40	RS50	RS60	RS80	RS100	RS120
TGM3	*30	22	17	15				
TGM6	*30	22	17	15				
TGM20	*34	24	19	16	14			
TGM60		*32	26	21	18	15		
TGM200			*37	30	26	20	17	
TGM400				*41	35	*27	24	20
TGM800				*41	35	*27	24	20

* The numbers marked with * are not standard numbers of teeth.
(Note) Determine the number of teeth after checking the transfer capacity of the chain.
(Note) Insert the joint link from the outside of the sprocket.

● TGZ Series

Model No.	Sprocket minimum number of teeth									
	RS25	RS35	RS41	RS40	RS50	RS60	RS80	RS100	RS120	RS80
TGZ20L,M,H	(51)	(35)	(28)	30(29)	24(23)	20	16	13	13	—
TGZ30L,M,H	(62)	(43)	(33)	35(33)	30(27)	24(23)	18	16	14	17
TGZ40L,M,H		(54)	(41)	45(41)	35(34)	30(24)	24(23)	19	16	17
TGZ50L,M,H		62	48	48	40(39)	35(33)	26	21	18	22

* The numbers of teeth in parentheses are not those of standard A-type sprockets. Whenever possible, use sprockets with a larger number of teeth.

● TGK Series

Model No.	Sprocket minimum number of teeth				
	RS35	RS40	RS50	RS60	RS80
TGK20	30	24	20	17	—
TGK30	37	29	24	20	16
TGK45	50	38	32	27	21

Maintenance

1. Shock Guard (TGB)

Lightly coat the balls and bearings with grease once per year or every 1,000 trips.

●Grease

EMG Marketing	Showa Shell	Idemitsu	JX Nippon Oil & Energy	Cosmo Oil
Mobilux EP2	Alvania EP Grease 2	Daphne Eponex Grease EP 2	Epinoc Grease AP(N)2	Cosmo Dynamax EP Grease 2

2. Coupling portion(TGB20-C to TGB130-C)

- Coat the roller chain and sprocket with grease once per month.
  Use the same grease for the Shock Guard.

3. Sprocket portion

- For more information on sprocket and roller chain maintenance, refer to TSUBAKI drive chain catalog.
- If operating with a sprocket and roller chain for a long period of time, even if the trip frequency and number of times is very low, it is possible for the sprocket to wear. Inspect the sprocket for wear on a regular basis. Refer to the TSUBAKI drive chain catalog for inspection procedures.

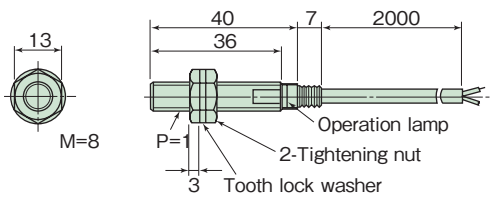
TG Sensor

The TG Sensor is a Shock Guard specific proximity switch system overload detecting sensor. After detecting Shock Guard overload (movement of plate in the axis direction), the motor can be stopped and the alarm can be signaled. It is of course possible to install the TG Sensor on other series' and sizes as well.

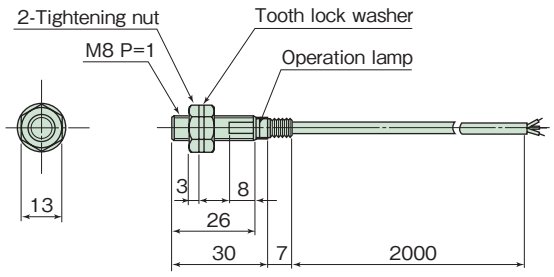
		AC Type	DC Type
Model no.		**TGS8**	**TGS8D**
Power supply voltage	Rating	AC24 to 240V	DC12 to 24V
	Range to be used	AC20 to 264V(50/60Hz)	DC10 to 30V
Current consumption		1.7mA and below(at AC200V)	13mA and below
Control output (opening and closing capacity)		5 to 100mA	Max. 200mA
Indicator lamp		Operation indicator	
Ambient operating temperature		−25 to + 70℃ (does not freeze)	
Ambient operating humidity		35 to 95% RH	
Output form		NC(When not detecting the sensor plate, output opening and closing state is displayed)	
Operation mode		—	Open collector
Insulation resistance		More than 50M Ω (at DC50V megger) In between the energized part and the case	
Mass		Approx. 45g (with 2m code)	
Residual voltage		Refer to characteristic data	Less than 2.0V (load current 200mA/code length 2m)

■ Dimensions Diagram

●AC Type TGS8



●DC Type TGS8D

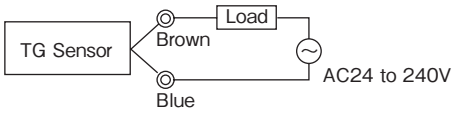


■TG Sensor Handling

* Do not swing, excessively pull or strike the detecting portion with an object.

AC Type TGS8

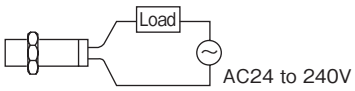
●Circuit diagram



No need to consider the polarity of TG sensor (brown,blue).

●Precautions for wiring

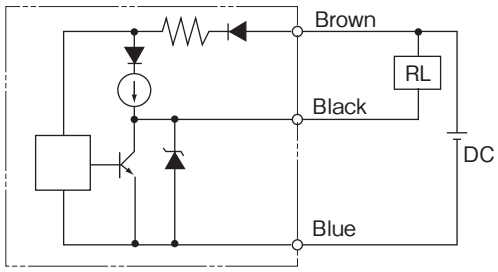
- Make sure to turn on the power after connecting the load, or the machine will likely be damaged.



- In order to prevent damage due to surge and noise when an electric/power line runs close to the TG sensor code, use a single and separate wiring pipe.

DC Type TGS8D

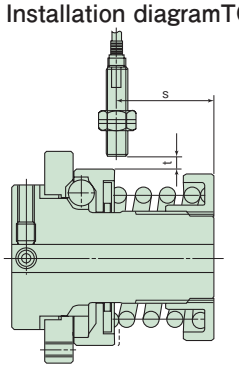
●Circuit diagram



■ Overload detection(TG Sensor handling)

- The detecting distance of a TG Sensor is 1.5mm. Set the Shock Guard at non-trip condition with the dimensions (s, t) in the chart below.
- Install the TG Sensor with the Shock Guard at the tripped position. Then, while rotating the Shock Guard by hand, verify that the TG Sensor is functioning (LED at the side is lighting) and there is no interference with the plate. Finally, reset the Shock Guard .

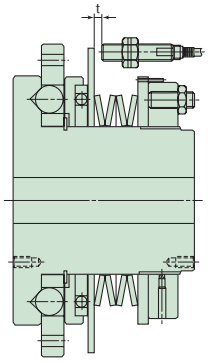
● Installation diagramTGB08 to 16



Unit: mm

	s	t	Amount of sensor plate movement
TGB08-L,M,H	19.2	1.2	0.9
TGB12-L,M,H	22.7	1.2	1.0
TGB16-L,M,H	27.5	1.2	1.2

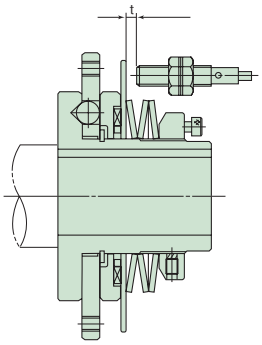
● Installation diagram TGB70 to 130



Unit: mm

	t	Amount of sensor plate movement
TGB70-H	3.3 to 4.8	3.3
TGB90-L,H	5.6 to 6.8	5.4
TGB110-L,H	6.2 to 7.4	6.0
TGB130-L,H	6.8 to 8.0	6.6

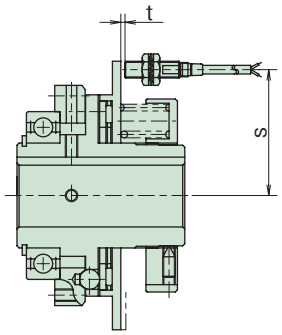
● Installation diagram TGB20 to 50



Unit: mm

	t	Amount of sensor plate movement
TGB20-H	1.8 to 3.3	1.8
TGB30-L,H	2.0 to 3.5	2.0
TGB50-L,M,H	2.7 to 4.2	2.7

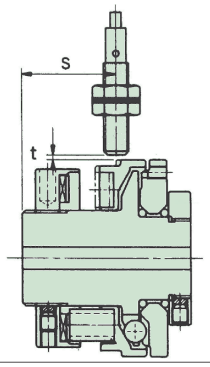
• Installation diagram TGE17 to 50



Unit: mm

Type \ Dimension	s	t	Displacement of housing
TGE17	34	2.2±0.2	1.6
TGE25	48	2.6±0.2	2.0
TGE35	60	3.0±0.2	2.4
TGE50	80	3.8±0.2	3.2

• Installation diagram TGX10 to 70

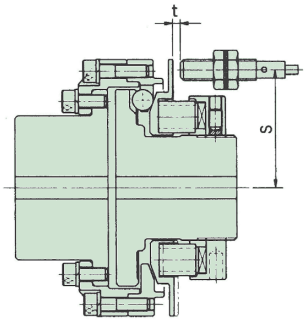


Unit: mm

Type \ Dimension	s	t	Displacement of plate
TGX10	29.9	1.2	1.4
TGX20	28.3	1.2	1.6
TGX35	29.5	1.2	2.0
TGX50	35.6	1.2	2.6
TGX70	34.5	1.2	3.5

Note) The TG sensor can only be attached to the Shock Guard in the radial direction.

• Installation diagram TGX10-C to 70-C

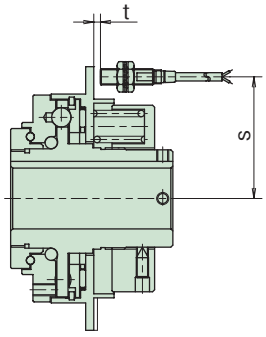


Unit: mm

Type \ Dimension	s	t	Displacement of plate
TGX10-C	36.5	2.1 to 2.8	1.3
TGX20-C	45	2.4 to 3.1	1.6
TGX35-C	59	2.7 to 3.4	1.9
TGX50-C	83	3.2 to 3.9	2.4
TGX70-C	105	4.1 to 4.8	3.3

Note) Regarding the TG sensor to be mounted on a coupling type, attach this sensor horizontally as shown in the figure on the left. Contact us for details on attachment in the radial direction.

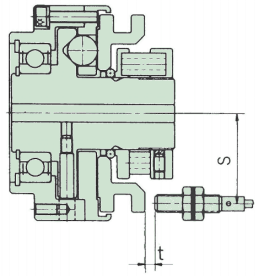
• Installation diagram TGF20 to 90



Unit: mm

Type \ Dimension	s	t	Displacement of housing
TGF20	46	2.2±0.2	1.6
TGF30	60	2.6±0.2	2.0
TGF45	78	3.0±0.2	2.4
TGF65	100	3.0±0.2	2.4
TGF90	136	3.8±0.2	3.2

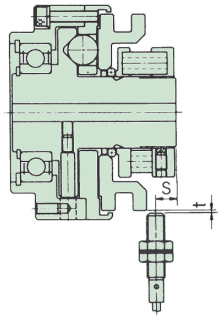
• Installation diagram TGZ20 to 50



Unit: mm

Type \ Dimension	s	t	Displacement of plate
TGZ20	40	4.2 to 5.6	4.1
TGZ30	50	4.8 to 6.2	4.7
TGZ40	66.5	6.0 to 7.4	5.9
TGZ50	79	7.1 to 8.5	7.0

• Installation diagram TGZ20 to 50



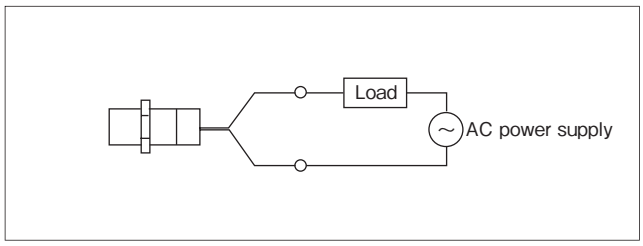
Unit: mm

Type \ Dimension	s	t	Displacement of plate
TGZ20	9.5	1.2	4.1
TGZ30	10.2	1.2	4.7
TGZ40	15	1.2	5.9
TGZ50	12.2	1.2	7.0

Selecting overload and wiring information (AC type for TGS8)

- **Connecting to a power source**

  Make sure to connect via load. A direct connection will damage the internal elements.



- **Using a metal pipe to prevent malfunction/damage**

  In order to prevent malfunction or damage, insert the proximity switch code inside a metal pipe when it runs close to the power cable.

- **Surge protection**

  The TG Sensor has built-in absorbing circuits, but when the TG Sensor is used near a device such as a motor or arc welder where a large surge occurs, make sure to insert a surge absorber such as a varister in the source.

- **Influence of consumption (leakage) current**

  Even when the TG Sensor is OFF, in order to keep the circuits running, a small amount of current flows as current consumption. (Refer to the Consumption (leakage) Current graph) Consequently, because there is a small amount of voltage on the load, it may cause the occurring load to malfunction when resetting. Before using the sensor, confirm that this voltage is less than the load reset voltage. As well, when using the relay as load, be aware that due to the relay's construction when the leakage current is OFF, a buzz will sound.

- **When power supply voltage is low**

  When power supply voltage is smaller than AC48V and load current is less than 10mA, the output residual voltage when the TG Sensor is ON will become large, and the load residual voltage will become large when it is OFF. (Refer to the Load Residual Voltage Characteristics graph.) Take note of operating voltage load when using a relay, etc.

- **When load current is small**

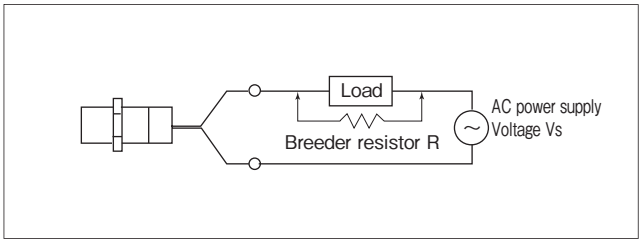
  When load current is less than 5mA, load residual voltage becomes large in the TG Sensor. (Refer to the Residual Voltage Load Characteristics graph.) In this situation, connect the breeder resistance and load in a parallel formation like in the diagram below. If load voltage is above 5mA make residual voltage less than load reset voltage. The breeder resistace value and allowable power are calculated using the below calculation. To be on the safe side, it is recommended to use 20kΩ 1.5W (3W) and above at AC100V, 39kΩ 3W (5W) and above at AC200V.

* When the effect from heat build up becomes a problem, use the wattage in ( ) and above.

$$R \leqq \frac{V}{5-i}\ (k\Omega) \qquad P \leqq \frac{V^2 S}{5-i}\ (mW)$$

P : Breeder resistance W number (As a practical matter, use the number of W several times or more)

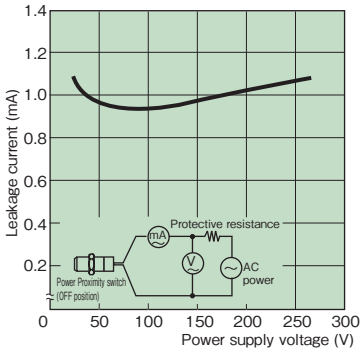
i : Load current (mA)



- **The large inrush current load**

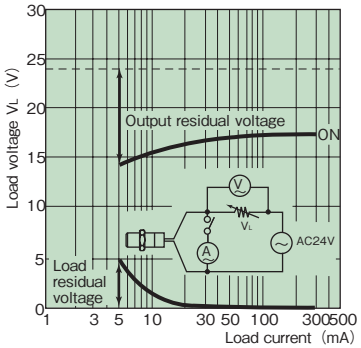
  A load with large inrush current such as a lamp or motor can cause damage or deterioration to open c lose elements of the sensor.Inthistypeof situation, use the sensor via a relay.

- **Consumption (leakage) Current Characteristics**

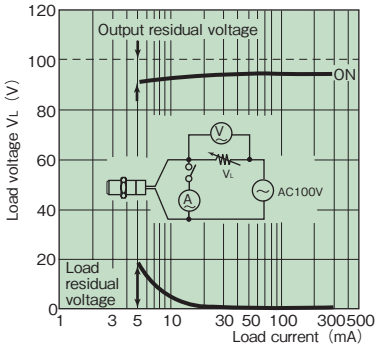


- **Load Residual Voltage Characteristics**

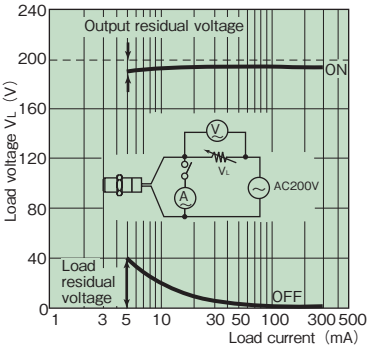
Load residual voltage characteristics
AC24V



Load residual voltage characteristics
AC100V



Load residual voltage characteristics
AC200V



Ordering method

● TGB Series

TGB 50 - H -40 J-25

- TGB: Series
- 50: Size
- H: Spring strength (L=weak spring, M=medium spring, H=strong spring)
- 40: Finished bore measurements (only when finished bore is indicated)
- J: Key way (J=new JIS standards, E=old JIS 2 type)
- 25: Set torque value is displayed as a gravitational system of units 245N·m {25kgf·m} (Only when set torque is indicated)

Rough Bore Product

TGB 50 - H

- TGB: Series
- 50: Size
- H: Spring strength (L=weak spring, M=medium spring, H=strong spring)

Coupling type

TGB 50 - L C - T35 J×C45 E -10

- TGB: Series
- 50: Size
- L: Spring strength (L=weak spring, M=medium spring, H=strong spring)
- C: Coupling type
- T35: Shock Guard side finished bore measurements (TRB for rough bore)
- J: Key way (J=new JIS standard, E= old JIS 2 type)
- C45: Coupling side finished bored measurements (CRB for rough bore)
- E: Key way (J=new JIS standard, E= old JIS 2 type)
- 10: Set torque value is displayed as a gravitational system of units 98N·m {10kgf·m} (Only when set torque is indicated)

Rough Bore Product

TGB 50 - M C

- TGB: Series
- 50: Size
- M: Spring strength (L=weak spring, M=medium spring, H=strong spring)
- C: Coupling type

● TGE Series

TGE 50 - M 3 - 40 J - 25

- TGE: Series
- 50: Size
- M: Spring strength (L=weak spring, M=medium spring, H=strong spring)
- 3: Type (1=Type 1、3=Type 3)
- 40: Finished bore measurements (only when finished bore is indicated)
- J: Key way (J=new JIS standard, E= old JIS 1 type)
- 25: Set torque value is displayed as a gravitational system of units 245N·m {25kgf·m} (Only when set torque is indicated)

Rough Bore Product

TGE 50 - M 3

- TGE: Series
- 50: Size
- M: Spring strength (L=weak spring, M=medium spring, H=strong spring)
- 3: Type (1=Type 1、3=Type 3)

● TGX Series

TGX 20 - H - 15 J - 5.0

- TGX: Series
- 20: Size
- H: Coil spring type
- 15: Finished bore dimensions (no number is displayed if bore is not finished)
- J: Fastening method key way…J: new JIS standard type or E: old JIS 2type Power Lock…No. of Power Locks
- 5.0: Set torque value is displayed as a gravitational system of units (only when set torque is indicated)

Coupling Type

TGX 50 - MC - T35 2 × C50 2 - 10

- TGX: Series
- 50: Size
- MC: Coil spring type
- T35: Shock Guard side Finished bore dimensions (TRB for rough bore)
- 2: Fastening method key way… J: new JIS standard type or E: old JIS 2type (For special type there is no key way) Power lock…No. of Power Locks
- C50: Coupling side finished bored measurements (CRB for rough bore)
- 2: Fastening method key way… J: new JIS standard type or E: old JIS 2type (For special type there is no key way) Power lock…No. of Power Locks
- 10: Set torque value is displayed as a gravitational system of units 98N·m {10kgf·m} (only when set torque is indicated)

● TGF Series

TGF 20 - L 2 - 20 J - 5.0

- TGF: Series
- 20: Size
- L: Spring strength (L=weak spring, M=medium spring, H=strong spring)
- 2: Type (2=Type 2、3=Type 3)
- 20: Finished bore dimensions
- J: Key way (J=new JIS standards, F=old JIS 1 type, P=New JIS fine class)
- 5.0: Set torque value is displayed as a gravitational system of units (only when set torque is indicated)

Coupling Type

TGF 20 - L 7 - T20 P × C30 P- 1.8

- TGF: Series
- 20: Size
- L: Spring strength (L=weak spring, M=medium spring, H=strong spring)
- 7: Type (5=Type 5、7=Type 7)
- T20: Shock Guard side finished bore dimensions
- P: Key way (J=new JIS standards, F=old JIS 1 type, P=New JIS fine class)
- C30: Coupling side finished bore dimensions
- P: Key way (J=new JIS standards, F=old JIS 1 type, P=New JIS fine class)
- 1.8: Set torque value is displayed as a gravitational system of units 17.8N·m {1.8kgf·m} (only when set torque is indicated)

● TGM Series

TGM 60 - D30 - WS - 2.5

- TGM: Series
- 60: Size
- D30: Bore diameter
- WS: Spring specifications
  S:Reinforced spring WS:Weak spring
  Nothing:Standard spring
- 2.5: Set torque value is displayed as a gravitational system of units
  (only when set torque is indicated)

Coupling Type

TGM 60C - D30 × C40 J - SS - 10.0

- TGM: Series
- 60C: Size
- D30: Shock Guard side Bore diameter
- C40: Coupling side Bore diameter
  (CRB for rough bore)
- J: Fastening method
  key way…
  J: new JIS standard type or E: old JIS 2type
  (For special type there is no key way)
- SS: Spring specifications
  SS:Reinforced spring WS:Weak spring Nothing:Standard spring
- 10.0: Set torque value is displayed as a gravitational system of units
  (only when set torque is indicated)

● TGZ Series

TGZ 30 - L - 25 J - 1.8

- TGZ: Series
- 30: Size
- L: Spring strength
  (L=weak spring
  M=medium spring
  H= strong spring)
- 25: Finished bore measurements
  (Not applicable for rough bore)
- J: Fastening method
  key way…
  J: new JIS standard type or E: old JIS 2type
  (For special type there is no key way)
- 1.8: The torque set value is displayed as the gravitational system of units
  17.8N·m {1.8kgf·m} (Only when set torque is indicated)

Coupling Type

TGZ 30 - LC - T25 J × C35 E - 1.8

- TGZ: Series
- 30: Size
- LC: Coupling Type
- T25: Shock Guard side finished bore measurements
  (TRB for rough bore)
- J: Fastening method
  key way…J: new JIS standard type or E: old JIS 2type
  (For special type there is no key way)
- C35: Coupling side finished bored measurements (CRB for rough bore)
- E: Fastening method
  key way…
  J: new JIS standard type or E: old JIS 2type
  (For special type there is no key way)
- 1.8: Set torque value is displayed as a gravitational system of units
  17.8N·m {1.8kgf·m} (only when set torque is indicated)

● TGK Series

TGK 20 - A 2 - 20 J

- TGK: Series
- 20: Size
- A: A=Air pressure
- 2: Type
  (2=Type 2)
- 20: Finished bore dimensions
- J: Key way
  (J=new JIS standards, F=old JIS 1 type, P=New JIS fine class)

Coupling Type

TGK 20 - A 5 - T20 J × C30 J

- TGK: Series
- 20: Size
- A: A=Air pressure
- 5: Type
  (5=Type 5、7=Type 7)
- T20: Shock Guard side finished bore dimensions
- J: Key way
  (J=new JIS standards, F=old JIS 1 type, P=New JIS fine class)
- C30: Coupling side finished bore dimensions
- J: Key way
  (J=new JIS standards, F=old JIS 1 type, P=New JIS fine class)

Shock Guard TGB Series

Features

Easy to operate and reasonably priced.
This standard model can be used with a broad range of applications.

Wide variety of sizes available

From 0.294N・m {0.03kgf・m} to 7154N・m {730kgf・m}, 58 sizes are available.

Automatic reset

After removing the cause of overload, the TGB Series automatically re-engages by rotating the drive side.

One position type

The balls and pockets, which transfer the torque, are engaged only in one position because of the unique structure.

Easy torque adjustment

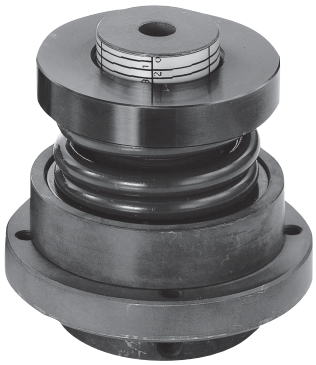
By simply turning the adjustment nut (bolts), trip torque can be easily adjusted.

Compact and precise

(TGB08 to 16) Ideal for use in compact motors, robots, and compact precision machines.

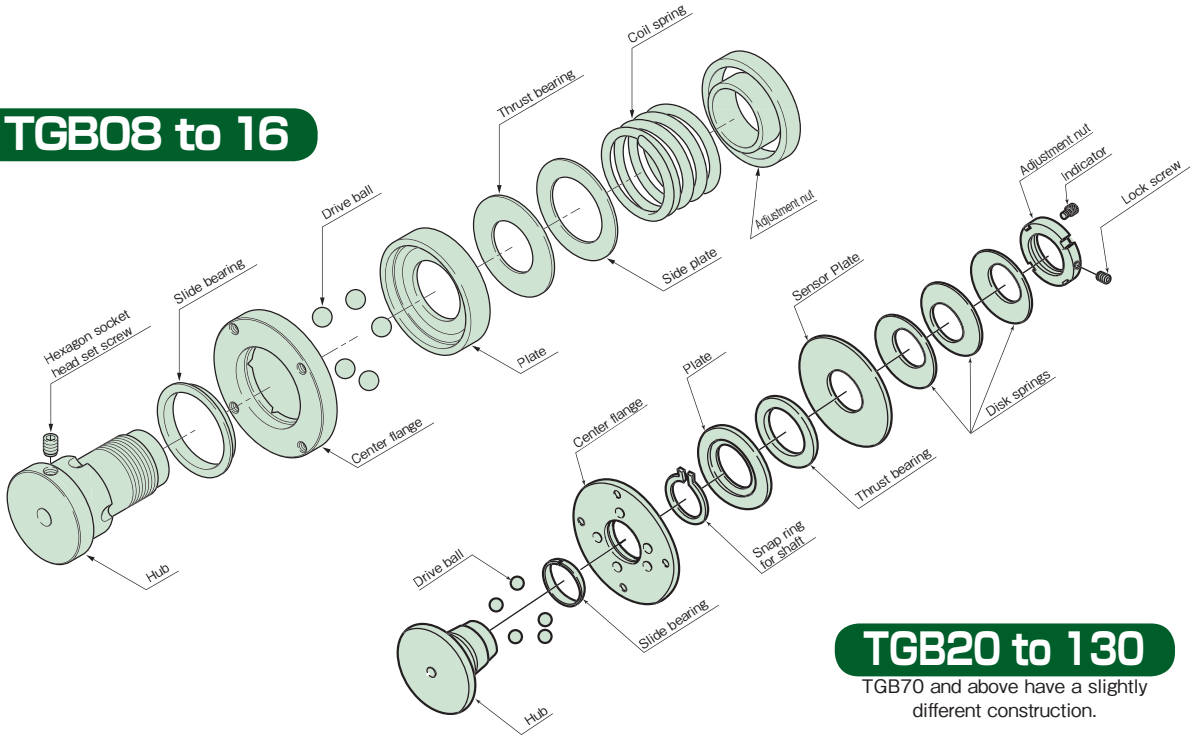
Non-backlash

TGB08 to 12 only. However, backlash may occur in the coupling portion for the coupling type.



Construction and Operating Principles

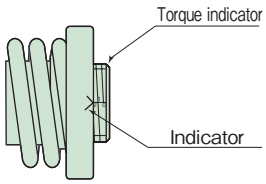
TGB08 to 16



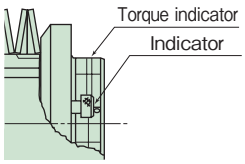
TGB20 to 130

TGB70 and above have a slightly different construction.

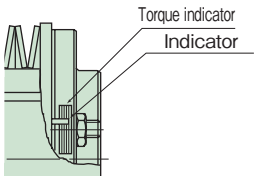
TGB08,12,16



TGB20,30,50

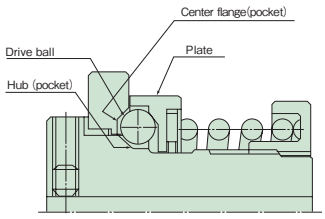


TGB70,90,110,130



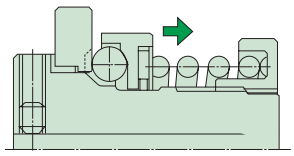
TGB08 to 16

During normal operation (engagement)



Torque transmission is carried out using several balls. The non-symmetric arrangement of the balls and pockets allows only one engagement position.
As well, there is no backlash due to non-clearance engagement between the retained and pressured balls and pockets.
Torque is transmitted from the center flange pockets) → drive balls → hub (pockets) → shaft.
(As well as the opposite)

During overload (trip)

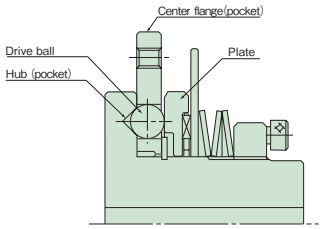


When the TGB Series trips due to overload, the ball pops out of the center flange pocket and it slides between the plate and center flange.

TGB20 to 50

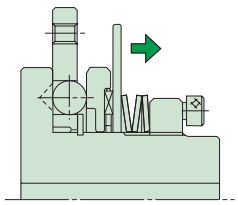
The principle of operation is the same for TGB70 to TGF130.

During normal operation (engagement)



Torque transmission is carried out using several balls. The non-symmetric arrangement of the balls and pockets allows only one engagement position.
Torque is transmitted from the center flange → drive balls → hub (pockets) → shaft. (As well as the opposite)

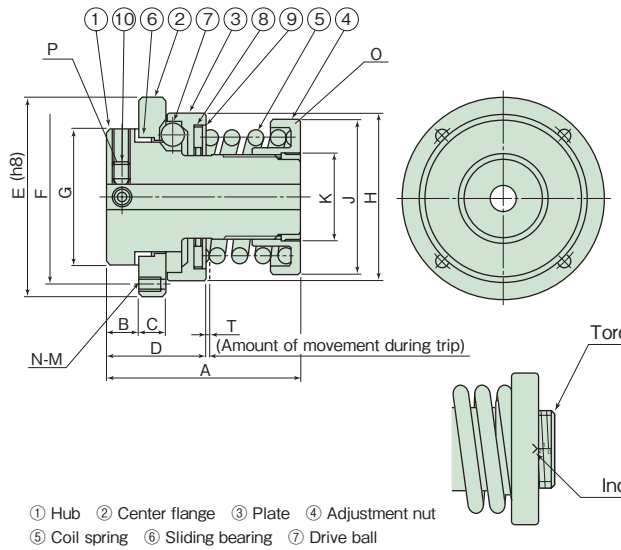
During overload (trip)



When it trips due to overload, the ball pops out of the hub pocket and rolls between the plate and hub.
When tripping, the rotational portion is entirely received by the bearings, so it rotates lightly and smoothly.

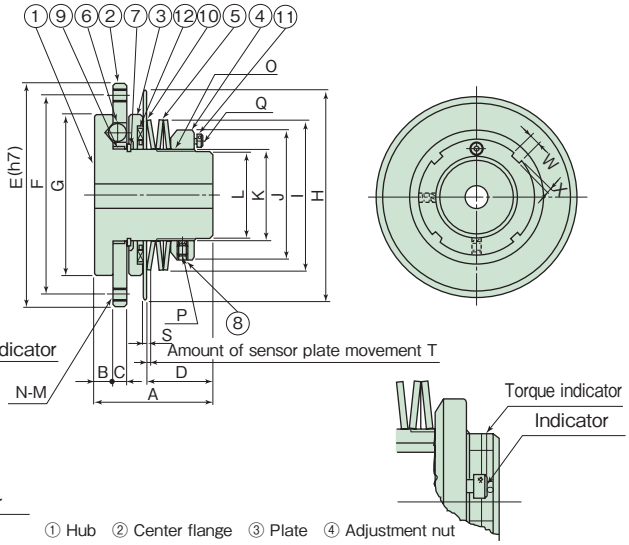
Transmissible Capacity/Dimensions

■ TGB08 to TGB16



① Hub ② Center flange ③ Plate ④ Adjustment nut
⑤ Coil spring ⑥ Sliding bearing ⑦ Drive ball
⑧ Thrust bearings ⑨ Side plate ⑩ Hexagon socket head set screw

■ TGB20 to TGB50



① Hub ② Center flange ③ Plate ④ Adjustment nut
⑤ Disk spring ⑥ Drive ball ⑦ Snap ring for shaft ⑧ Lock screw (note)
⑨ Sliding bearing ⑩ Sensor plate ⑪ Indicator ⑫ Thrust bearings

Note: One lock screw for fastening the adjustment nut is included with the Shock Guard. After setting to the optimal torque, tighten either lock screw with the torque amount given below.
Lock screw size: M5···3.8N·m{38.7kgf·cm}

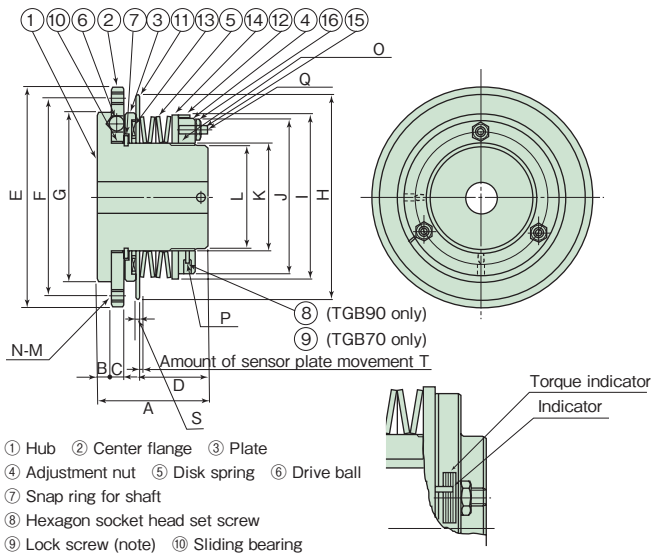
Unit : mm

Model No.	Set torque range N·m	Maximum r/min	Spring color	Rough bore diameter *1	Minimum bore diameter	Maximum bore diameter	A	B	C	D	E	F P.C.D	G	H	I
TGB08-L	0.29 to 1.47	1200	Yellow	5	6	8	39	6.5	5	20	40	34	26	33	—
TGB08-M	0.78 to 2.16		Blue												
TGB08-H	1.17 to 2.94		Orange												
TGB12-L	0.68 to 2.94	1000	Yellow	6	7	12	47	8	6	23.5	48	40	32	40	—
TGB12-M	1.96 to 4.9		Blue												
TGB12-H	2.94 to 5.88		Orange												
TGB16-L	1.47 to 4.9	900	Yellow	7	8	16	56	8.5	8	27.7	58	50	39	48	—
TGB16-M	2.94 to 7.84		Blue												
TGB16-H	5.88 to 11.76		Orange												
TGB20-H	9.8 to 44	700	Orange	8	9	20	47	7.5	5.7	25	90	78	62	82	54
TGB30-L	20 to 54	500	Yellow	12	14	30	60	9.5	7	33	113	100	82	106	75
TGB30-H	54 to 167		Orange												
TGB50-L	69 to 147	300	Yellow	22	24	50	81	14.5	8.5	44.8	160	142	122	150	116.7
TGB50-M	137 to 412		Blue												
TGB50-H	196 to 539		Orange												

Model No.	J	K	L	M	N	O screw diameter ×pitch	P screw diameter ×length	Q screw diameter ×length	S	T	W	X	Snap ring size Y	Mass kg*2	Moment of inertia*2 ×10^{-2}kg·m^2
TGB08-L	29.5	15	—	M 3	3	M15×1	M3× 4	—	—	0.9	—	—	—	0.14	0.0025
TGB08-M															
TGB08-H															
TGB12-L	35	20	—	M 4	3	M20×1	M4× 6	—	—	1	—	—	—	0.24	0.0065
TGB12-M															
TGB12-H															
TGB16-L	46	25	—	M 4	3	N25×1.5	M5× 6	—	—	1.2	—	—	—	0.44	0.018
TGB16-M															
TGB16-H															
TGB20-H	48	32	30	M 5	4	M32×1.5	M5× 6	M4× 8	2	1.8	5	2	32	0.9	0.058
TGB30-L	65	45	42.5	M 6	6	M45×1.5	M5× 6	M4×10	2	2	6	2.5	45	2	0.2
TGB30-H															
TGB50-L	98	75	70	M 8	6	M75×2	M5×10	M4×14	3	2.7	8	3.5	75	5.9	1.21
TGB50-M															
TGB50-H															

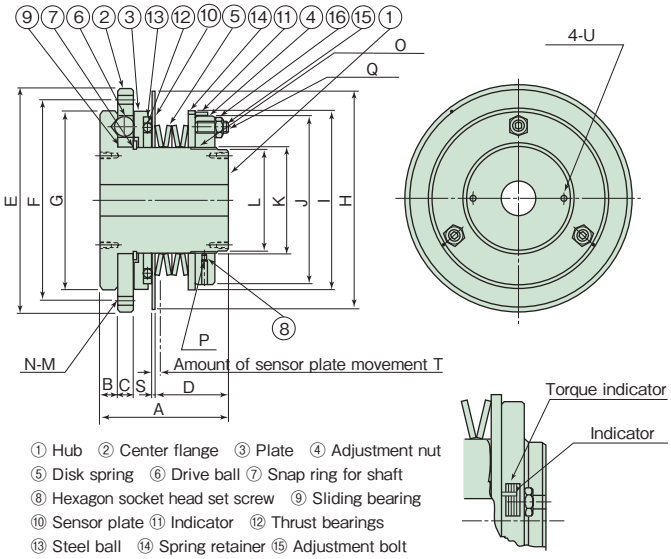
*1. All the models are in stock.
2. Mass and moment of inertia are based on the bores' maximum diameters.

■ TGB70 to TGB90



① Hub ② Center flange ③ Plate
④ Adjustment nut ⑤ Disk spring ⑥ Drive ball
⑦ Snap ring for shaft
⑧ Hexagon socket head set screw
⑨ Lock screw (note) ⑩ Sliding bearing
⑪ Sensor plate ⑫ Indicator ⑬ Thrust bearing
⑭ Spring retainer ⑮ Adjustment bolt ⑯ Hexagon nut

■ TGB110 to TGB130



① Hub ② Center flange ③ Plate ④ Adjustment nut
⑤ Disk spring ⑥ Drive ball ⑦ Snap ring for shaft
⑧ Hexagon socket head set screw ⑨ Sliding bearing
⑩ Sensor plate ⑪ Indicator ⑫ Thrust bearings
⑬ Steel ball ⑭ Spring retainer ⑮ Adjustment bolt
⑯ Hexagon nut

Unit : mm

Model No.	Set torque range N·m	Maximum r/min	Disk spring color	Rough bore diameter *1	Minimum bore diameter	Maximum bore diameter	A	B	C	D	E	F P.C.D	G	H	I
TGB 70-H	294 to 1080	160	Orange	32	35	70	110	14.5	12	68.5	220	200	170	205	166
TGB 90-L	441 to 1320	120	Yellow	42	44	90	157	25	22	88.6	295	265	236	290	213
TGB 90-H	931 to 3140		Orange												
TGB110-L	686 to 1960	100	Yellow	52	54	110	195	30	25	105	355	325	287	345	278
TGB110-H	1570 to 5100		Orange												
TGB130-L	1176 to 3038	80	Yellow	60	62	130	220	35	27	130	400	360	319	390	316
TGB130-H	2650 to 7154		Orange												

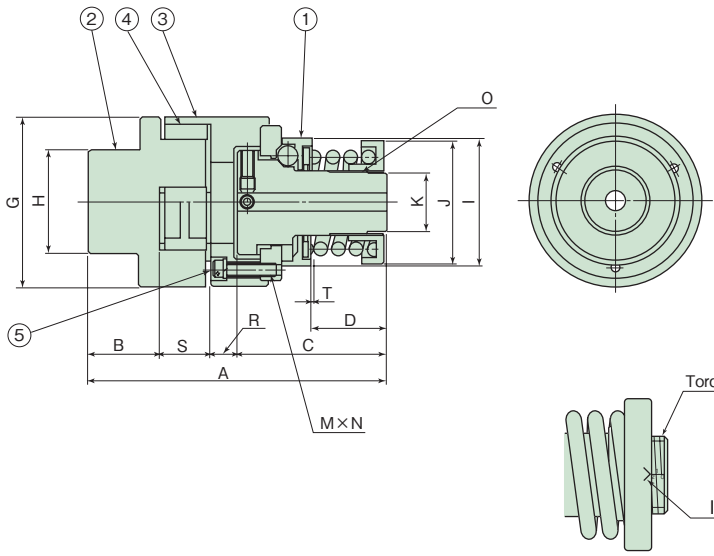
Model No.	J	K	L	M	N	O screw diameter × pitch	P screw diameter × length	Q screw diameter × length	S	T	U screw diameter × length	Snap ring size Y	Mass kg *2	Moment of inertia *2 ×10^{-2}kg·m^2
TGB 70-H	157	110	106	M10	6	M110×2	M 5×10	M10×28	3	3.3	—	110	17	6.3
TGB 90-L	203	130	124	M12	8	M130×2	M10×20	M16×35	5.5	5.4	M8×16	130	37.5	33.8
TGB 90-H														
TGB110-L	266	160	155	M16	6	M160×3	M12×20	M16×45	7	6	M10×20	160	69.6	91
TGB110-H														
TGB130-L	304	190	184	M16	8	M190×3	M16×30	M20×60	7	6.6	M12×34	190	102	167
TGB130-H														

*1. The models written in bold letters are in stock, and those in small letters are made to order.
2. Mass and moment of inertia are based on the bores' maximum diameters.

Transmissible Capacity/Dimensions

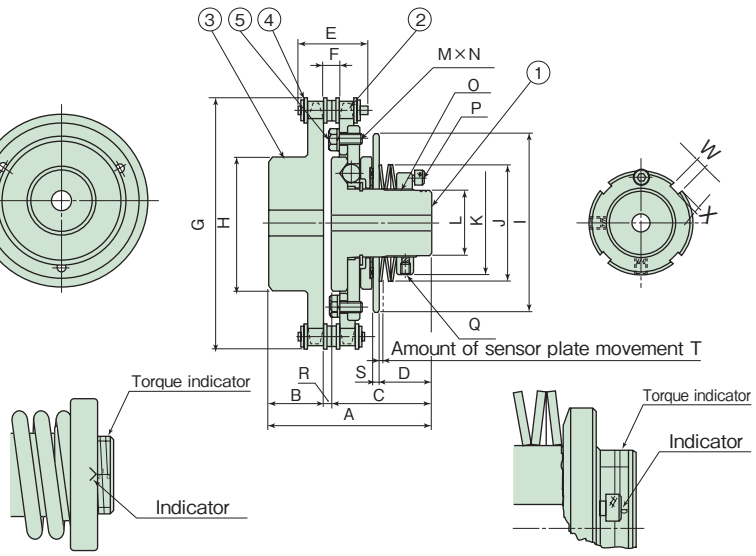
Coupling Type

■ TGB08-C to TGB16-C



① Main Shock Guard unit ② Coupling hub A ③ Coupling hub B ④ Insert
⑤ Hexagon bolt

■ TGB20-C to TGB50-C



① Main Shock Guard unit ② TGB sprocket ③ CP sprocket ④ Roller chain
⑤ Hexagon bolt

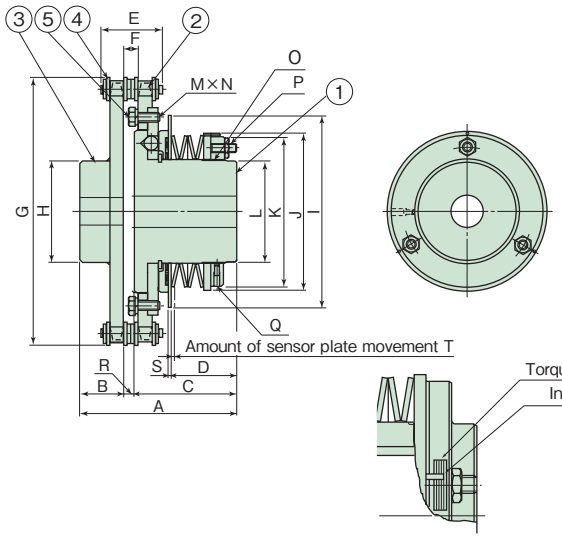
Unit : mm

Model No.	Set torque range N·m	Maximum r/min	Spring color	Shock Guard			Coupling			A	B	C	D	E	F	G	H	I
				Rough bore diameter *1	Minimum bore diameter	Maximum bore diameter	Rough bore diameter *1	Minimum bore diameter	Maximum bore diameter									
TGB08-LC	0.29 to 1.47	1200	Yellow	5	6	8	—	—	15	80	20.6	39	19	—	—	44.5	24	33
TGB08-MC	0.78 to 2.16		Blue															
TGB08-HC	1.17 to 2.94		Orange															
TGB12-LC	0.68 to 2.94	1000	Yellow	6	7	12	—	—	20	88	19.9	47	23.5	—	—	53.6	32	40
TGB12-MC	1.96 to 4.9		Blue															
TGB12-HC	2.94 to 5.88		Orange															
TGB16-LC	1.47 to 4.9	900	Yellow	7	8	16	—	—	25	112	27	56	28.3	—	—	64.3	38	48
TGB16-MC	2.94 to 7.84		Blue															
TGB16-HC	5.88 to 11.76		Orange															
TGB20-HC	9.8 to 44	700	Orange	8	9	20	12.5	14	42	76	25	47	25	32.6	7.4	117.4	63	82
TGB30-LC	20 to 54	500	Yellow	12	14	30	18	20	48	93	28	60	33	40.5	9.7	146.7	73	106
TGB30-HC	54 to 167		Orange															
TGB50-LC	69 to 147	300	Yellow	22	24	50	18	20	55	126	40	81	44.8	51	11.6	200.3	83	150
TGB50-MC	137 to 412		Blue															
TGB50-HC	196 to 539		Orange															

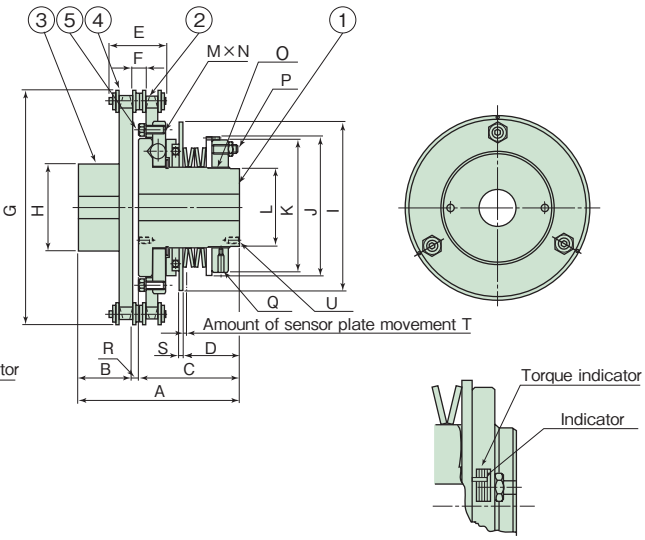
Model No.	J	K	L	M×N×No. of pieces	O screw diameter × pitch	P screw diameter ×length	Q screw diameter ×length	R	S	T	W	X	Coupling model No. or sprocket	Mass kg *2	Moment of inertia ×10²kg·m² *2
TGB08-LC	29.5	15	—	M3×12ℓ×3	M15×1	—	—	7.2	13.2	0.9	—	—	L075A	0.235	0.005
TGB08-MC															
TGB08-HC															
TGB12-LC	37	20	—	M4×16ℓ×3	M20×1	—	—	7.9	13.2	1	—	—	L090A	0.38	0.0123
TGB12-MC															
TGB12-HC															
TGB16-LC	46	25	—	M4×20ℓ×3	M25×1.5	—	—	10.2	18.8	1.2	—	—	L100A	0.673	0.0324
TGB16-MC															
TGB16-HC															
TGB20-HC	54	48	30	M5×12ℓ×4	M32×1.5	M4× 8	M5× 6	4	2	1.8	5	2	RS40-26	2.5	0.313
TGB30-LC	75	65	42.5	M6×16ℓ×6	M45×1.5	M4×10	M5× 6	5	2	2	6	2.5	RS50-26	4.8	0.948
TGB30-HC															
TGB50-LC	116.7	98	70 5	M8×20ℓ×6	M75×2	M4×14	M5×10	5	3	2.7	8	3.5	RS60-30	12.2	4.43
TGB50-MC															
TGB50-HC															

*1. All the models are in stock.
2. Mass and moment of inertia are based on the bores' maximum diameters.

■ TGB70-C to TGB90-C



■ TGB110-C to TGB130-C



① Main Shock Guard unit ② TGB sprocket ③ CP sprocket ④ Roller chain ⑤ Hexagon bolt

Unit : mm

Model No.	Set torque range N·m	Maximum r/min	Spring color	Shock Guard			Coupling			A	B	C	D	E	F	G	H	I
				Rough bore diameter	Minimum bore diameter	Maximum bore diameter	Rough bore diameter	Minimum bore diameter	Maximum bore diameter									
TGB 70-HC	294 to 1080	160	Orange	32	35	70	28	30	75	165	45	110	68.5	64.8	15.3	283.2	107	205
TGB 90-LC	441 to 1320	120	Yellow	42	44	90	33	35	103	242	80	157	88.6	78.5	18.2	394.4	147	290
TGB 90-HC	931 to 3140		Orange															
TGB110-LC	686 to 1960	100	Yellow	52	54	110	38	40	113	303	100	195	105	99.2	21.9	473.4	157	345
TGB110-HC	1570 to 5100		Orange															
TGB130-LC	1180 to 3038	80	Yellow	60	62	130	53	55	145	365	120	230	130	127.3	29.1	534.2	197	390
TGB130-HC	2650 to 7154		Orange															

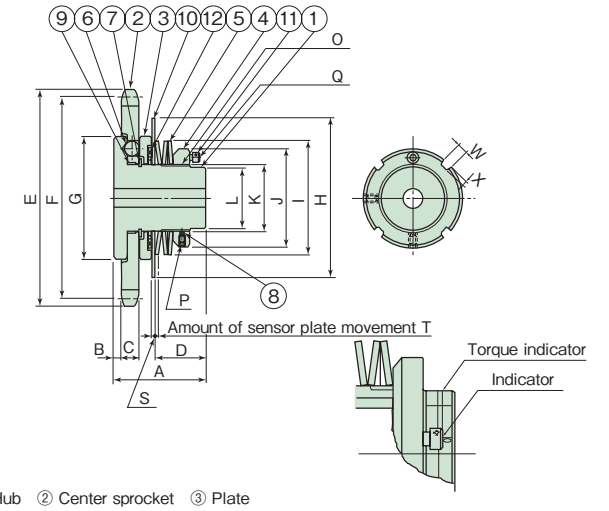
Model No.	J	K	L	M×N×No. of pieces	O screw diameter × pitch	P screw diameter × length	Q screw diameter × length	R	S	T	U screw diameter × length	Sprocket	Mass kg *1	Moment of inertia ×10²kg·m² *1
TGB 70-HC	166	157	106	M10×25ℓ×6	M110×2	M10×28	M 5×10	10	3	3.3	—	RS80-32	32.0	22.43
TGB 90-LC	213	203	124	M12×35ℓ×8	M130×2	M16×35	M10×20	5	5.5	5.4	M 8×16	RS100-36	71.1	117.32
TGB 90-HC														
TGB110-LC	278	266	155	M16×45ℓ×6	M160×3	M16×45	M12×20	8	7	6	M10×20	RS120-36	130.5	314.15
TGB110-HC														
TGB130-LC	316	304	184	M16×50ℓ×8	M190×3	M20×60	M16×30	15	7	6.6	M12×24	RS160-30	202.3	632.66
TGB130-HC														

*1. The models written in bold letters are in stock, and those in small letters are made to order.
2. Mass and moment of inertia are based on the bores' maximum diameters.

Transmissible Capacity/Dimensions

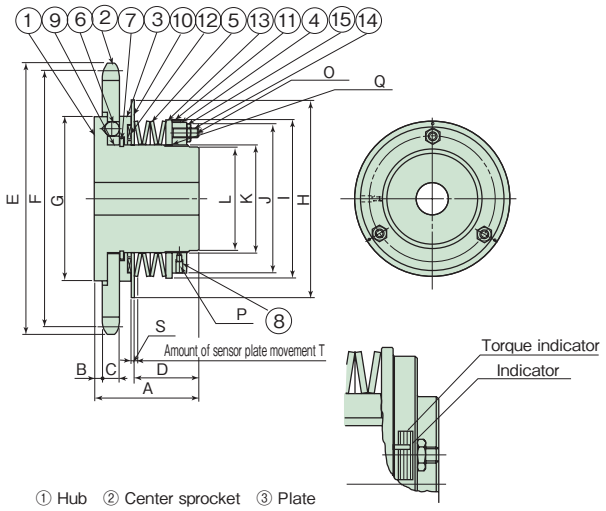
With Sprocket TGB

■ TGB20-□ to TGB50-□



① Hub ② Center sprocket ③ Plate
④ Adjustment nut ⑤ Disk spring ⑥ Drive ball ⑦ Snap ring for shaft
⑧ Lock screw (note) ⑨ Slide bearing
⑩ Sensor plate ⑪ Indicator ⑫ Thrust bearings

■ TGB70 to □



① Hub ② Center sprocket ③ Plate
④ Adjustment nut ⑤ Disk spring ⑥ Drive ball
⑦ Snap ring for shaft ⑧ Lock screw (note) ⑨ Slide bearing
⑩ Sensor plate ⑪ Indicator ⑫ Thrust bearings
⑬ Spring retainer ⑭ Adjustment bolt ⑮ Hexagon nut

Note: One lock screw for fastening the adjustment nut is included with the Shock Guard. After setting to the optimal torque, tighten either lock screw with the torque amount given below.
Lock screw size: M5···3.8N·m{38.7kgf·cm} M8···16N·m{163kgf·cm}

Unit : mm

Model No.	Set torque range N·m	Maximum r/min	Sprocket specifications	Disk spring color	Rough bore diameter	Minimum bore diameter	Maximum bore diameter	A	B	C	D	E	F P.C.D	G	H	I
TGB20-H-□	9.8 to 44	700	RS40-22T	Orange	8	9	20	47	5.9	7.2	25	96	89.24	62	82	54
			RS40-27T									116	109.4			
TGB30-L-□	20 to 54	500	RS60-19T	Yellow	12	14	30	60	4.8	11.6	33	126	115.74	82	106	75
TGB30-H-□	54 to 167		RS60-24T	Orange								156	145.95			
TGB50-L-□	69 to 147	300	RS80-20T	Yellow	22	24	50	81	8.42	14.5	44.8	176	162.37	122	150	116.7
TGB50-M-□	137 to 412			Blue												
TGB50-H-□	196 to 539		RS80-25T	Orange								216	202.66			
TGB70-H-□	294 to 1080	160	RS100-22T	Orange	32	35	70	110	8.9	17.5	68.5	240	223.10	170	205	166
			RS100-26T									281	263.40			

Model No.	J	K	L	O screw diameter xpitch	P screw diameter xlength	Q screw diameter xlength	S	T	W	X	Snap ring size Y	Mass kg	Moment of inertia ×10⁻²kg·m²
TGB20-H-□	48	32	30	M 32×1.5	M5× 6	M 4× 8	2	1.8	5	2	32	0.94	0.255
												1.15	0.486
TGB30-L-□	65	45	42.5	M 45×1.5	M5× 6	M 4×10	2	2	6	2.5	45	2.21	1.06
TGB30-H-□												2.78	2.07
TGB50-L-□	98	75	70	M 75×2	M5×10	M 4×14	3	2.7	8	3.5	75	6.35	6.10
TGB50-M-□													
TGB50-H-□												7.66	10.7
TGB70-H-□	157	110	106	M110×2	M5×10	M10×28	3	3.3	—	—	110	17.8	29.4
												19.9	42.5

*1. All products have a short delivery time.
2. Specify the preferable sprocket size.
3. Mass and moment of inertia are based on the bores' maximum diameters.
4. Sprocket specifications go in the box at the end of the model number. As well, refer to the below chart for Model No.

Model No.

TGB 50 - H - 08025 □ - 50 J - 30

- TGB: Series
- 50: Size
- H: Spring strength (L=weak spring, M=medium spring, H=strong spring)
- 08025: Sprocket model No.
- □: Sprocket mounting method (A : Adapter, B : External, No mark = Central)
- 50: Finished bore measurements (only when finished bore is indicated)
- J: Key way (J=new JIS standard, E= old JIS 2 type)
- 30: Set torque value is displayed as a gravitational system of units 294N·m {30kgf·m} (Only when set torque is indicated)

Sprocket Indication Method

Model No.	Sprocket specifications	Indication of Model No.
TGB20	RS40-22T	04022
	RS40-27T	04027
TGB30	RS60-19T	06019
	RS60-24T	06024
TGB50	RS80-20T	08020
	RS80-25T	08025
TGB70	RS100-22T	10022
	RS100-26T	10026

Finished Bore Shock Guard TGB/Coupling Type TGB-C

Finished bore products can be made for quick delivery

■ Bores and keyways are already finished before delivery.

TGB20-TGB70 and TGB20-C-TGB70-C finished bore is standard

■ Finished Bore Dimension Chart

Unit : mm

Shock Guard TGB		Finished bore dimensions	
Shock Guard Model No.	Coupling Type Model No.	Shock Guard side	Coupling side (Coupling Type only)
TGB20	**TGB20-C**	9,10,11,12,14,15,16,17,18,19,20	14,15,16,17,18,19,20,22,24,25,28,29,30,32,33,35,36,38,40,42
TGB30	**TGB30-C**	14,15,16,17,18,19,20,22,24,25,28,29,30	20,22,24,25,28,29,30,32,33,35,36,38,40,42,43,45,46,48
TGB50	**TGB50-C**	24,25,28,29,30,32,33,35,36,38,40,42,43,45,46,48,50	20,22,24,25,28,29,30,32,33,35,36,38,40,42,43,45,46,48,50,52,55
TGB70	**TGB70-C**	35,36,38,40,42,43,45,46,48,50,52,55,56,57,60,63,65,70	30,32,33,35,36,38,40,42,43,45,46,48,50,52,55,56,57,60,63,65,70,71,75
Delivery		Ex.-Japan 4 weeks by sea	

Model No.

Shock Guard

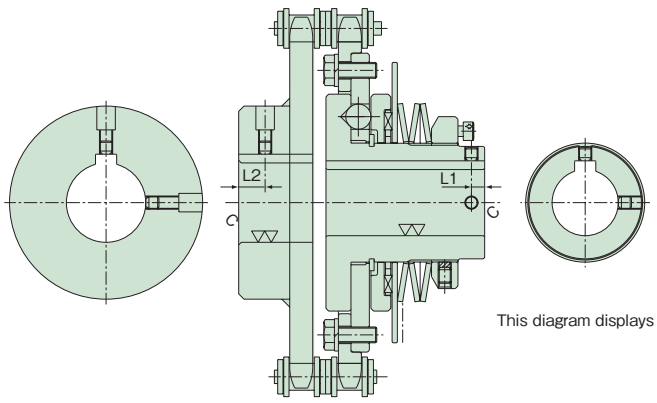
TGB30 - H - 30J

- TGB30: Size
- H: Spring type
- 30J: Bore diameter
- J: New JIS key standard type

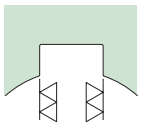
Coupling Type

TGB50 - MC - T40J×C50J

- TGB50: Size
- MC: Spring type
- T40J: Shock Guard side bore diameter
- J: New JIS key standard type
- C50J: Coupling side bore diameter
- J: New JIS key standard type



This diagram displays a coupling type



Keyway portion enlargement

Shock Guard TGB		Shock Guard Side		Coupling Side (Coupling Type only)	
Shock Guard Model No.	Coupling Type Model No.	Set screw	Set screw position L1	Set screw	Set screw position L2
TGB20	**TGB20-C**	2-M4× 4	4	2-M4× 4	8
TGB30	**TGB30-C**	2-M5× 5	5	2-M5× 5	10
TGB50	**TGB50-C**	2-M6× 6	6	2-M6× 6	12
TGB70	**TGB70-C**	2-M8×12	6	2-M8×12	15

1. Set screws are located at 2 positions, on the keyway and 90° CW from it.

■ Bore Diameter and Keyway Specifications

- Bore diamter tolerance is as follows:
  - ϕ18 and below ……0 to +0.021mm
  - ϕ19 and above ……H7
- The keyway is new JIS (JIS B 1301-1996) "standard".
- Set screws are included in the delivery

Bore diameter	Chamfer dimensions
ϕ25 and below	C0.5
ϕ50 and below	C1
ϕ51 and above	C1.5

● Roller chain and sprocket selection

For more information on roller chain and sprocket selection and handling, refer to the TSUBAKI drive chain catalog.

● Sprocket specifications

Sprockets are hardened.

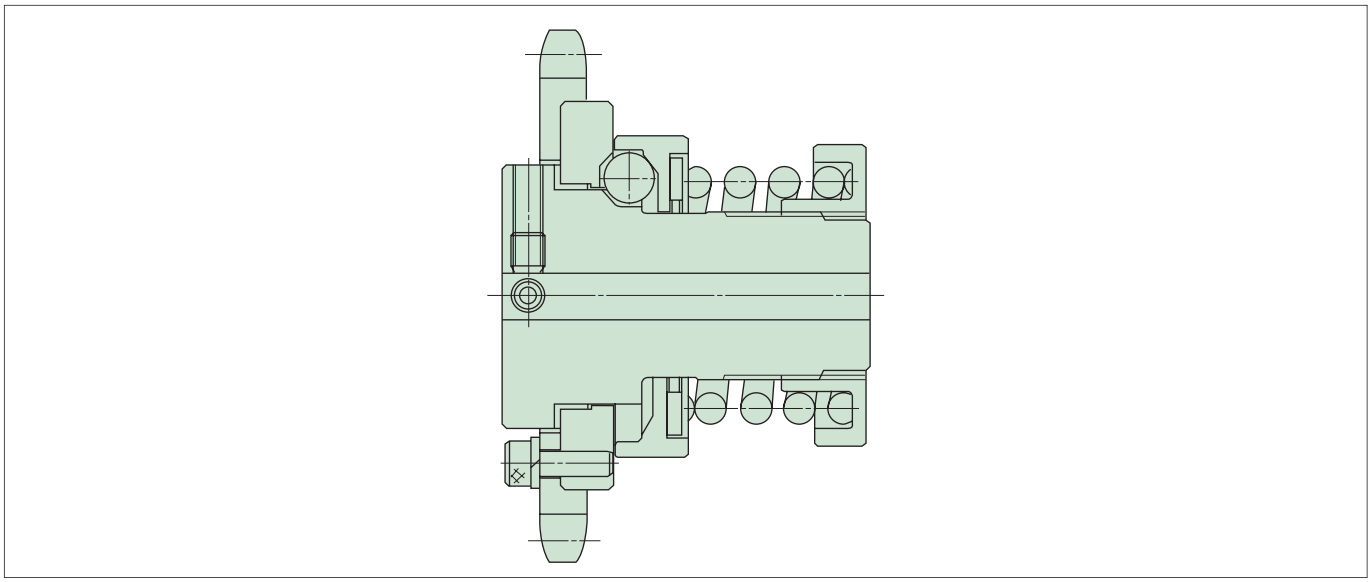
● Sprocket lubrication

- For more information on sprocket lubrication, refer to the TSUBAKI drive chain catalog.
- If the Shock Guard is lubricated in an oil bath or by the rotary plate or forced pump, there is a possibility that the indicator and name sticker may come off.

● Use of V pulley and timing pulley

- Confirm that the radial load caused by belt tension does not exceed the permissible load.

■ Installation example



Handling

1. Setting trip torque

(1)TGB Shock Guards are all set at the "0" point (minimum torque value) for delivery. Confirm that the torque indicator is set at "0" when you receive the Shock Guard. (Refer to the diagrams for each size)

(2)For the TGB70 to 130, loosen the three hexagon locknuts for adjusting bolts.
(The adjustment nuts of TGB08-50 can be turned as is.)

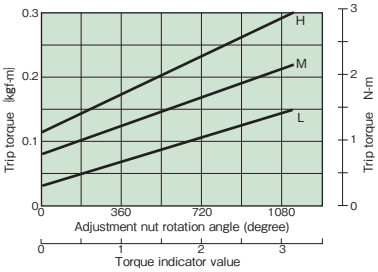
(3)From the "Tightening Amount - Torque Correlation Chart" (next page), find the adjustment nut's (bolt) tightening angle equivalent to the predetermined trip torque, and tighten them. Set at 60° toward the determined tightening value, then install to the machine and conduct a trip test. Gradually tighten and set at optimum trip torque. Each product's trip torque does not always correspond with the value listed in the "Tightening Amount - Torque Correlation Chart", so use them only as a rough guide.

(4)For the TGB20 to 50, tighten one lock screw for the adjustment nut.
For the TGB70 to 130, use a hexagon nut to lock it.
(The TGB08 to 16 adjustment nut is locked with a nylon coating.)

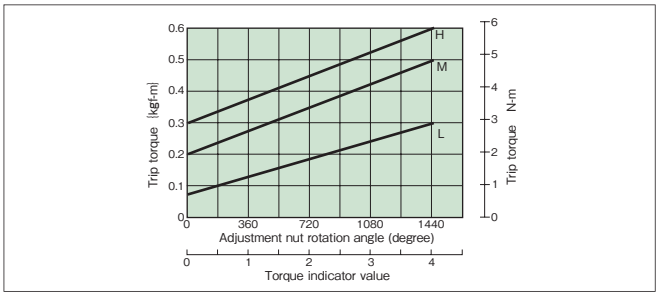
(5)Do not turn the adjustment nut (bolt) more than the torque indicator's maximum value. Doing so will put it in a locked position, and there will be no leeway for the disk spring to bend when tripping. (TGB08-16 uses a coil spring)

2. Tightening Amount-Torque Correlation Chart

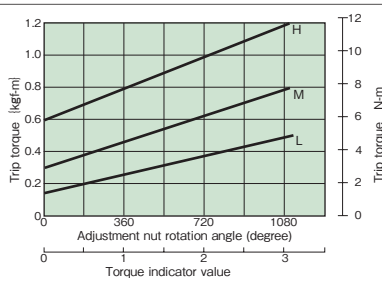
TGB08



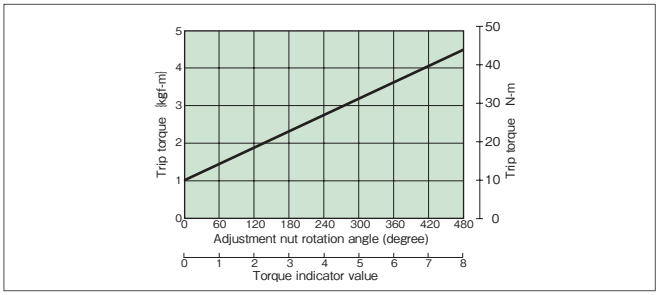
TGB12



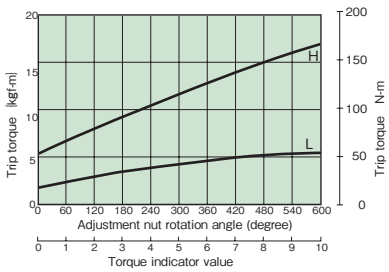
TGB16



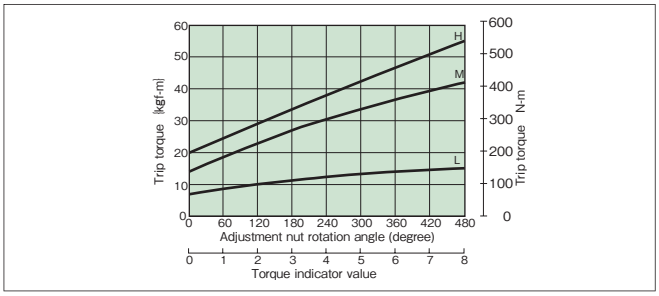
TGB20



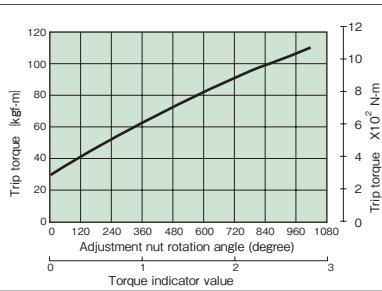
TGB30



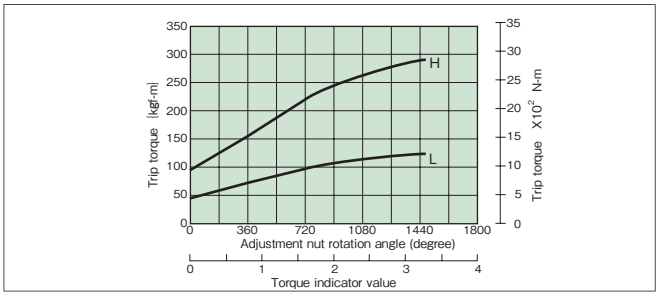
TGB50



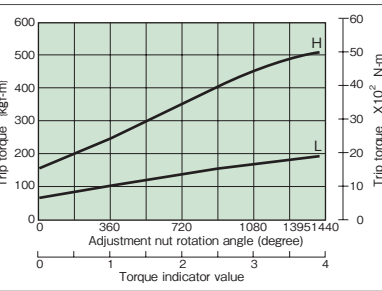
TGB70



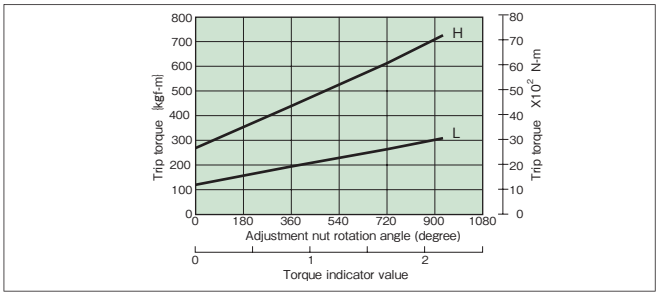
TGB90



TGB110



TGB130



3. Bore finishing

TGB08 to 16

- The hub's materials are made up of a surface-hardened iron based sintered alloy.

(1) Loosen the adjustment nut and disassemble all components. Make sure not to get any dust or dirt on the components.
(2) Chuck the hub flange's outside diameter and center the hub portion. The hub's material is a surface-hardened iron based sintered alloy, so we recommend the cutting tool be made of a hard material (JIS 9-20, K-01).
(3) Keyway machining should be carried out directly below the set screw tap.
(4) After bore finishing is completed and when reassembling the Shock Guard, make sure to coat the drive ball and thrust bearings with grease.
(5) For bore finishing, refer to the table and drawings below and make stepped bores.

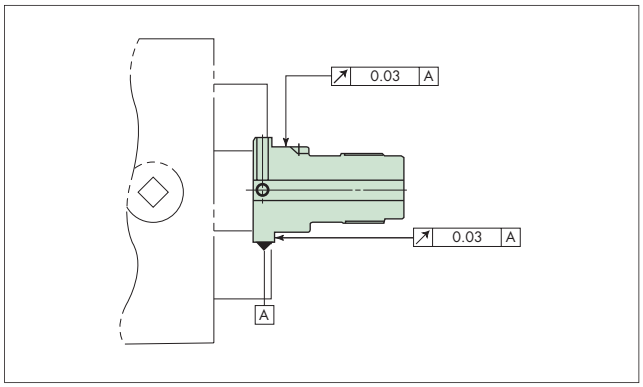
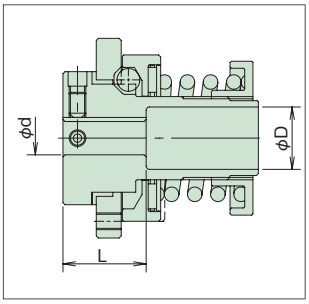
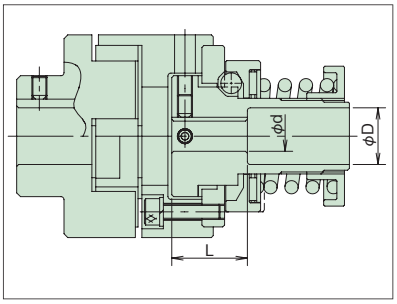


Table of bore lengths

Model No.	Bore diameter (φd)	Bore length (L mm)	Counterbore diameter (φD)
TGB08 TGB08-C	φ 6 and above φ 8 and below	20mm	φ11
TGB12 TGB12-C	φ 7 and above less than φ 10	20mm	φ15
	φ 10 and above less than φ 12	30mm	
	φ12	Total length	N/A
TGB16 TGB16-C	φ 8 and above less than φ 10	20mm	φ15
	φ 10 and above less than φ 12	30mm	
	φ 12 and above φ 16 and below	Total length	N/A



TGB08 to 16

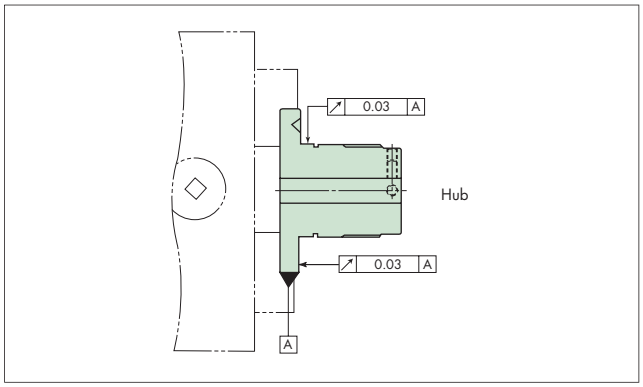


TGB08C to 16C

TGB20 to 130

- The hub has been thermally refined.

(1) Loosen the adjustment nut and disassemble all components. Remove both the Snap ring for shaft and the center plate. Make sure not to get any dust or dirt on the components.
(2) Chuck the hub flange's outside diameter and center the hub portion.
(3) Tapping for the set screws should be machined so they are spaced 90° from each other around the keyway.
(4) After bore finishing is completed and when reassembling the Shock Guard, make sure to coat the drive ball and thrust bearings with grease.



4. Resetting

As it is an automatic reset system, just re-starting the drive side of the motor, etc., can automatically reset it.

(1) When the Shock Guard trips due to overload, stop the rotation and remove the cause of the overload.
(2) When resetting, reset (re-engage) with input rpm at less than 50r/min or by inching the motor.

⚠ To avoid injury, do not reset the Shock Guard main unit or the shaft by hand.
(3) A distinct clicking sound is made when the drive ball settles in its pocket.

Drive member selection and manufacture

A sprocket, gear and pulley can be installed in the Shock Guard to act as the drive member (center member).
When selecting and manufacturing a drive member, refer to the precautions listed below.

(1)Use the outer diameter of the center flange as the spigot facing, and fix the drive member with bolts.
Verify the diameter of the Shock Guard's spigot facing with that of the drive member.
Each spigot is as listed in the chart below.

Unit : mm

Model No.	Spigot diameter	Model No.	Spigot diameter
TGB08-L,M,H	40(h8)	**TGB50-L,M,H**	160(h7)
TGB12-L,M,H	48(h8)	**TGB70-H**	220(h7)
TGB16-L,M,H	58(h8)	**TGB90-L,H**	295(h7)
TGB20-H	90(h7)	**TGB110-L,H**	355(h7)
TGB30-L,H	113(h7)	**TGB130-L,H**	400(h7)

(2)Center flange installation

・TGB08 to 16

The center flange's installation tap hole is penetrated. If the bolt's length is longer than the center flange, it will make contact with the plate. Make sure it does not stick out on the plate side.

・TGB20 to 130

The center flange's installation tap hole is penetrated. If the the bolt's length is too long there may be contact with the sensor plate. The recommended bolt screw lengths are listed in the chart below.

Unit : mm

Model No.	Bolt screw length	Model No.	Bolt screw length
TGB08-L,M,H	4	**TGB50-L,M,H**	9 to 11
TGB12-L,M,H	5	**TGB70-H**	13 to 15
TGB16-L,M,H	7	**TGB90-L,H**	23 to 25
TGB20-H	6 to 7	**TGB110-L,H**	26 to 28
TGB30-L,H	8 to 10	**TGB130-L,H**	28 to 30

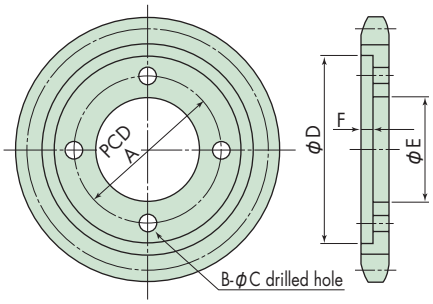
(3)Refer to the chart below for drive member bolt diameters (JIS B1001-1985).

●Bolt bore diameter JIS B1001 — 1985

Unit : mm

Nominal screw diameter	3	4	5	6	8	10	12	16
Bolt bore diameter	3.4	4.5	5.5	6.6	9	11	13.5	17.5

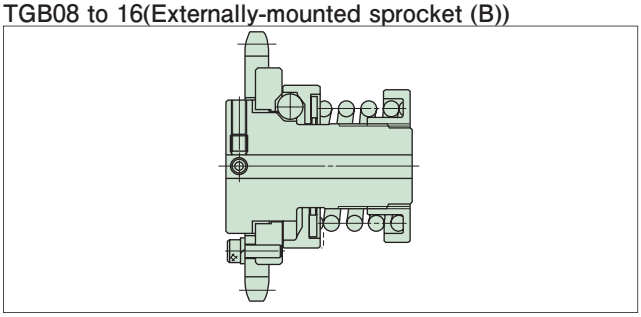
●Recommended dimensions for drive member finishing



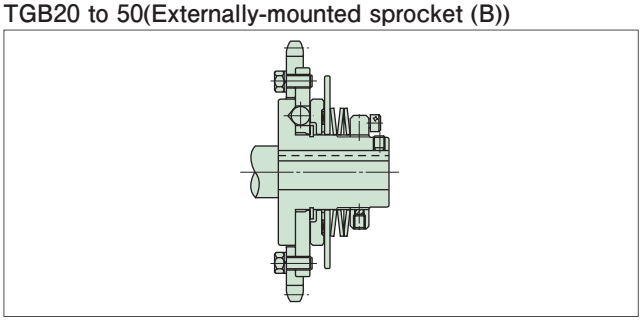
Series name	Drive member finishing dimensions					
	A	B	C	D	E	F
TGB08-L,M,H	34	3	3.4	40_{H7}	28	3
TGB12-L,M,H	40	3	4.5	48_{H7}	33	3
TGB16-L,M,H	50	3	4.5	58_{H7}	41	3
TGB20-H	78	4	5.5	90_{H7}	64	3
TGB30-L,H	100	6	6.6	113_{H7}	84	4
TGB50-L,M,H	142	6	9.0	160_{H7}	124	5
TGB70-H	200	6	11	220_{H7}	172	5
TGB90-L,H	265	8	13.5	295_{H8}	240	5
TGB110-L,H	325	6	17.5	355_{H8}	292	5
TGB130-L,H	360	8	17.5	400_{H8}	325	5

■ Installation example

TGB08 to 16(Externally-mounted sprocket (B))



TGB20 to 50(Externally-mounted sprocket (B))



Lock screw/tightening torque reference chart

Hexagon socket head screw	Tightening torque N·m{kgf·cm}
M5	3.8 {38.7}
M8	16 {163}

Precautions:

When re-tightening the lock screws that are once removed, make sure to take the following precautions:

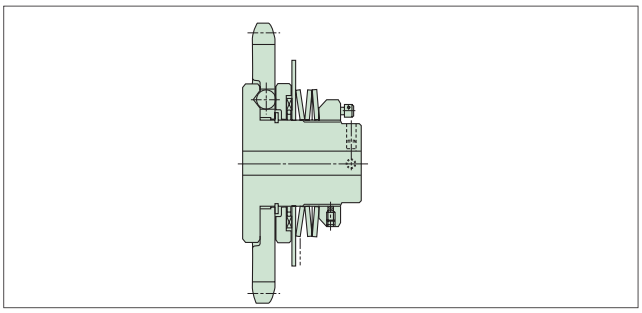
1. Confirm that the plug tip has not been removed. If a lock screw is used with a tipless plug, the hub's thread may be damaged or the hub's pocket may get jammed.
2. Confirm that the plug tip has not been heavily damaged. If a lock screw is used with a heavily damaged plug tip, the hub's thread may be damaged.

*If 1. or 2. is found to be the case, exchange the damaged parts with new ones.

Special specifications

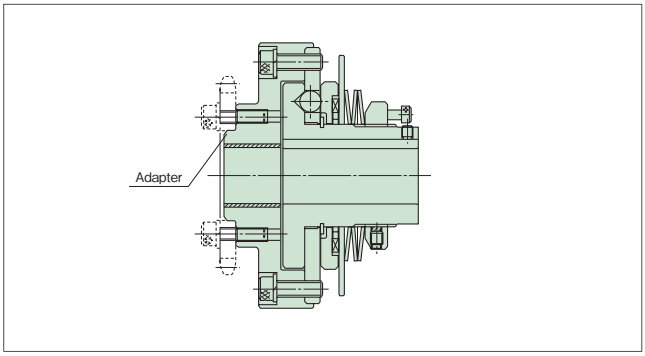
1. With sprocket type

We accept orders for with the sprocket the type that are not included among our standard products. Contact TEM to help you with your selection.



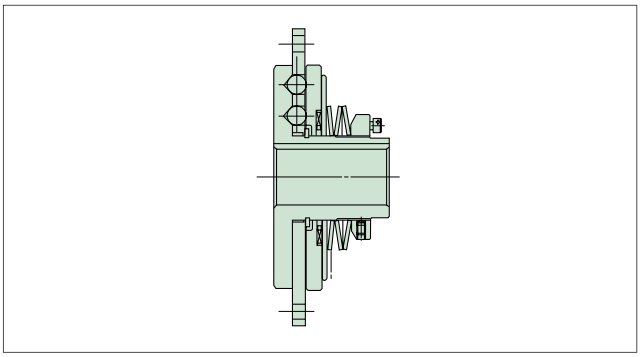
2. Adapter specifications(A)

It is convenient to use sprockets and pulleys with a small outside diameter. Contact TEM for more information on the sprocket and pulley you will install.



3. Forward-reverse type

Depending on Shock Guard rotation direction, the trip torque set value can be changed. Contact TEM for more information.



MEMO

Shock Guard TGE Series (Ex-MYTORQ310 Series)

Features

Applicable to small-diameter sprockets and wide pulleys.

Easy torque adjustment

You only have to adjust the nut height to adjust the torque.

Quick boring

Products with standard bores are delivered in a short period of time.

Automatic reset

Thanks to automatic re-engagement, you only have to turn the drive side after removing the causes of overload.

One position type

The balls and pockets, which transfer the torque, are engaged only in one position because of the unique structure.

TGE	
Type 1	Applicable to small-diameter sprockets and wide pulleys.
Type 3	A general-purpose type on which A type sprockets and pulleys can be directly mounted.

Type 1 With sprocket

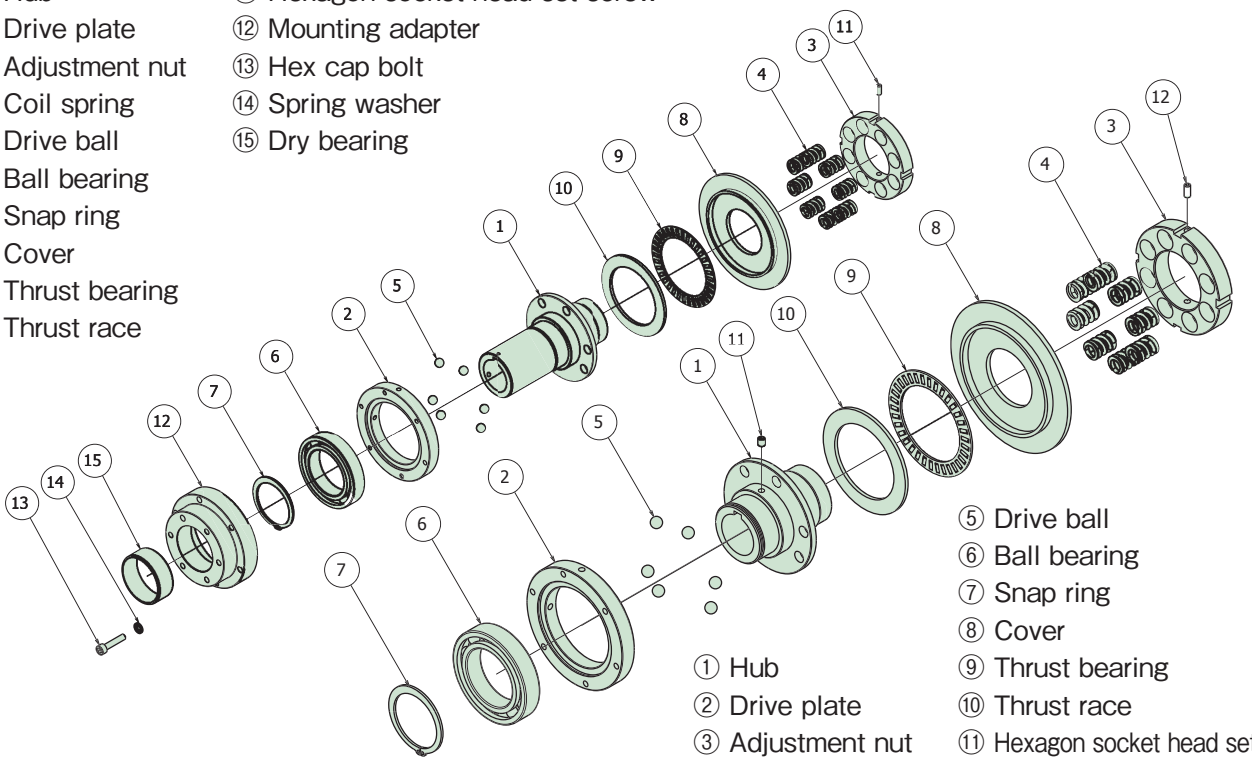
Type 3

Type 3 With sprocket

Construction and Operating Principles

TGE17-1 to 50-1 (Type 1)

① Hub
② Drive plate
③ Adjustment nut
④ Coil spring
⑤ Drive ball
⑥ Ball bearing
⑦ Snap ring
⑧ Cover
⑨ Thrust bearing
⑩ Thrust race
⑪ Hexagon socket head set screw
⑫ Mounting adapter
⑬ Hex cap bolt
⑭ Spring washer
⑮ Dry bearing

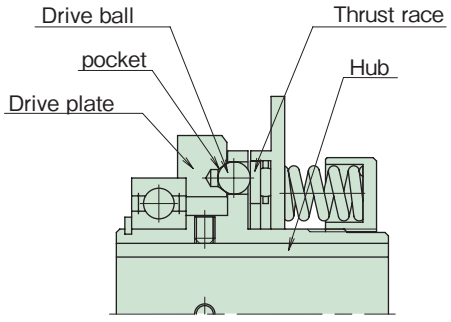


TGE17-3 to 50-3 (Type 3)

① Hub
② Drive plate
③ Adjustment nut
④ Coil spring
⑤ Drive ball
⑥ Ball bearing
⑦ Snap ring
⑧ Cover
⑨ Thrust bearing
⑩ Thrust race
⑪ Hexagon socket head set screw
⑫ Hexagon socket head set screw

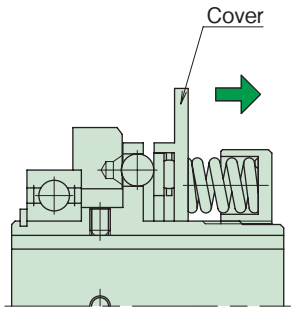
TGE17 to 50

During normal operation (engagement)



The TGE series transfers driving force from the hub to the drive plate on the output side via drive balls (and vice versa).
Bolt a sprocket or timing pulley directly to the drive plate.
The hub flange has several holes to hold the drive balls.
There are pockets on the drive plate on the output side, and the drive balls are pushed by coil springs via the thrust race to be fitted into the pockets to transfer the driving force.
If an overload occurs, the drive balls push the thrust race toward the coil springs and come out of the pockets of the drive plate while rotating to release the driving force.

During overload (trip)



Then, the cover moves toward the coil springs. Therefore, it is easy to stop the drive source automatically after the occurrence of an overload by detecting the amount of movement of the cover using a TG sensor or a similar device.

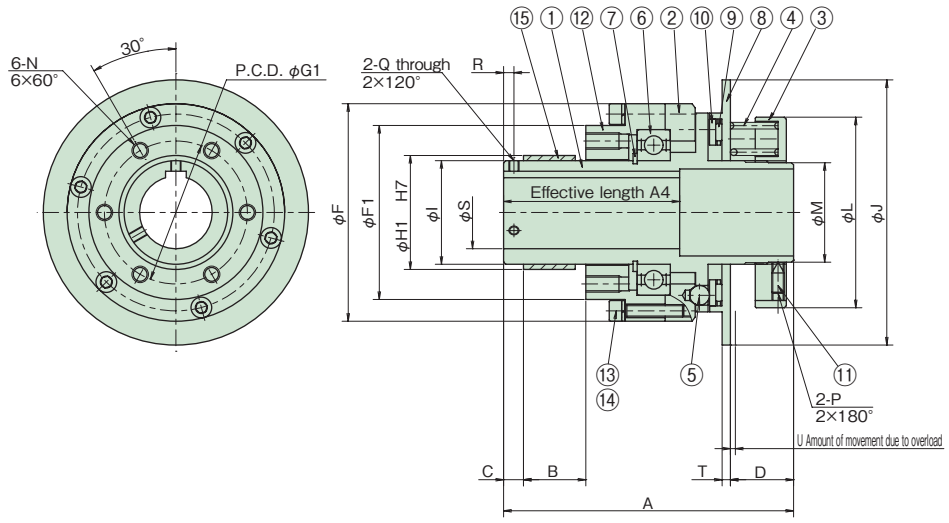
Resetting procedure

If you restart the operation after the occurrence of an overload, the drive balls automatically return to their positions within one revolution. If you continue to rotate the TGE series after the occurrence of an overload, the TGE series is repeatedly reset. Therefore, detect overloads using a TG sensor or a similar device and shutdown the drive source immediately.

Transmissible Capacity/Dimensions

■ TGE17-1 to TGE50-1

Type 1



① Hub
② Drive plate
③ Adjustment nut
④ Coil spring
⑤ Drive ball
⑥ Ball bearing
⑦ Snap ring
⑧ Cover
⑨ Thrust bearing
⑩ Thrust race
⑪ Hex cap bolt
⑫ Mounting adapter
⑬ Hexagon socket head set screw
⑭ Spring washer
⑮ Dry bearing

Unit : mm

Model No.	Set torque range N · m	Max. rpm r/min *1	Coil spring number	S				A	A4*4	B	C	D	F	F1	G1 P.C.D.	H1*5
				Rough bore diamter *2	Minimum bore diameter	JIS keyway for max. bore dia.	Half keyway for max. bore dia.*3									
TGE17-L1	1 to 5	870	2	—	12	15	17	87	30	22.6	7.9	16.9	57	42	35	28
TGE17-M1	2 to 10		4													
TGE17-H1	4 to 20		8													
TGE25-L1	5 to 25	540	2	—	12	22	25	110	50	30.1	9.6	21	84	65.5	53	44
TGE25-M1	10 to 50		4													
TGE25-H1	20 to 100		8													
TGE35-L1	20 to 100	430	2	—	17	32	35	140	85	30.1	9.6	30.5	105	84	69	55
TGE35-M1	40 to 200		4													
TGE35-H1	80 to 400		8													
TGE50-L1	30 to 200	310	3	—	27	48	50	165	115	48	9.6	30.5	145	116	94	75
TGE50-M1	60 to 400		6													
TGE50-H1	120 to 700		12													

Model No.	I	J	L	M	N screw diamter × length	P screw diameter × length	Q screw diameter*6	R*6	T	U	Mass kg*7	Moment of inertia kg · m²*7	Allowable radial load N	Dry bearing
TGE17-L1	25	70	56	26	M4×8	M4×10	M4	4	2.5	1.6	0.84	0.0011	6100	#70B2520
TGE17-M1														
TGE17-H1														
TGE25-L1	40	98	70	36	M5×9	M4×10	M5	5	3	2.0	1.9	0.0021	12200	#70B4025
TGE25-M1														
TGE25-H1														
TGE35-L1	50	128	92	48	M8×16	M6×10	M5	5	4	2.4	3.5	0.0054	12200	#70B5020
TGE35-M1														
TGE35-H1														
TGE50-L1	70	168	115	68	M8×12	M6×15	M5	5	5	3.2	7.5	0.0215	34300	#70B7040
TGE50-M1														
TGE50-H1														

*1. Contact us for details on use at speeds higher than the maximum speed.
2. Only center bore processing is available.
3. The half keyway dimension is the maximum bore diameter when the keyway depth is limited.
4. Contact us if an effective keyway length longer than the A4 dimension is required.
5. The H1 dimension is the machining dimension of the inner diameter of pulleys and sprockets (machining dimension tolerance of inner diameter H7).
6. Standard stocks are not processed. Dimensions are for reference only (products are delivered with a setscrew inserted upon request for processing).
7. Mass and moment of inertia are based on the bores' maximum diameters.

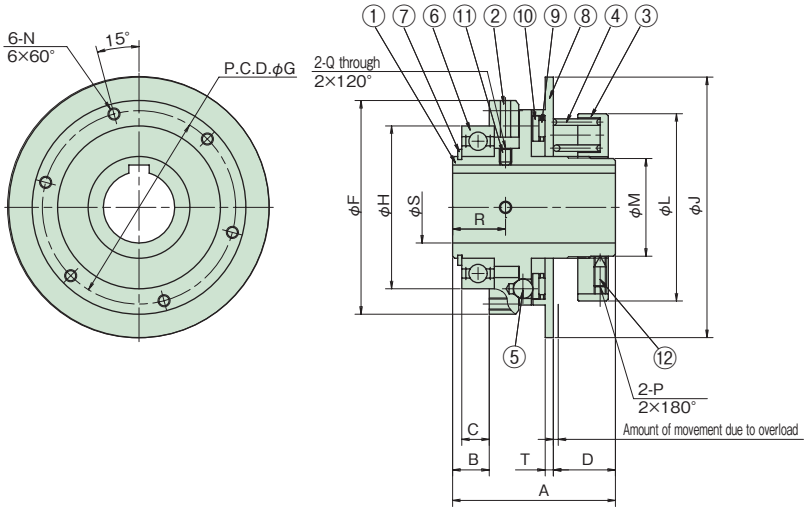
Note) When in stalling a pulley or sprocket, use high-tensile bolts (G10.9 or higher) and determine the length carefully so that the bolts are not buried deeper than the mounting tap depth N.

Limitation of keyway depth

Model No.	S bore diameter	Keyway width	Keyway depth
TGE17	16 – 17	5	1.8
TGE25	24 – 25	7,8	2
TGE35	34 – 35	10	2.4
TGE50	49 – 50	12,14	2.2

Transmissible Capacity/Dimensions

■ TGE17-3 to TGE50-3 Type 3



① Hub
② Drive plate
③ Adjustment nut
④ Coil spring
⑤ Drive ball
⑥ Ball bearing
⑦ Snap ring
⑧ Cover
⑨ Thrust bearing
⑩ Thrust race
⑪ Hexagon socket head set screw
⑫ Hexagon socket head set screw

Unit : mm

Model No.	Set torque range N · m	Max. rpm r/min *1	Coil spring number	S						A	B	C	D	F	G P.C.D.
				Rough bore diamter *2	Minimum bore diameter	JIS keyway for max. bore dia.	Standard bore diameter (Tolerance: H7) *3								
TGE17-L3	1 to 5	900	2	–	12	17	12	15	17	47	9	6	16.9	57	50
TGE17-M3	2 to 10		4												
TGE17-H3	4 to 20		8												
TGE25-L3	5 to 25	900	2	10	12	25	20	22	25	60	13	9	21	84	75
TGE25-M3	10 to 50		4												
TGE25-H3	20 to 100		8												
TGE35-L3	20 to 100	750	2	15	17	35	25	30	35	80	18	13.5	30.5	105	95
TGE35-M3	40 to 200		4												
TGE35-H3	80 to 400		8												
TGE50-L3	30 to 200	570	3	25	27	50	40	45	50	95	20	15	30.5	145	130
TGE50-M3	60 to 400		6												
TGE50-H3	120 to 700		12												

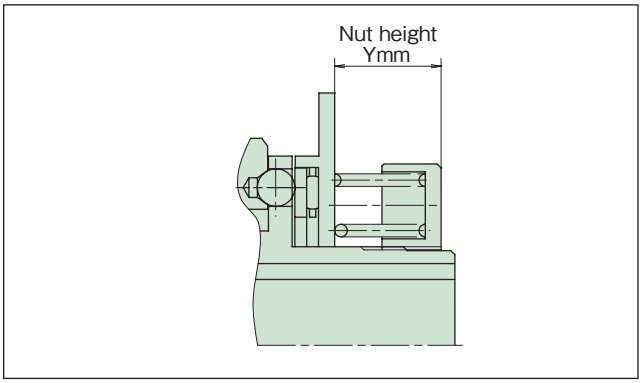
Model No.	H	J	L	M	N screw diamter × length	P screw diamter × length	Q screw diameter *4	R *4	T	U	Mass kg *5	Moment of inertia kg · m² *5	Allowable radial load N	Dry bearing
TGE17-L3	42	70	56	26	M4×8	M4×10	M4	15	2.5	1.6	0.56	0.0010	3400	#6905ZZ
TGE17-M3														
TGE17-H3														
TGE25-L3	62	98	70	36	M5×10	M4×10	M5	20	3	2.0	1.3	0.0016	7500	#6908ZZ
TGE25-M3														
TGE25-H3														
TGE35-L3	80	128	92	48	M6×14	M6×10	M6	26	4	2.4	2.6	0.0037	12400	#6010ZZ
TGE35-M3														
TGE35-H3														
TGE50-L3	110	168	115	68	M8×17	M6×15	M8	31.5	5	3.2	5.1	0.0142	23200	#6014ZZ
TGE50-M3														
TGE50-H3														

*1. Contact us for details on use at speeds higher than the maximum speed.
2. Only center bore processing is available.
3. The keyway dimension of a product with a standard bore complies with JIS B 1301, and the keyway width tolerance is Js9.
4. Standard stocks are not processed. Dimensions are for reference only.
5. Mass and moment of inertia are based on the bores' maximum diameters.

Note) When in stalling a pulley or sprocket, use high-tensile bolts (G10.9 or higher) and determine the length carefully so that the bolts are not buried deeper than the mounting tap depth N.
Products with a standard bore are delivered with a shaft-securing setscrew inserted. If you will not use the setscrew to secure the shaft, be sure to remove the setscrew from the hub (screw the setscrew to make it penetrate and come out of the hole).

Torque adjustment

1. Read the nut height that corresponds to the required torque from the torque correlation charts and tighten the torque adjustment nut to that height (refer to the figure below). To tighten the torque adjustment nut, loosen the two setscrews, hook a hook spanner (sold separately, refer to the table on the right) on the notch in the periphery of the nut, and then turn the nut.

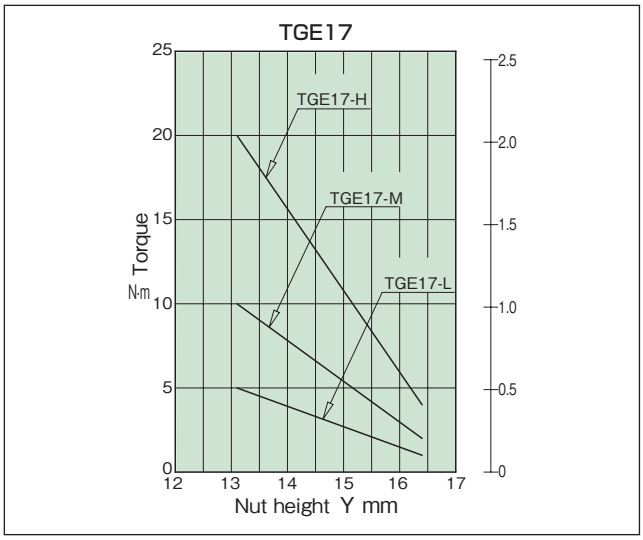


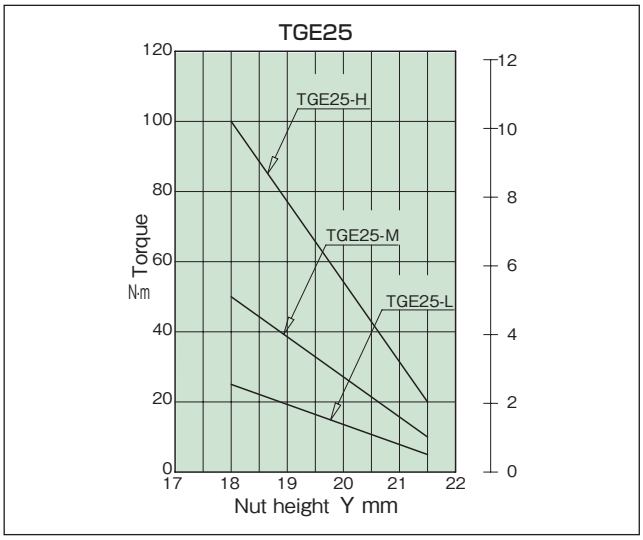
Hook spanner wrench

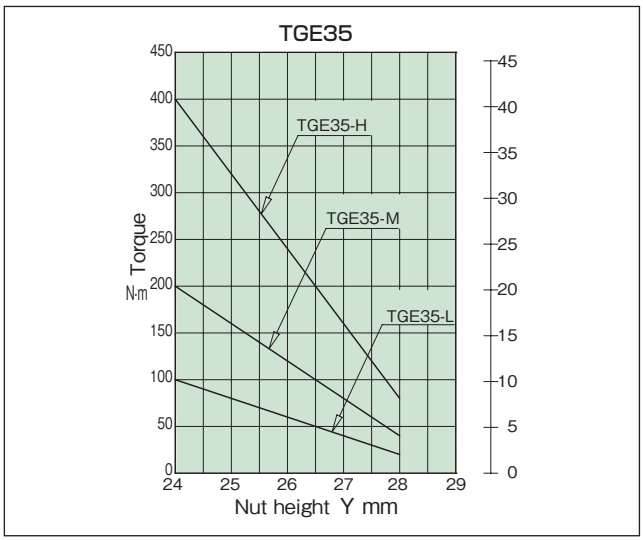
Size	TGE25	TGE35	TGE50
Spanner No.	FK-0070	FK-0092	FK-0105

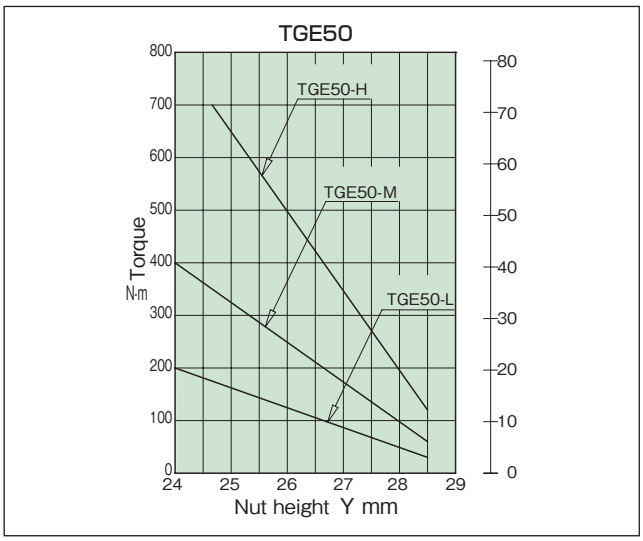
2. When the torque is determined, write down the torque on the nameplate so that you can easily set the torque to the previous value even after an overhaul. If you mark matchmarks on both the nut and the edge of the hub, you can reset the torque more precisely.

Torque Correlation Chart









MEMO

Shock Guard TGX Series

Features

Non-backlash. Provides superb rigidity during normal operation. Ideal for applications that require highly accurate positioning.

Highly accurate trip

The lost motion during trip is very small.

Non-backlash

Due to its innovative ball and wedge construction (PAT.), there is almost no backlash.

Coupling function

For the coupling, the ball and wedge mechanism absorbs the angle, parallel and axial displacement misalignment.

Easy torque adjustment

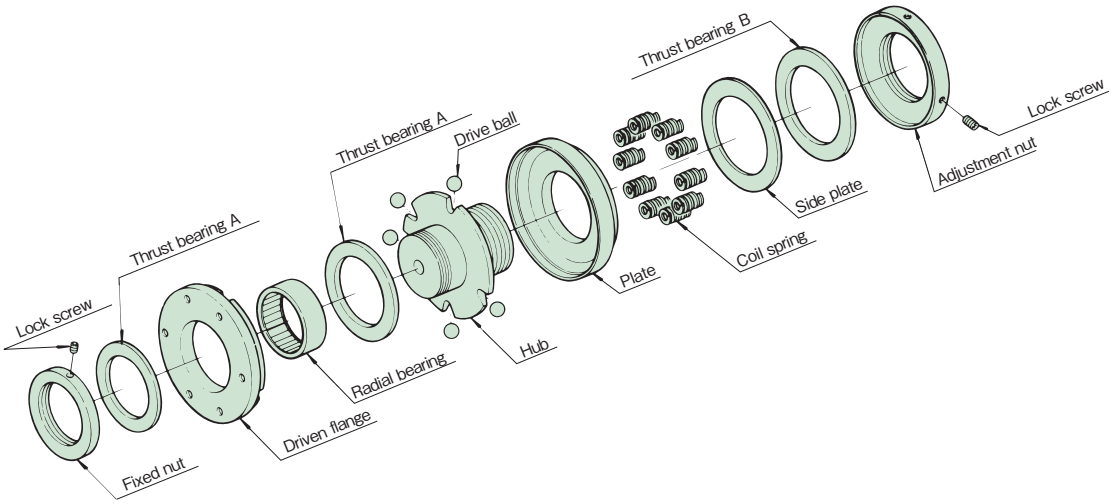
Just by turning the adjusting nut, trip torque can be freely adjusted.

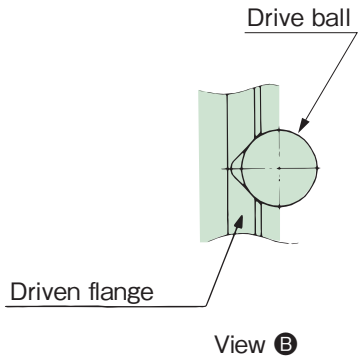
One position

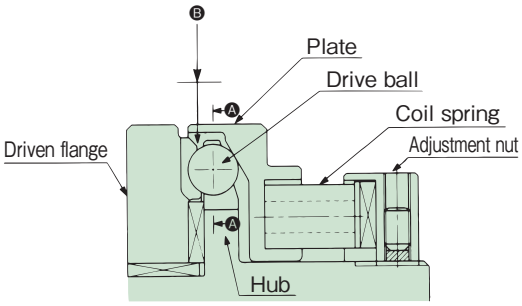
The unique assembly of the TGX Series means the ball and wedge configuration engages in only 1 position.

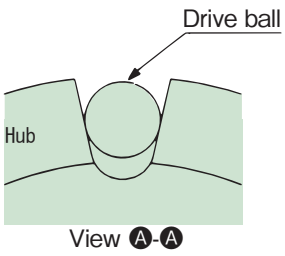
TG Sensor

Construction and Operating Principles







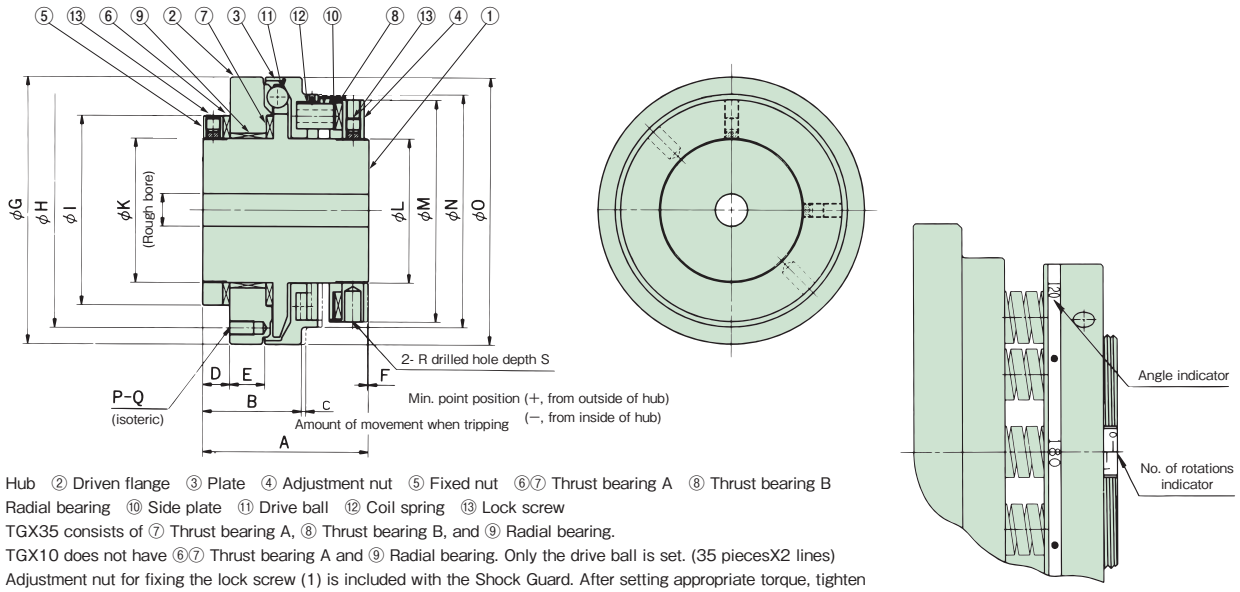


Ball and Wedge Mechanism

Torque transmission is transmitted from the hub → drive ball → driven flange. (As well as the reverse direction.)
Due to the force of the coil spring, the drive ball is retained in between the hub and driven flange, and the contact portion between the plate and the drive ball are tapered, and the clearance between the drive balls and V-shape retaining portions is always zero. (View A-A)
In addition, because of the 2 points contact of drive balls with the driven flange at V-shaped pocket, there is no backlash. (View B)
This mechanism is a ball and wedge mechanism (PAT.).
During overload the drive balls pop out from their pockets and start rolling.
Because of this not sliding but all rolling mechanism, the friction torque when idling is extremely small and it is a highly durable mechanism.
Reset is carried out by an automatic reset system. As operation is resuming, the drive ball resets to its pocket.
As well as the TGB Series, the non-symmetric arrangement of the 5 drive balls and pockets allows only one engagement position, and there is no phase shift.

Transmissible Capacity/Dimensions

Shock Guard (high precision TGX Series)



① Hub ② Driven flange ③ Plate ④ Adjustment nut ⑤ Fixed nut ⑥⑦ Thrust bearing A ⑧ Thrust bearing B
⑨ Radial bearing ⑩ Side plate ⑪ Drive ball ⑫ Coil spring ⑬ Lock screw
*1 TGX35 consists of ⑦ Thrust bearing A, ⑧ Thrust bearing B, and ⑨ Radial bearing.
*2 TGX10 does not have ⑥⑦ Thrust bearing A and ⑨ Radial bearing. Only the drive ball is set. (35 piecesX2 lines)
*3 Adjustment nut for fixing the lock screw (1) is included with the Shock Guard. After setting appropriate torque, tighten with the following torque to avoid interference with the hub's pocket.
Lock screw size: TGX10 to 35 M5…3.8N·m{38.7kgf·cm} TGX50/70 M8…16N·m{163kgf·cm}

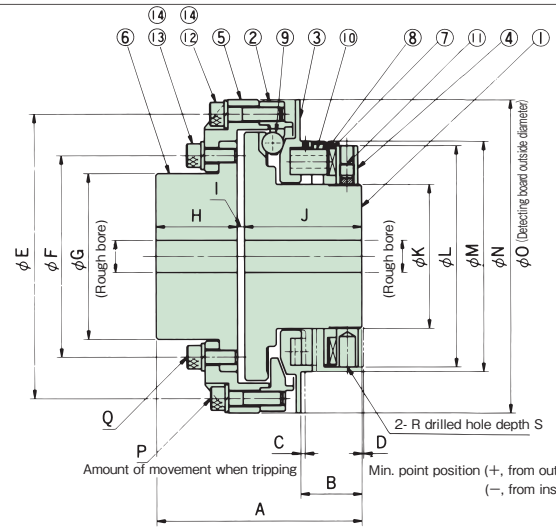
Unit : mm

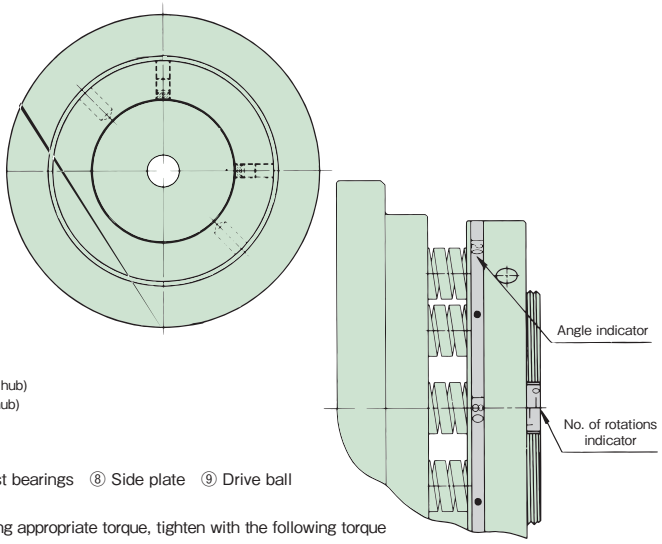
Shock Guard Model No.	Set Torque range N·m	Max. *r/min	Coil spring color × number	Rough bore diamter	Min. bore diameter	Max. bore diameter	A	B	C amount of movement during trip	D	E	F min. point position	G h7	H PCD	I
TGX10-L	1.7 to 6.4	1400	Yellow×3	7	9	15	53	22	1.4	7.5	6.6	+0.3	62	54	42
TGX10-M	5.4 to 15		Red×3												
TGX10-H	11 to 29		Red×6												
TGX20-L	6.5 to 24	1100	Yellow×6	8.5	10	25	64	35	1.6	10	13.4	+0.7	86	74	60
TGX20-M	13 to 34		Red×3												
TGX20-H	25 to 68		Red×6												
TGX35-L	23 to 68	800	Red×5	12	14	35	68	37.5	2.0	11	11.6	− 0.5	107	88	70
TGX35-M	43 to 98		Green×5												
TGX35-H	87 to 196		Green×10												
TGX50-L	45 to 118	600	Red×5	18	20	55	92	54.8	2.6	15	19.5	+ 0.3	148	130	105
TGX50-M	90 to 196		Green×5												
TGX50-H	176 to 392		Green×10												
TGX70-L	127 to 363	480	Red×8	23	25	70	98	61	3.5	15	19.2	+ 1.0	185	164	135
TGX70-M	265 to 510		Green×8												
TGX70-H	392 to 784		Green×12												

Shock Guard Model No.	K Screw diameter × pitch	L Screw diameter × pitch	M	N	O	P	Q screw diamter × length	R	S	*Mass kg	* Moment of inertia $\times 10^{-2}$kg·m^2
TGX10-L	M 25×1.5	M 30×1.5	56	58	61.8	4	M 4× 6	5	10	0.75	0.0293
TGX10-M											
TGX10-H											
TGX20-L	M 40×1.5	M 40×1.5	70	73	86	6	M 5× 8	5	10	1.67	0.134
TGX20-M											
TGX35-L	M 50×1.5	M 55×1.5	88	91	107	6	M 6× 7	6	10	2.51	0.333
TGX35-M											
TGX50-L	M 80×1.5	M 80×1.5	123	129	148	6	M 8×13	9	17	7.03	1.83
TGX50-M											
TGX50-H											
TGX70-L	M100×2.0	M100×2.0	148	153	185	6	M10×13	10	18	11.4	4.88
TGX70-M											
TGX70-H											

*1. All the models are in stock.
2. Instantaneous stop is not possible, TGXZ Series is recommended. (Refer to page 77)
3. Mass and moment of inertia are based on the bores' maximum diameters.
4. Maximum bore diameter is with key installation. In case of Power-Lock installation, refer to p 48.

Coupling Type





① Hub ② Center flange ③ Plate ④ Adjustment nut ⑤ Flange ⑥ Boss ⑦ Thurst bearings ⑧ Side plate ⑨ Drive ball
⑩ Coil spring ⑪ Lock screw ⑫ Hex cap bolt ⑬ Hex cap bolt ⑭ Spring washer

* Adjustment nut for fixing the lock screw (1) is included with the Shock Guard. After setting appropriate torque, tighten with the following torque to avoid interference with the hub's pocket. Lock screw size: TGX10 to 35 M5···3.8N·m{38.7kgf·cm} TGX50/70 M8···16N·m{163kgf·cm}

Unit : mm

Coupling Type Model No.	Set Torque range N·m	Max. *r/min	Coil spring color × number	Shock Guard			Coupling			A	B	C	D min. point position	E PCD	F PCD	G	H
				Rough bore diameter	Minimum bore diameter	*Maximum bore diameter	Rough bore diameter	Minimum bore diameter	*Maximum bore diameter								
TGX10-LC	1.5 to 5.4	700	Yellow×3	7	9	15	7	9	19	69	24	1.3	+ 0.3	62	42	33	25
TGX10-MC	4.6 to 13		Red×3														
TGX10-HC	9.3 to 25		Red×6														
TGX20-LC	5.2 to 19	550	Yellow×6	8.5	10	25	8.5	10	35	84	24	1.6	+ 0.3	89	66	55	35
TGX20-MC	9.8 to 27		Red×3														
TGX20-HC	21 to 55		Red×6														
TGX35-LC	19 to 57	400	Red×5	12	14	35	12	14	50	88	24	1.9	− 0.5	113	83	70	35
TGX35-MC	36 to 84		Green×5														
TGX35-HC	74 to 167		Green×10														
TGX50-LC	40 to 98	300	Red×5	18	20	55	18	20	60	114	34	2.4	+ 0.9	158	112	92	45
TGX50-MC	81 to 176		Green×5														
TGX50-HC	167 to 343		Green×10														
TGX70-LC	118 to 323	240	Red×8	23	25	70	23	25	80	124	36	3.3	+ 0.6	200	145	116	50
TGX70-MC	235 to 461		Green×8														
TGX70-HC	353 to 696		Green×12														

Coupling Type Model No.	I	J	K Screw diamter × pitch	L	M	N	O	P screw diameter ×length	Q screw diameter ×length	R	S	* Mass kg	* Moment of inertia $\times 10^{-2}$kg·m^2	Allowable angular misalignment(deg.)	Allowable parallel misalignment	Allowable shaft direction displacement
TGX10-LC	2	42	M 30×1.5	56	−	74	74	M 4×18	M 4×10	5	10	1.07	0.0555	0.6	0.1	±0.5
TGX10-MC																
TGX10-HC																
TGX20-LC	3	46	M 40×1.5	70	−	98	98	M 5×20	M 5×12	5	10	2.38	0.231	0.6	0.1	±0.5
TGX20-MC																
TGX20-HC																
TGX35-LC	3	50	M 55×1.5	88	−	125	125	M 6×25	M 6×15	6	10	3.92	0.663	0.6	0.1	±0.5
TGX35-HC																
TGX50-LC	4	65	M 80×1.5	123	128	174	174	M 8×32	M 8×20	9	17	10.9	3.35	0.6	0.1	±0.6
TGX50-MC																
TGX50-HC																
TGX70-LC	4	70	M100×2.0	148	152	218	218	M10×22	M10×38	10	18	16.3	8.93	0.6	0.1	±0.7
TGX70-MC																
TGX70-HC																

*1. All the models are in stock.
2. Instantaneous stop is not possible, TGXZ Series is recommended. (Refer to page 77)
3. Mass and moment of inertia are based on the bores' maximum diameters.
4. Maximum bore diameter is with key installation. In case of Power-Lock installation, refer to p 48.

Shock Guard TGX・Coupling Type TGX-C with Finished Bore

Finished bore products can be made for quick delivery

■ Bores and keyways are already finished before delivery.

The finished bores for TGX10 to TGX70 and TGX10-C to TGX70-C are standard.

■ Finished Bore Dimension Chart

Unit : mm

Shock Guard TGX		Bore dimensions	
Shock Guard Model No.	Coupling Type Model No.	Shock Guard Side	Coupling Side (Coupling Type only)
TGX10	**TGX10-C**	(10),(11),12,14,15	10,11,12,14,15,16,17,18,19
TGX20	**TGX20-C**	(14),(15),(16),(17),18,19,20,22,24,25	10,11,12,14,15,16,17,18,19,20,22,24,25,28,29,30,32,33,35
TGX35	**TGX35-C**	(14),(15),(16),(17),18,19,20,22,24,25,28,29,30,32,33,35	14,15,16,17,18,19,20,22,24,25,28,29,30,32,33,35,36,38,40,42,43,45,46,48,50
TGX50	**TGX50-C**	20,22,24,25,28,29,30,32,33,35,36,38,40,42,43,45,46,48,50,52,55	20,22,24,25,28,29,30,32,33,35,36,38,40,42,43,45,46,48,50,52,55,56,57,60
TGX70	**TGX70-C**	25,28,29,30,32,33,35,36,38,40,42,43,45,46,48,50,52,55,56,57,60,63,65,70	25,28,29,30,32,33,35,36,38,40,42,43,45,46,48,50,52,55,56,57,60,63,65,70,71,75,80
Delivery		EX.-Japan 4 weeks by sea	

1. Finished bore dimensions with ( ) at Shock Guard side are applied only for Shock Guard Coupling.

Model No.

Shock Guard

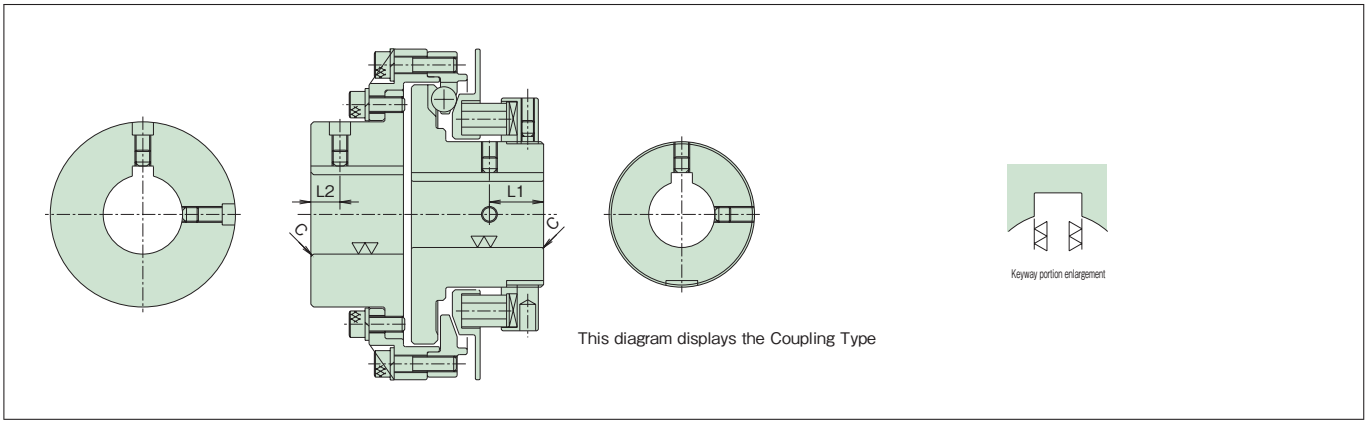
TGX20 - H - 15J

- TGX20 — Size
- H — Coil spring type
- 15 — Bore diameter
- J — New JIS key standard type

Coupling Type

TGX50 - MC - T35J×C50J

- TGX50 — Size
- MC — Coil spring type
- T35 — Shock Guard side bore diameter
- J — New JIS key standard type
- C50 — Coupling side bore diameter
- J — New JIS key standard type



This diagram displays the Coupling Type

Shock Guard TGX		Shock Guard side			Coupling side (Coupling Type only)		
Shock Guard Model No.	Coupling Type Model No.	Bore diameter	Set screw	Set screw position L1	Bore diameter	Set screw	Set screw position L2
TGX10	**TGX10-C**	φ15 and below	2-M4×4	21	φ19 and below	2-M4×4	8
TGX20	**TGX20-C**	φ23 and below	2-M5×5	20.5	φ35 and below	2-M5×5	12
		φ24,25	2-M4×4				
TGX35	**TGX35-C**	φ35 and below	2-M6×6	20.5	φ50 and below	2-M6×6	11
TGX50	**TGX50-C**	φ55 and below	2-M6×6	24.5	φ60 and below	2-M6×6	13
TGX70	**TGX70-C**	φ70 and below	2-M6×6	25	φ80 and below	2-M6×6	15

1. Set screws are located at 2 positions, on the keyway and 90° CW from it.
2. For Shock Guard Couplings, only the TGX10-C has a different keyway phase between the Shock Guard side and the coupling side.

■ Bore diameter and keyway specifications

- Bore diameter tolerance is as follows:
  φ18 and below……0 to +0.021mm
  φ19 and above……H7
- Keyway is New JIS (JIS B 1301-1996) "standard".
- Set screws are included in the delivery.

Bore diameter	Chamfer dimensions
φ25 and below	C0.5
φ50 and below	C1
φ51 and above	C1.5

Handling

1. Setting trip torque

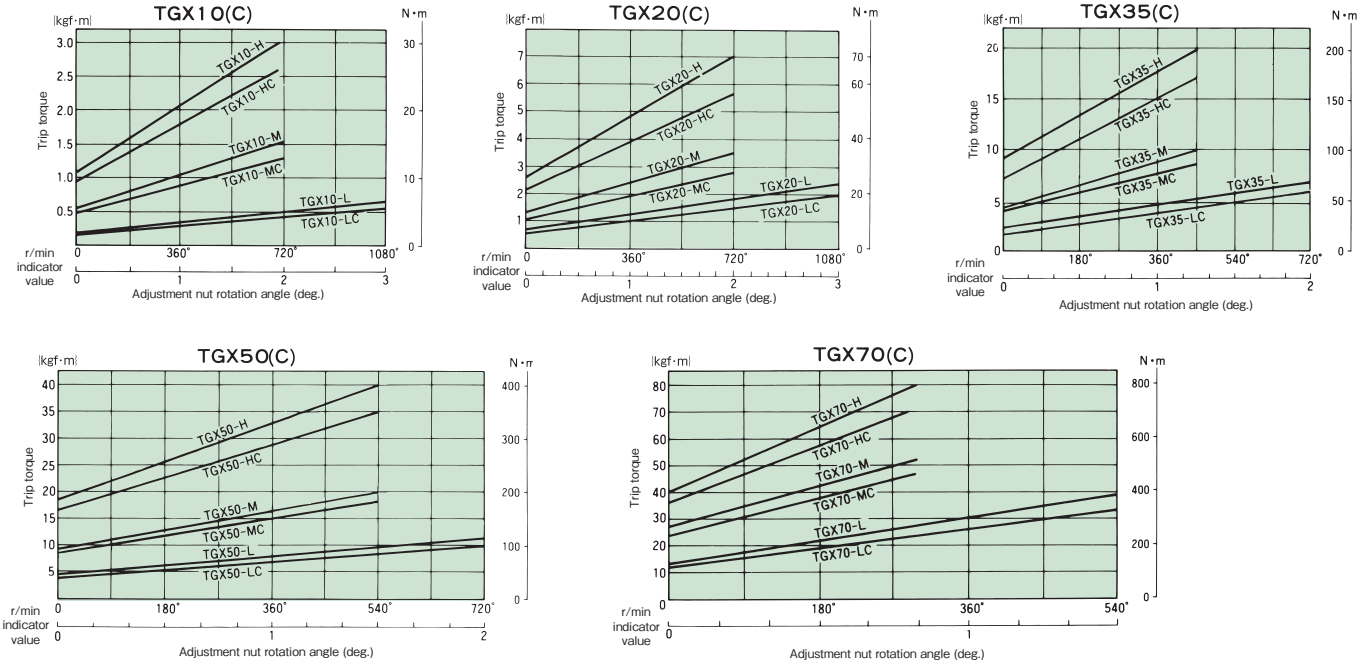
(1) TGX Shock Guards are all set at the "0" point (minimum torque value) for delivery. Confirm that the torque indicator is set at "0" when you receive the Shock Guard. (Refer to pages 43, 44)

(2) From the "Tightening Amount-Torque Correlation Chart" (below), find the adustment nut's (bolt) tightening angle equivalent to the predetermined trip torque and tighten them. The torque indicator is at every 60° pitch. Set at 60° toward the determined tightening value, then install to the machine and conduct a trip test. Gradually tighten and set at optimum trip torque. Each product's trip torque does not always correspond with the value listed in the "Tightening Amount - Torque Correlation Chart", so use these values only as a rough guide.

(3) After setting torque, screw the lock screw to adjustment nut.

(4) Do not turn the adjustment nut (bolt) more than the torque indicator's maximum value. Doing so will put it in a locked position, and there will be no leeway for the disk spring to bend. Refer to page 32 for the lock screws' tightening torque and precautions.

■ Tightening Amount-Torque Correlation Chart



Centering method

(1) Centering method Ⅰ

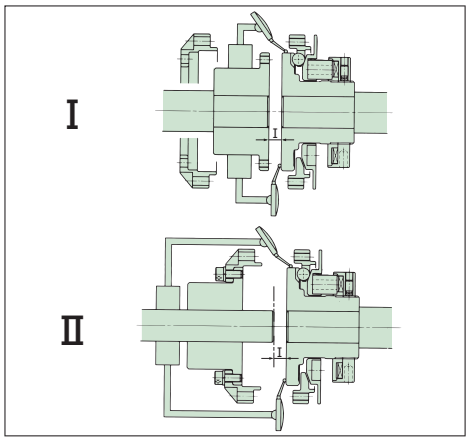
a .Separate the flange from the hub and center flange.
b .Move the flange, then set to the I dimensions shown in Table 1.
c .Fix a dial gauge to the hub (coupling side hub), then measure the run-out of the hub's end face and outer circumference.

(2) Centering method Ⅱ

a .Separate the flange and the center flange.
b .Fix a dial gauge to the shaft, then measure the run-out of the hub's end face and outer circumference.
c .Move the boss (coupling side hub), then set to the I dimensions shown in Table1.

Table 1 Unit: mm

Model No.	I dimensions
TGX10-C	2
TGX20-C	3
TGX35-C	3
TGX50-C	4
TGX70-C	4



Note	Make sure to secure it using the I dimensions in Table 1, otherwise the Shock Guard can not be used because backlash will occur.

Allowable Misalignment

Unit: mm

Model No.	Allowable angular misalignment deg.	Allowable parallel misalignment	Allowable axial misalignment
TGX10-C	0.6	0.1	±0.5
TGX20-C	0.6	0.1	±0.5
TGX35-C	0.6	0.1	±0.5
TGX50-C	0.6	0.1	±0.6
TGX70-C	0.6	0.1	±0.7

For reference: Hub end face run-out per angular misalignment $\theta = 0.10°$ Unit : mm

Model No.	Outside diameter	Hub end face run-out
TGX10-C	ϕ53	0.092
TGX20-C	ϕ75	0.131
TGX35-C	ϕ98	0.171
TGX50-C	ϕ138	0.241
TGX70-C	ϕ177	0.309

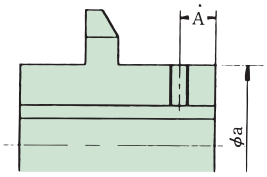
* Make angular misalignment as small as possible when installing the Shock Guard.

Bore finishing

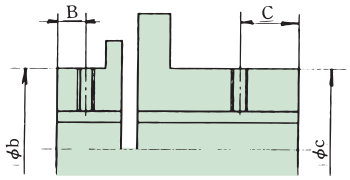
Refer to the instruction manual for more information on Shock Guard TGX and Shock Guard Coupling TGX-C disassembly for bore finishing, finishing and assembly.

Bore Keyway Set Screw Dimensions

Dimensions / Model No.	A x screw diameter	B x screw diameter	C x screw diameter	a	b	c
TGX10	21×M5 and below	—	—	30	—	—
TGX20	20.5×M5	—	—	40	—	—
TGX35	20.5×M6	—	—	55	—	—
TGX50	24.5×M6	—	—	80	—	—
TGX70	26 ×M6	—	—	100	—	—
TGX10-C	—	8×M 4 and below	21 ×M5 and below	—	33	30
TGX20-C	—	12×M 8 and below	20.5×M5	—	55	40
TGX35-C	—	11×M10 and below	20.5×M6	—	70	55
TGX50-C	—	13×M10 and below	24.5×M6	—	92	80
TGX70-C	—	15×M10 and below	25.2×M6	—	116	100

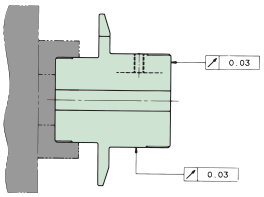


Shock Guard

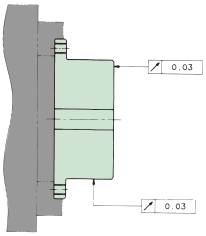


Shock Guard Coupling

Chuck the hub's end face, then center and finish it as shown in the diagram below.



Chuck the flange's outer diameter, then center and finish it as shown in the diagram below.



Combination with a Power Lock

1. Applicable range and Transmissible torque

It is possible to combine Shock Guards and Shock Guard Couplings with the Power Locks listed below. TEM will also supply a Shock Guard combined with a Power Lock and special pressure flange and bolts upon request. The chart shows Power Lock transmissible torque for a single set. In the case of multiple sets, multiply by the coefficient below to get the transmissible torque.

N	S
2	1.55
3	1.85

N = Line Power Lock sets

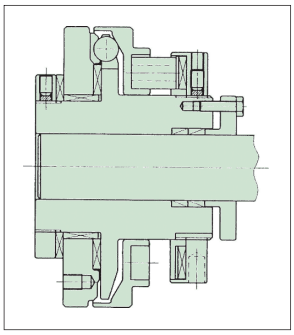
S = coefficient

(Example) In case the shaft diameter of 10 mm and 2 sets of Power Locks for TGX20

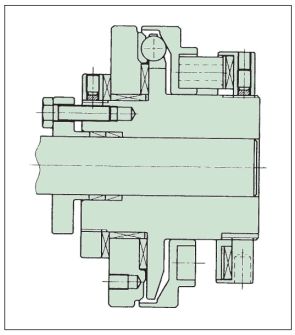
1.10 × 1.55 = 1.705 about 1.70kgf·m

(1)Shock Guard TGX

Adjustment nut side



Fixed nut side



Power Lock transmissible torque

N·m {kgf·m}

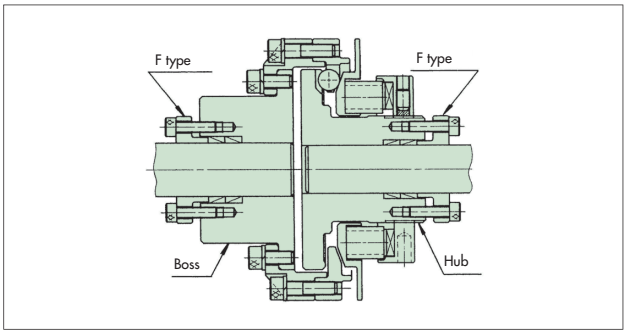
Bore diameter	Power Lock Model No.	Model No. of Adjustment Guard									
		TGX10		TGX20		TGX35		TGX50		TGX70	
		Adjustment nut side	Fixed nut side	Adjustment nut side	Fixed nut side	Adjustable nut side	Fixed nut side	Adjustment nut side	Fixed nut side	Adjustment nut side	Fixed nut side
10	PL010×013E	10.8 {1.10}		10.8 {1.10}	10.8 {1.10}						
12	PL012×015E	15.7 {1.60}		15.7 {1.60}	15.7 {1.60}						
13	PL013×016E			18.6 {1.90}	18.6 {1.90}						
14	PL014×018E			30.4 {3.10}	30.4 {3.10}						
15	PL015×019E			35.3 {3.60}	35.3 {3.60}	35.3 {3.60}	35.3 {3.60}				
16	PL016×020E			39.2 {4.00}	39.2 {4.00}	40.2 {4.10}	40.2 {4.10}				
17	PL017×021E			43.1 {4.40}	43.1 {4.40}	45.1 {4.60}	45.1 {4.60}				
18	PL018×022E			46.1 {4.70}	46.1 {4.70}	51.0 {5.20}	51.0 {5.20}				
19	PL019×024E			41.2 {4.20}	41.2 {4.20}	56.8 {5.80}	56.8 {5.80}				
20	PL020×025E			44.1 {4.50}	44.1 {4.50}	62.7 {6.40}	62.7 {6.40}	62.7 {6.40}	62.7 {6.40}		
22	PL022×026E					75.5 {7.70}	75.5 {7.70}	75.5 {7.70}	75.5 {7.70}		
24	PL024×028E					90.2 {9.20}	90.2 {9.20}	90.2 {9.20}	90.2 {9.20}		
25	PL025×030E					91.1 {9.30}		98.0 {10.0}	98.0 {10.0}	98.0 {10.0}	98.0 {10.0}
28	PL028×032E					111 {11.3}		123 {12.5}	123 {12.5}	123 {12.5}	123 {12.5}
30	PL030×035E					115 {11.7}		141 {14.4}	141 {14.4}	141 {14.4}	141 {14.4}
32	PL032×036E					124 {12.7}		160 {16.3}	160 {16.3}	160 {16.3}	160 {16.3}
35	PL035×040E					127 {13.0}		217 {22.1}	217 {22.1}	217 {22.1}	217 {22.1}
36	PL036×042E							229 {23.4}	229 {23.4}	229 {23.4}	229 {23.4}
38	PL038×044E							256 {26.1}	256 {26.1}	256 {26.1}	256 {26.1}
40	PL040×045E							312 {31.8}	312 {31.8}	312 {31.8}	312 {31.8}
42	PL042×048E							344 {35.1}	344 {35.1}	344 {35.1}	344 {35.1}
45	PL045×052E							366 {37.3}	366 {37.3}	490 {50.0}	490 {50.0}
48	PL048×055E							398 {40.6}	398 {40.6}	530 {54.1}	530 {54.1}
50	PL050×057E							419 {42.8}	419 {42.8}	557 {56.8}	557 {56.8}
55	PL055×062E									624 {63.7}	624 {63.7}
56	PL056×064E									590 {60.2}	590 {60.2}
60	PL060×068E									644 {65.7}	644 {65.7}
63	PL063×071E									685 {69.9}	685 {69.9}
65	PL065×073E									711 {72.6}	711 {72.6}
70	PL070×079E									724 {73.9}	724 {73.9}

Pressure bolt tightening torque

N·m {kgf·m}

Bore diameter	Power Lock Model No.	Model No. of Shock Guard									
		TGX10		TGX20		TGX35		TGX50		TGX70	
		Adjustment nut side	Fixed nut side	Adjustment nut side	Fixed nut side	Adjustment nut side	Fixed nut side	Adjustment nut side	Fixed nut side	Adjustment nut side	Fixed nut side
10	PL010×013E	2.94 {0.30}		1.96 {0.20}	1.96 {0.20}						
12	PL012×015E	3.14 {0.32}		2.06 {0.21}	2.06 {0.21}						
13	PL013×016E			2.16 {0.22}	2.16 {0.22}						
14	PL014×018E			3.53 {0.36}	3.53 {0.36}						
15	PL015×019E			3.92 {0.40}	3.92 {0.40}	2.94 {0.30}	5.00 {0.51}				
16	PL016×020E			4.02 {0.41}	4.02 {0.41}	3.04 {0.31}	5.10 {0.52}				
17	PL017×021E			4.02 {0.41}	4.02 {0.41}	3.14 {0.32}	5.19 {0.53}				
18	PL018×022E			4.02 {0.41}	4.02 {0.41}	3.23 {0.33}	5.39 {0.55}				
19	PL019×024E			4.02 {0.41}	4.02 {0.41}	3.63 {0.37}	6.17 {0.63}				
20	PL020×025E			4.02 {0.41}	4.02 {0.41}	3.72 {0.38}	6.37 {0.65}	5.49 {0.56}	5.49 {0.56}		
22	PL022×026E					3.72 {0.38}	6.27 {0.64}	5.59 {0.57}	5.59 {0.57}		
24	PL024×028E					3.92 {0.40}	6.66 {0.68}	5.59 {0.57}	5.59 {0.57}		
25	PL025×030E					4.02 {0.41}		6.27 {0.64}	6.27 {0.64}	5.00 {0.51}	5.00 {0.51}
28	PL028×032E					4.02 {0.41}		6.47 {0.66}	6.47 {0.66}	5.19 {0.53}	5.19 {0.53}
30	PL030×035E					4.02 {0.41}		7.06 {0.72}	7.06 {0.72}	5.59 {0.57}	5.59 {0.57}
32	PL032×036E					4.02 {0.41}		7.35 {0.75}	7.35 {0.75}	5.88 {0.60}	5.88 {0.60}
35	PL035×040E					4.02 {0.41}		9.11 {0.93}	9.11 {0.93}	7.25 {0.74}	7.25 {0.74}
36	PL036×042E							9.51 {0.97}	9.51 {0.97}	7.64 {0.78}	7.64 {0.78}
38	PL038×044E							9.90 {1.01}	9.90 {1.01}	7.94 {0.81}	7.94 {0.81}
40	PL040×045E							11.7 {1.19}	11.7 {1.19}	9.31 {0.95}	9.31 {0.95}
42	PL042×048E							12.3 {1.26}	12.3 {1.26}	9.80 {1.00}	9.80 {1.00}
45	PL045×052E							13.7 {1.40}	13.7 {1.40}	13.7 {1.40}	13.7 {1.40}
48	PL048×055E							13.7 {1.40}	13.7 {1.40}	13.7 {1.40}	13.7 {1.40}
50	PL050×057E							13.7 {1.40}	13.7 {1.40}	13.7 {1.40}	13.7 {1.40}
55	PL055×062E									13.7 {1.40}	13.7 {1.40}
56	PL056×064E									13.7 {1.40}	13.7 {1.40}
60	PL060×068E									13.7 {1.40}	13.7 {1.40}
63	PL063×071E									13.7 {1.40}	13.7 {1.40}
65	PL065×073E									13.7 {1.40}	13.7 {1.40}
70	PL070×079E									13.7 {1.40}	13.7 {1.40}

(2) Coupling Type TGX-C



Power Lock transmissible torque

N·m {kgf·m}

Bore diameter	Power Lock Model No.	Model No. of Shock Guard									
		TGX10-C		TGX20-C		TGX35-C		TGX50-C		TGX70-C	
		Shock Guard side	Coupling side	Shock Guard side	Coupling side	Shock Guard side	Coupling side	Shock Guard side	Coupling side	Shock Guard side	Coupling side
10	PL010×013E	10.8 {1.10}	10.8 {1.10}	10.8 {1.10}	10.8 {1.10}						
12	PL012×015E	15.7 {1.60}	15.7 {1.60}	15.7 {1.60}	15.7 {1.60}						
13	PL013×016E			18.6 {1.90}	18.6 {1.90}						
14	PL014×018E			30.4 {3.10}	30.4 {3.10}						
15	PL015×019E			35.3 {3.60}	35.3 {3.60}	35.3 {3.60}	35.3 {3.60}				
16	PL016×020E			39.2 {4.00}	39.2 {4.00}	40.2 {4.10}	40.2 {4.10}				
17	PL017×021E			43.1 {4.40}	43.1 {4.40}	45.1 {4.60}	45.1 {4.60}				
18	PL018×022E			46.1 {4.70}	46.1 {4.70}	51.0 {5.20}	51.0 {5.20}				
19	PL019×024E			41.2 {4.20}	41.2 {4.20}	56.8 {5.80}	56.8 {5.80}				
20	PL020×025E			44.1 {4.50}	44.1 {4.50}	62.7 {6.40}	62.7 {6.40}	62.7 {6.40}	62.7 {6.40}		
22	PL022×026E					75.5 {7.70}	75.5 {7.70}	75.5 {7.70}	75.5 {7.70}		
24	PL024×028E					90.2 {9.20}	90.2 {9.20}	90.2 {9.20}	90.2 {9.20}		
25	PL025×030E					91.1 {9.30}	91.1 {9.30}	98.0 {10.0}	98.0 {10.0}	98.0 {10.0}	98.0 {10.0}
28	PL028×032E					111 {11.3}	111 {11.3}	123 {12.5}	123 {12.5}	123 {12.5}	123 {12.5}
30	PL030×035E					115 {11.7}	115 {11.7}	141 {14.4}	141 {14.4}	141 {14.4}	141 {14.4}
32	PL032×036E					124 {12.7}	124 {12.7}	160 {16.3}	160 {16.3}	160 {16.3}	160 {16.3}
35	PL035×040E					127 {13.0}	127 {13.0}	217 {22.1}	217 {22.1}	217 {22.1}	217 {22.1}
36	PL036×042E							229 {23.4}	229 {23.4}	229 {23.4}	229 {23.4}
38	PL038×044E							256 {26.1}	256 {26.1}	256 {26.1}	256 {26.1}
40	PL040×045E							312 {31.8}	312 {31.8}	312 {31.8}	312 {31.8}
42	PL042×048E							344 {35.1}	344 {35.1}	344 {35.1}	344 {35.1}
45	PL045×052E							366 {37.3}	366 {37.3}	490 {50.0}	490 {50.0}
48	PL048×055E							398 {40.6}	398 {40.6}	530 {54.1}	530 {54.1}
50	PL050×057E							419 {42.8}	419 {42.8}	557 {56.8}	557 {56.8}
55	PL055×062E									624 {63.7}	624 {63.7}
56	PL056×064E									590 {60.2}	590 {60.2}
60	PL060×068E									644 {65.7}	644 {65.7}
63	PL063×071E									685 {69.9}	685 {69.9}
65	PL065×073E									711 {72.6}	711 {72.6}
70	PL070×079E									724 {73.9}	724 {73.9}

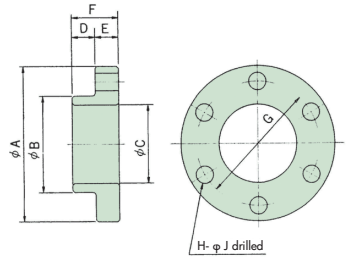
Pressure bolt tightening torque

N·m {kgf·m}

Bore diameter	Power Lock Model No.	Model No. of Shock Guard									
		TGX10-C		TGX20-C		TGX35-C		TGX50-C		TGX70-C	
		Shock Guard side	Coupling side	Shock Guard side	Coupling side	Shock Guard side	Coupling side	Shock Guard side	Coupling side	Shock Guard side	Coupling side
10	PL010×013E	2.94 {0.30}	2.94 {0.30}	1.96 {0.20}	1.96 {0.20}						
12	PL012×015E	3.14 {0.32}	3.14 {0.32}	2.06 {0.21}	2.06 {0.21}						
13	PL013×016E			2.16 {0.22}	2.16 {0.22}						
14	PL014×018E			3.53 {0.36}	3.53 {0.36}						
15	PL015×019E			3.92 {0.40}	3.92 {0.40}	2.94 {0.30}	2.94 {0.30}				
16	PL016×020E			4.02 {0.41}	4.02 {0.41}	3.04 {0.31}	3.04 {0.31}				
17	PL017×021E			4.02 {0.41}	4.02 {0.41}	3.14 {0.32}	3.14 {0.32}				
18	PL018×022E			4.02 {0.41}	4.02 {0.41}	3.23 {0.33}	3.23 {0.33}				
19	PL019×024E			4.02 {0.41}	4.02 {0.41}	3.63 {0.37}	3.63 {0.37}				
20	PL020×025E			4.02 {0.41}	4.02 {0.41}	3.72 {0.38}	3.72 {0.38}	5.49 {0.56}	5.49 {0.56}		
22	PL022×026E					3.72 {0.38}	3.72 {0.38}	5.59 {0.57}	5.59 {0.57}		
24	PL024×028E					3.92 {0.40}	3.92 {0.40}	5.59 {0.57}	5.59 {0.57}		
25	PL025×030E					4.02 {0.41}	4.02 {0.41}	6.27 {0.64}	6.27 {0.64}	5.00 {0.51}	5.00 {0.51}
28	PL028×032E					4.02 {0.41}	4.02 {0.41}	6.47 {0.66}	6.47 {0.66}	5.19 {0.53}	5.19 {0.53}
30	PL030×035E					4.02 {0.41}	4.02 {0.41}	7.06 {0.72}	7.06 {0.72}	5.59 {0.57}	5.59 {0.57}
32	PL032×036E					4.02 {0.41}	4.02 {0.41}	7.35 {0.75}	7.35 {0.75}	5.88 {0.60}	5.88 {0.60}
35	PL035×040E					4.02 {0.41}	4.02 {0.41}	9.11 {0.93}	9.11 {0.93}	7.25 {0.74}	7.25 {0.74}
36	PL036×042E							9.51 {0.97}	9.51 {0.97}	7.64 {0.78}	7.64 {0.78}
38	PL038×044E							9.90 {1.01}	9.90 {1.01}	7.94 {0.81}	7.94 {0.81}
40	PL040×045E							11.7 {1.19}	11.7 {1.19}	9.31 {0.95}	9.31 {0.95}
42	PL042×048E							12.3 {1.26}	12.3 {1.26}	9.80 {1.00}	9.80 {1.00}
45	PL045×052E							13.7 {1.40}	13.7 {1.40}	13.7 {1.40}	13.7 {1.40}
48	PL048×055E							13.7 {1.40}	13.7 {1.40}	13.7 {1.40}	13.7 {1.40}
50	PL050×057E							13.7 {1.40}	13.7 {1.40}	13.7 {1.40}	13.7 {1.40}
55	PL055×062E									13.7 {1.40}	13.7 {1.40}
56	PL056×064E									13.7 {1.40}	13.7 {1.40}
60	PL060×068E									13.7 {1.40}	13.7 {1.40}
63	PL063×071E									13.7 {1.40}	13.7 {1.40}
65	PL065×073E									13.7 {1.40}	13.7 {1.40}
70	PL070×079E									13.7 {1.40}	13.7 {1.40}

2. Rough bore pressure flange

Special pressure flange and pressure bolts are MTO upon request.
Special pressure bolts are JIS Strength Class 10.9.
Pressure flange is installed with tap holes at the hub or boss (coupling side hub) end faces.
Refer to page 50 for the recommended finished dimensions.



Rough Bore Pressure Flange Dimensions

Unit: mm

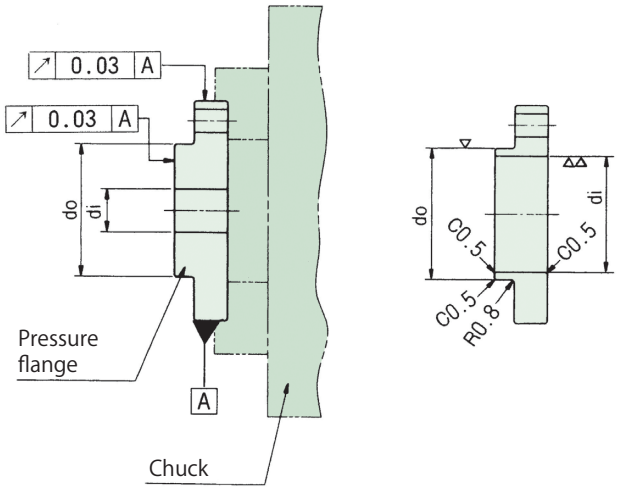
Pressure flange Model No.	A	Rough bore measurements B	Rough bore measurements C	D	E	F	G PCD	H	J	*1Mass kg	Moment of inertia kg·m²	*2GD² kgf·m²	Pressure bolt size × the number		Tap side screw effective depth
TGX10-F	30	14.9	10.1	5	6	11	22	4	4.5	0.037	0.043	0.173	M4×14R	4	M4× 8R
TGX20-F	40	24.8	10.1	6	6	12	32	6	4.5	0.080	0.150	0.600	M4×14R	6	M4× 8R
TGX35-F	55	39.8	15.1	6	6	12	47	8	4.5	0.16	0.598	2.39	M4×14R	8	M4× 8R
TGX50-F	81	56.8	20.2	7	10	17	69	8	6.6	0.53	4.240	16.96	M6×22R	8	M6×12R
TGX70-F	101	78.7	25.2	7	10	17	89	10	6.6	0.87	10.83	43.33	M6×22R	10	M6×12R

*1, *2 Weight and GD² are together as 1 set of pressure flange (max. bore) and pressure bolt.
Note: All products are MTO.

3. Pressure flange recommended finishing dimensions

(1) Centering
Chuck and center based on the flange external diameter. (Refer to the diagram on the right)

(2) Recommended dimensions
Depending on Power Lock size, choose the finishing dimensions from the chart below.



Pressure flange centering and processing diagram

Unit: mm

Bore diameter (mm)	Power Lock Model No.	TGX10 (C) F		TGX20 (C) F		TGX35 (C) F		TGX50 (C) F		TGX70 (C) F	
		$do_{-0.1}^{0}$	$di_{-0}^{+0.1}$	$do_{-0.1}^{0}$	$di_{-0}^{+0.1}$	$do_{-0.1}^{0}$	$di_{-0}^{+0.1}$	$do_{-0.1}^{0}$	$di_{-0}^{+0.1}$	$do_{-0.1}^{0}$	$di_{-0}^{+0.1}$
10	PL010×013E	12.9	10.1	12.9	10.1						
12	PL012×015E	14.9	12.1	14.9	12.1						
13	PL013×016E			15.9	13.1						
14	PL014×018E			17.9	14.1						
15	PL015×019E			18.9	15.1	18.9	15.1	18.9	15.1		
16	PL016×020E			19.9	16.1	19.9	16.1	19.9	16.1		
17	PL017×021E			20.9	17.1	20.9	17.1	20.9	17.1		
18	PL018×022E			21.9	18.1	21.9	18.1	21.9	18.1		
19	PL019×024E			23.8	19.2	23.8	19.2	23.8	19.2		
20	PL020×025E			24.8	20.2	24.8	20.2	24.8	20.2		
22	PL022×026E					25.8	22.2	25.8	22.2		
24	PL024×028E					27.8	24.2	27.8	24.2		
25	PL025×030E					29.8	25.2	29.8	25.2	29.8	25.2
28	PL028×032E					31.8	28.2	31.8	28.2	31.8	28.2
30	PL030×035E					34.8	30.2	34.8	30.2	34.8	30.2
32	PL032×036E					35.8	32.2	35.8	32.2	35.8	32.2
35	PL035×040E					39.8	35.2	39.8	35.2	39.8	35.2
36	PL036×042E							41.8	36.2	41.8	36.2
38	PL038×044E							43.8	38.2	43.8	38.2
40	PL040×045E							44.8	40.2	44.8	40.2
42	PL042×048E							47.8	42.2	47.8	42.2
45	PL045×052E							51.8	45.2	51.8	45.2
48	PL048×055E							54.8	48.2	54.8	48.2
50	PL050×057E							56.8	50.2	56.8	50.2
55	PL055×062E									61.8	55.2
56	PL056×064E									63.8	56.2
60	PL060×068E									67.8	60.2
63	PL063×071E									70.8	63.2
65	PL065×073E									72.8	65.2
70	PL070×079E									78.7	70.3

* Refer to the instruction manual for information on hub bore finishing when installing the Power Lock.

Shock Guard TGF Series (Ex-MYTORQ 300 Series)

Features

Ideal for direct mounting of an index table thanks to the excellent mounting surface accuracy of the output flange.

High accuracy

Ideal for indexers thanks to its minimal backlash and excellent reset position accuracy.

One position type

The balls and pockets, which transfer the torque, are engaged only in one position because of the unique structure.

Easy torque adjustment

You only have to turn the adjustment nut (or bolt) to adjust the trip torque thanks to the torque scale.

Automatic reset

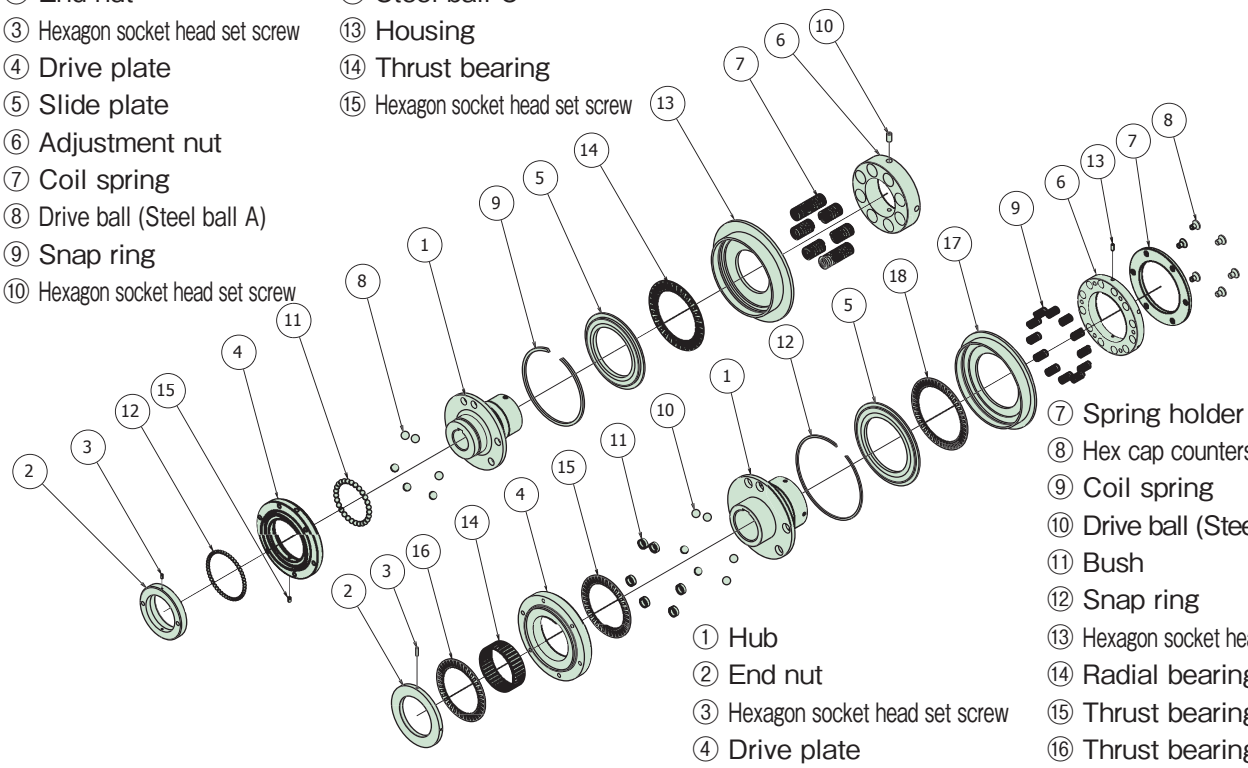
Thanks to automatic re-engagement, you only have to rotate the drive side after removing the cause of overload.

TGF	
Type 2	Enables direct mounting of timing pulleys. The shaft-securing setscrew can be tightened from the outside.
Type 3	Thinner than Type 2 and ideal for Power-Lock mounting.
Type 5	The Echt-Flex Coupling provides an angular tolerance. Parallelism errors are not allowed.
Type 7	The Echt-Flex Coupling provides angular and parallelism tolerances.

Construction and Operating Principles

TGF20 to 45

① Hub
② End nut
③ Hexagon socket head set screw
④ Drive plate
⑤ Slide plate
⑥ Adjustment nut
⑦ Coil spring
⑧ Drive ball (Steel ball A)
⑨ Snap ring
⑩ Hexagon socket head set screw
⑪ Steel ball B
⑫ Steel ball C
⑬ Housing
⑭ Thrust bearing
⑮ Hexagon socket head set screw



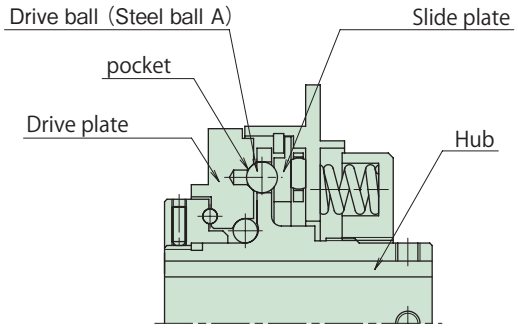
① Hub
② End nut
③ Hexagon socket head set screw
④ Drive plate
⑤ Slide plate
⑥ Adjustment nut
⑦ Spring holder
⑧ Hex cap countersunk screw
⑨ Coil spring
⑩ Drive ball (Steel ball A)
⑪ Bush
⑫ Snap ring
⑬ Hexagon socket head set screw
⑭ Radial bearing
⑮ Thrust bearing A
⑯ Thrust bearing A
⑰ Housing
⑱ Thrust bearing B

TGF65 to 90

TGF20 to 45

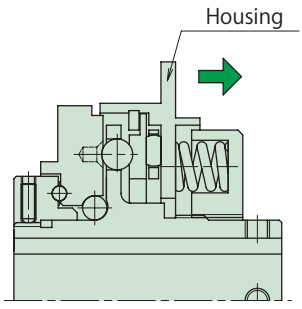
The principle of operation is the same for TGF65 and TGF90.

During normal operation (engagement)



The TGF series transfers driving force from the hub to the drive plate on the output side via drive balls (and vice versa).
Bolt a sprocket or timing pulley directly to the drive plate.
The hub flange has several holes to hold the drive balls.
There are pockets on the drive plate on the output side, and the drive balls are pushed by coil springs via the slide plate to be fitted into the pockets to transfer the driving force.
If an overload occurs, the drive balls push the slide plate toward the coil springs and come out of the pockets of the drive plate while rotating to release the driving force.

During overload (trip)



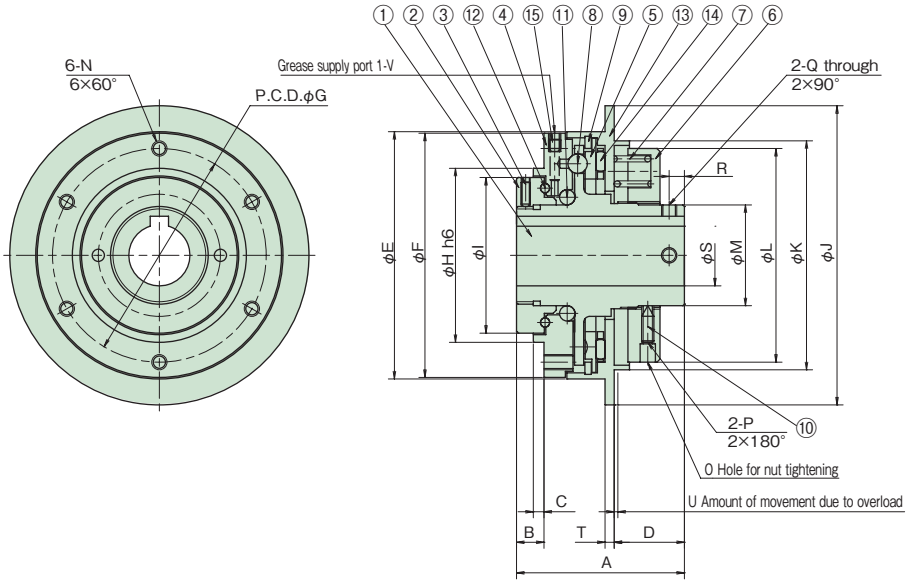
Then, the housing moves toward the coil springs. Therefore, it is easy to stop the drive source automatically after the occurrence of an overload by detecting the amount of movement of the housing using aTG sensor or a similar device.

Resetting procedure

If you restart the operation after the occurrence of an overload, the drive balls automatically return to their positions within one revolution.
If you continue to rotate the TGF series after the occurrence of an overload, the TGF series is repeatedly reset. Therefore, detect overloads using a TG sensor or a similar device and shutdown the drive source immediately.

Transmissible Capacity/Dimensions

■ TGF20-□2 • TGF30-□2 • TGF45-□2 Type 2



① Hub
② End nut
③ Hexagon socket head set screw
④ Drive plate
⑤ Slide plate
⑥ Adjustment nut
⑦ Coil spring
⑧ Drive ball (Steel ball A)
⑨ Snap ring
⑩ Hexagon socket head set screw
⑪ Steel ball B
⑫ Steel ball C
⑬ Housing
⑭ Thrust bearing
⑮ Hexagon socket head set screw

Unit : mm

Model No.	Set torque range N · m	Max. rpm r/min*1	Coil spring number	S			A	B	C	D	E	F	G P.C.D.	H h6	I	J
				Rough bore diamter	Min. bore diameter	JIS keyway for max. bore dia.										
TGF20-L2	5 to 20	900	2	8	10	20	55	9	3.5	23	81	80	70	57	51	98
TGF20-M2	10 to 40		4													
TGF20-H2	20 to 80		8													
TGF30-L2	5 to 73.5	740	2	10	12	30	80	11	5.5	39	103	100	90	75	69	130
TGF30-M2	10 to 147		4													
TGF30-H2	20 to 294		8													
TGF45-L2	30 to 156	600	3	20	22	45	95	14	7.0	46	142	140	125	100	92	165
TGF45-M2	60 to 313		6													
TGF45-H2	120 to 568		12													

Model No.	K	L	M	N screw diamter ×length	O No. of pcs. - hole dia. × depth	P screw diamter × length	Q screw diameter*2	R*2	T	U	V screw diamter ×length	W screw diamter ×length	Mass*3 kg	Moment of inertia*3 kg · m²	Allowable radial load N
TGF20-L2	75	70	33	M5×9	4-φ5×6	M4×12	M5	5	3	1.2	M4×8	—	1.4	0.00108	1300
TGF20-M2															
TGF20-H2															
TGF30-L2	98	92	48	M6×11	4-φ7×7	M6×15	M6	5	4	1.8	M4×8	—	3.3	0.00435	3100
TGF30-M2															
TGF30-H2															
TGF45-L2	132	124	66	M8×13	6-φ7×7	M6×20	M8	8	4	2.2	M4×8	—	6.7	0.0165	3900
TGF45-M2															
TGF45-H2															

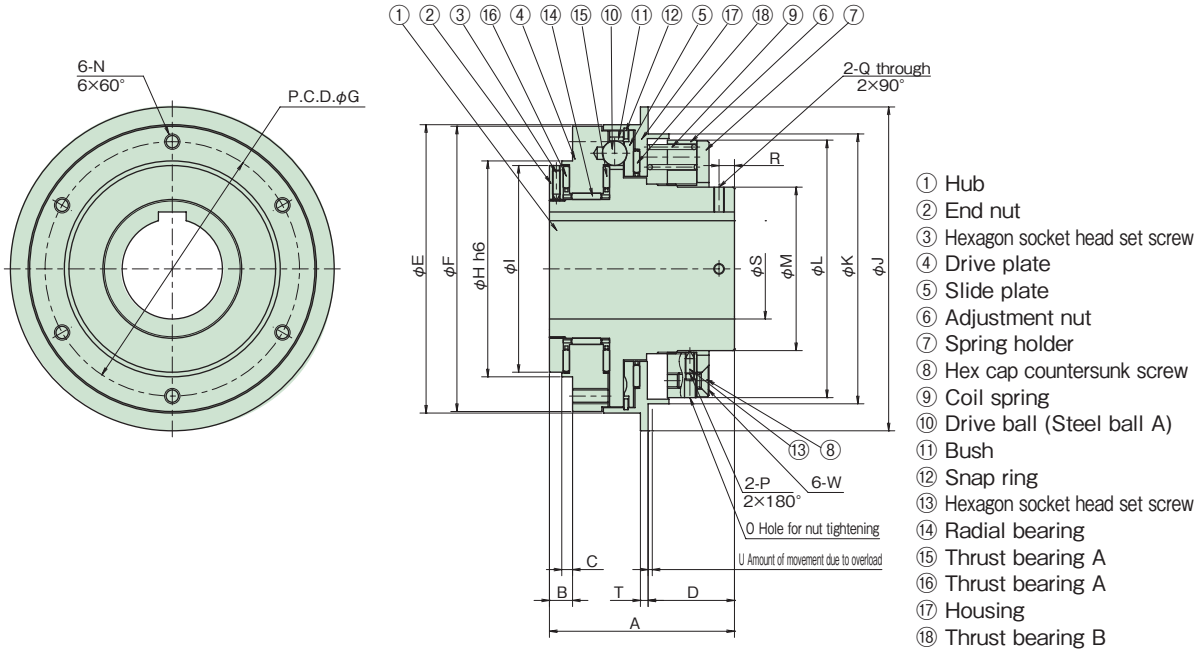
*1. Contact us for details on use at speeds higher than the maximum speed.
2. Setscrew taps are not processed. Dimensions are for reference only.
3. Mass and moment of inertia are based on the bores' maximum diameters.

Note) When installing a pulley or sprocket, use high-tensile bolts (G10.9 or higher) and determine the length carefully so that the bolts are not buried deeper than the mounting tap depth N.

Transmissible Capacity/Dimensions

■TGF65-□2 • TGF90-□2

Type 2



① Hub
② End nut
③ Hexagon socket head set screw
④ Drive plate
⑤ Slide plate
⑥ Adjustment nut
⑦ Spring holder
⑧ Hex cap countersunk screw
⑨ Coil spring
⑩ Drive ball (Steel ball A)
⑪ Bush
⑫ Snap ring
⑬ Hexagon socket head set screw
⑭ Radial bearing
⑮ Thrust bearing A
⑯ Thrust bearing A
⑰ Housing
⑱ Thrust bearing B

Unit : mm

Model No.	Set torque range N · m	Max. rpm r/min*1	Coil spring number	S			A	B	C	D	E	F	G P.C.D.	H h6	I	J
				Rough bore diamter	Min. bore diameter	JIS keyway for max. bore dia.										
TGF65-L2	40 to 264	430	3	30	32	65	120	15	7	56	187	185	165	140	134	210
TGF65-M2	80 to 539		6													
TGF65-H2	160 to 1078		12													
TGF90-L2	196 to 1225	330	3	45	47	90	170	23	9	93	252	246	215	175	170	280
TGF90-M2	392 to 2450		6													
TGF90-H2	784 to 4900		12													

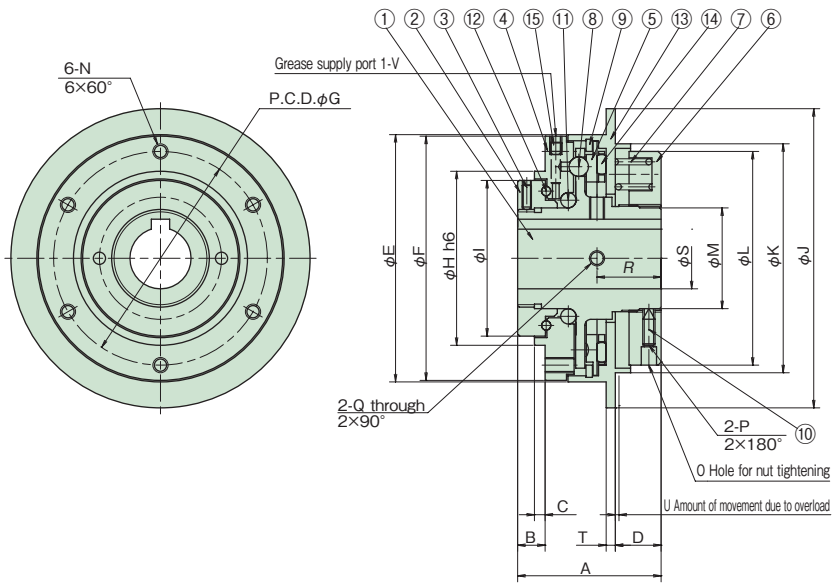
Model No.	K	L	M	N screw diamter ×length	O No. of pcs. - hole dia. × depth	P screw diamter × length	Q screw diameter*2	R*2	T	U	V screw diamter ×length	W screw diamter ×length*3	Mass*4 kg	Moment of inertia kg · m² *4	Allowable radial load N
TGF65-L2	175	167	106	M10×17	6-ϕ7×12	M6×20	M10	10	5	2.7	–	M10×20	16	0.0678	30000
TGF65-M2															
TGF65-H2															
TGF90-L2	243	233	150	M16×20	6-ϕ12×15	M10×30	M12	10	8	5.0	–	M12×35	37	0.267	33000
TGF90-M2															
TGF90-H2															

*1. Contact us for details on use at speeds higher than the maximum speed.
2. Setscrew taps are not processed. Dimensions are for reference only.
3. TGF65 uses hex cap countersunk screws, and TGF90 uses hex bolts.
4. Mass and moment of inertia are based on the bores' maximum diameters.

Note) When installinga pulley or sprocket, use high-tensile bolts (G10.9 or higher) and determine the length carefully so that the bolts are not buried deeper than the mounting tap depth N.

Transmissible Capacity/Dimensions

■TGF20-□3 • TGF30-□3 • TGF45-□3 Type 3



① Hub
② End nut
③ Hexagon socket head set screw
④ Drive plate
⑤ Slide plate
⑥ Adjustment nut
⑦ Coil spring
⑧ Drive ball (Steel ball A)
⑨ Snap ring
⑩ Hexagon socket head set screw
⑪ Steel ball B
⑫ Steel ball C
⑬ Housing
⑭ Thrust bearing
⑮ Hexagon socket head set screw

Unit : mm

Model No.	Set torque range N · m	Max. rpm r/min*1	Coil spring number	S			A	B	C	D	E	F	G P.C.D.	H h6	I	J
				Rough bore diamter	Min. bore diameter	JIS keyway for max. bore dia.										
TGF20-L3	5 to 20	900	2	8	10	20	47	9	3.5	15	81	80	70	57	51	98
TGF20-M3	10 to 40		4													
TGF20-H3	20 to 80		8													
TGF30-L3	5 to 73.5	740	2	10	12	30	71	11	5.5	30	103	100	90	75	69	130
TGF30-M3	10 to 147		4													
TGF30-H3	20 to 294		8													
TGF45-L3	30 to 156	600	3	20	22	45	81	14	7.0	32	142	140	125	100	92	165
TGF45-M3	60 to 313		6													
TGF45-H3	120 to 568		12													

Model No.	K	L	M	N screw diamter ×length	O No. of pcs. - hole dia. × depth	P screw diamter × length	Q screw diameter*2	R*2	T	U	V screw diamter ×length	W screw diamter ×length	Mass*3 kg	Moment of inertia kg · m²	Allowable radial load N
TGF20-L3	75	70	33	M5×9	4-φ5×6	M4×12	M5	21	3	1.2	M4×8	—	1.3	0.00108	1300
TGF20-M3															
TGF20-H3															
TGF30-L3	98	92	48	M6×11	4-φ7×7	M6×15	M6	37	4	1.8	M4×8	—	3.2	0.00429	3100
TGF30-M3															
TGF30-H3															
TGF45-L3	132	124	66	M8×13	6-φ7×7	M6×20	M8	40	4	2.2	M4×8	—	6.5	0.0163	3900
TGF45-M3															
TGF45-H3															

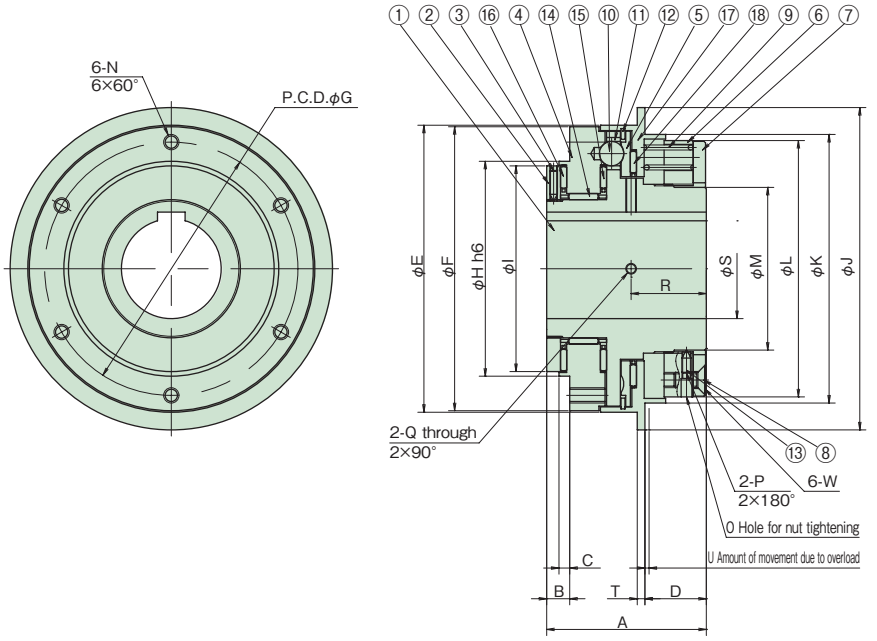
*1. Contact us for details on use at speeds higher than the maximum speed.
2. Setscrew taps are not processed. Dimensions are for reference only.
3. Mass and moment of inertia are based on the bores' maximum diameters.

Note) When installing a pulley or sprocket, use high-tensile bolts (G10.9 or higher) and determine the length carefully so that the bolts are not buried deeper than the mounting tap depth N.

Transmissible Capacity/Dimensions

■TGF65-□3 • TGF90-□3

Type 3



① Hub
② End nut
③ Hexagon socket head set screw
④ Drive plate
⑤ Slide plate
⑥ Adjustment nut
⑦ Spring holder
⑧ Hex cap countersunk screw
⑨ Coil spring
⑩ Drive ball (Steel ball A)
⑪ Bush
⑫ Snap ring
⑬ Hexagon socket head set screw
⑭ Radial bearing
⑮ Thrust bearing A
⑯ Thrust bearing A
⑰ Housing
⑱ Thrust bearing B

Unit : mm

Model No.	Set torque range N · m	Max. rpm r/min*1	Coil spring number	S			A	B	C	D	E	F	G P.C.D.	H h6	I	J
				Rough bore diamter	Min. bore diameter	JIS keyway for max. bore dia.										
TGF65-L3	40 to 264	430	3	30	32	65	104	15	7	40	187	185	165	140	134	210
TGF65-M3	80 to 539		6													
TGF65-H3	160 to 1078		12													
TGF90-L3	196 to 1225	330	3	45	47	90	150	23	9	73	252	246	215	175	170	280
TGF90-M3	392 to 2450		6													
TGF90-H3	784 to 4900		12													

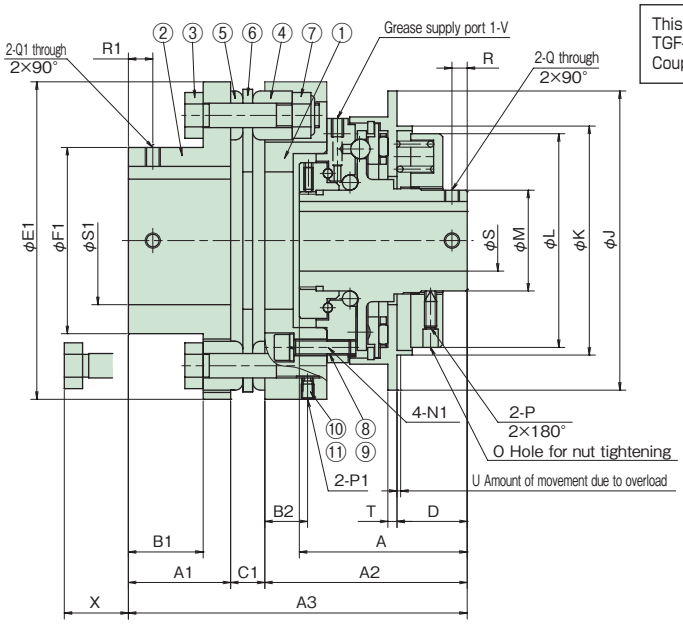
Model No.	K	L	M	N screw diamter ×length	O No. of pcs. - hole dia. × depth	P screw diamter × length	Q screw diameter*2	R*2	T	U	V screw diamter ×length	W screw diamter ×length*3	Mass*4 kg	Moment of inertia kg · m² *4	Allowable radial load N
TGF65-L3	175	167	106	M10×17	6-ϕ7×12	M6×20	M10	49	5	2.7	—	M10×20	15.2	0.0662	30000
TGF65-M3															
TGF65-H3															
TGF90-L3	243	233	150	M16×20	6-ϕ12×15	M10×30	M12	75	8	5.0	—	M12×35	34.7	0.258	33000
TGF90-M3															
TGF90-H3															

*1. Contact us for details on use at speeds higher than the maximum speed.
2. Setscrew taps are not processed. Dimensions are for reference only.
3. TGF65 uses hex cap countersunk screws, and TGF90 uses hex bolts. (Hex bolts will protrude a maximum of 7.5 mm from the edge of the hub.)
4. Mass and moment of inertia are based on the bores' maximum diameters.

Note) When installing a pulley or sprocket, use high-tensile bolts (G10.9 or higher) and determine the length carefully so that the bolts are not buried deeper than the mounting tap depth N.

Transmissible Capacity/Dimensions

■TGF20-□5 • TGF30-□5 • TGF45-□5 Type 5



This is a combination of the TGF-2 and the Echt-Flex Coupling NEF Series Single Type.

① Mounting adapter
② Coupling hub
③ Reamer bolt
④ Washer A
⑤ Washer B
⑥ Disk
⑦ U nut
⑧ Hex cap bolt
⑨ Spring washer
⑩ Hexagon socket head set screw
⑪ Set piece

Unit : mm

Model No.	Set torque range N · m	Max. rpm r/min*1	Coil spring number	Shock Guard S			Coupling S1			A	A1	A2	A3	B1	B2	C1
				Rough bore diamter	Min. bore diameter	JIS keyway for max. bore dia.	Rough bore diamter	Min. bore diameter	JIS keyway for max. bore dia.							
TGF20-L5	5 to 20	900	2	8	10	20	15	17	42	55	33.5	66.3	111	24.5	14	11.2
TGF20-M5	10 to 40		4													
TGF20-H5	20 to 80		8													
TGF30-L5	5 to 73.5	740	2	10	12	30	15	17	60	80	47.8	102.5	162	33.8	22	11.7
TGF30-M5	10 to 147		4													
TGF30-H5	20 to 294		8													
TGF45-L5	30 to 156	600	3	20	22	45	25	27	74	95	57.2	110	184	43.2	17	16.8
TGF45-M5	60 to 313		6													
TGF45-H5	120 to 568		12													

Model No.	D	E1	F1	J	K	L	M	N1 screw diamter × length	O No. of pcs. - hole dia. × depth	P screw diamter × length	P1 screw diamter × length	Q*2	Q1*2	R*2	R1*2	T	U
TGF20-L5	23	104	61	98	75	70	33	M5×20	4-φ5×6	M4×12	M4×6	M5	M5	5	8	3	1.2
TGF20-M5																	
TGF20-H5																	
TGF30-L5	39	143	84	130	98	92	48	M6×25	4-φ7×7	M6×15	M5×6	M6	M6	5	12	4	1.8
TGF30-M5																	
TGF30-H5																	
TGF45-L5	46	168	106	165	132	124	66	M8×25	6-φ7×7	M6×20	M5×6	M8	M8	8	15	4	2.2
TGF45-M5																	
TGF45-H5																	

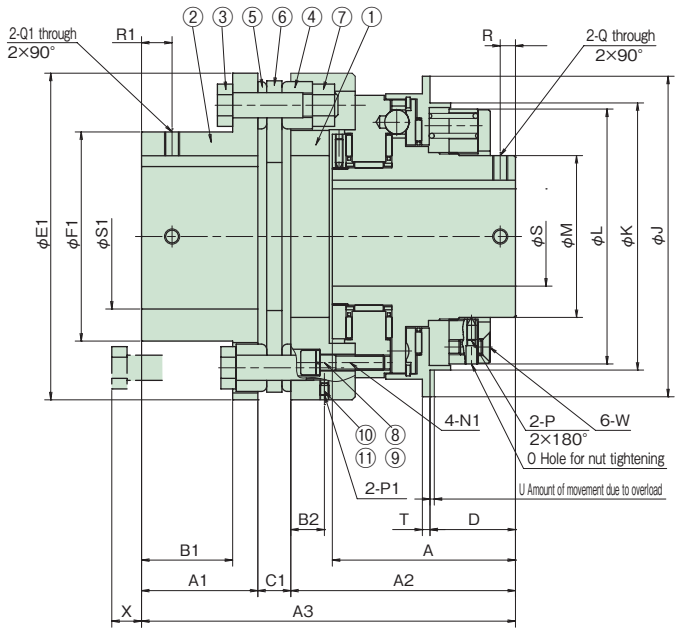
Model No.	V screw diamter × length	W screw diamter × length	Mass*3 kg	Moment of inertia*3 kg · m²	Coupling model No.	X*4	Allowable Misalignment	
							Angular misalignment deg	Shaft direction displacement*5
TGF20-L5	M4×8	—	3.2	0.00365	NEF25S	21	1	±1.4
TGF20-M5								
TGF20-H5								
TGF30-L5	M4×8	—	8.6	0.0188	NEF80S	29.5	1	±1.8
TGF30-M5								
TGF30-H5								
TGF45-L5	M4×8	—	14.0	0.0437	NEF130S	20	1	±2.5
TGF45-M5								
TGF45-H5								

*1. Contact us for details on use at speeds higher than the maximum speed.
2. Setscrew taps are not processed. Dimensions are for reference only.
3. Mass and moment of inertia are based on the bores' maximum diameters.
4. This is the space required for the insertion of a reamer bolt.
5. The allowable displacement in the shaft direction is the value when the angular error is zero. Parallelism errors are not allowed.

Transmissible Capacity/Dimensions

■TGF65-□5 • TGF90-□5

Type 5



This is a combination of the TGF-2 and the Echt-Flex Coupling NEF Series Single Type.

① Mounting adapter
② Coupling hub
③ Reamer bolt
④ Washer A
⑤ Washer B
⑥ Disk
⑦ U nut
⑧ Hex cap bolt
⑨ Spring washer
⑩ Hexagon socket head set screw
⑪ Set piece

Unit : mm

Model No.	Set torque range N · m	Max. rpm r/min*1	Coil spring number	Shock Guard S			Coupling S1			A	A1	A2	A3	B1	B2	C1
				Rough bore diamter	Min. bore diameter	JIS keyway for max. bore dia.	Rough bore diamter	Min. bore diameter	JIS keyway for max. bore dia.							
TGF65-L5	40 to 264	430	3	30	32	65	45	47	95	120	76.2	147.2	245	59.7	22	21.6
TGF65-M5	80 to 539		6													
TGF65-H5	160 to 1078		12													
TGF90-L5	196 to 1225	330	3	45	47	90	50	52	118	170	101.6	211.2	340	76.1	35	27.2
TGF90-M5	392 to 2450		6													
TGF90-H5	784 to 4900		12													

Model No.	D	E1	F1	J	K	L	M	N1 screw diamter × length	O No. of pcs. - hole dia. × depth	P screw diamter × length	P1 screw diamter × length	Q*2	Q1*2	R*2	R1*2	T	U
TGF65-L5	56	214	137	210	175	167	106	M10×45	6-ϕ7×12	M6×20	M6×8	M10	M10	10	20	5	2.7
TGF65-M5																	
TGF65-H5																	
TGF90-L5	93	276	169	280	243	233	150	M16×60	6-ϕ12×15	M10×30	M6×10	M12	M12	10	30	8	5.0
TGF90-M5																	
TGF90-H5																	

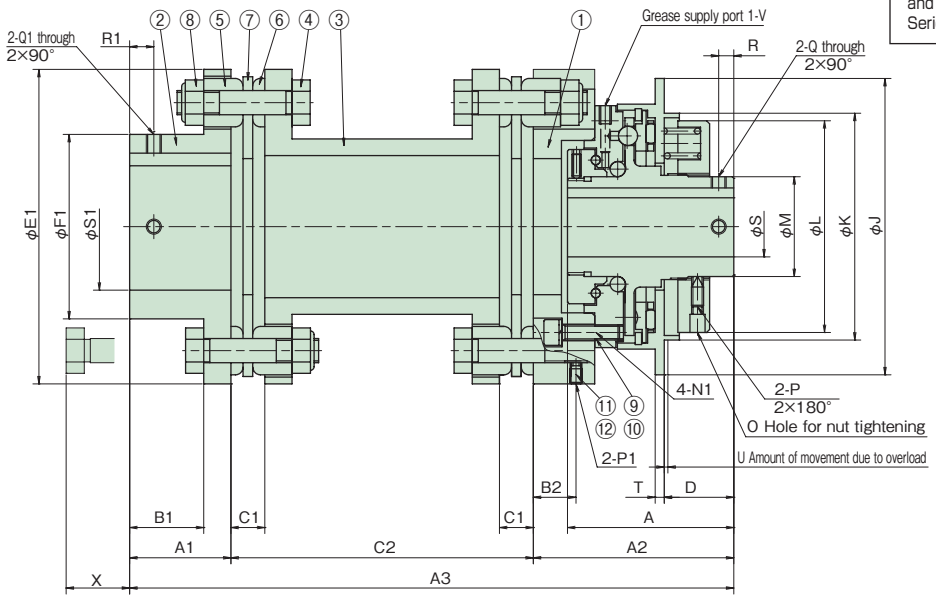
Model No.	V screw diamter × length	W screw diamter × length*3	Mass*4 kg	Moment of inertia*4 kg · m²	Coupling model No.	X*5	Allowable Misalignment	
							Angular misalignment deg	Shaft direction displacement*6
TGF65-L5	—	M10×20	32.0	0.166	NEF340S	19.5	1	±3.3
TGF65-M5								
TGF65-H5								
TGF90-L5	—	M12×35	75.6	0.660	NEF700S	40	1	±4.0
TGF90-M5								
TGF90-H5								

*1. Contact us for details on use at speeds higher than the maximum speed.
2. Setscrew taps are not processed. Dimensions are for reference only.
3. TGF65 uses hex cap countersunk screws, and TGF90 uses hex bolts.
4. Mass and moment of inertia are based on the bores' maximum diameters.
5. This is the space required for the insertion of a reamer bolt.
6. The allowable displacement in the shaft direction is the value when the angular error is zero.
Parallelism errors are not allowed.

Transmissible Capacity/Dimensions

■TGF20-□7 • TGF30-□7 • TGF45-□7 Type 7

This is a combination of the TGF-2 and the Echt-Flex Coupling NEF Series Long Spacer Type.



① Mounting adapter
② Coupling hub
③ Long spacer
④ Reamer bolt
⑤ Washer A
⑥ Washer B
⑦ Disk
⑧ U nut
⑨ Hex cap bolt
⑩ Spring washer
⑪ Hexagon socket head set screw
⑫ Set piece

Unit : mm

Model No.	Set torque range N · m	Max. rpm r/min*1	Coil spring number	Shock Guard S			Coupling S1			A	A1	A2	A3	B1	B2	C1	C2
				Rough bore diamter	Min. bore diameter	JIS keyway for max. bore dia.	Rough bore diamter	Min. bore diameter	JIS keyway for max. bore dia.								
TGF20-L7	5 to 20	900	2	8	10	20	15	17	42	55	33.5	66.3	199.8	24.5	14	11.2	100
TGF20-M7	10 to 40		4														
TGF20-H7	20 to 80		8														
TGF30-L7	5 to 73.5	740	2	10	12	30	15	17	60	80	47.8	102.5	277.3	33.8	22	11.7	127
TGF30-M7	10 to 147		4														
TGF30-H7	20 to 294		8														
TGF45-L7	30 to 156	600	3	20	22	45	25	27	74	95	57.2	110	307.2	43.2	17	16.8	140
TGF45-M7	60 to 313		6														
TGF45-H7	120 to 568		12														

Model No.	D	E1	F1	J	K	L	M	N1 screw diamter × length	O No. of pcs. - hole dia. × depth	P screw diamter × length	P1 screw diamter × length	Q*2	Q1*2	R*2	R1*2	T	U
TGF20-L7	23	104	61	98	75	70	33	M5×20	4-φ5×6	M4×12	M4×6	M5	M5	5	8	3	1.2
TGF20-M7																	
TGF20-H7																	
TGF30-L7	39	143	84	130	98	92	48	M6×25	4-φ7×7	M6×15	M5×6	M6	M6	5	12	4	1.8
TGF30-M7																	
TGF30-H7																	
TGF45-L7	46	168	106	165	132	124	66	M8×25	6-φ7×7	M6×20	M5×6	M8	M8	8	15	4	2.2
TGF45-M7																	
TGF45-H7																	

Model No.	V screw diamter × length	W screw diamter × length*3	Mass*4 kg	Moment of inertia*4 kg · m²	Coupling model No.	X*4	Allowable Misalignment		
							Angular misalignment deg	Shaft direction displacement*5	Parallel misalignment*5
TGF20-L7	M4×8	—	4.8	0.00586	NEF25W	21	2	±2.8	1.5
TGF20-M7									
TGF20-H7									
TGF30-L7	M4×8	—	12.4	0.0299	NEF80W	29.5	2	±3.6	2.0
TGF30-M7									
TGF30-H7									
TGF45-L7	M4×8	—	19.1	0.0651	NEF130W	20	2	±5.0	2.1
TGF45-M7									
TGF45-H7									

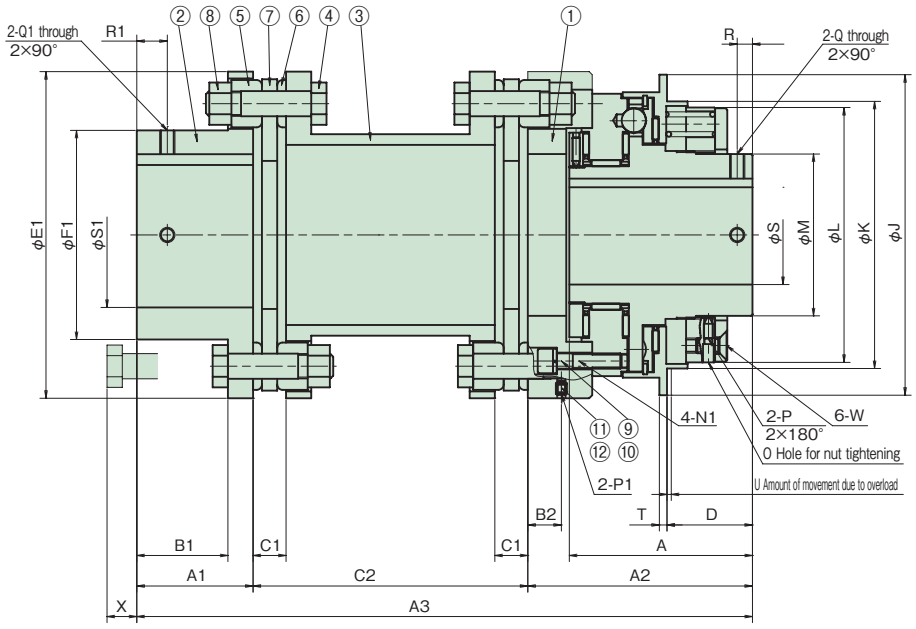
*1. Contact us for details on use at speeds higher than the maximum speed.
2. Setscrew taps are not processed. Dimensions are for reference only.
3. Mass and moment of inertia are based on the bores' maximum diameters.
4. This is the space required for the insertion of a reamer bolt.
5. The allowable displacement in the shaft direction is the value when the angular error is zero.

Transmissible Capacity/Dimensions

■ TGF65-□7 • TGF90-□7

Type 7

This is a combination of the TGF-2 and the Echt-Flex Coupling NEF Series Long Spacer Type.



① Mounting adapter
② Coupling hub
③ Long spacer
④ Reamer bolt
⑤ Washer A
⑥ Washer B
⑦ Disk
⑧ U nut
⑨ Hex cap bolt
⑩ Spring washer
⑪ Hexagon socket head set screw
⑫ Set piece

Unit : mm

Model No.	Set torque range N · m	Max. rpm r/min*1	Coil spring number	Shock Guard S			Coupling S1			A	A1	A2	A3	B1	B2	C1	C2
				Rough bore diamter	Min. bore diameter	JIS keyway for max. bore dia.	Rough bore diamter	Min. bore diameter	JIS keyway for max. bore dia.								
TGF65-L7	40 to 264	430	3	30	32	65	45	47	95	120	76.2	147.2	403.4	59.7	22	21.6	180
TGF65-M7	80 to 539		6														
TGF65-H7	160 to 1078		12														
TGF90-L7	196 to 1225	330	3	45	47	90	50	52	118	170	101.6	211.2	562.8	76.1	35	27.2	250
TGF90-M7	392 to 2450		6														
TGF90-H7	784 to 4900		12														

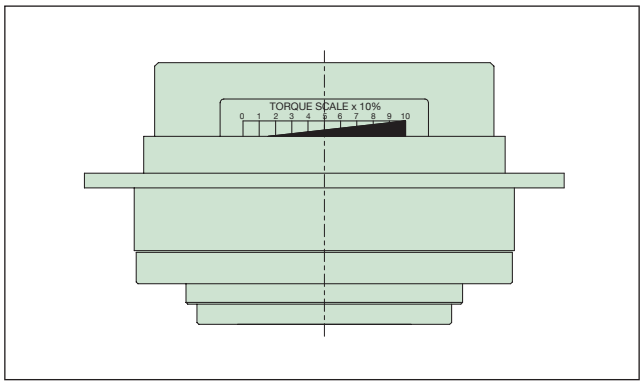
Model No.	D	E1	F1	J	K	L	M	N1 screw diamter × length	O No. of pcs. - hole dia. × depth	P screw diamter × length	P1 screw diamter × engath	Q*2	Q1*2	R*2	R1*2	T	U
TGF65-L7	56	214	137	210	175	167	106	M10×45	6-ϕ7×12	M6×20	M6×8	M10	M10	10	20	5	2.7
TGF65-M7																	
TGF65-H7																	
TGF90-L7	93	276	169	280	243	233	150	M16×60	6-ϕ12×15	M10×30	M6×10	M12	M12	10	30	8	5.0
TGF90-M7																	
TGF90-H7																	

Model No.	V screw diamter × length	W screw diamter × length*3	Mass*4 kg	Moment of inertia*4 kg · m²	Coupling model No.	X*5	Allowable Misalignment		
							Angular misalignment deg	Shaft direction displacement*6	Parallel misalignment*6
TGF65-L7	—	M10×20	42.6	0.236	NEF340W	19.5	2	±6.6	2.7
TGF65-M7									
TGF65-H7									
TGF90-L7	—	M12×35	102	0.954	NEF700W	40	2	±8.0	3.8
TGF90-M7									
TGF90-H7									

*1. Contact us for details on use at speeds higher than the maximum speed.
2. Setscrew taps are not processed. Dimensions are for reference only.
3. TGF65 uses hex cap countersunk screws, and TGF90 uses hex bolts.
4. Mass and moment of inertia are based on the bores' maximum diameters.
5. This is the space required for the insertion of a reamer bolt.
6. The allowable displacement in the shaft direction is the value when the angular error is zero.

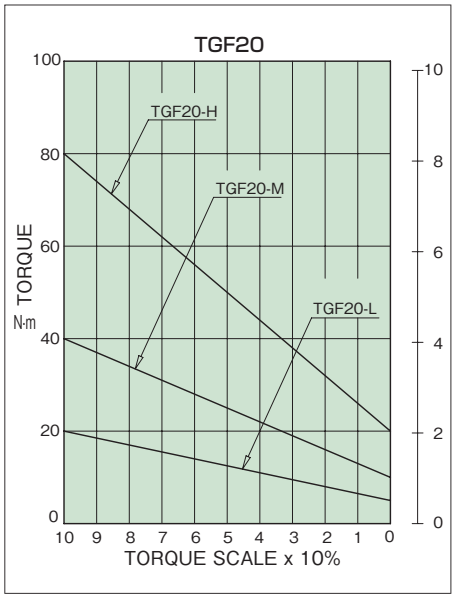
Torque adjustment

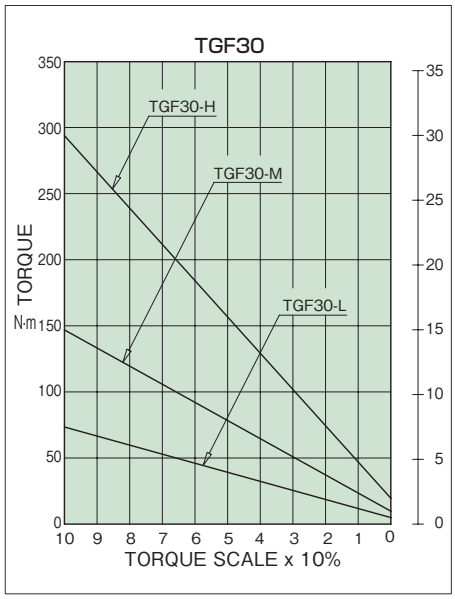
1. Read the torque scale value that corresponds to the required torque from the torque correlation charts and tighten the adjustment nut (6) to that value. To tighten the adjustment nut (6), hook a hook spanner or insert a round bar in the hole in the periphery of the nut, and then turn the nut.
   Note) If you are using the TGF30 or TGF45 size and a high torque (200 N · m or higher) is required, use the dedicated hook spanner (sold separately).
   If you are using the TGF65 or TGF90 size and a high torque is required, loosen the bolt (8) to adjust the torque, turn the adjustment nut (6) to the required torque scale value, lock the adjustment nut (6) with the hex cap setscrew (13), and then retighten the bolt.
2. When the torque is determined, write down the torque on the name plate so that you can easily set the torque to the previous value even after an overhaul. If you mark matchmarks on both the nut and the edge of the hub, you can reset the torque more precisely.

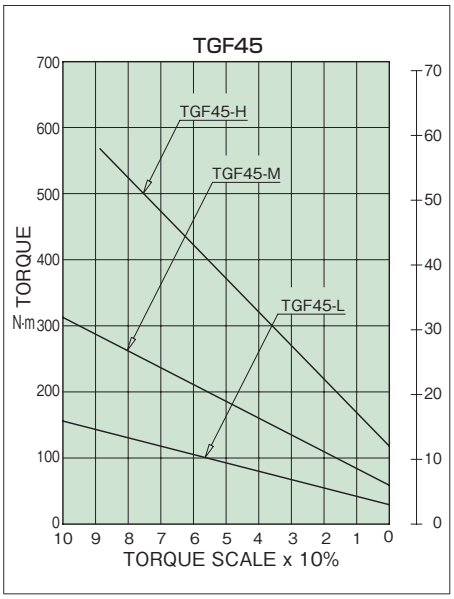


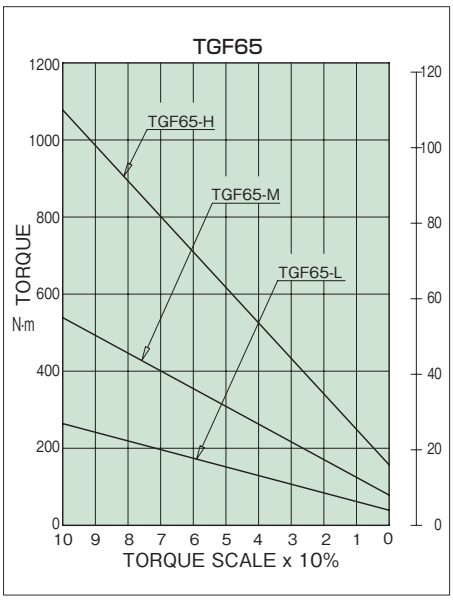
Torque scale

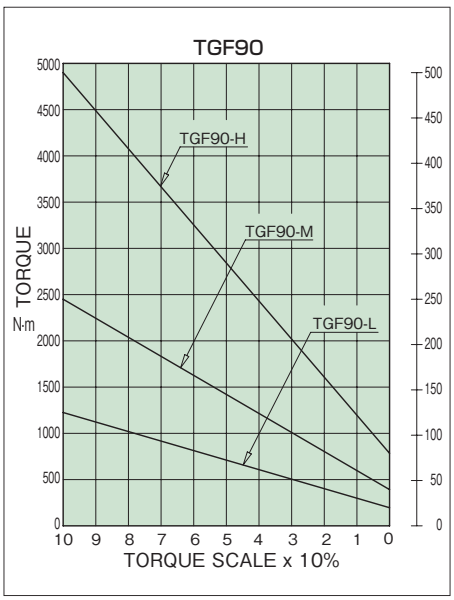
Torque Correlation Chart









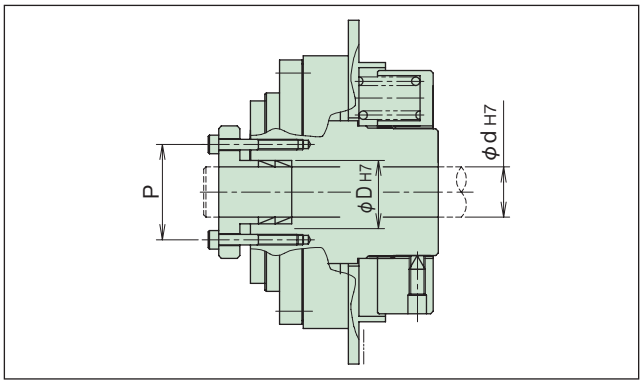


Power Lock Mounting Dimensions

The Shock Guard TGF Series can be combined with the Power Lock EL series.
The maximum applicable sizes of the mounting geometries of the TGF series are shown below.
The transmissible torque is the value when using one power lock unit. If using multiple power lock units, multiply the transmissible torque by the coefficients shown in the table on the right.
We will select the appropriate geometry if you designate your shaft dimensions and intended torque.

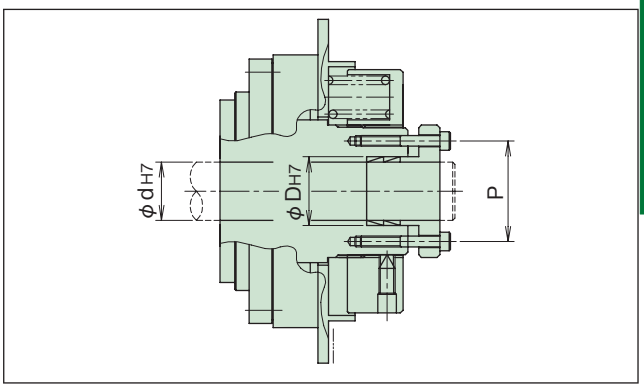
Number of units	coefficient
1	1
2	1.55
3	1.85

Mounting geometry a



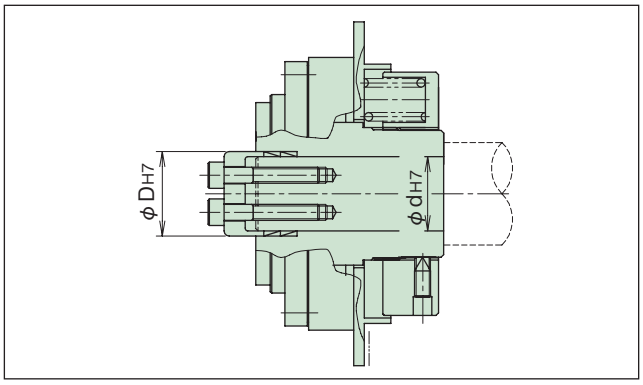
TGF Series size	Mounting geometry					Transmissible torque Nm
	Maximum applicable size	d	D	P	Bolt	
TGF20	–	–	–	–	–	–
TGF30	18×22	18	22	34	M4× 6	46.1
TGF45	32×36	32	36	50	M4× 8	123
TGF65	50×57	50	57	73	M6× 8	419
TGF90	71×80	71	80	99	M8×10	1560

Mounting geometry b



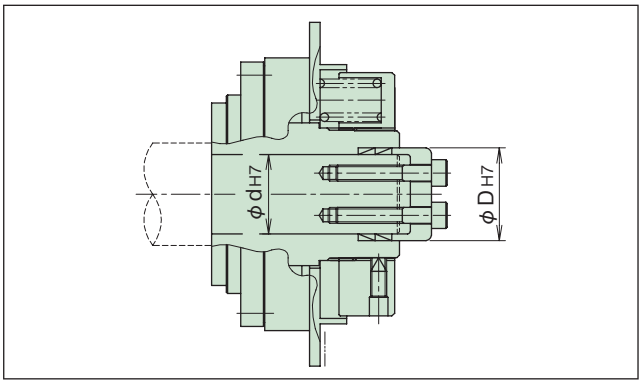
TGF Series size	Mounting geometry					Transmissible torque Nm
	Maximum applicable size	d	D	P	Bolt	
TGF20	–	–	–	–	–	–
TGF30	22×26	22	26	38	M 4× 6	55.9
TGF45	35×40	35	40	55	M 5× 6	167
TGF65	65×73	65	73	91	M 8× 8	1140
TGF90	95×106	95	106	126	M10×10	3390

Mounting geometry c



TGF Series size	Mounting geometry				Transmissible torque Nm
	Maximum applicable size	d	D	Bolt	
TGF20	20×25	20	25	M10×1	39.2
TGF30	32×36	32	36	M 6×3	100
TGF45	45×52	45	52	M 6×8	321
TGF65	65×73	65	73	M10×4	813
TGF90	85×96	85	96	M10×8	2000

Mounting geometry d



TGF Series size	Mounting geometry				Transmissible torque Nm
	Maximum applicable size	d	D	Bolt	
TGF20	24×28	24	28	M10×1	56.8
TGF30	36×42	36	42	M 5×6	144
TGF45	50×57	50	57	M 6×8	397
TGF65	75×84	75	84	M10×6	1260
TGF90	100×114	100	114	M12×8	3450

Shock Guard TGM Series

Features

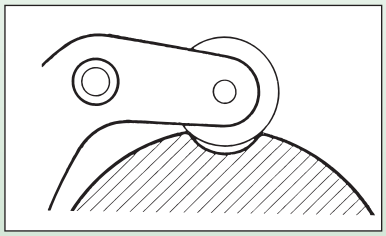
Highly accurate sealed type.
Excels in wet, oily and dusty environments.

Sealed construction

Covered in a special aluminum alloy casing, the TGM Series is sealed, so it is almost impossible for dust, oil or water to penetrate it. Therefore, it does not affect trip torque precision, making it an ideal overload protection device.

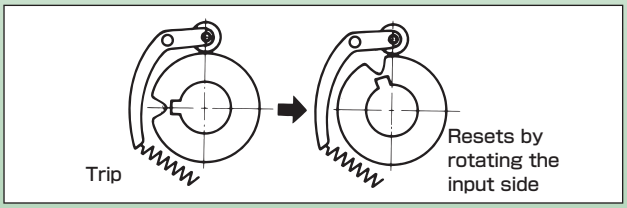
Non-backlash

The cam follower and pocket's engagement is a 2 point contact pressed against each other, meaning there is no backlash.



Automatic reset

Once the cause of overload is removed, the Shock Guard automatically moves back to its original position by rotating the input side a little (at less than 50r/min), or by inching the motor.



Long life

LS detecting plate for overload detector

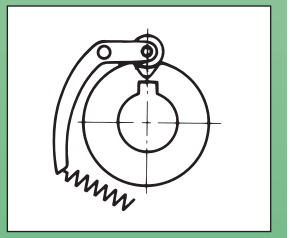
When the Shock Guard trips the LS detecting plate slides in the axial direction, so it is easy to actuate the limit switch, shut off the power or set off the alarm.
When tripping it can be used whether it stops on the camshaft side or the housing (Shock Guard case) side.
The LS detecting plate can be mounted on all models.

No need to lubricate

The Shock Guard TGM Series is packed in high quality grease before shipment.

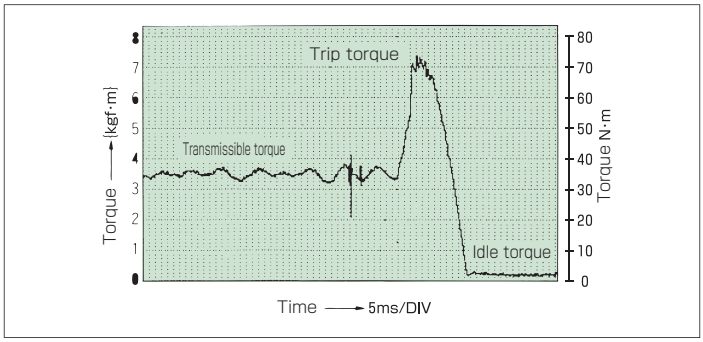
One position

Because the cam follower and pocket of the cam shaft engage together, there is no phase shift between the drive side and the driven side.



High precision trip torque

Repetitive motion torque accuracy is within ±5%.
One (1) high precision cam follower pressurizes tightly from the radial direction in the precisely machined pocket. A highly rigid and stable load rate rectangular spring is used. Trip movement is a rolling movement, so even a repeat trip produces almost no torque variation.



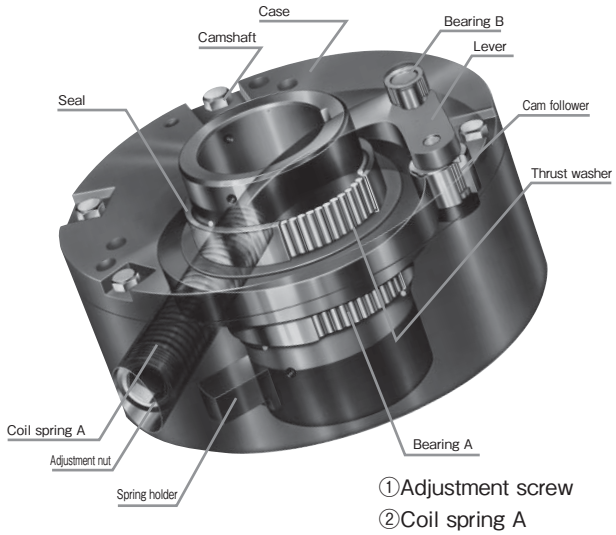
●Easy to use

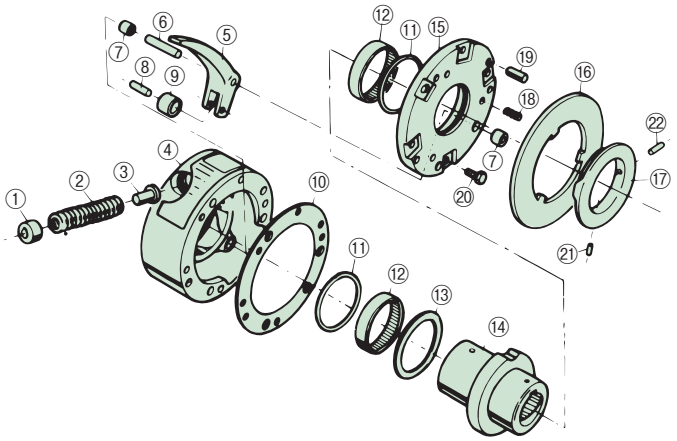
The camshaft and case can be used on either the drive or driven sides. As well, it can be used in either direction of rotation. For the drive member, you can choose between using a chain, pulley or gear. Assembling with a coupling is also possible. Refer to page 76 to see the assembly of a Shock Guard coupling with a roller chain coupling.

●Torque setting is easy

By simply turning the adjustment screw with a hexagon wrench, precise torque can be set. As well, the adjustment nut is on the outer surface of the Shock Guard, so torque setting can be done easily.

Construction and Operating Principles

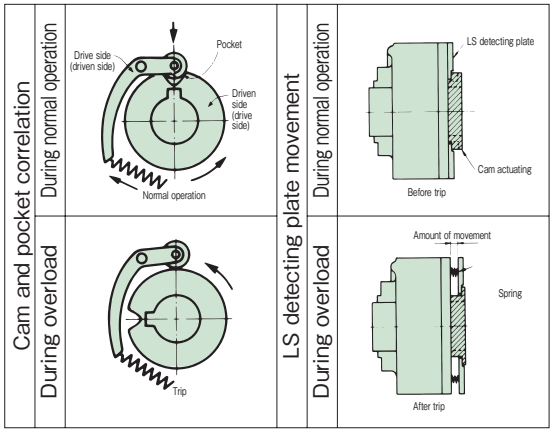




①Adjustment screw
②Coil spring A
③Spring seat
④Case
⑤Lever
⑥Fulcrum pin
⑦Bearing B
⑧Roller pin
⑨Cam follower
⑩Gasket
⑪Seal
⑫Bearing A
⑬Thrust washer
⑭Cam shaft
⑮Cover
⑯LS detecting plate
⑰Cam actuation plate
⑱Coil spring B
⑲Spring pin
⑳Hexagon bolt
㉑Hexagon socket head set screw
㉒Hexagon socket head set screw

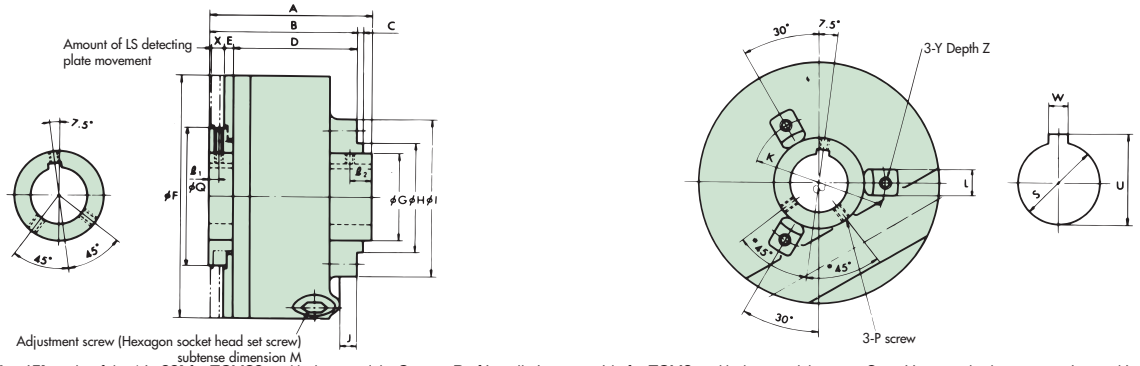
TGM60/200/400/800 models with strong spring specifications and TGM400 and 800 models with standard specifications employ two ② Coil spring A components.

1. The cam follower transmits torque by engaging with the camshaft pocket in a radial direction.
   When the machine is overloaded, the cam follower pops out of the pocket, and completely separates from the overload.
2. The cam follower and pocket are precision machined and heat treated, so it is able to maintain high torque precision for extended periods of time.
3. The cam follower and pocket are non-backlash, with a 2-point contact system.
4. Using the leverage on one rectangular coil spring pressurizes the cam follower, so it is able to give high precision pressure.
5. Torque level is infinitely adjustable with the adjustment screws.
6. Due to overload, the idling during trip is received by 5 needle bearings, so there is no slide, and idling friction torque is minute.
7. Because the case and cover are made from a solution treated aluminum, it has a light but strong construction.
8. Due to its sealed construction, it is highly difficult for dust, water or oil to penetrate the TGM Series.
9. If the Shock Guard trips because of overload, the LS detecting plate slides in the axis direction, so by operating the limit switch, overload detection is easy.



1. Torque is transmitted by the engagement of the cam follower and the pocket with a 2 point contact system.
   The method to pressurize the cam follower to the cam pocket is to hold it by one rectangular coil spring in a radial direction.
   Therefore there is no backlash, allowing it to function as a high trip torque precision overload protection device. Reset is carried out using an automatic reset system, so as the cam follower settles into its pocket position, operation resumes. As it is a two-point contact, there is no phase shift from the original position.
2. When overloaded, the cam follower comes out of its pocket and starts rolling on the outer diameter of the camshaft. As there is no slide section, the idling friction torque is small, making it a highly durable device. As well, the simple one position engagement construction of the TGM Series means its high trip torque precision does not diminish.
3. When the Shock Guard trips, the LS detecting plate slides in the axis direction. From this point, the limit switch can be actuated and the power can be turned off. The alarm can also be sounded. For each one trip, the LS detecting plate slides three times.

Dimensions



Note: The 45° angle of the * is 60° for TGM20 and below models. Screws P of installation seat side for TGM6 and below models are at 2 positions, at the keyway portion and its left side.

■ Transmissible capacity

Unit : mm

Model No.	Set torque range N・m	Max. rpm * r/min	Bore range	Stock bore diameter H7	Semi-standard bore diameter H7	Moment of inertia $\times 10^{-2}$kg・m^2	Mass kg
TGM3	1.5 to 3.7	600	10 to 14	**14**	10, 12	0.0425	0.6
TGM6	2.5 to 6.4	600	10 to 14	**14**	10, 12	0.0425	0.6
TGM20	6.4 to 20	500	14 to 20	**20**	14, 16, 18	0.168	1.1
TGM60	20 to 69	300	20 to 30	**30**	20, 22, 25, 28	0.938	2.5
TGM200	68 to 225	200	28 to 50	**50**	30, 35, 40, 45	4.03	5.4
TGM400	225 to 451	150	38 to 60	—	60	40.0	17.2
TGM800	451 to 902	150	38 to 60	—	60	40.0	17.2

*1. Cam shafts for semi-standard bore diameters are in stock for quick delivery.
2. The keyway is made with JIS1301-1996 (new JIS standard) dimensions.

■ Dimensions

Unit : mm

Model No.	A	B	C	D	E	F	G	H h7	I	J	K	L	M	P	Q	ℓ1	ℓ2	S H7	U	W	X	Y	Z
TGM3	60	57	2	48	3	80	22	30	50	3	40	8	5	M4	40	4	6	14	16.3	5	4	M 4	8
TGM6	60	57	2	48	3	80	22	30	50	3	40	8	5	M4	40	4	6	14	16.3	5	4	M 4	8
TGM20	70	66	3	57	3	100	30	40	60	4	50	10	6	M4	50	4	7	20	22.8	6	4	M 5	10
TGM60	89	81	3	68	5	133	47.6	60	86	7	73	14	12	M5	76	6	12	30	33.3	8	6	M 6	13
TGM200	110	100	3	85	5	178	69.9	82	133	14	114	20	12	M6	105	7	14	50	53.8	14	6	M10	19
TGM400	157	147	9	131	5	273	88.9	114	190	17	165	28	17	M8	124	7	16	60	64.4	18	8	M12	28
TGM800	157	147	9	131	5	273	88.9	114	190	17	165	28	17	M8	124	7	16	60	64.4	18	8	M12	28

*1. The model numbers in bold are stock items, and the rest are assembled for shipment. 2. The keyway is made with JIS1301-1996 (new JIS standard) dimensions.
3. Minimum torque is set temporariry when shipped.

Semi-standard

1. Torque setting

If necessary, torque can be set at TEM's factory before shipment. Torque setting tolerance is within ±5%. The set torque value is on the nameplate, and the adjustment nut is coated with Loctite 242, or its equivalent, and tightened. When ordering, indicate set torque value (kgf・m) after bore diameter. (Please refer to the table on the right)

2. Weak spring and strong spring specifications

For when it is necessary to operate with a trip torque other than the standard torque value range:

(1) TGM6 and TGM800 do not have weak spring specifications.
(2) The standard torque range can be replaced by weak or strong spring torque ranges on the nameplate.
(3) The minimum and maximum torque indicator on the nameplate does not change for the weak and strong springs.
(4) When ordering, indicate weak spring (WS) or strong spring (SS) in the last part of the product number.

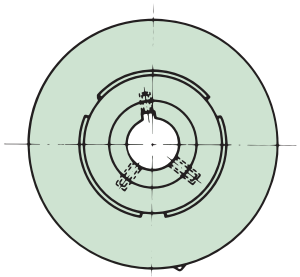
Model No.	Weak spring, torque range N·m {kgf·m}	Reinforced spring, torque range N·m {kgf·m}
TGM3(C)	0.59 to 1.5 {0.06 to 0.15}	——
TGM6(C)	——	6.0 to 12.7 {0.61 to 1.3}
TGM20(C)	3.7 to 12 {0.38 to 1.2}	7.3 to 23 {0.74 to 2.3}
TGM60(C)	7.6 to 26 {0.78 to 2.7}	44 to 105 {4.5 to 10.7}
TGM200(C)	30 to 98 {3.1 to 10}	101 to 289 {10.3 to 29.5}
TGM400(C)	118 to 235 {12 to 24}	——
TGM800(C)	——	532 to 1060 {54.3 to 108}

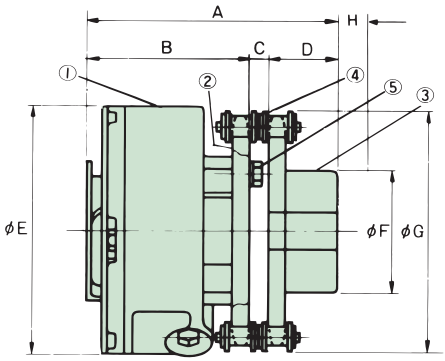
Coupling type-sprocket combination

■ Coupling type

This is the Shock Guard and roller chain coupling combination series. It is a Shock Guard with high trip torque accuracy and an easy to use roller chain coupling, all in one. It is ideal for direct coupling between the drive and driven machines. (In the case it is coupled with a non-backlash coupling, contact TEM for a consultation.)

Transmissible Capacity/Dimensions





① Shock Guard
② TG sprocket
③ CP sprocket
④ Chain
⑤ Hexagon bolt

H: The space necessary for inserting the joint link

Unit : mm

Coupling Type Model No.	Set torque range N·m	Max. rpm * r/min	Shock Guard bore		Coupling bore		A	B	C	D	E	F	G	H	Sprocket	Mass kg	Moment of inertia $\times 10^{-2}$kg·m^2
			Standard bore diameter H7	Semi-standard bore diameter H7	Rough bore diameter	Maximum bore diameter											
TGM3C	1.5 to 3.7	600	14	10,12	12.5	30	90	64.2	5.8	20	80	50	70	9	RS35-20	1.12	0.07
TGM6C	2.5 to 6.4																
TGM20C	6.4 to 20	500	20	14,16,18	12.5	32	100	72.2	5.8	22	100	53	82	7	RS35-24	1.78	0.218
TGM60C	20 to 69	300	30	20,22,25,28	12.5	42	120.6	88.2	7.4	25	133	63	117	17	RS40-26	4.15	1.21
TGM200C	68 to 225	200	50	30,35,40,45	18	55	163.3	111.7	11.6	40	178	83	188	26	RS60-28	11.8	6.80
TGM400C	225 to 451	150	–	60	28	75	221.9	161.6	15.3	45	273	107	251	38	RS80-28	31	50.8
TGM800C	451 to 902																

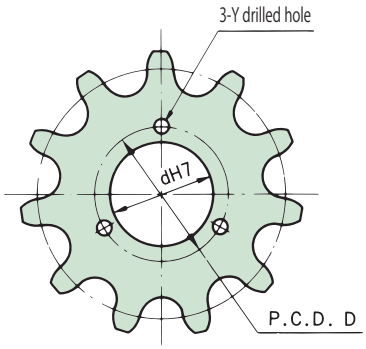
*1. All model numbers are MTO.
2. Apply the lubricant such as molybdenum disulfide to the chain and top of the sprocket teeth periodically (every 2000 hours).

■ Sprocket combination

When using a sprocket with a drive member, select the appropriate sprocket from the chart below.
This table shows the available sprocket machining dimensions.

Unit : mm

Shock Guard Model No.	Finished sprocket dimensions		
	d_{H7}	D	Y
TGM3	30	40	4.5
TGM6	30	40	4.5
TGM20	40	50	5.5
TGM60	60	73	6.6
TGM200	82	114	11.0
TGM400	114	165	14.0
TGM800	114	165	14.0



Note: Verify the chain transmissible capacity when determining the number of sprocket teeth.
Note: Insert the joint link from the outside of the sprocket.

Torque setting

By simply turning the adjustment screw with a hexagon wrench, precise torque can be set.

1. The minimum torque value is set for shipment. The top surface of the adjustment screw is adjusted to the minimum torque (torque indicator 1) printed on the nameplate. This is the base tightening quantity.

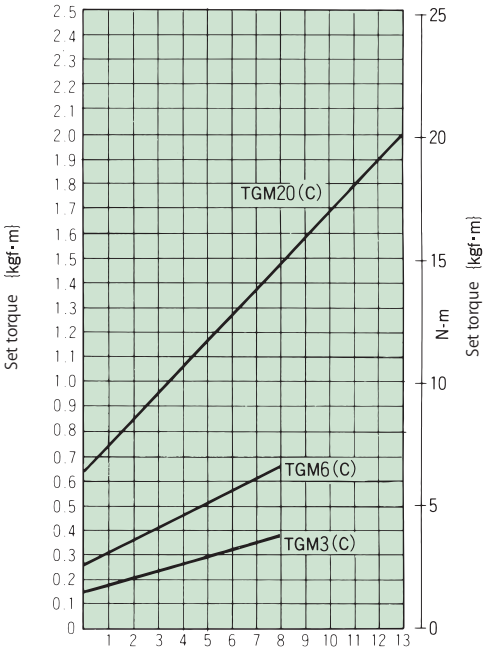
2. Before setting the torque, apply Loctite 242 or an equivalent adhesive to the exposed surface of the adjustment screw's thread portion. After setting torque, it becomes anti-loosing.
3. From the "Tightening Amount-Torque Correlation Chart" (below), find the adjustment screw tightening angle equivalent to the predetermined trip torque and tighten them. Set at 60° toward the determined tightening value, then install to the machine and conduct a trip test. Gradually tighten and set at optimum trip torque. Each product's trip torque does not always correspond with the value listed in the "Tightening Amount - Torque Correlation Chart", so use these values only as a rough guide.
4. Do not set torque lower than the minimum torque (torque indicator 1 on the nameplate). If it is necessary to use a torque level lower than the minimum, use a weak spring type.
5. Do not turn the adjustment screw when the Shock Guard is in a tripped state.
6. Torque setting before shipment is available. (Please refer to page 65).

Model No.	Amount of torque variation per one (1) rotation N·m {kgf·m}	Total number of rotations
TGM3	0.28 {0.029}	8
TGM6	0.48 {0.049}	8
TGM20	1.02 {0.10}	13
TGM60	4.90 {0.5}	10
TGM200	9.80 {1.0}	16
TGM400	20.6 {2.1}	11
TGM800	41.2 {4.2}	11

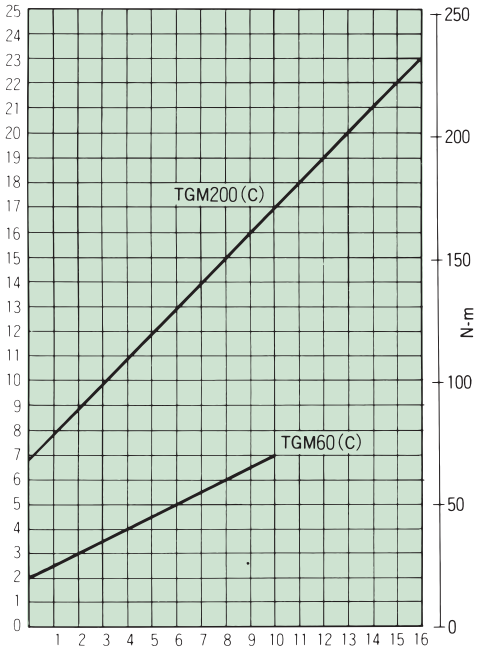
Set torque = min. torque + (amount of torque variation per one (1) rotation X total number of rotations of the adjustment screw)

Tightening Amount-Torque Correlation Chart

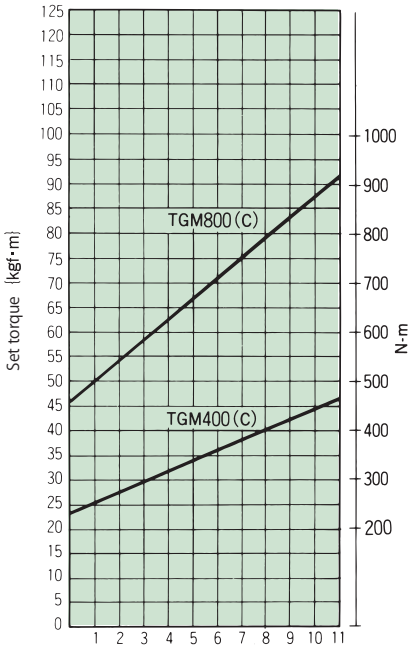
TGM3(C) TGM6(C) TGM20(C)



TGM60(C) TGM200(C)



TGM400(C) TGM800(C)



Overload detection

Using the limit switch, overload can be detected easily. If the Shock Guard trips due to overload, the cam follower will disengage from the pocket and the camshaft and main unit (case) will idle. At the same time, the LS detecting plate slides in the axial direction.
The limit switch detects this movement, shuts the power off and sets off an alarm. Whether the stopping side is on the camshaft side or the main unit case side, overload can be detected. For every one trip, the LS detecting plate slides three times.

(1) Table 1 shows LS detecting plate movement and force during trip.
Choose a limit switch from Table 1 that meets the "movement until operation" and its "necessary amount of force".

(2) Diagrams 1 and 2 are limit switch installation examples.

(3) Connect the limit switch's "b contact" parallel to the start button's contact.

(4) Diagram 3 shows an example of a typical circuit. TEM recommends using a self-holding circuit.

Table 1

Model No.	Amount of movement mm	Force when moving N {gf}
TGM3	4	3.9 {400}
TGM6	4	3.9 {400}
TGM20	4	3.9 {400}
TGM60	6	3.9 {400}
TGM200	6	5.4 {550}
TGM400	8	5.9 {600}
TGM800	8	5.9 {600}

■ Limit Switch Installation Example

Diagram 1

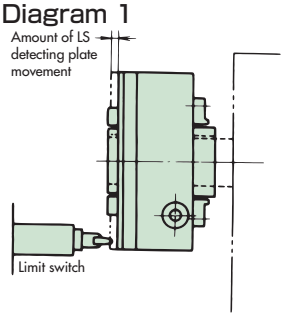
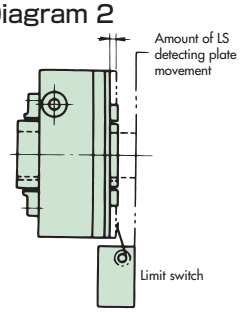
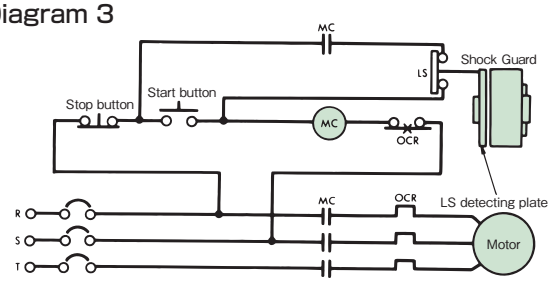


Diagram 2



■ Circuit Example

Diagram 3



Installation

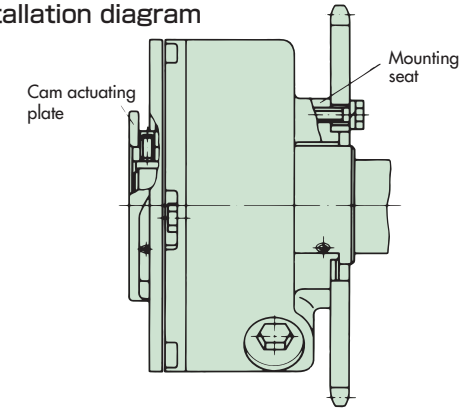
1. Installing to the axis

- A shaft diameter tolerance of h7 for installing the Shock Guard to the shaft is recommended.
  Use a JIS 1301-1996 (New JIS standards) parallel key. Allow some clearance between the top of the key and keyway
- When installing the cam actuating plate to the shaft, tighten bolts in three places. (For the key, 1 place; for the shaft, 2 places)
- When mounting the Shock Guard to the end face of the shaft, depending on the installation method, the cam actuating plate set screws cannot be used. In this case use the tap holes on the mounting seat side. Set screws for these tap holes are not included, so use bolts with a length that fits the bore diameter. Take care to ensure that the head of the set screws do not come out from the outer diameter of the camshaft. If the head of the screws come out, they will interfere with the inner diameter and lateral side of the mounting seats when the Shock Guard trips.
- If during operation there is a chance vibration will cause the screws to loosen, apply Loctite 242 or an equivalent for anti-loosening.

2. Installation of drive member

- By utilizing 3 mounting seats, tighten the bolts with the torque shown in Table 2 to install the sprockets, pulleys, gears and couplings to the housing.
- Refer to page 66 for sprocket installation. If it is necessary to combine a TSUBAKI Power Lock (keyless locking device) with a non-backlash coupling, contact TEM for a consultation.

Installation diagram



3. Installation bolts

The screw-in length of the mounting seat installation bolts and their tightening torque recommended values are listed on table. As well, use JIS B1001 2 class and lower class for rough bore for installation bolts.

Table 2

Model No.	Bolt screw-in length (mm)	Bolt tightening torque N・m {kgf・m}	Prepared hole diameter for installation bolt (mm)
TGM3	6 to 7	2.0 to 2.9 {0.2 to 0.3}	4.5
TGM6	6 to 7	2.0 to 2.9 {0.2 to 0.3}	4.5
TGM20	8 to 9	3.9 to 5.9 {0.4 to 0.6}	5.5
TGM60	9 to 11	6.9 to 11 {0.7 to 1.1}	6.6
TGM200	15 to 17	34 to 51 {3.5 to 5.2}	11.0
TGM400	18 to 25	59 to 89 {6.0 to 9.1}	14.0
TGM800	18 to 25	59 to 89 {6.0 to 9.1}	14.0

4. Connecting

The input/output connection is placed between the variator, reducer or intermittent drive device and the device/machine. Diagrams 4, 5 and 6 show typical connecting examples.

Diagram 4

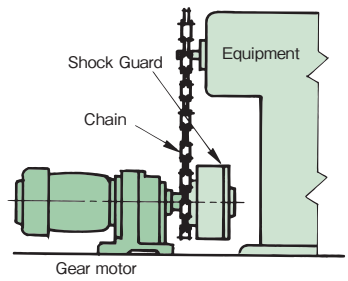


Diagram 5

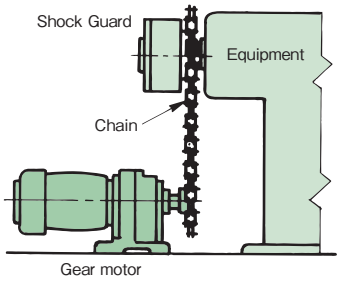
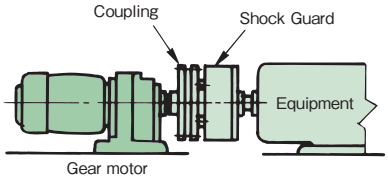


Diagram 6



Resetting

As it is an automatic reset system, just re-starting the drive side can automatically reset it.

1. When the Shock Guard trips due to overload, stop the rotation and remove the cause of the overload.
2. When resetting, reset (re-engage) with input rpm at less than 50r/min or by inching the motor. To avoid injury, do not reset the Shock Guard main unit or the shaft by hand.
3. A distinct clicking sound is made when the cam follower settles in its pocket.

Grease

Shock Guard TGM Series are packed in high quality grease before shipment, so they can be used as is. Under normal conditions greasing is not necessary.

Grease used:

EMG Marketing	Mobilux EP-2

MEMO

Features

TGZ Series can be used as a simple layout release type protection device or an ON-OFF clutch.

Release type

After tripping due to overload, the input side freely rotates. Even a high-speed shaft can be operated worry-free.

Resetting by external force

After the Shock Guard has been stopped, remove the cause of overload. Then give load to the axial direction manually or with external force.

ON-OFF function

The rotation (ON) or shut-off (OFF) functions are available arbitrarily. They can be used as an accurate mechanical type ON-OFF clutch.

Easy torque adjustment

Just by turning the adjustment nut,
trip torque can be easily set.

Easy to see torque indicator

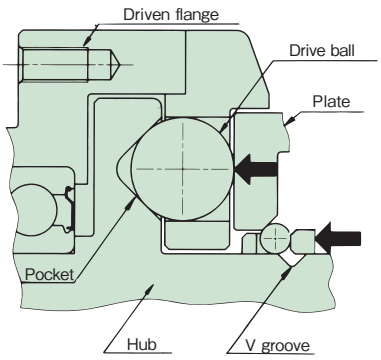
By using the revolution indicator and angle indicator, set torque can be monitored at any time.

One position type

This uniquely assembled torque transmission element ball and pocket configuration only engages in one position.

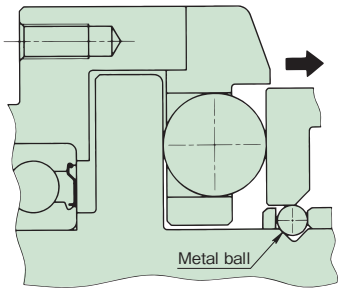
Operating Principles

During normal operation (engagement)



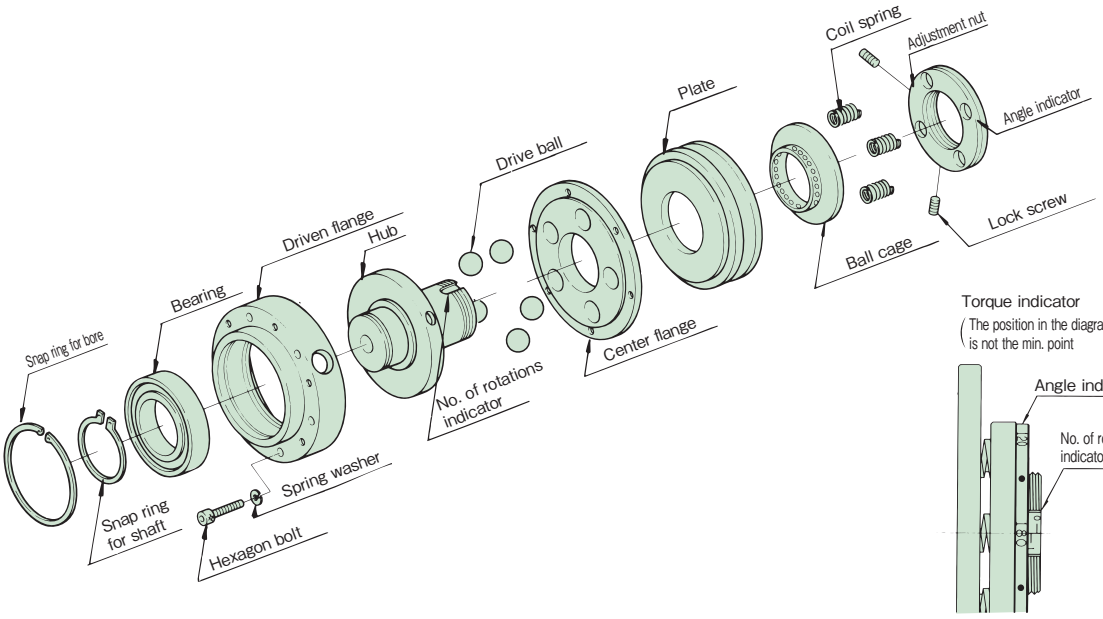
Torque transmission is made by a drive ball which is pressurized and retained at the hub pocket and the driven flange.
The non-symmetric arrangement of the balls and pockets allows only one engagement position per one rotation, and there is no phase shift after tripping.

During overload (trip)



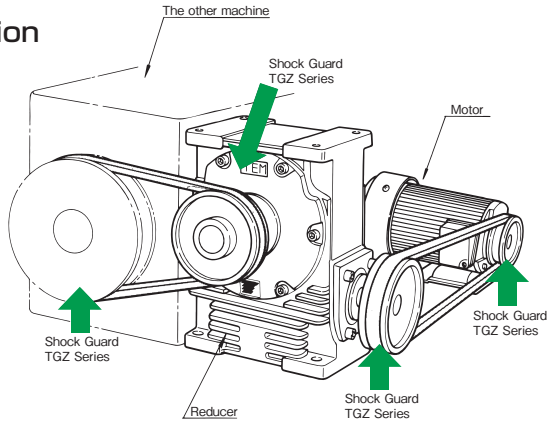
When overloading (when OFF), a drive ball instantly pops out of its pocket, and the plate and a steel ball simultaneously move to the adjustment nut side.
A drive ball comes completely out of its pocket and a steel ball enters the hub outer circumference V-groove, and the pressure from the springs is not transferred to the plate. Therefore, a drive ball freely rotates without returning to the pocket.

Construction



Applications classified by use

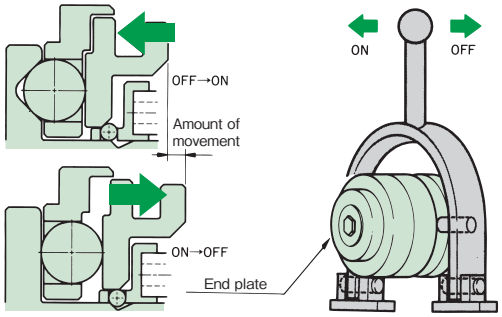
1. Overload protection



As demonstrated in the diagram on the left, the TGZ Series can be installed with any motor shaft, reducer (variator) or other machines. When considering the layout, make sure to leave sufficient space to adjust torque and for resetting procedures. After removing the cause of overload, do not reset the machine while it is running.

⚠If the Shock Guard is reset during rotation, the machine will suddenly run.

2. ON-OFF clutch



By using manual or mechanical external force (pneumatic, hydraulic, etc.), the plate can be moved, cutting off the input rotation (OFF) or transmitting it (ON). The necessary axial load for turning the machine ON or OFF is written in the table below.

Necessary shaft direction load when ON-OFF

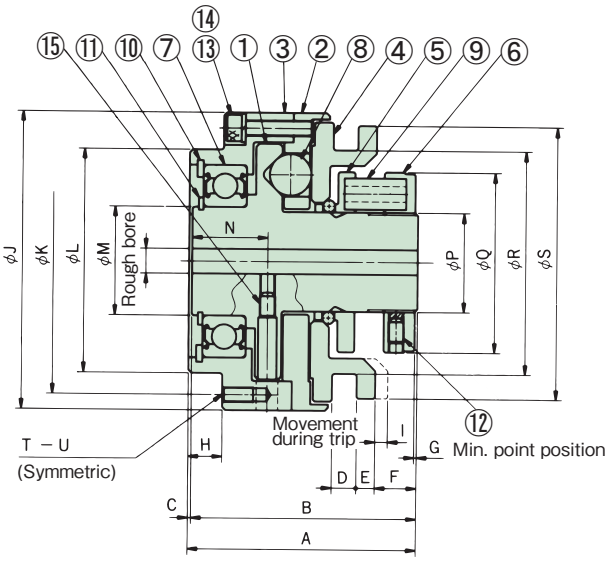
Actuation / Model No.	OFF → ON N {kgf}	ON → OFF N {kgf}	Amount of movement mm
TGZ20-L	49 { 5}	245 { 25}	4.1
TGZ20-M	88 { 9}	431 { 44}	
TGZ20-H	176 {18}	862 { 88}	
TGZ30-L	98 {10}	470 { 48}	4.7
TGZ30-M	235 {24}	1176 {120}	
TGZ30-H	470 {48}	2352 {240}	

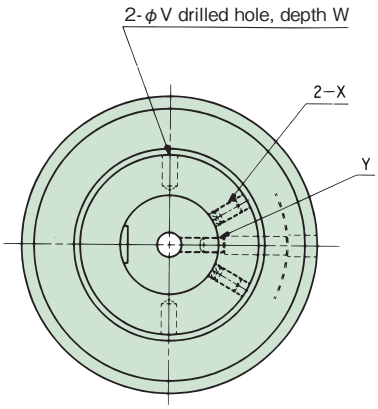
Actuation / Model No.	OFF → ON N {kgf}	ON → OFF N {kgf}	Amount of movement mm
TGZ40-L	157 { 16}	774 { 79}	5.9
TGZ40-M	421 { 43}	2087 {213}	
TGZ40-H	833 { 85}	4155 {424}	
TGZ50-L	451 { 46}	2269 {231}	7
TGZ50-M	902 { 92}	4518 {461}	
TGZ50-H	1382 {141}	6919 {706}	

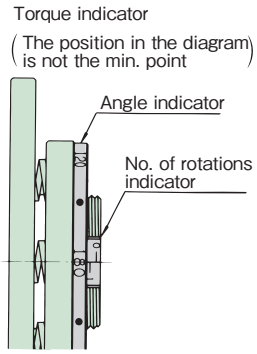
Axial load fluctuates depending on the number of actuations and usage conditions. Set the load with margin.

Transmissible Capacity/Dimensions

Shock Guard (TGZ Series)







① Hub ② Center flange ③ Driven flange ④ Plate ⑤ Ball cage ⑥ Adjustment nut
⑦ Ball bearing ⑧ Drive ball (Steel ball) ⑨ Coil spring ⑩ Snap ring for bore ⑪ Snap ring for shaft
⑫ Lock screw ⑬ Hexagon socket head bolt ⑭ Spring washer ⑮ Hexagon socket head set screw

* Adjustment nut for fixing the lock screw (1) is included with the Shock Guard. After setting appropriate torque, tighten with the following torque to avoid interference with the pocket of hub. Lock screw size: M5···3.8N·m{38.7kgf·cm} M8···16N·m{163kgf·cm}

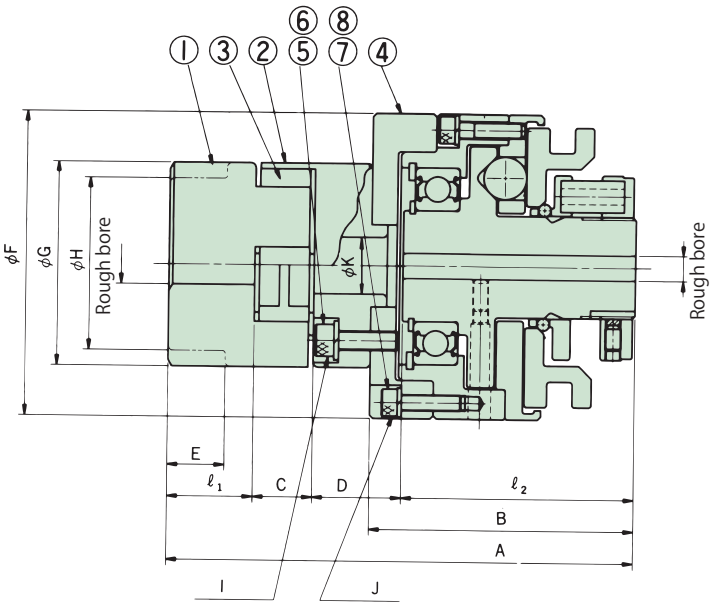
Unit : mm

Shock Guard Model No.	Set torque range N·m	Max. rpm r/min	Coil spring color X the number	Rough bore diamter	Min. bore diameter	Max. bore diameter	A	B	C	D	E	F	G min. point position	H	I amount of movement during trip	J	K PCD
TGZ20-L	2.4 to 8.3	1800	Yellow×3	8	10	20	74	73	1	8	6	13.5	0.8	11	4.1	96	86
TGZ20-M	4.1 to 16		Blue ×3														
TGZ20-H	8.2 to 31		Blue ×6														
TGZ30-L	5.9 to 21	1800	Yellow×4	12	14	30	83.5	82	1.5	8	6	14.5	1.1	11.5	4.7	118	106
TGZ30-M	20 to 52		Red ×4														
TGZ30-H	39 to 108		Red ×8														
TGZ40-L	25 to 93	1800	Blue ×5	17	19	40	101	100	1	9	8	20	1.1	14	5.9	152	139
TGZ40-M	44 to 127		Red ×5														
TGZ40-H	88 to 245		Red ×10														
TGZ50-L	63 to 157	1800	Red ×5	22	24	50	114.5	112	2.5	10	9	20.2	1.2	16	7	178	162
TGZ50-M	127 to 304		Red ×10														
TGZ50-H	245 to 451		Green×10														

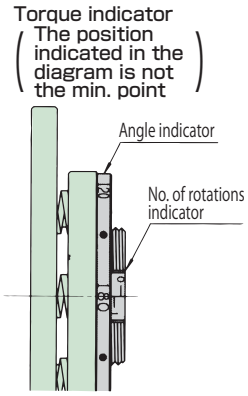
Shock Guard Model No.	L h7	M	N	P	Q	R	S	T	U screw diameter X length	V	W	X screw size X length	Y screw size X length	* Mass kg	* Moment of inertia ×10⁻²kg·m²
TGZ20-L	72	35	24.5	32	57	70	88	4	M5×10	5	10	M5×10	M5×10	2.57	0.273
TGZ20-M															
TGZ20-H															
TGZ30-L	87	45	27.5	45	75	88	108	4	M6×12	6	10	M5×10	M6×10	4.17	0.695
TGZ30-M															
TGZ30-H															
TGZ40-L	114	65	32.5	65	103	119	141	6	M6×12	8	14	M8×10	M8×10	8.71	2.40
TGZ40-M															
TGZ40-H															
TGZ50-L	133	75	37	75	113	138	166	6	M8×16	9	14	M8×10	M8×10	13.7	5.30
TGZ50-M															
TGZ50-H															

*1. All products are stock items.
2. Mass and moment of inertia are based on the bores' maximum diameters.

Coupling type



Combined with TSUBAKI
"Jaw Flex Coupling L Series"



① Coupling hub A ② Coupling hub B ③ Insert ④ Adapter
⑤ Hexagon socket head bolt ⑥ Spring washer ⑦ Hexagon socket head bolt ⑧ Spring washer

Unit : mm

Shock Guard Model No.	Set torque range N·m	Max. rpm r/min	Shock Guard			Coupling			A	B	C	D	ℓ1	ℓ2	E
			Rough bore diamter	Min. bore diameter	Max. bore diameter	Rough bore diamter	Min. bore diameter	Max. bore diameter							
TGZ20-LC	2.4 to 8.3	1800	8	10	20	12.7	16	35	146	83	18.8	27.2	27	73	—
TGZ20-MC	4.1 to 16														
TGZ20-HC	8.2 to 31														
TGZ30-LC	5.9 to 21	1800	12	14	30	18.0	21	47	180	93.5	22.6	32.5	42.9	82	—
TGZ30-MC	20 to 52														
TGZ30-HC	39 to 108														
TGZ40-LC	25 to 93	1800	17	19	40	19.1	22	58	213	111	26.1	32.9	54	100	34.9
TGZ40-MC	44 to 127														
TGZ40-HC	88 to 245														
TGZ50-LC	63 to 157	1800	22	24	50	19.1	22	63	242	127.5	26.1	40.4	63.5	112	34.9
TGZ50-MC	127 to 304														
TGZ50-HC	245 to 451														

Shock Guard Model No.	F	G	H	I No. of pieces-screw size X length	J No. of pieces-screw size X length	* Mass kg	* Moment of inertia ×10⁻²kg·m²	Model No. of coupling used	K	Allowable angular misalignment (deg.)	Allowable parallel misalignment	Allowable shaft direction displacement
TGZ20-LC	96	64.3	—	3-M6×20	4-M5×22	4.34	0.44	L099-H	27	0.5	0.38	±0.5
TGZ20-MC												
TGZ20-HC												
TGZ30-LC	118	84.1	—	6-M6×22	4-M6×22	7.77	1.22	L110-H	40	0.5	0.38	±0.7
TGZ30-MC												
TGZ30-HC												
TGZ40-LC	152	114.3	101.6	6-M6×25	6-M6×25	15.4	4.05	L190-H	54	0.5	0.38	±1.0
TGZ40-MC												
TGZ40-HC												
TGZ50-LC	178	127	107.9	6-M8×25	6-M8×25	23.2	8.63	L225-H	60	0.5	0.38	±1.0
TGZ50-MC												
TGZ50-HC												

*1. All products are stock items.
2. Mass and moment of inertia are based on the bores' maximum diameters.

Handling

1. Bore finishing (Shock Guard)

(1) Before finishing

The Shock Guard TGZ Series is shipped set at the minimum point (minimum torque value). Once received, confirm that the revolution indicator and angle indicator are set at zero.

(2) Disassembly

Loosen the setscrews, remove the adjustment nut and take out the coil springs, ball cage, plate and balls. Next, take out the shaft snap ring, and remove the bearing and driven flange. When disassembling, take care not to lose the ball B at s ball cage. Make sure the Shock Guard parts do not become dusty or dirty.

(3) Chucking

Chuck the hub flange's outside diameter and center the hub portion.

(4) Machining

① Keyway specifications

Table 1 shows the maximum bore diameters for keyway specifications.

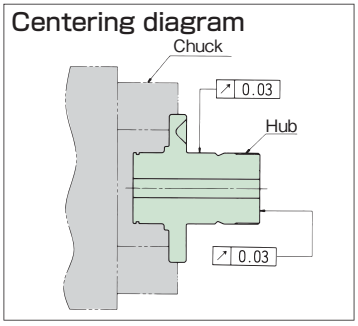
Table 1

Model No.	Max. bore diameter	Applicable standard
TGZ20	ϕ20	parallel key
TGZ30	ϕ30	
TGZ40	ϕ40	New JIS Old JIS
TGZ50	ϕ50	

② Centering

Chuck the hub flange's outer edge and center the hub as shown in the figure on the right.

Centering diagram



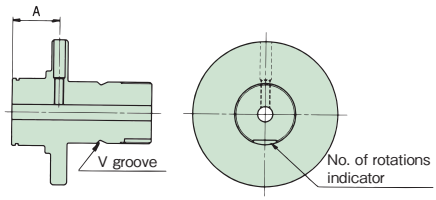
③ Machining

The keyway should be machined directly below the setscrew tap at the hub flange section as shown below.

Table 2

Model No.	A
TGZ20	24.5
TGZ30	27.5
TGZ40	32.5
TGZ50	37.0

Set screw position



(5) Reassembly

After bore finishing is completed and when reassembling the Shock Guard, make sure to coat the drive balls, steel balls, pockets, and the V-groove with grease.

2. Bore finishing (Coupling type)

(1) Machining

① Keyway specifications

Table 3 shows the maximum bore diameters on the coupling side. For the maximum bore diameters of the Shock Guard hub, refer to Table 1.

② Centering

Chuck the coupling hub's outer edge and center the hub as shown in the below diagram. For the recommended positions of the coupling hub setscrew, refer to Table 4 (Length F).

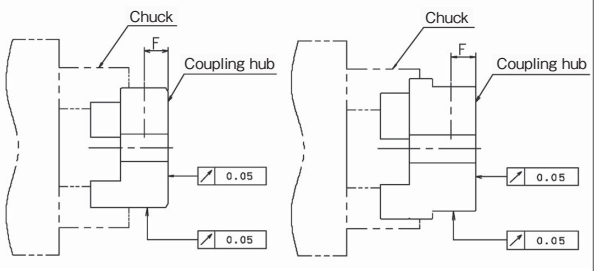
Table 3

Model No.	Max. bore diameter	Applicable standard
TGZ20	ϕ35	Parallel key
TGZ30	ϕ47	
TGZ40	ϕ58	New JIS Old JIS
TGZ50	ϕ63	

Table 4

Model No.	Coupling model No.	Length F
TGZ20-C	L099-H	13.5
TGZ30-C	L110-H	20.5
TGZ40-C	L190-H	25.5
TGZ50-C	L225-H	25.5

Bore finishing diagram



L099,L110
(TGZ20-C,TGZ30-C)

L190,L225
(TGZ40-C,TGZ50-C)

3. Trip Torque setting

(1) Shock Guard TGZs are all shipped with torque set at the minimum point (min. torque value). Confirm that the angle indicator and the No. of rotations indicator are set at zero. The No. of rotations indicator can be read at the end face of the adjustment nut. Refer to page 73 for more information.

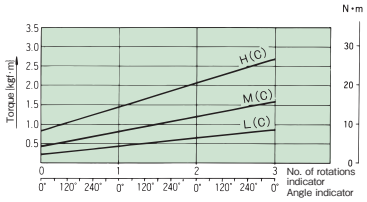
(2) From the "Tightening Amount-Torque Correlation Chart", find the adjustment nut tightening angle equivalent to the predetermined trip torque and tighten them. Set at 60° toward the determined tightening value, then install to the machine and conduct a trip test. Gradually tighten and set at optimum trip torque.

(3) After setting torque, screw the lock screw to the adjustment nut. Refer to page 32 for lock screw tightening torque and precautions.

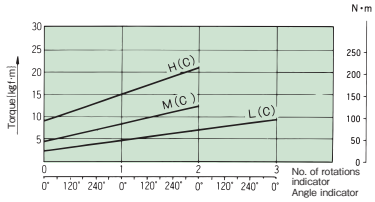
(4) Do not turn the adjustment nut (bolt) more than the torque indicator's maximum value. Doing so will put it in a locked position, and there will be no leeway for the disk spring to bend.

* Each product's trip torque does not always correspond with the value listed in the "Tightening Amount - Torque Correlation Chart", so use these values only as a rough guide.

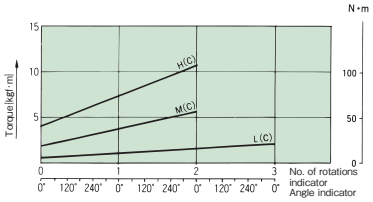
TGZ 20(C)



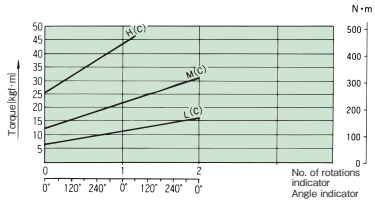
TGZ 40(C)



TGZ 30(C)



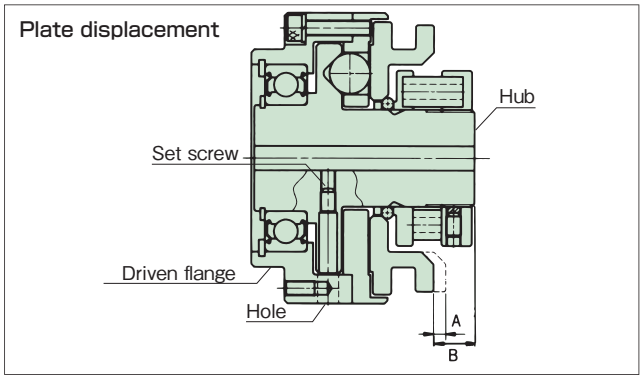
TGZ 50(C)

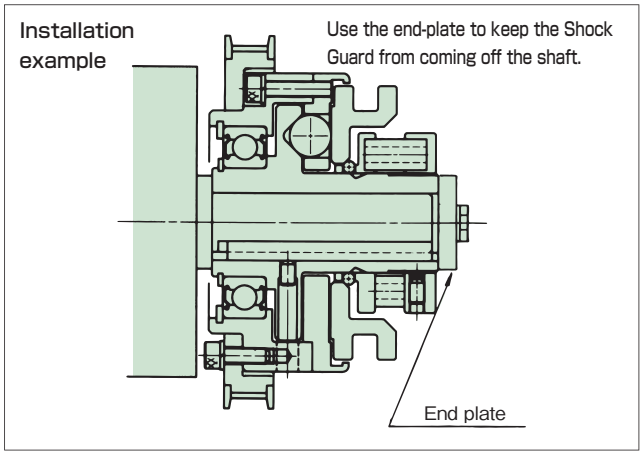


4. Resetting

Match up one hole of the driven flange with the hub side's setscrew position. (This position is the pocket and drive ball's correct phase.)

Next, apply axial load to the plate to reset (refer to the following table). To determine whether the Shock Guard has completely reset, verify it using the measurements of the table below (displacement A).





Model No.	Axial load N {kgf}	Amount of displacement A mm	B mm
TGZ20-L	49 {5}	4.1	13.5
TGZ20-M	88 {9}		
TGZ20-H	176 {18}		
TGZ30-L	98 {10}	4.7	14.5
TGZ30-M	235 {24}		
TGZ30-H	470 {48}		
TGZ40-L	157 {16}	5.9	20.0
TGZ40-M	421 {43}		
TGZ40-H	833 {85}		
	451 {46}	7.0	18.2
TGZ50-M	902 {92}		
TGZ50-H	1382 {141}		

Maintenance

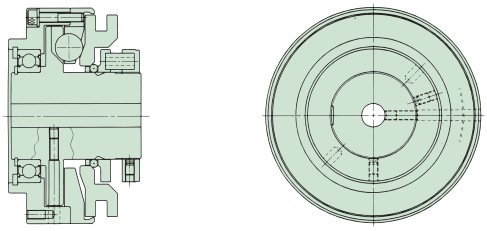
Grease the drive ball and ball cage either once per year or every thousand trips.

Special Specifications

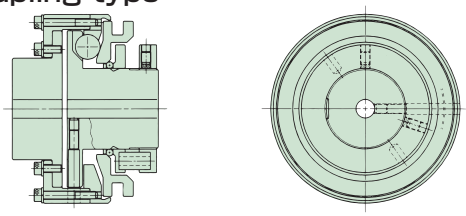
TGXZ Series

Non-backlash and complete release type. With its high-speed specifications (up to 1800r/min), it is ideal for when instant stop is not possible. Please contact TEM for more information.

■ TGXZ Series only



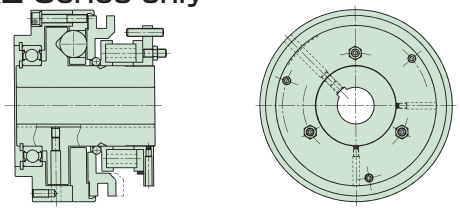
■ Coupling type



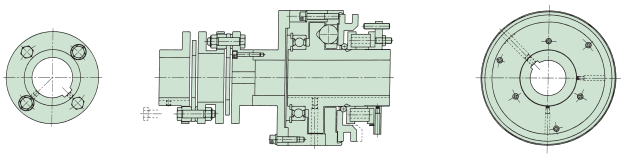
TGZ Large Series

For the application of setting torque 451N・m and above, please contact TEM for more information.

■ TGXZ Series only



■ Coupling type



MEMO

Shock Guard TGK Series (Ex-MYTORQ 630 Series)

Features

A multifunctional product combining a ball type overload protection device and an air clutch function.

Pneumatic torque adjustment mechanism

You can remotely adjust the torque during operation by adjusting the air pressure in the regulator.

One position type

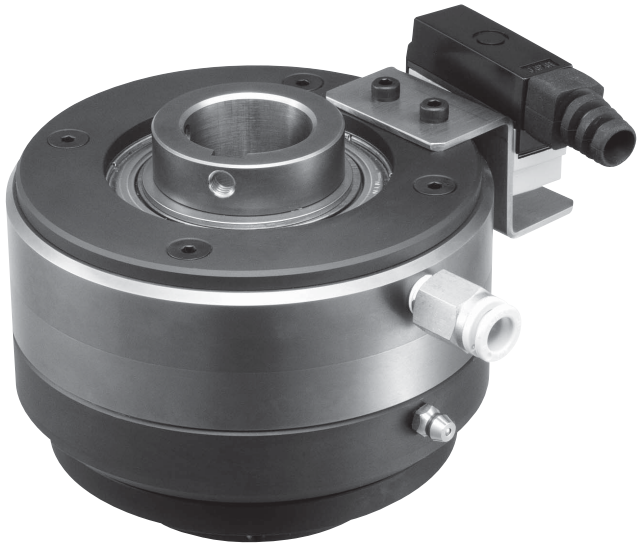
This uniquely assembled torque transmission element ball and pocket configuration only engages in one position.

High accuracy

Achieves minimal backlash.

Air clutch ON-OFF mechanism

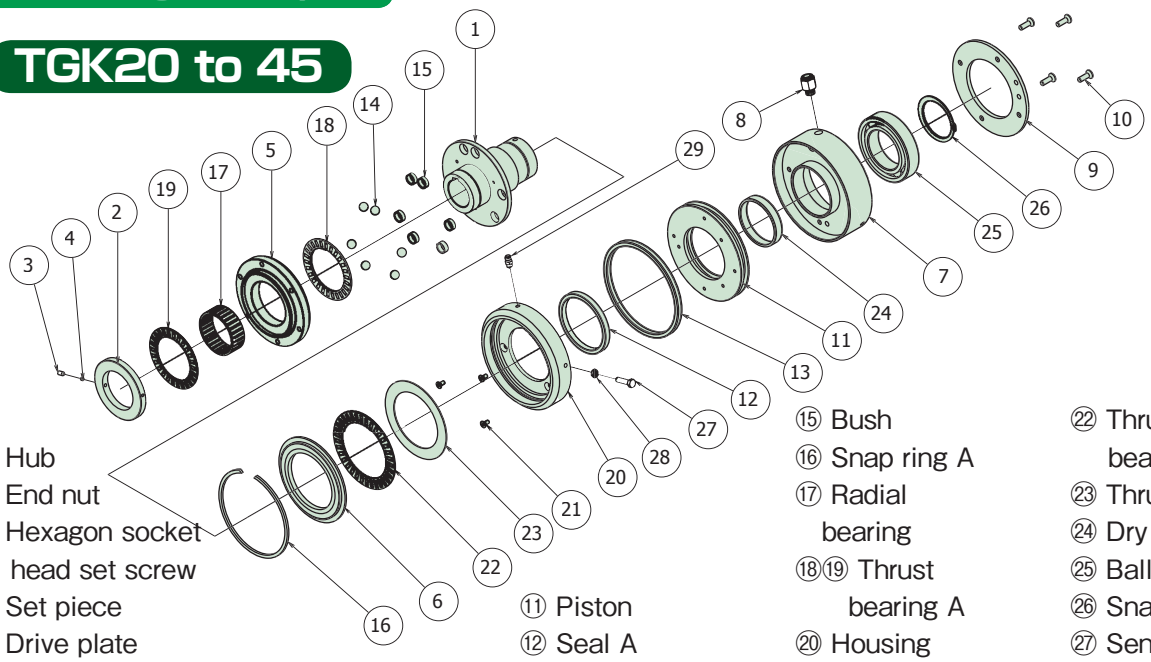
Also usable as an ON-OFF clutch in remote control.



TGK	
Type 2	Enables direct mounting of A type sprockets and pulleys.
Type 5	The Echt-Flex Coupling provides angular tolerance. Parallelism errors are not allowed.
Type 7	The Echt-Flex Coupling provides angular tolerance and parallelism tolerance.

Construction and Operating Principles

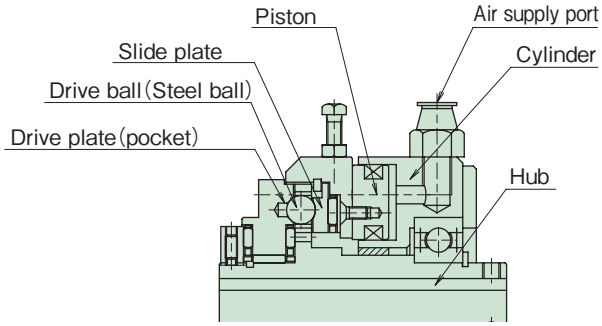
TGK20 to 45



① Hub
② End nut
③ Hexagon socket head set screw
④ Set piece
⑤ Drive plate
⑥ Slide plate
⑦ Cylinder
⑧ Pipe joint
⑨ Cylinder cover
⑩ Hex cap countersunk screw
⑪ Piston
⑫ Seal A
⑬ Seal B
⑭ Drive ball (Steel ball A)
⑮ Bush
⑯ Snap ring A
⑰ Radial bearing
⑱⑲ Thrust bearing A
⑳ Housing
㉑ Hex cap countersunk screw
㉒ Thrust bearing B
㉓ Thrust race
㉔ Dry bearing
㉕ Ball bearing
㉖ Snap ring B
㉗ Sensor target
㉘ Hex nut
㉙ Grease nipple

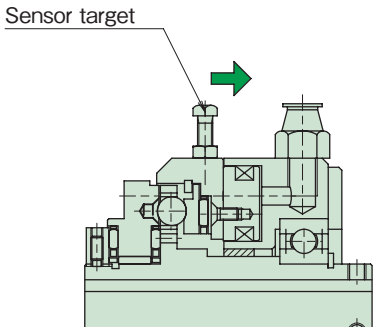
TGK20 to 45

During normal operation (engagement)



The TGK series transfers driving force from the hub to the drive plate on the output side via drive balls (and vice versa).
Bolt a sprocket or timing pulley directly to the drive plate.
The hub flange has several holes to hold the drive balls.
There are pockets on the drive plate on the output side, and the drive balls are fitted into
the pockets.
If you feed air into the cylinder through the air supply port, the piston moves toward the drive plate.
Then, the drive balls are pushed via the slide plate and transfer the driving force.
You can change the torque according to the load during operation. You can also change the torque automatically by making a system to change the pressure using a timer or controller.
For instance, by using such a system to switch between a high torque corresponding to the starting torque and a low operating torque, you can set the torque to the optimal value for the machine.
When an overload occurs, the drive balls push back the slide plate toward the cylinder against the air pressure.The drive balls then come out of the pockets and start to idle.

During overload (trip)



By detecting the amount of movement of the sensor target toward the cylinder by a limit switch and removing the force applied to the drive balls by removing the air from the cylinder, you can completely release the driving force and protect the machine.

Clutch mechanism

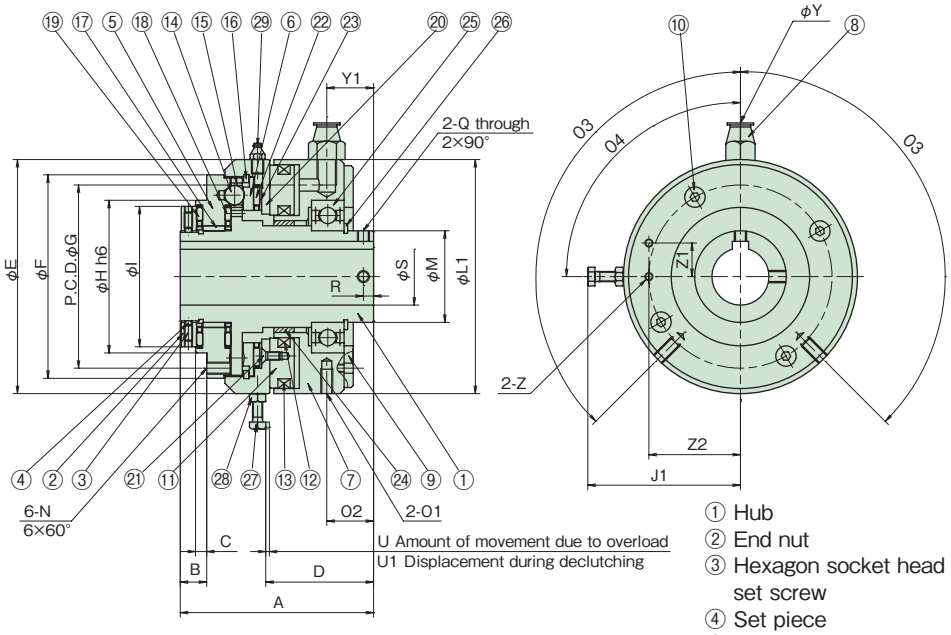
To disconnect the drive source for adjustment or maintenance of the machine, stop feeding air and remove the air from the cylinder. The housing and slide plate are then pushed back toward the cylinder by the built-in spring.
Consequently, the drive balls come out of the pockets on the drive plate for declutching.
The drive plate has a bearing inside, and therefore there are no problems even if the drive plate is left to idle for a long period of time.

Resetting (clutching) procedure

If you supply air from the air supply port and restart the operation, the drive balls automatically return to their positions within one revolution.
If you continue to rotate the TGK series while feeding air after the occurrence of an overload, the TGK series repeatedly reset. Therefore, detect overloads using a limit switch or a similar device and stop feeding air.

Transmissible Capacity/Dimensions

■ TGK20-A2 • TGK30-A2 • TGK45-A2 Type 2



① Hub
② End nut
③ Hexagon socket head set screw
④ Set piece
⑤ Drive plate
⑥ Slide plate
⑦ Cylinder
⑧ Pipe joint
⑨ Cylinder cover
⑩ Hex cap countersunk screw
⑪ Piston
⑫ Seal A
⑬ Seal B
⑭ Drive ball (Steel ball A)
⑮ Bush
⑯ Snap ring A
⑰ Radial bearing
⑱⑲ Thrust bearing A
⑳ Housing
㉑ Hex cap countersunk screw
㉒ Thrust bearing B
㉓ Thrust race
㉔ Dry bearing
㉕ Ball bearing
㉖ Snap ring B
㉗ Sensor target
㉘ Hex nut
㉙ Grease nipple

Unit : mm

Model No.	Set torque range N・m	Max. rpm r/min*1	Air pressure MPa	Shock Guard S			A	B	C	D	E	F	G P.C.D.	H h6	I
				Rough bore diamter	Min. bore diameter	JIS keyway for max. bore dia.									
TGK20-A2	15 to 65	340	0.14 to 0.55	8	10	20	79	11	3.5	45.5	88	80	70	57	51
TGK30-A2	30 to 147	230	0.14 to 0.55	10	12	30	95	13	5.5	53	115	100	90	75	69
TGK45-A2	90 to 392	430	0.14 to 0.55	20	22	45	124	15.5	7	74.4	159	140	125	100	94

Model No.	J1	L1	M	N screw diameter × length	O1 screw diameter × length	O2	O3	O4	Q screw diameter*2	R*2	U	U1	Air supply port Y*3	Y1
TGK20-A2	61	88	30	M5×9	M5×10	21	135°	90°	M5	5	1.2	1.8	4	21
TGK30-A2	75	115	45	M6×11	M6×12	23	135°	90°	M6	5	1.8	2.0	8	23
TGK45-A2	98	159	60	M8×13	M8×15	34	120°	90°	M8	8	2.2	2.9	8	34

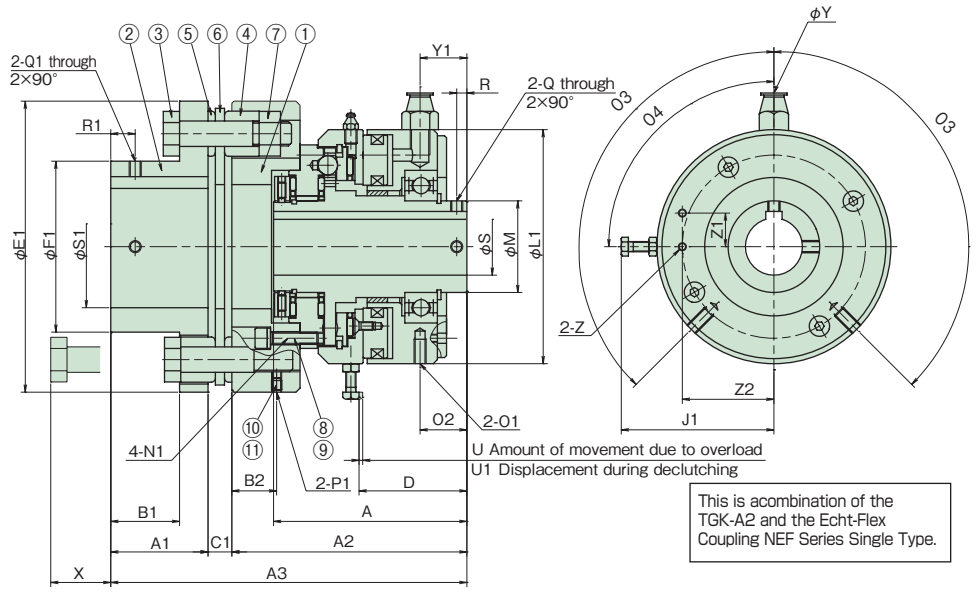
Model No.	Z		Z1	Z2	Mass*4 kg	Moment of inertia*4 kg・m²	Allowable radial load N
	Screw diamter × length	Facing diameter × Depth					
TGK20-A2	M4×10	φ5×3.5	15	35	2.3	0.00061	6200
TGK30-A2	M4×10	φ5×4.5	16.5	45	4.6	0.00201	9500
TGK45-A2	M5×10	φ6×5	20	65	11.2	0.00854	12700

*1. Contact us for details on use at speeds higher than the maximum speed.
2. Setscrew taps are not processed. Dimensions are for reference only.
3. Y represents the outer diameter of the applicable tube.
4. Mass and moment of inertia are based on the bores' maximum diameters.

Note) When installing a pulley or sprocket, use high-tensile bolts (G10.9 or higher) and determine the length carefully so that the bolts are not buried deeper than the mounting tap depth N.
The air supply port is a pipe joint applicable to both nylon and urethane tubes.
An example of the installation of a limit switch is shown on page 84.

Transmissible Capacity/Dimensions

■ TGK20-A5 • TGK30-A5 • TGK45-A5 Type 5



① Mounting adapter
② Coupling hub
③ Reamer bolt
④ Washer A
⑤ Washer B
⑥ Disk
⑦ U nut
⑧ Hex cap bolt
⑨ Spring washer
⑩ Hexagon socket head set screw
⑪ Set piece

Unit : mm

Model No.	Set torque range N · m	Max. rpm r/min*1	Air pressure MPa	Shock Guard S			Coupling S1			A	A1	A2	A3	B1	B2	C1	D
				Rough bore diamter	Min. bore diameter	JIS keyway for max. bore dia.	Rough bore diamter	Min. bore diameter	JIS keyway for max. bore dia.								
TGK20-A5	15 to 65	340	0.14 to 0.55	8	10	20	15	17	42	79	33.5	88.3	133	24.5	14	11.2	45.5
TGK30-A5	30 to 147	230	0.14 to 0.55	10	12	30	15	17	60	95	47.8	115.5	175	33.8	22	11.7	53
TGK45-A5	90 to 392	430	0.14 to 0.55	20	22	45	25	27	74	124	57.2	137.5	211.5	43.2	17	16.8	74.4

Model No.	E1	F1	J1	L1	M	N1 screw diamter × length	O1 screw diameter × length	O2	O3	O4	P1 screw diameter × length	Q screw diameter *2	Q1 screw diameter *2	R*2	R1*2	U	U1	Air supply port Y*3	Y1
TGK20-A5	104	61	61	88	30	M5×20	M5×10	21	135°	90°	M4×6	M5	M5	5	8	1.2	1.8	4	21
TGK30-A5	143	84	75	115	45	M6×25	M6×12	23	135°	90°	M5×6	M6	M6	5	12	1.8	2.0	8	23
TGK45-A5	168	106	98	159	60	M8×25	M8×15	34	120°	90°	M5×6	M8	M8	8	15	2.2	2.9	8	34

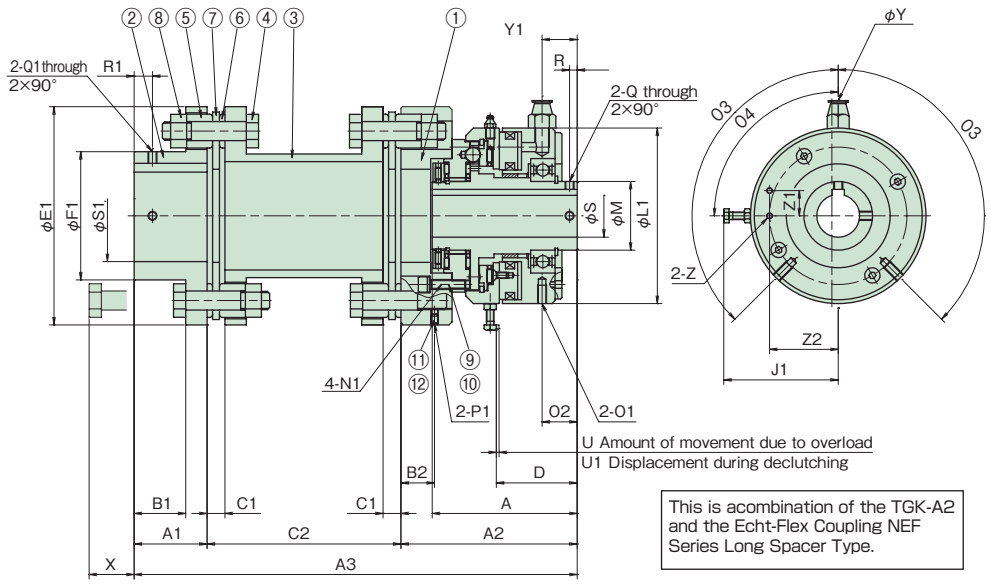
Model No.	Z		Z1	Z2	Mass*4 kg	Moment of inertia*4 kg · m²	Coupling model No.	X*5	Allowable Misalignment	
	Screw diamter × length	Facing diameter × Depth							Angular misalignment deg	Shaft direction displacement*6
TGK20-A5	M4×10	φ5×3.5	15	35	4.2	0.00319	NEF25S	21	1	±1.4
TGK30-A5	M4×10	φ5×4.5	16.5	45	9.9	0.0164	NEF80S	29.5	1	±1.8
TGK45-A5	M5×10	φ6×5	20	65	18.4	0.0359	NEF130S	20	1	±2.5

*1. Contact us for details on use at speeds higher than the maximum speed.
2. Setscrew taps are not processed. Dimensions are for reference only.
3. Y represents the outer diameter of the applicable tube.
4. Mass and moment of inertia are based on the bores' maximum diameters.
5. This is the space required for the insertion of a reamer bolt.
6. The allowable displacement in the shaft direction is the value when the angular error is zero.

Note) The air supply port is a pipe joint applicable to both nylon and urethane tubes.
An example of the installation of a limit switch is shown on page 84.
Parallelism errors are not allowed.

Transmissible Capacity/Dimensions

■ TGK20-A7 • TGK30-A7 • TGK45-A7 Type 7



① Mounting adapter
② Coupling hub
③ Long spacer
④ Reamer bolt
⑤ Washer A
⑥ Washer B
⑦ Disk
⑧ U nut
⑨ Hex cap bolt
⑩ Spring washer
⑪ Hexagon socket head set screw
⑫ Set piece

Unit : mm

Model No.	Set torque range N · m	Max. rpm r/min*1	Air pressure MPa	Shock Guard S			Coupling S1			A	A1	A2	A3	B1	B2	C1	C2	D
				Rough bore diamter	Min. bore diameter	JIS keyway for max. bore dia.	Rough bore diamter	Min. bore diameter	JIS keyway for max. bore dia.									
TGK20-A7	15 to 65	340	0.14 to 0.55	8	10	20	15	17	42	79	33.5	88.3	221.8	24.5	14	11.2	100	45.5
TGK30-A7	30 to 147	230	0.14 to 0.55	10	12	30	15	17	60	95	47.8	115.5	290.3	33.8	22	11.7	127	53
TGK45-A7	90 to 392	430	0.14 to 0.55	20	22	45	25	27	74	124	57.2	137.5	334.7	43.2	17	16.8	140	74.4

Model No.	E1	F1	J1	L1	M	N1 screw diamter × length	O1 screw diameter ×length	O2	O3	O4	P1 screw diameter ×length	Q screw diameter *2	Q1 screw diameter *2	R*2	R1*2	U	U1	Air supply port Y*3	Y1
TGK20-A7	104	61	61	88	30	M5×20	M5×10	21	135°	90°	M4×6	M5	M5	5	8	1.2	1.8	4	21
TGK30-A7	143	84	75	115	45	M6×25	M6×12	23	135°	90°	M5×6	M6	M6	5	12	1.8	2.0	8	23
TGK45-A7	168	106	98	159	60	M8×25	M8×15	34	120°	90°	M5×6	M8	M8	8	15	2.2	2.9	8	34

Model No.	Z		Z1	Z2	Mass*4 kg	Moment of inertia*4 kg · m²	Coupling model No.	X*5	Allowable Misalignment		
	Srew diamter × length	Facing diameter × Depth							Angular misalignment deg	Shaft direction displacement*6	Parallel misalignment
TGK20-A7	M4×10	φ5×3.5	15	35	5.7	0.00540	NEF25W	21	2	±2.8	1.5
TGK30-A7	M4×10	φ5×4.5	16.5	45	13.8	0.0276	NEF80W	29.5	2	±3.6	2.0
TGK45-A7	M5×10	φ6×5	20	65	23.5	0.0573	NEF130W	20	2	±5.0	2.1

*1. Contact us for details on use at speeds higher than the maximum speed.
2. Setscrew taps are not processed. Dimensions are for reference only.
3. Y represents the outer diameter of the applicable tube.
4. Mass and moment of inertia are based on the bores' maximum diameters.
5. This is the space required for the insertion of a reamer bolt.
6. The allowable displacement in the shaft direction is the value when the angular error is zero.

Note)The air supply port is a pipe joint applicable to both nylon and urethane tubes.
An example of the installation of a limit switch is shown on page 84.

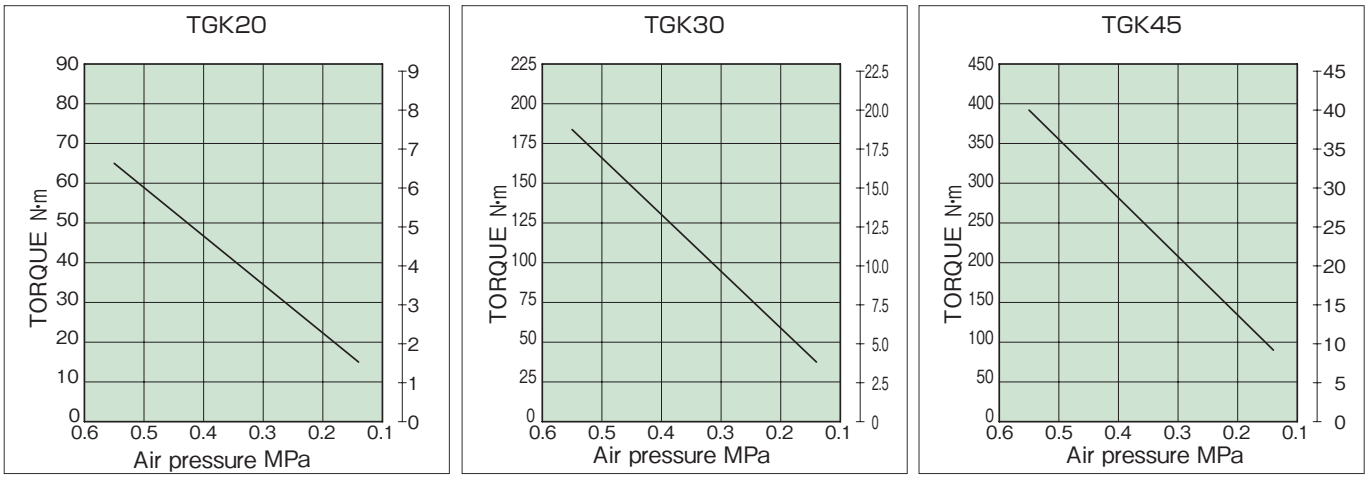
Torque adjustment

You can adjust the torque precisely by adjusting the air pressure corresponding to the required torque. To adjust the air pressure, use a regulator (pressure controller), refer to the torque correlation charts, and feed air into the cylinder of the TGK series. You can even change the operating torque during operation by changing the air pressure. Operating air pressure: 0.14 to 0.55 MPa

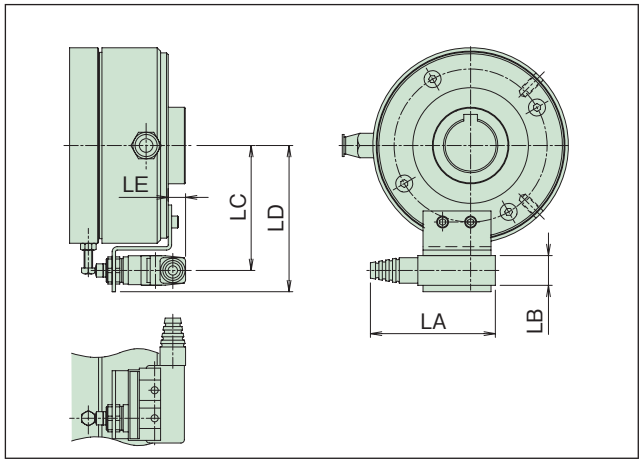
(Note) Be careful to keep the air supply source pressure higher than the preset pressure.

Size	Minimum torque N · m	Maximum torque N · m
TGK20	15.0	65.0
TGK30	30.0	147
TGK45	90.0	392

Torque Correlation Chart



Limit Switch Installation Example (Standard option)



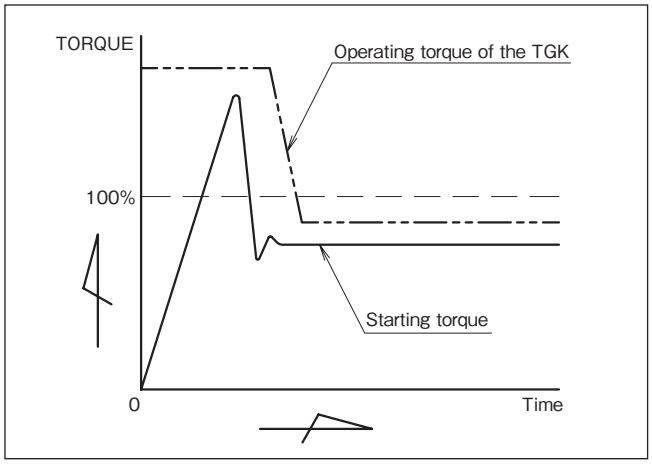
Upon request, the product is delivered with a limit switch installed.

Size	LA	LB	LC	LD	LE	Model of limit switch (Omron)
TGK20	73.5	17.5	59	71.5	16.2	SHL-Q55
TGK30	73.5	17.5	73.5	86	10.2	
TGK45	73.5	17.5	95.5	108.5	–	

Air control system

The operating torque of existing protection devices cannot be changed during operation.

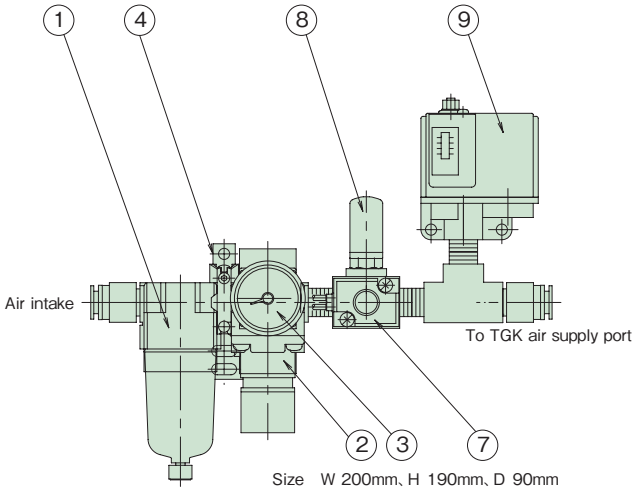
However, it is possible to change the operating torque of the TGK series during operation by changing the air pressure. Therefore, you can protect the machine by setting the torque higher than the starting torque only at startup, and then change the torque to the optimal value at a later time (refer to the figure on the right).



Single air control system

This system is for simple torque adjustment.
You can adjust the torque within an air pressure range of 0.14 to 0.55 MPa.

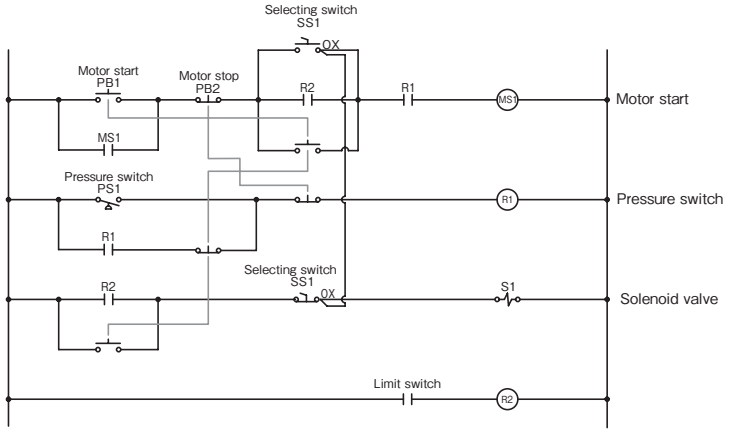
Air device configuration



Part number	Device name	Referential model number (SMC)
1	Air filter	AF20-02
2	Regulator	AR20-02
3	Pressure gauge	G36-02
4	Spacer with bracket	Y200T
5	—	—
6	—	—
7	3-port solenoid valve	VT307-1G-02
8	Silencer	AN20-02
9	Pressure switch	IS3000-02

Electrical diagram

PB 1	Motor start button
PB 2	Motor stop button
SS 1	Selecting switch
SS 2	Pressure switch
S 1	Solenoid valve

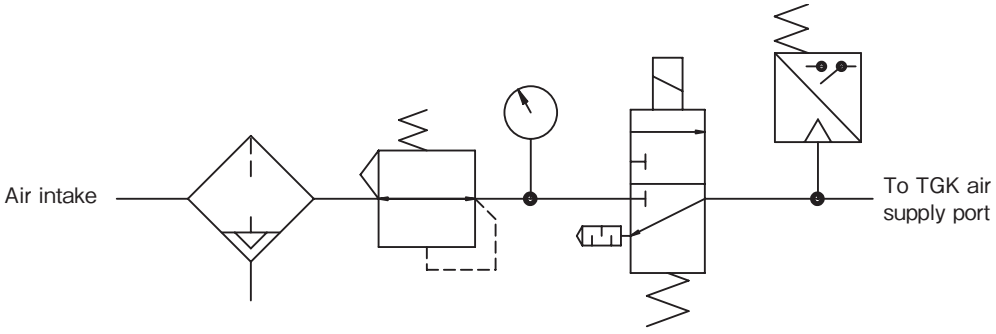


Basic operation

Selecting switch (SS1) is set to "AIR ON."
Press the motor start button (PB1). The motor starts and the TGK series returns to the "CLUTCH ON" state. The limit switch is turned on, the self-holding of the motor is completed, and the motor continues to rotate even if you release the motor start button (PB1)
Note) If the pressure switch is off, the motor does not rotate even if you press the motor start button (PB1).

The sensor target of the TGK series moves simultaneously when an overload occurs, and the amount of movement is detected by a limit switch or a similar device.
If the limit switch is turned off, the solenoid valve (S1) switches to turn off the self-holding of the motor, and then the motor stops.
In the "CLUTCH OFF" state, you can do this by turning the selecting switch (SS1) to "AIR OFF." When turned to "AIR OFF," the solenoid valve switches, the air supply to the TGK series stops, the TGK series turns to "CLUTCH OFF," and the motor continues to rotate, but the driving force is not transferred to the driven side.

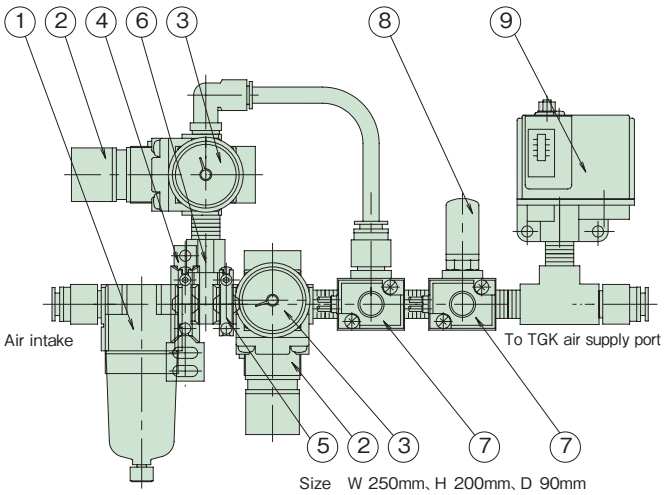
Electrical diagram



Dual air control system

This system uses two regulators. At the time of startup, the regulator set to the higher pressure feeds air to the TGK series. A timer is used to count several seconds (1 to 10 seconds), and then the regulator set to the lower pressure is switched in order to reset the torque to the optimal value. Such a system enables various types of automatic torque adjustments during operation.

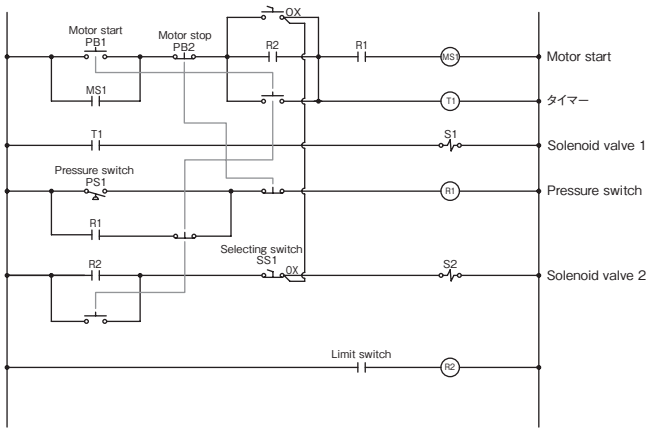
Air device configuration



Part number	Device name	Referential model number (SMC)
1	Air filter	AF20-02
2	Regulator	AR20-02
3	Pressure gauge	G36-02
4	Spacer with bracket	Y200T
5	Spacer	Y200
6	T type spacer	Y210-02
7	3-port solenoid valve	VT307-1G-02
8	Silencer	AN20-02
9	Pressure switch	IS3000-02

Electrical diagram

PB 1	Motor start button
PB 2	Motor stop button
SS 1	Selecting switch
SS 2	Pressure switch
S 1	Solenoid valve 1
S 2	Solenoid valve 2

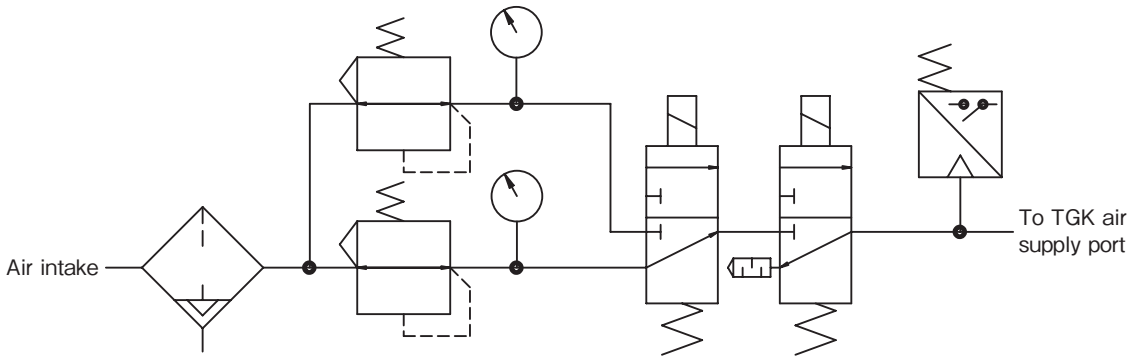


Basic operation

Selecting switch (SS1) is set to "AIR ON."
Press the motor start button (PB1). The motor starts and the TGK series returns to the "CLUTCH ON" state. The limit switch is turned on, the self-holding of the motor is completed, and the motor continues to rotate even if you release the motor start button (PB1)
Note) If the pressure switch is off, the motor does not rotate even if you press the motor start button (PB1).

The sensor target of the TGK series moves simultaneously when an overload occurs, and the amount of movement is detected by a limit switch or a similar device.
If the limit switch is turned off, the solenoid valve (S1) switches to turn off the self-holding of the motor, and then the motor stops.
In the "CLUTCH OFF" state, you can do this by turning the selecting switch (SS1) to "AIR OFF." When turned to "AIR OFF," the solenoid valve switches, the air supply to the TGK series stops, the TGK series turns to "CLUTCH OFF," and the motor continues to rotate, but the driving force is not transferred to the driven side.

Electrical diagram



Torque Limiter

Features

Traditional friction type
Economically priced and easy to use

Easy torque adjustment

Slip torque setting and adjusting can be done by simply tightening the adjusting nut or bolts. The friction of the friction facings and the center member transmits torque, so overload is guaranteed to cause the Torque Limiter to slip, thus protecting the machine.

Automatic reset

If overload occurs the Torque Limiter will slip. If overload is removed it will automatically reset and begin to rotate. Because there are no parts to replace like a shear pin, the Torque Limiter requires little labor to keep it operating.

Can be fixed to each type of drive

Sprockets and gears can be fixed to the center member.

A wide variety of Torque Limiters are available

From small capacity to large, all standard models can be used in all transmission conditions.

Finished bores for quick delivery

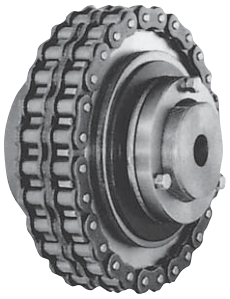
Finished bore products can be made for quick delivery. (Refer to pages 91, 93)

Series

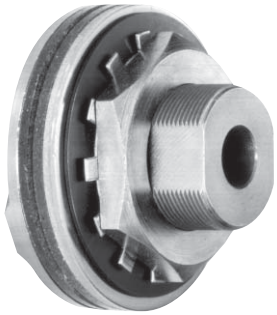
Torque Limiter
Once attached to the shaft, torque transmission is conveyed through roller chains, belts and gears.
Torque Limiter with sprocket
The torque of finished bore Torque Limiters with machined sprockets is factory pre-set.
Torque Limiter coupling
A combined Torque Limiter and roller chain coupling.

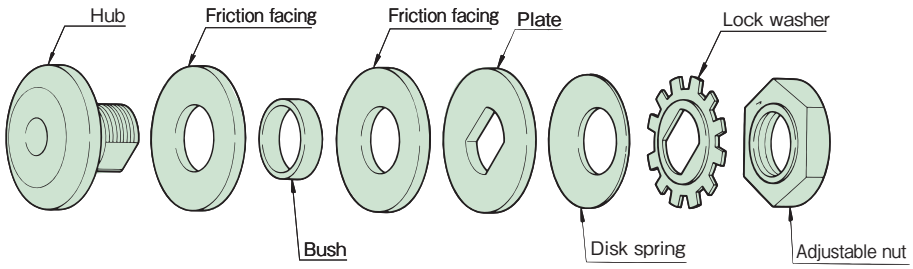
Torque Limiter with sprocket

TL500
TL200 to TL700
Torque Limiter (rough bore)

TL10
TL200 to TL20
Torque Limiter coupling (rough bore)

TL500-C
TL200-C to TL20-C

Construction and operating principles





- During normal operation, the disk spring inserted between the center member (sprockets and gear) and friction facings applies pressure to the center member. Below the set torque, the frictional force transmits rotation.
- If the operational torque exceeds the set torque due to overload, the center member will slip between the friction facings. When overload is stopped, it automatically resets.

Model No.

1.Torque Limiter

TL350－1－B6.5－20J

- Size: TL350
- No. of disk springs: 1: 1pc, 2: 2pcs, 1L: weak spring
- Bush length (No symbol if there is no bush): B6.5
- Shaft diameter (No symbol for rough bore products): 20
- Keyway type (J: New JIS normal type, E: Old JIS 2nd grade,No symbol: special keyway): J

2.Torque Limiter coupling

TL350－2C－T20J×C40J－9.0

- Size: TL350
- No. of disk springs: 1: 1pc, 2: 2pcs, 1L: weak spring
- Torque Limiter side bore diameter (TRB for rough bore products): T20J
- Keyway type (J: New JIS normal type, E: Old JIS 2nd grade , No symbol: special keyway): J
- Coupling side bore diameter (CRB for rough bore products): C40J
- Keyway type (J: New JIS normal type, E: Old JIS 2nd grade, No symbol: special keyway): J
- Set torque (Unit: kgf.m, No symbol if there is no torque setting): 9.0

Rough Bore Product (Rough Bores on Both Sides) Model No.

TL350－2C

- Size: TL350
- No. of disk springs: 2C

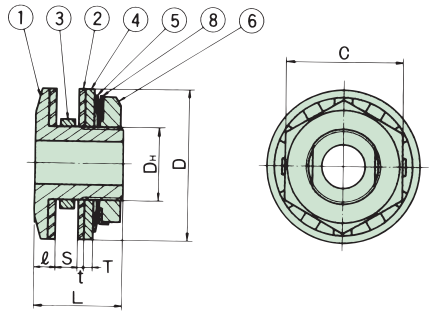
When using the Torque Limiter

Before installing a Torque Limiter rough bore product to the shaft, it is necessary to finish the bore, keyway and center member as well as torque setting.

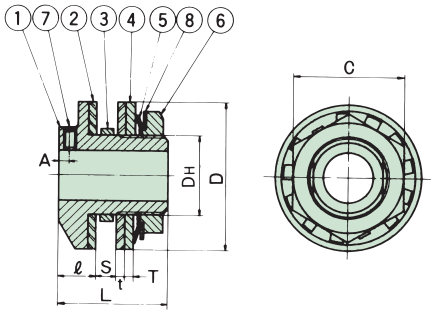
- Refer to page 96 for more information on Torque Limiter selection and center member selection/machining.
- Before assembling the Torque Limiter, remove any oil, rust or dust from the hub, friction facings, plate or center member (sprockets and gear).
- Refer to page 94 for more information on setting torque.
- When the direction of rotation is reversed, it will cause backlash. Use the Shock Guard TGX series for machines for which backlash is not allowed.
- If the friction coefficient decreases, the slip torque also decreases. Therefore, be careful to keep the friction facings free of water and oil. However, tightening the adjustable nut too firmly may apply excessive load to the friction facings via the disk spring and break the facings.
- Slipping at a high speed may cause the friction facings to become extremely hot, which will lead to surface carbonization and deterioration of strength. Therefore, do not use the product at speeds higher than the maximum rotation speed.

Transmissible capacity/dimensions

TL200



TL250 · TL350



① Hub
② Friction facing
③ Bush
④ Plate
⑤ Disk spring
⑥ Adjustable nut
⑦ Hexagon socket head set screw
⑧ Lock washer

· TL200 does not have a tap for the setscrew.

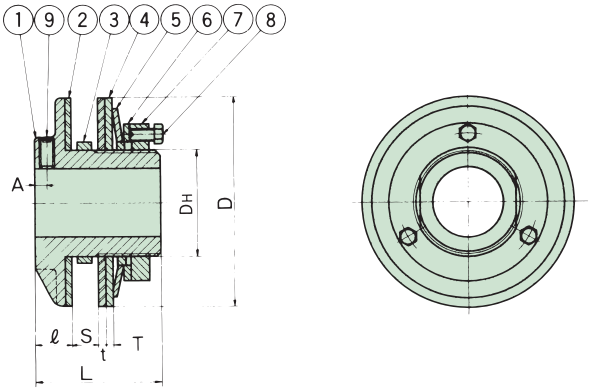
· TL200-1L, TL250-1L and TL350-1L have a spacer between the disk spring and lock washer.

Unit : mm

Model No.	Set torque range N·m	Max.rpm (r/min)	Rough bore diameter	Min. bore diameter	Max. bore diameter	Bush length	Bush outer diameter	Center member bore diameter	Dimensions D	D_H	L	ℓ	T	t	S max.	A	C	Adjustable nut diameter X pitch	Set screw diameter	Mass kg
TL200-IL	1.0 to 2.0	1,800	7	10	14	3.8 6.0	30	$30^{+0.03}_{0}$	50	24	29	6.5	2.6	2.5	7	—	38	M24×1.0	—	0.2
TL200-1	2.9 to 9.8																			
TL200-2	6.9 to 20																			
TL250-IL	2.9 to 6.9		10	12	22	4.5 6.5	41	$41^{+0.05}_{0}$	65	35	48	16	4.5	3.2	9	4	50	M35×1.5	M5	0.6
TL250-1	6.9 to 27																			
TL250-2	14 to 54																			
TL350-IL	9.8 to 20		17	18	25	4.5 6.5 9.5	49	$49^{+0.05}_{0}$	89	42	62	19	4.5	3.2	16	6	63	M42×1.5	M6	1.2
TL350-1	20 to 74																			
TL350-2	34 to 149																			

Note: 1. The products in bold are stock items. The rest are MTO.
2. The hexagon socket head set screw is included.
3. On TL200, setting to the shaft by hexagon socket head set screw is not possible. Use a snap ring for the shaft or end plate.
4. The torque values above are values for continuous slip torque, intended for protecting the equipment from overload.
5. For the selection of bush length, refer to the Selection page.
6. The mass is that of one with the maximum bore diameter.

TL500, TL700



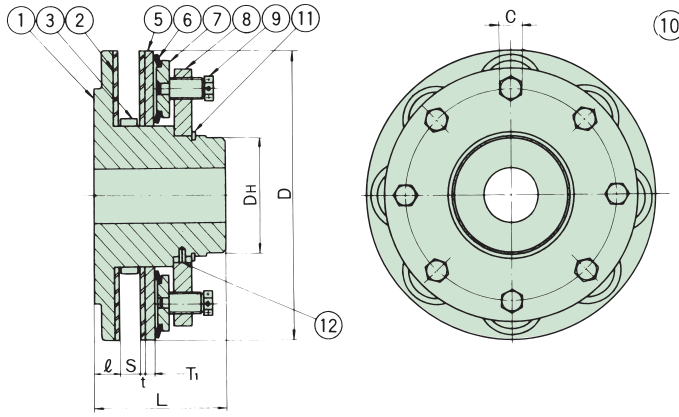
① Hub ② Friction facing ③ Bush ④ Plate ⑤ Disk spring ⑥ Pilot plate ⑦ Adjustable nut ⑧ Adjustable bolt ⑨ Hexagon socket headcap set screw

Unit : mm

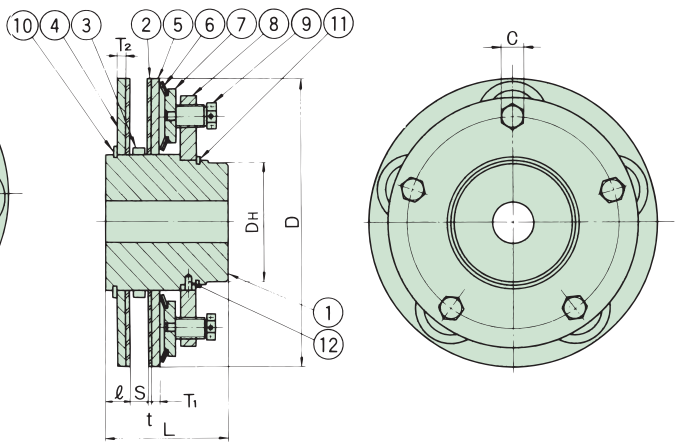
Model No.	Set torque range N·m	Max.rpm (r/min)	Rough bore diameter	Min. bore diameter	Max. bore diameter	Bush length	Bush outer diameter	Center member bore diameter	Dimensions D	D_H	L	ℓ	T	t	S Max	A	Adjustable nut diameter X pitch	Adjustable bolt diameter X pitch	Set screw diameter	Mass kg
TL500-1L	20 to 49	1,800	20	22	42	6.5 9.5	74	$74^{+0.05}_{0}$	127	65	76	22	6	3.2	16	7	M65×1.5	M8×1	M 8	3.5
TL500-1	47 to 210																			
TL500-2	88 to 420																			
TL700-1L	49 to 118		30	32	64	9.5 12.5	105	$105^{+0.05}_{0}$	178	95	98	24	8	3.2	29	8	M95×1.5	M10×1.25	M10	8.4
TL700-1	116 to 569																			
TL700-2	223 to 1080																			

Note: 1. The products in bold are stock items. The rest are MTO.
2. The hexagon socket head set screw is included.
3. The torque values above are values for continuous slip torque, intended for protecting the equipment from overload.
4. For the selection of bush length, refer to the Selection page.
5. The mass is that of one with the maximum bore diameter.

TL10



TL14, TL20



① Hub ② Friction facing ③ Bush ④ Plate (A) ⑤ Plate (B) ⑥ Disk spring ⑦ Spring retainer
⑧ Pilot plate ⑨ Adjustable bolt ⑩⑪ Snap ring ⑫ Spring pin

Unit : mm

Model No.	Set torque range N·m	Max.rpm (r/min)	Rough bore diameter	Min. bore diameter	Max. bore diameter	Bush length	Bush outer diameter	Center member bore diameter	Dimensions D	D_H	L	ℓ	T_1	T_2	t	S max.	C	Adjustable bolt diameter X pitch	Mass kg
TL10 – 16	392 to 1274	1,000	30	32	72	12.5 15.5 19.5	135	$135^{+0.07}_{0}$	254	100	115	23	8.5	–	4.0	24	19	M18×1.5	21
TL10 – 24	588 to 1862																		
TL14 – 10	882 to 2666	500	40	42	100	15.5 19.5 23.5	183	$183^{+0.07}_{0}$	356	145	150	31	13	13	4.0	29	27	M26×1.5	52
TL14 – 15	1960 to 3920																		
TL20 – 6	2450 to 4900		50	52	130	15.5 19.5 23.5	226	$226^{+0.07}_{0}$	508	185	175	36	15	18	4.0	31	36	M32×1.5	117
TL20 – 12	4606 to 9310																		

Note : 1. All products are MTO.
2. If the model larger than TL20-12 is required, contact TEM.
3. The torque values above are values for continuous slip torque, intended for protecting the equipment from overload.
4. For the selection of bush length, refer to the Selection page.
5. The mass is that of one with the maximum bore diameter.

TL200-350

Without bush

Product code	Model No.
S110701	TL200-1L
S110001	TL200-1
S110011	TL200-2
S110702	TL250-1L
S110002	TL250-1
S110012	TL250-2
S110703	TL350-1L
S110003	TL350-1
S110013	TL350-2

With bush

Product code	Model No.
S110711	TL200-1L-B3.8
S110721	TL200-1L-B6.0
S110101	TL200-1-B3.8
S110102	TL200-1-B6.0
S110103	TL200-2-B3.8
S110104	TL200-2-B6.0
S110712	TL250-1L-B4.5
S110722	TL250-1L-B6.5
S110105	TL250-1-B4.5
S110106	TL250-1-B6.5
S110107	TL250-2-B4.5
S110108	TL250-2-B6.5
S110713	TL350-1L-B4.5
S110723	TL350-1L-B6.5
S110724	TL350-1L-B9.5
S110109	TL350-1-B4.5
S110110	TL350-1-B6.5
S110111	TL350-1-B9.5
S110112	TL350-2-B4.5
S110113	TL350-2-B6.5
S110114	TL350-2-B9.5

TL500-700

Without bush

Product code	Model No.
S110704	TL500-1L
S110004	TL500-1
S110014	TL500-2
S110705	TL700-1L
S110005	TL700-1
S110015	TL700-2

With bush

Product code	Model No.
S110714	TL500-1L-B6.5
S110725	TL500-1L-B9.5
S110115	TL500-1-B6.5
S110116	TL500-1-B9.5
S110117	TL500-2-B6.5
S110118	TL500-2-B9.5
S110715	TL700-1L-B9.5
S110726	TL700-1L-B12.5
S110119	TL700-1-B9.5
S110120	TL700-1-B12.5
S110121	TL700-2-B9.5
S110122	TL700-2-B12.5

TL10-20

Without bush

Product code	Model No.
S110006	TL10-16
S110016	TL10-24
S110017	TL14-10
S110018	TL14-15
S110019	TL20-6
S110020	TL20-12

With bush

Product code	Model No.
S110123	TL10-16-B12.5
S110124	TL10-16-B15.5
S110125	TL10-16-B19.5
S110126	TL10-24-B12.5
S110127	TL10-24-B15.5
S110128	TL10-24-B19.5
S110129	TL14-10-B15.5
S110130	TL14-10-B19.5
S110131	TL14-10-B23.5
S110132	TL14-15-B15.5
S110133	TL14-15-B19.5
S110134	TL14-15-B23.5
S110135	TL20-6-B15.5
S110136	TL20-6-B19.5
S110137	TL20-6-B23.5
S110138	TL20-12-B15.5
S110139	TL20-12-B19.5
S110140	TL20-12-B23.5

Finished bore Torque Limiter with sprockets

■ Finished bore Torque Limiter and finished sprockets are available for quick delivery. If sold as a combination, torque is pre-set before shipment.

■ With sprocket

Sprocket comes standard with TL200 to TL700.

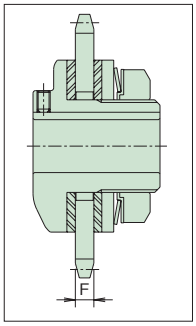
■ Bores and keyways are already finished

Bore finishing is standard for Torque Limiter TL200 to 700.

■ Easy torque setting

Because the adjustable nut or adjustable bolt is set at the predetermined 120°, it is easy for the customer to set torque.

* The torque setting is determined using a static torque tester.



Sprocket and bore finishing dimension table

Torque Limiter Model No.	Finished bore diameter(mm)		Sprockets					Mass (kg)
			Type	F(mm)	Bush length (mm)	No. of teeth	No. of teeth	
TL200	11,12,14,	10	RS35	4.3 $^{0}_{-0.25}$	3.8	20,21,22,23,24,25,26,27,28,30	–	0.3
			RS40	7 $^{0}_{-0.35}$	6.0	16,17,18,19,20,21,22,23,24,25,26	–	0.33
TL250	12,14,15,16, 18,19,20,22	17	RS40	7 $^{0}_{-0.35}$	6.5	22,23,24,25,26,27,28,30	21,32	0.85
			RS50	7 $^{0}_{-0.25}$	6.5	18,19,20,21,22,23,24,25,26,27,28	17	0.92
TL350	18,19,20, 22,24,25	–	RS40	7 $^{0}_{-0.35}$	6.5	26,27,28,30,32,34,35,36,38	40,42,45	1.55
			RS50	7 $^{0}_{-0.25}$	6.5	22,23,24,25,26,27,28,30,32	21,34,35,36	1.68
			RS60	10 $^{0}_{-0.30}$	9.5	–	18,19,20,21,22,23,24,25,26,27,28,30	1.91
TL500	22,24,25, 28,30, 32,35,38, 40,42	29,33,36	RS50	7 $^{0}_{-0.25}$	6.5	30,32,34,35,36,38,40,42,45	48,50	4.3
			RS60	10 $^{0}_{-0.30}$	9.5	25,26,27,28,30,32,34,35,36,38	40	4.7
			RS80	13 $^{0}_{-0.30}$	9.5	–	19,20,21,22,23,24,25,26,27,28,30	5.2
TL700	35,40,42,45, 50,55,60, 63,64	32,33,36, 38,43,46, 48,52,56,57	RS60	10 $^{0}_{-0.30}$	9.5	35,36,38,40,42,45,48,50,54	–	10.7
			RS80	13 $^{0}_{-0.30}$	12.5	26,27,28,30,32,34,35,36,38	–	11.2
			RS100	16.5 $^{0}_{-0.30}$	12.5	–	21,22,23,24,25,26,27,28,30	12.2
Delivery	*1	*1				*1	*2	–

Delivery *1 = Ex.-Japan 4weeks by sea
*2 = Ex.-Japan 6weeks by sea

1. Delivery dates are listed in each column. If ordering the finished bore and with sprocket combination, the longer time of delivery applies.
2. If a finished bore is a size other than that listed in the chart above or hardened teeth are needed, it may be possible to provide this. Contact TEM for a consultation.
3. The thickness of sprocket F is different from the thickness of the standard sprocket. Ex.-Japan 4weeks by sea
4. For Torque Limiter dimensions, refer to pages 89 and 90.
5. The mass of the above is based on rough bore and minimum number of sprocket teeth.
6. On TL200, setting to the shaft by hexagon socket head set screw is not possible. Use a snap ring for the shaft or end plate.

Model No.

TL250 - 2 - 040 22 - 20J - 5.0

- TL250 — Size
- 2 — No. of disk springs
- 040 — Sprocket Model No.(RS40)
- 22 — No. of sprocket teeth
- 20J — Bore diameter
  - J — New JIS key normal type
- 5.0 — Set torque(Unit: kgf.m, no number if no torque setting)

■ Torque setting

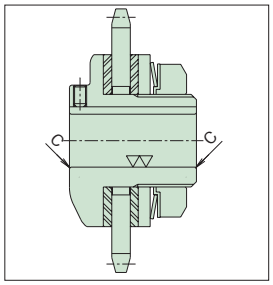
・Torque setting is done at 120° on the "Tightening Amount - Torque Correlation Graph". When using the Torque Limiter, set the torque based on 120° with the adjusting nuts or bolts.

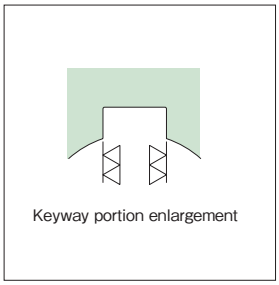
■ Bore diameter and keyway specifications

・The bore tolerance is H7.
・The keyway is New JIS (JIS B 1301-1996) "normal type"
・Set screws are included.

■ Chamfer and finish

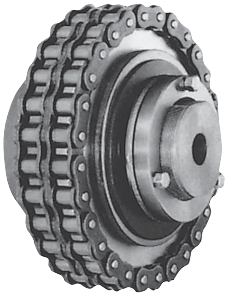
Bore diameter	Chamfer dimensions
ϕ 25 and less	C0.5
ϕ 50 and less	C1
ϕ 51 and above	C1.5

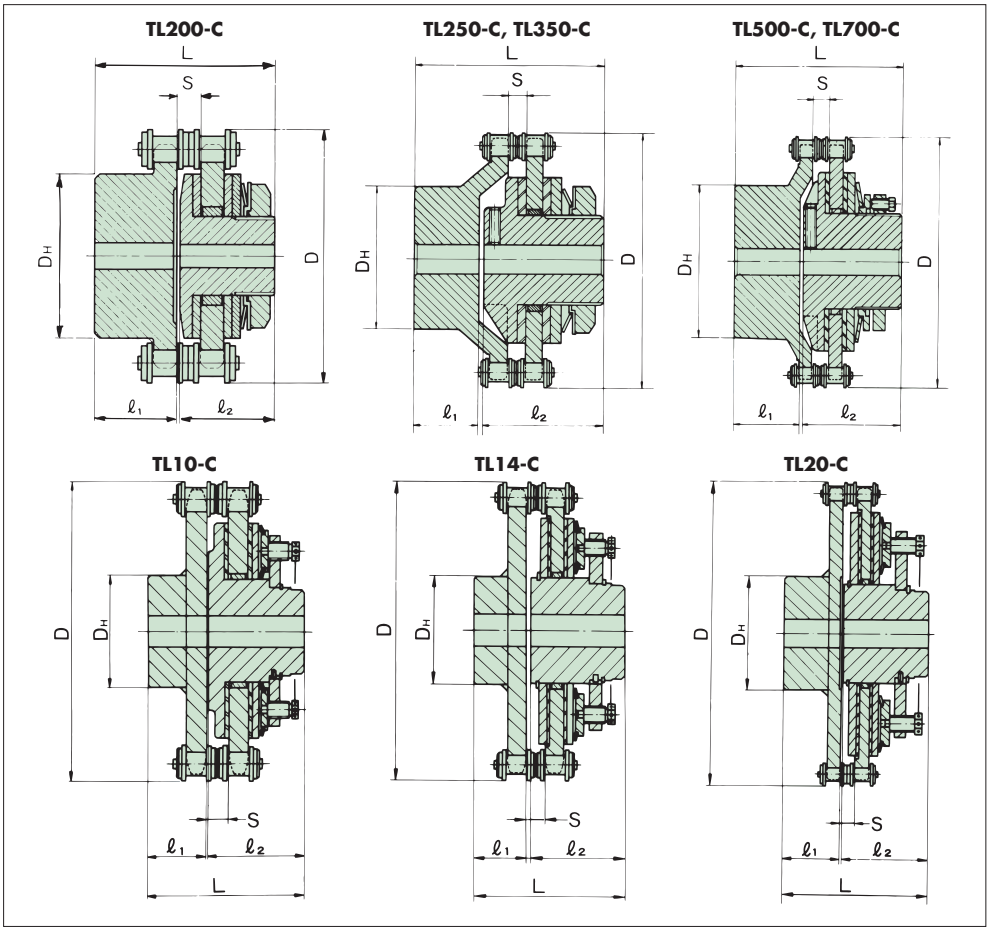




Torque Limiter coupling

The Torque Limiter coupling is a flexible coupling that uses a Torque Limiter and special type sprocket, and is connected by 2 rows of roller chains.
Centering the shaft coupling is easy and handling is simple. The Torque limiter acts as an automatic safety device, protecting machinery from damage due to overload.





· Torque Limiter unit of TL200-1LC, TL250-1LC and TL350-1LC have a spacer between the disk spring and lock washer.

Unit : mm

Model No.	Set torque range N·m	Max. rpm (r/min) *	Rough bore diameter		Min. bore diameter		Max. bore diameter		Sprocket	Dimensions						Mass kg
			Coupling side	Torque Limiter side	Coupling side	Torque Limiter side	Coupling side	Torque Limiter side		D	D_H	L	ℓ_1	ℓ_2	S	
TL200-1LC	1.0 to 2.0	1200	8	7	10	10	31	14	RS 40-16T	76	50	55	24	29	7.5	1.0
TL200-1C	2.9 to 9.8															
TL200-2C	6.9 to 20															
TL250-1LC	2.9 to 6.9	1000	13	10	15	12	38	22	RS 40-22T	102	56	76	25	48	7.4	1.9
TL250-1C	6.9 to 27															
TL250-2C	14 to 54															
TL350-1LC	9.8 to 20	800	13	17	15	18	45	25	RS 50-24T	137	72	103	37	62	9.7	4.2
TL350-1C	20 to 74															
TL350-2C	34 to 149															
TL500-1LC	20 to 49	500	18	20	20	22	65	42	RS 60-28T	188	105	120	40	76	11.6	10
TL500-1C	47 to 210															
TL500-2C	88 to 420															
TL700-1LC	49 to 118	400	23	30	25	32	90	64	RS 80-28T	251	150	168	66	98	15.3	26
TL700-1C	116 to 569															
TL700-2C	223 to 1088															
TL10-16C	392 to 1274	300	33	30	35	32	95	72	RS140-22T	355	137	189	71	115	26.2	66
TL10-24C	588 to 1860															
TL14-10C	882 to 2666	200	38	40	40	42	118	100	RS160-26T	470	167	235	80	150	30.1	140
TL14-15C	1960 to 3920															
TL20-6C	2450 to 4900	140	43	50	45	52	150	130	RS160-36T	631	237	300	120	175	30.1	285
TL20-12C	4606 to 9310															

1. The products in bold are all stock items. The rest are MTO.
2. Using a sprocket with induction-hardened teeth, TL200 to 700 can be used at up to 1800 r/min. The larger ones can be used at up to 800 r/min.
3. If the model larger than TL20-12C is required, contact TEM.
4. The mass is that of one with the maximum bore diameter.

Torque Limiter coupling with finished bore

Finished bore products are available for quick delivery.

■ Bores and keyways are already finished

Bore finishing is standard for Torque Limiter couplings TL200C to 700C.

■ Finished Bore Dimension Chart

Unit : mm

Torque Limiter Coupling Model No.	Finished bore dimensions	
	Torque Limiter side	Coupling side
TL200-1LC	10,11,12,14	10,11,12,14,15,16,17,18,19,20,22,24,25,28,29,30
TL200-1C		
TL200-2C		
TL250-1LC	12,14,15,16,17,18,19,20,22	15,16,17,18,19,20,22,24,25,28,29,30,32,33,35,36,38
TL250-1C		
TL250-2C		
TL350-1LC	18,19,20,22,24,25	15,16,17,18,19,20,22,24,25,28,29,30,32,33,35,36,38,40,42,43,45
TL350-1C		
TL350-2C		
TL500-1LC	22,24,25,28,29,30,32,33,35,36,38,40,42	20,22,24,25,28,29,30,32,33,35,36,38,40,42,43,45,46,48,50,52,55,56,57,60,63,64,65
TL500-1C		
TL500-2C		
TL700-1LC	32,33,35,36,38,40,42,43,45,46,48,50,52,55,56,57,60,63,64	25,28,29,30,32,33,35,36,38,40,42,43,45,46,48,50,52,55,56,57,60,63,64,65,70,71,75,80,85,90
TL700-1C		
TL700-2C		
Delivery	Ex.-Japan 4 weeks by sea	

1.For finished bore and hardened teeth specifications outside those written in the above chart, please conact TEM for more information.

Model No.

TL250 - 2C - T18J×C30J - 5.0

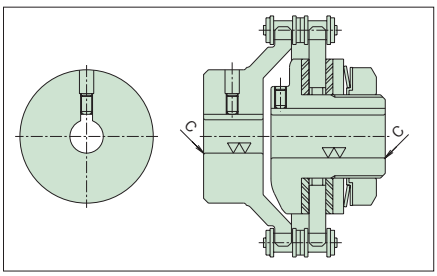
- TL250 — Size
- 2C — No. of disk springs
- T18J — Torque Limiter side bore diameter
- J — Keyway type: (J: new JIS normal type)
- C30J — Coupling side bore diameter
- J — Keyway type: (J: new JIS normal type)
- 5.0 — Set torque (unit: kgf·m, no number is displayed when torque is not set)

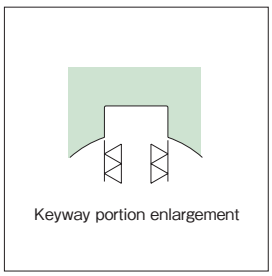
■ Bore diameter and keyway specifications

- Bore diameter tolerance is H7.
- The keyway is New JIS (JIS B 1301-1996) "Normal type"
- Setscrews are included.

■ Chamfer and finish

Bore diameter	Chamfer dimensions
ϕ 25 and less	C0.5
ϕ 50 and less	C1
ϕ 51 and above	C1.5





Selection

If using the Torque Limiter with human transportation or lifting devices, take the necessary precautions with equipment to avoid serious injury or death from falling objects.

1 From the machine's strength and load, as well as other information, set the trip torque at the point where it should not go any higher. This torque is the Torque Limiter slip torque.
When the limit value is not clear, calculate the rated torque by using the rpm of the shaft where the Torque Limiter is installed and rated output power of the motor. Then, multiply by 1.5 to 2.0. This is the Torque Limiter slip torque.

2 Slip torque should be lower than rated torque.

3 Using the dimension table, verify that the maximum allowable bore diameter of the Torque Limiter is larger than the installation shaft diameter. If the installation shaft diameter is bigger, use a Torque Limiter one size larger.

4 Depending on the thickness of the center member which is clamped, use an appropriate length of bushing. Select a bush by referring to the bush length in the dimension table. Use a single bush or a combination of bushes, whichever is longest without exceeding the thickness of the center member.

Torque setting

Torque Limiter slip torque is set by tightening the adjusting nuts or bolts.

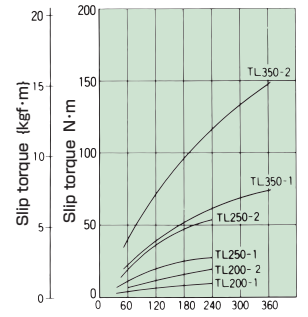
1 After installing the Torque Limiter to the equipment, tighten the adjusting nuts or bolts gradually from a loose position to find the optimal position.
In addition, by using the "Tightening Amount - Torque Correlation Charts" below, the tightening amount of the adjusting nut and bolts for slip torque can be found. However, due to the condition of the friction surface and other factors, the torque for the fixed tightening amount changes.
Using the graph as a rough guide, try test operating the Torque Limiter with the tightening amount slightly loose, then tighten gradually to find the optimal position. This is the most practical method.
When slip torque stability is especially important, hand tighten the adjusting nut or bolts as much as possible, and then slip approximately 500 times for running-in at a wrench-tightened 60° more. If the rotation speed is fast, slip several times and subject it to 500 slips.

2 With the center member, the torque can be set to the specified amount. In this case, it is necessary to use a finished bore.

Tightening Amount and Torque Correlation Chart

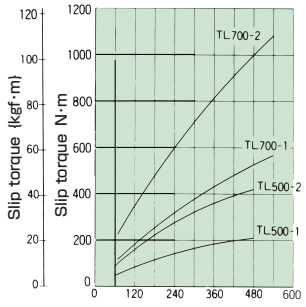
Zero (0) point is the condition at which the adjustable nut or adjustable bolts are tightened by hand, and the disk spring is fixed.

TL200, TL250, TL350



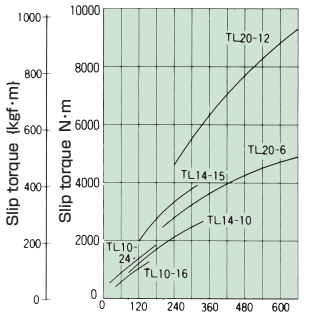
Adjustable nut tightening rotation angle (deg.)

TL500, TL700



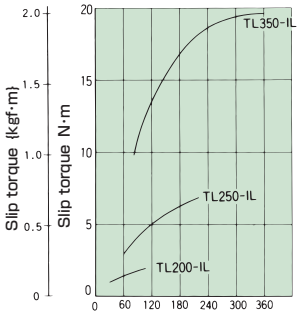
Adjustable bolt tightening rotation angle (deg.)

T10 TL14 TL20



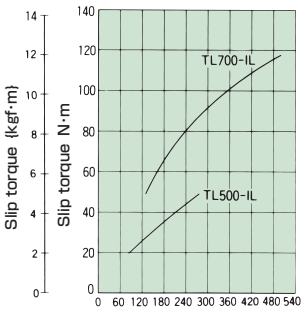
Adjustable bolt tightening rotation angle (deg.)

TL200 - IL, TL250 - IL, TL350 - IL



Adjustable nut tightening rotation angle (deg.)

TL500 - IL, TL700 - IL



Adjustable bolt tightening rotation angle (deg.)

Center member selection and manufacture

Sprockets and gears can be used as a center member with the Torque Limiter. If the customer intends to select or manufacture the center members by themselves, take the following precautionary steps:

1 For the Torque Limiter's outer diameter, the minimum diameter of the center member is restricted. When using a sprocket with a chain drive, refer to page 96 for minimum number of teeth.

2 Finish the friction face sides of the center member (both sides) in 3s - 6s.

3 For the bore diameter of the center member, machine it within the center member bore diameter tolerance from the dimension table in 3s - 6s.

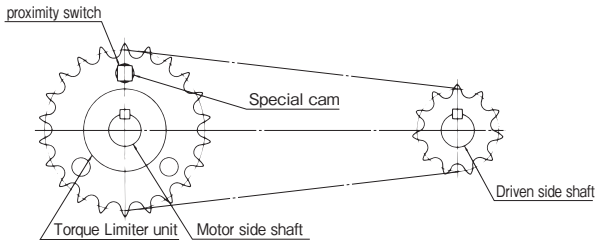
4 The width in which the center member is clamped should be within the S dimension in the dimension table.

Torque Limiter's operation detection

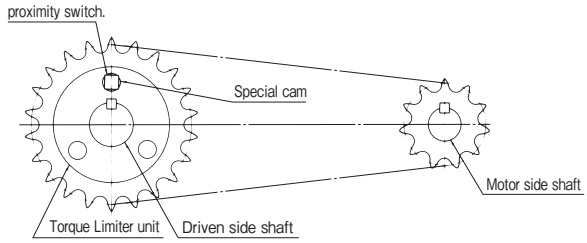
When overload occurs, the Torque Limiter slips and protects the machine, but if the driving source is not stopped, the Torque Limiter will continue to slip. If it continues to slip, the friction facing will be abnormally worn and become unusually hot, making it necessary to stop the drive source immediately.
The following are examples that detect Torque Limiter slips and stop the drive by using a proximity switch and digital tachometer.

■ Installation examples

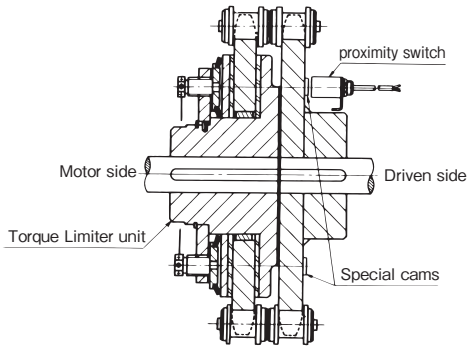
Type1 When the driven side experiences overload and the Torque Limiter's center member stops.



Type2 When the driven side experiences overload, the Torque Limiter unit stops.



Type 3 When the Torque Limiter is used with a coupling type and the center member side stops when overload occurs.



Type 4 When the Torque Limiter is used with a coupling type, and the main unit side stops when overload occurs.

For the installation of Type 4, it is quite difficult to install the special cams, so as much as possible avoid using this type.
When using the Torque Limiter with the coupling type, use Type 3.

Slip can be detected within approximately 1 to 10 seconds based on the rotational detection speed if the number of special cams selected is shown in the chart.

Number of special cams and rotational detection speed

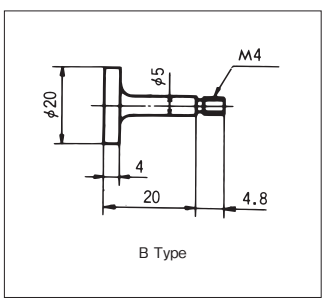
Number of Special cams	Rotational detection speed range r/min	Number of Special cams	Rotational detection speed range r/min
1	6 to 60	6	1.0 to 10
2	3 to 30	7	0.85 to 8.5
3	2 to 20	8	0.75 to 7.5
4	1.5 to 15	9	0.67 to 6.7
5	1.2 to 12	10	0.6 to 6.0

Note: In the case of 0.6 r/min and slower, the range is that of 6 to 60r/min divided by the number of special cams.

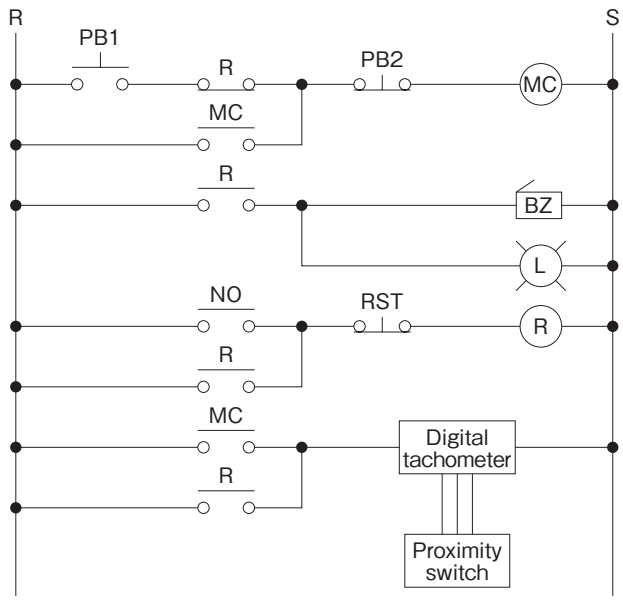
■ Special cam dimensions and installation

The special cam is fixed by a screw on the driven side. Use a screw lock to lock the screw.

■ Special cam for reference



■ Reference Electrical Schematic Diagram



PB1 : Motor start button
PB2 : Motor stop button
RST : BZ, L reset button
MC : Electromagnetic contactor for motor
R : Auxiliary relay
NO : Digital tachometer output a contact
BZ : Buzzer
L : Lamp

Digital tachometer:
OMRON H7CX-R11-N

Proximity switch:
OMRON TL-N5ME2

Note)
We recommend OMRON digital tachometers and proximity switches for the above. For more information, refer to the OMRON catalog.

■ Sprockets for the center member

When using the sprocket as a center member, refer to the notes below. In the below chart, the sprocket is used as a center member for the chain drive.

(1) Minimum number of teeth in which the chain does not interfere with the special cam (same as the reference drawing of the previous page) when using installation types 1 and 2 of the previous page.

(2) Minimum number of teeth in which the chain does not interfere with the friction facings of the Torque Limiter.

(3) Bush length

(4) Sprocket bore diameter (center member bore diameter)

Torque Limiter only and in the case the special cams shown in the previous page are used in type 2.

Torque Limiter Model No.	Sprocket bore diameter (center member bore diameter)	Min. No. of sprocket teeth																	
		RS35		RS40		RS50		RS60		RS80		RS100		RS120		RS140		RS160	
		Min.No. of teeth	Bush length	Min.No. of teeth	Bush length	Min.No. of teeth	Bush length	Min.No. of teeth	Bush length	Min.No. of teeth	Bush length	Min.No. of teeth	Bush length	Min.No. of teeth	Bush length	Min.No. of teeth	Bush length	Min.No. of teeth	Bush length
TL200	$30^{+0.03}_{0}$	△ 20	3.8	16	6														
TL250	$41^{+0.05}_{0}$			20	6.5	17	6.5												
TL350	$49^{+0.05}_{0}$			26	6.5	21	6.5	18	9.5	15	9.5								
TL500	$74^{+0.05}_{0}$					△ 29 (30)	6.5	25	9.5	19	9.5								
TL700	$105^{+0.05}_{0}$							△ 33 (35)	9.5	26	12.5	21	12.5	18	12.5				
TL10	$135^{+0.07}_{0}$											△ 29 (30)	12.5	24	15.5	△ 22	19.5		
TL14	$183^{+0.07}_{0}$											△ 39 (40)	15.5	△ 33 (35)	15.5	△ 29	19.5	△ 26	23.5
TL20	$226^{+0.07}_{0}$											△ 54	15.5	△ 46 (60)	15.5	△ 40	19.5	△ 35	23.5

Note: Those marked with " △ " are not standard A type sprockets. When using a standard stock sprocket, use the number of teeth in ( ).

In the case the special cams shown in the previous page are used in type 1.

Torque Limiter Model No.	Sprocket bore diameter (center member bore diameter)	Min. No. of sprocket teeth																	
		RS35		RS40		RS50		RS60		RS80		RS100		RS120		RS140		RS160	
		Min.No. of teeth	Bush length	Min.No. of teeth	Bush length	Min.No. of teeth	Bush length	Min.No. of teeth	Bush length	Min.No. of teeth	Bush length	Min.No. of teeth	Bush length	Min.No. of teeth	Bush length	Min.No. of teeth	Bush length	Min.No. of teeth	Bush length
TL200	$30^{+0.03}_{0}$	△ 25	3.8	19	6.0														
TL250	$41^{+0.05}_{0}$			24	6.5	20	6.5												
TL350	$49^{+0.05}_{0}$			30	6.5	24	6.5	21	9.5	17	9.5								
TL500	$74^{+0.05}_{0}$					32	6.5	△ 28 (30)	9.5	21	9.5								
TL700	$105^{+0.05}_{0}$							36	9.5	△ 28 (30)	9.5	△ 23 (24)	12.5	20	12.5				
TL10	$135^{+0.07}_{0}$											△ 31 (32)	12.5	26	15.5	△ 23	19.5		
TL14	$183^{+0.07}_{0}$											△ 41 (45)	15.5	35	15.5	△ 30	19.5	△ 27	23.5
TL20	$226^{+0.07}_{0}$											△ 56 (60)	15.5	△ 47 (60)	15.5	△ 41	19.5	△ 36	23.5

Note: Those marked with " △ " are not standard A type sprockets. When using a standard stock sprocket, use the number of teeth in ( ).

Axial Guard

Features

The Axial Guard is a new type of mechanical type overload protection device for mechanisms where the load acts linearly, such as pushers or cranks.

Highly accurate trip load

Even with repeated loads, the fluctuating trip load variation is always within ±15%.

Non-backlash

High rigidity means no backlash for overweight axial loads.

Easy load adjustment

By simply turning the adjustable screw, load can be adjusted. In the tensile or compression direction, the Axial Guard trips at almost the same load.

Release type

When overload occurs, the Axial Guard immediately trips and the connection between the drive side and load side is shut off. The drive side's thrust does not transmit.
The resetting requires a small load, making it easy to reset.

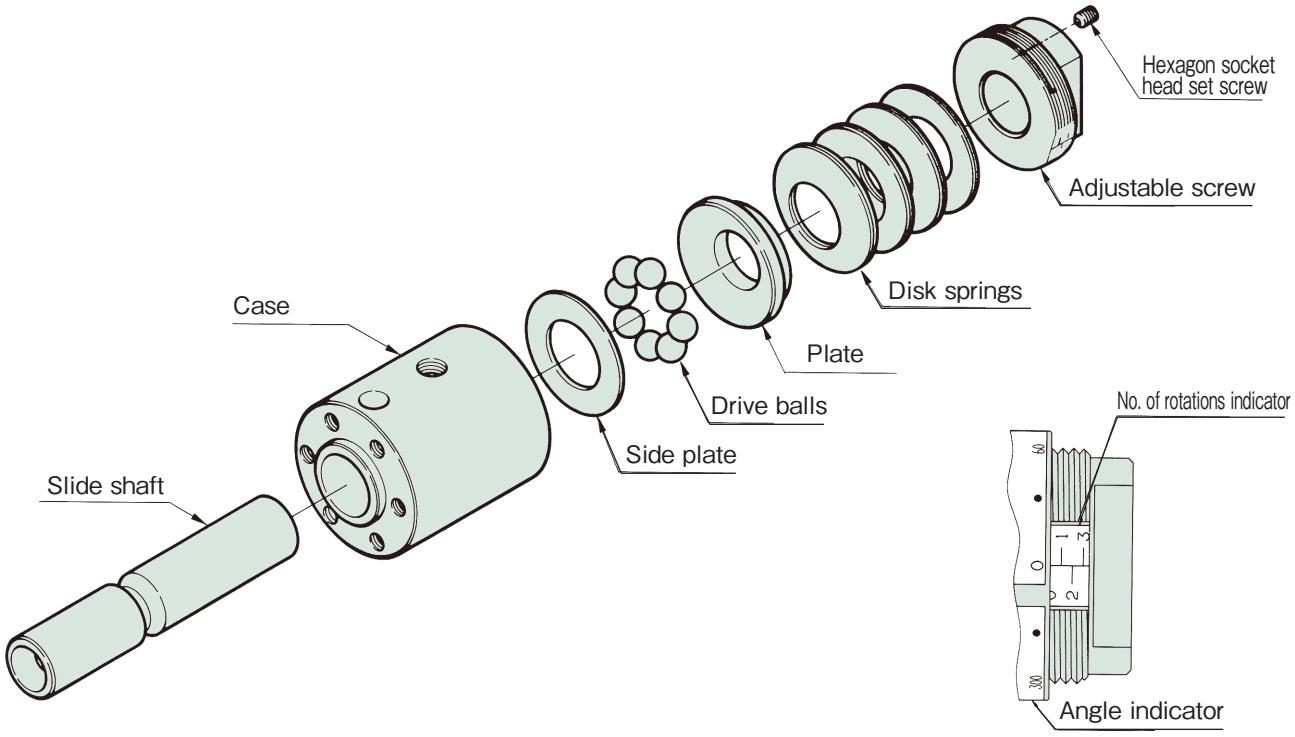
Easy installation

The end faces of the case and slide shaft have tap holes for easy built-in design.

Standard stock

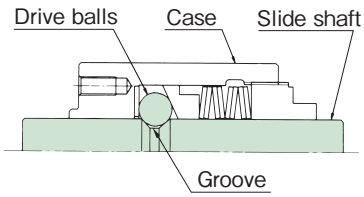
All Axial Guards are in stock.

Construction



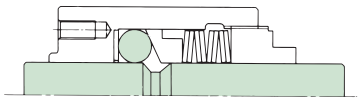
Operating principles

During normal operation (engagement)



Because the drive ball is held in the groove, thrust from the case (or slide shaft) is transmitted to the load side.

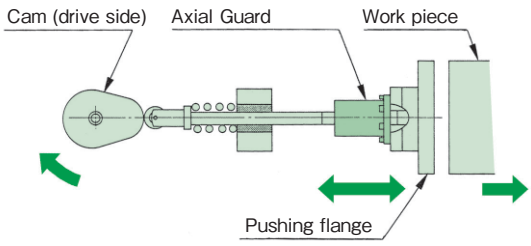
During overload (tripped)



When the load exceeds the pre-set value, the drive ball pops out of the groove; the connection between the slide shaft and the case disengages, and moves in a free state.

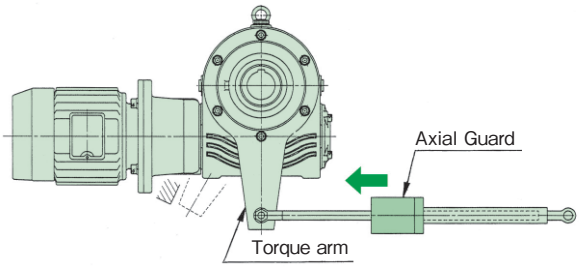
Applications

Pusher



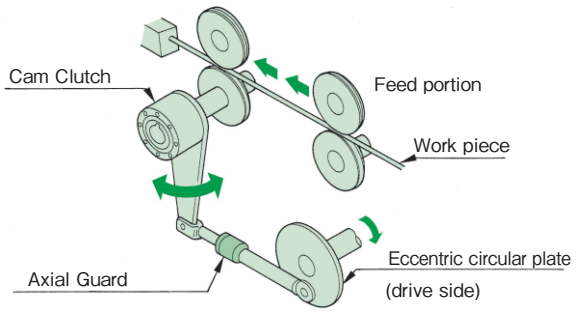
The cam pushes the work piece.
When overload occurs due to the over-weighted work piece or jamming, the Axial Guard trips and protects the machine.

Tie-rod of the shaft-mounted reducer



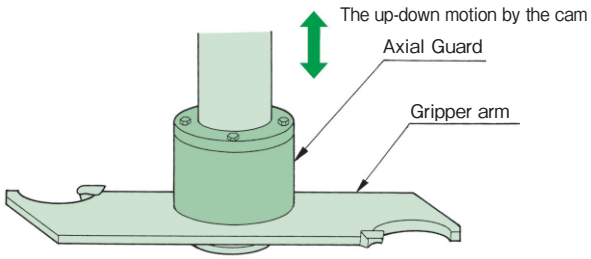
It is installed at the torque arm rotation-prevention portion of the shaft-mounted reducer.
When overload occurs and the moment is higher than the preset value, the Axial Guard trips.

Crank mechanism



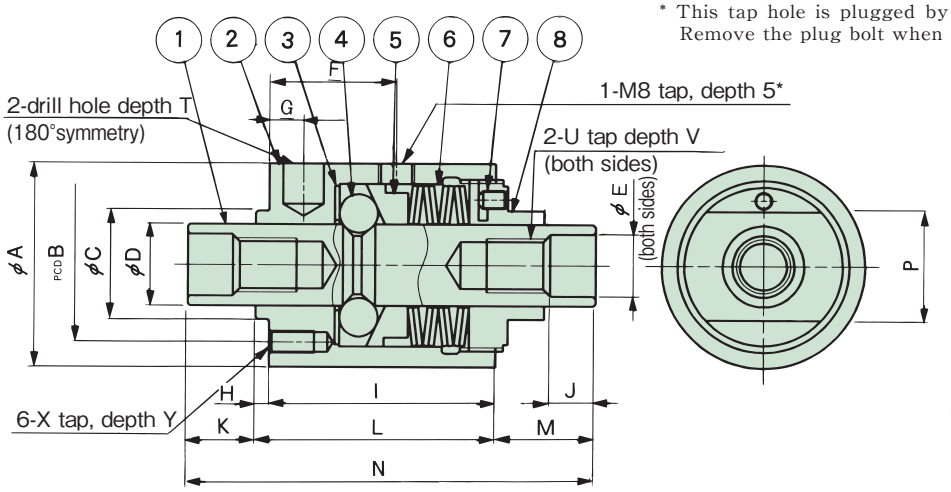
The combination of the crank and Cam Clutch motion sends the wire rod. When a foreign object gets caught up in the machine or the wire rod is deformed, overload occurs and the Axial Guard trips, thus protecting the feed portion.

The machining center's gripper

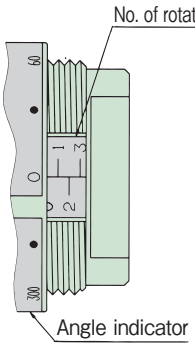


When a tool is being changed, the gripper portion is driven in the axial direction by the cam mechanism. When a tool gets caught up or the gripper hits the obstacle, the Axial Guard trips, thus protecting the cam and gripper from damage.

Transmissible capacity/dimensions



* This tap hole is plugged by plug bolt before shipment. Remove the plug bolt when installing the sensor.



This diagram displays the min. load (0 point).

① Slide shaft ⑤ Plate
② Case ⑥ Disk spring
③ Side plate ⑦ Hexagon socket head set screw (TGA65 is M3X5, TGA 150 to 350 is M4X8)
④ Drive ball ⑧ Adjustable screw

Model No.

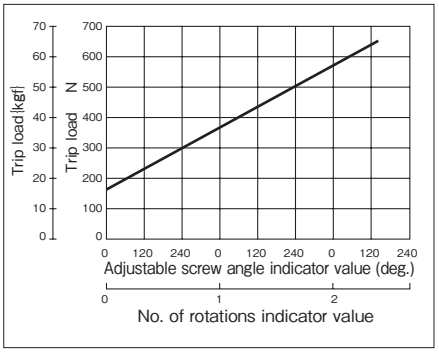
TGA 65

- Max. set load(kgf): 65, 150, 250, 350 (4 types)
- Series name

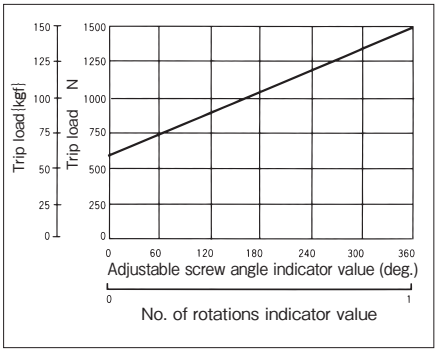
Unit : mm

Model No.	Trip load set range N	A	B	C h7	D	E H7	F	G	H	I	J	K	L	M	N	P	S	T	U	V	X	Y	Mass kg
TGA65	147 to 637	33	23	14	10	7	22.5	5	2	40	5	5	42	11	58	16	5	7.5	M 6	7	M3	6	0.2
TGA150	588 to 1470	38	28	18	14	10	24	6	2	43	7	8	45	19	72	21	7	8	M 8	10	M4	8	0.4
TGA250	735 to 2450	45	34	24	18	14	28	7.5	3	50	10	15	53	22	90	24	8	9	M12	14	M5	10	0.7
TGA350	980 to 3430	56	44	28	22	16	34	9	3	63	10	20	66	24	110	30	10	12	M14	15	M6	10	1.2

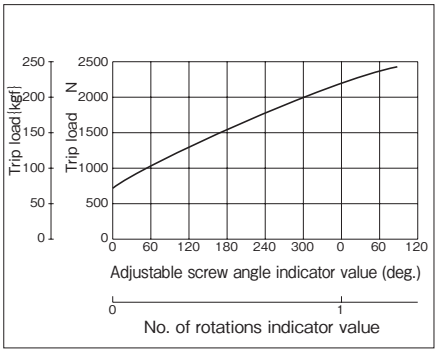
Load Curve (Tightening Amount-Load Correlation Diagram)



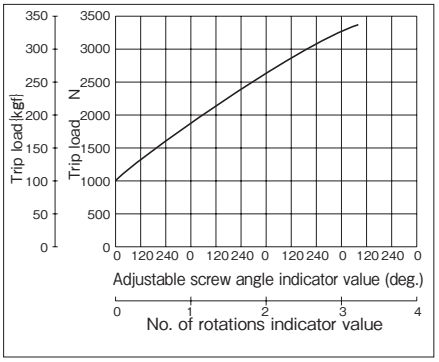
TGA65



TGA150



TGA250



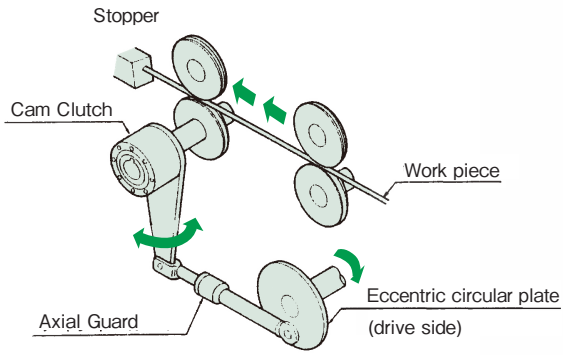
TGA350

Guide to calculating load

In order for the Axial Guard to be most effective as a safety protection device, install it on the driven side in the area where overload is most likely to occur.

Determining trip load

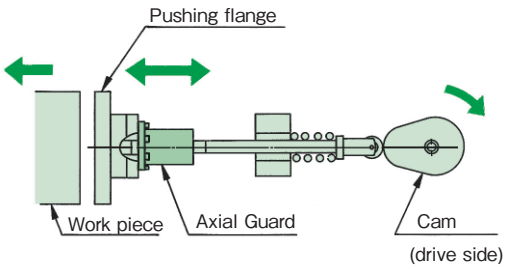
From the machine's strength and load, as well as other information, set the trip load at the point where it should not go any higher. When the limit value is not clear, it is decided by the load calculation (refer to the example below). As the low load on the equipment gradually increases, determine the appropriate set load.



This is an example of the combination of the crank and Cam Clutch motion sending the wire rod intermittently.
The following is a checklist of items for calculating load:

- The generated load due to the acceleration velocity of the drive side's crank motion.
- The impact load when hitting the work piece
- The load when machining the work piece
- Friction between each part

In addition, after checking the strength of each part, carry out a working load estimation for the Axial Guard.



This is an example of pusher actuation by the cam mechanism.

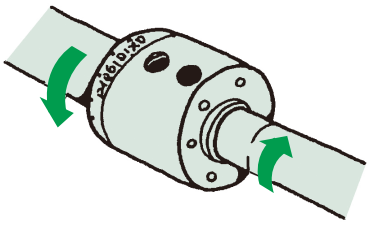
- The generated load is due to drive side cam acceleration velocity
- The impact load when hitting the work piece
- The generated load when pushing the work piece
- The friction when pushing the work piece

In addition, after checking if the work piece has been deformed and verifying the strength of each part, carry out a working load estimation for the Axial Guard.

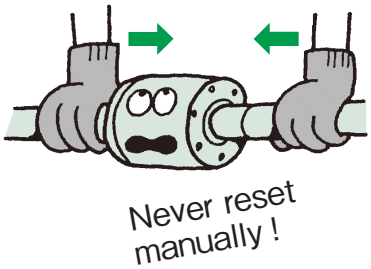
Caution

1 For most situations, avoid using the Axial Guard with human transportation or lifting devices. If you decide to use an Axial Guard with these devices, take the necessary precautions on the equipment side to avoid serious injury or death from falling objects.

2 For the Axial Guard, the case and slide shaft can rotate independently based on each shaft center. In the case that the prevention of independent rotation during operation is required, refer to page 73.

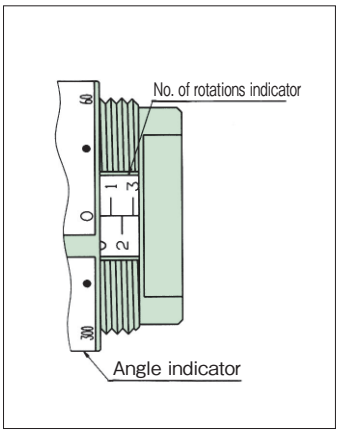


3 When resetting, the slide shaft or case rapidly/suddenly moves in the shaft direction, causing mechanical shock. Therefore, do not reset the Axial Guard by hand or touch it directly.



How to set the trip load

1 All Axial Guards are shipped with the load set at the minimum point (min. load). Confirm that the number of rotations indicator and angle indicator are set at "0". (Refer to the diagram on the right)



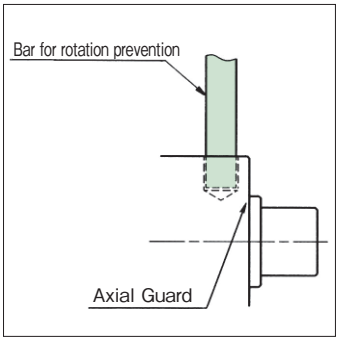
The No. of rotations indicator displays how many times the adjustable screw has rotated from the minimum load. If the end face of case is between 0 and 1, it indicates less than 1 rotation (less than 360°). As well, the angle indicator indicates how many degrees the adjustable screw has turned. The degree amount is indicated by the center line of the No. of rotations indicator. The total of the adjustable screw's number of rotations (1 rotation=360°) and angle indicator is the rotation angle of the adjustable screw.
(Example)
If the No. of rotations indicator is between 0 and 1, and the angle indicator shows 180°, the adjustable screw is turned to 180° position from minimum torque.

2 Loosen the hexagon socket head set screw to prevent loosing of adjustable screw.

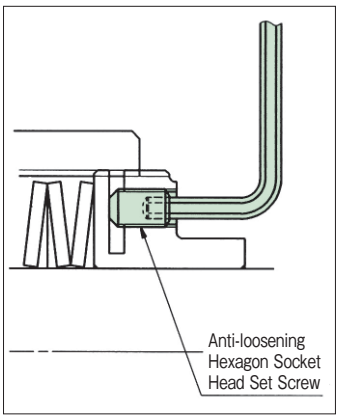
3 From the information in the "Tightening Amount - Load Correlation Diagram" on page 100, find the tightening angle of an equivalent adjustable screw for the predetermined trip load. Tighten to 60° less than the predetermined angle.

4 Next, carry out a load trip test. Gradually tighten to optimal trip load and set.

5 When the load has been set, tighten the hexagon socket head set screw to prevent loosing of adjustable screw portion, and verify that the adjustable screw is locked. (Refer to the diagram on the right)



When turning the adjustable screw, to prevent the Axial Guard from turning together with the adjustable screw, insert the bar into the drilled hole at the outer diameter of the cover.

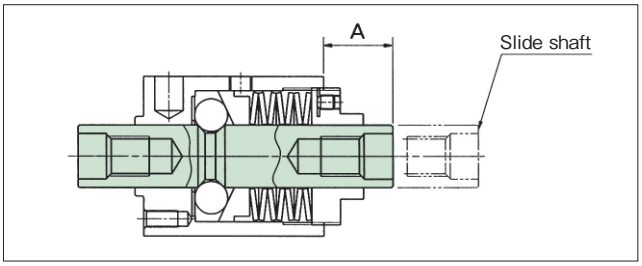


Reset

1 Before resetting, stop the machine and remove the cause of overload.
2 It is reset automatically when restarting the drive side (motor) to reverse load direction of trip direction. Turn the input (motor) using low rpm or inching. The axial load that is necessary for resetting is listed in the chart on the right.
3 When the Axial Guard resets, it makes a distinct "click" sound. To check whether the Axial Guard has reset, refer to dimension A in the diagram on the right.

Model No.	* Axial direction load for reset	Dimension A when resetting
TGA 65	83 N{8.5 kgf}	11
TGA150	196 N{20 kgf}	19
TGA250	343 N{35 kgf}	22
TGA350	490 N{50 kgf}	24

* At Max. load

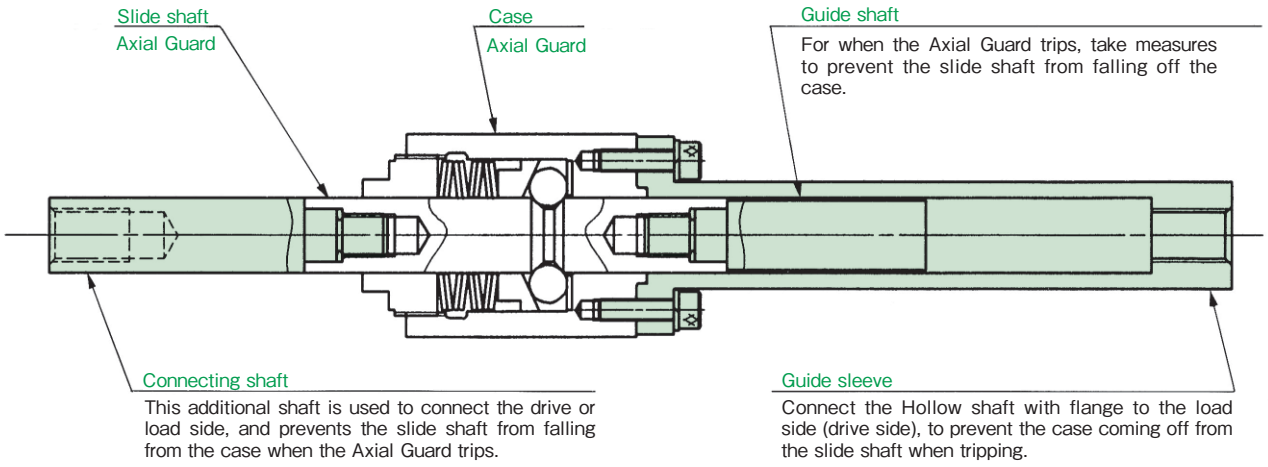


Caution

When resetting, the slide shaft or cover rapidly moves in the axial direction, causing mechanical shock. Therefore, do not reset by hand or directly touch the Axial Guard.

Auxiliary parts

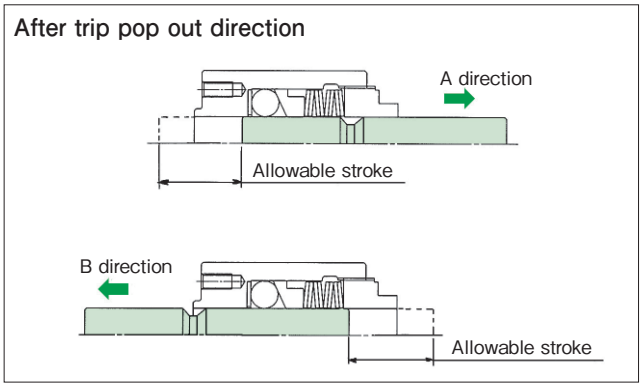
By incorporating the auxiliary parts in the below diagram, it is easier to use the Axial Guard.

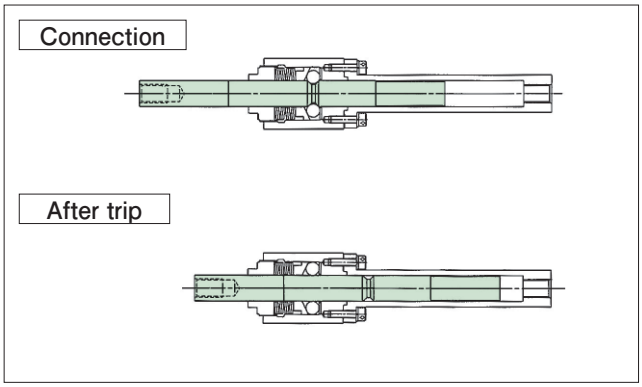


Axial Guard allowable stroke (Axial Guard unit only)

If the Axial Guard exceeds the stroke limits from the table below, the slide shaft will come out. In this case, the ball will fall out and the Axial Guard's functions will be lost. If after tripping the stroke is more than what is listed in the below table, connect the connecting and guide shafts.

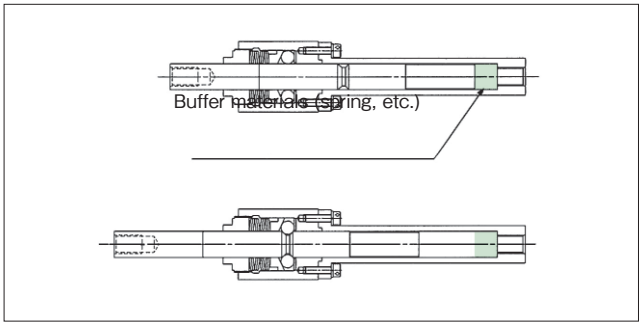
Model No.	TGA65	TGA150	TGA250	TGA350
A direction allowable stroke	14	20	30	38
B direction allowable stroke	14	22	24	26





1. The mechanical stop limits stroke after trip

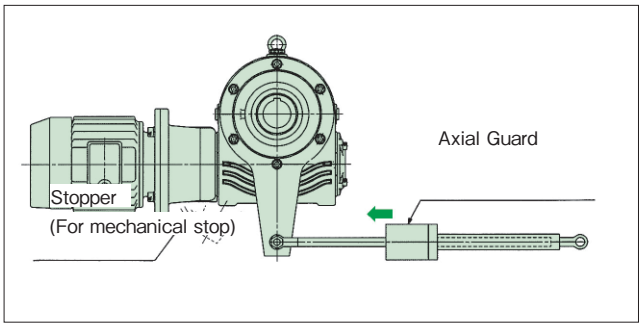
In the case of stopping the stroke at a certain position by sensor detection when tripping, it will become necessary to use a backup mechanism for stopping.
Install a spring or other such buffer material to absorb the stroke.



2. When installing at shaft-mounted reducer tie rod

This is an example of the application being used for shaft-mounted reducer torque arm as an overload protection device. Load direction is rotational direction, and the reducer rotates when tripping. Because of the reducer rotation, after the sensor detects overload and stops the motor, it stops mechanically at a certain position.

* For possible applications and model numbers, contact TEM.

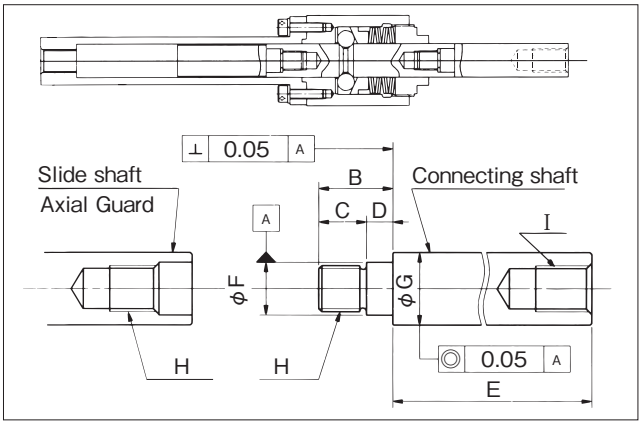


Recommended manufacturing dimensions for auxiliary devices

When installing a connecting shaft, guide shaft, guide sleeve or bolt to an Axial Guard, apply an adhesive for metal to the threaded portion to prevent loosening. (Loctite, etc.) (TEM recommends Loctite 262.)

1. Guide shaft, connecting shaft

Use the tap hole at the end face of the slide shaft to connect the guide and connecting shafts. The recommended dimensions of the connecting portion are in the diagram below.

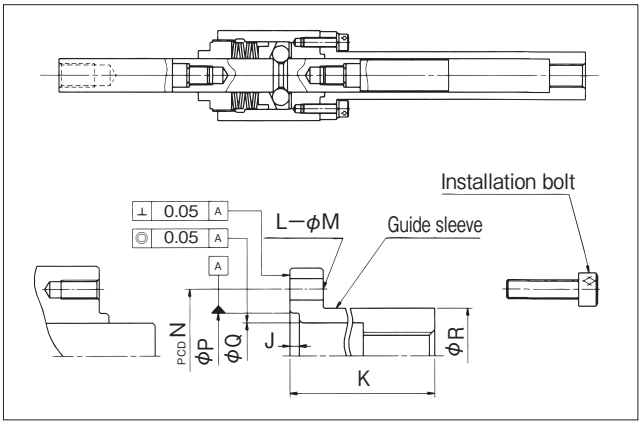


Model No.	B (0 / −0.2)	C (0 / −0.2)	D	E	F (h7)	G (h9)	H screw size	I * screw size
TGA65	10	6	4	Select by installation length, stroke, etc.	7	10	M6×P1.0	M6×P1.0
TGA150	15	9	6		10	14	M8×P1.25	M8×P1.25
TGA250	22	13	9		14	18	M12×P1.75	M12×P1.75
TGA350	23	14	9		16	22	M14×P2.0	M14×P2.0

* Not necessary for guide shaft

2. Guide sleeve

Use the tap holes at the end face of the case to connect the case and guide sleeve. The recommended dimensions of the connecting portion are in the diagram below.



Model No.	J (+0.2 / 0)	K	L	M	N	P (H7)	J (+0.2 / 0)	C (0 / −0.2)
TGA65	2.5	Select by installation length, stroke, etc.	6	3.4	23	14	10.5	16
TGA150	2.5		6	4.5	28	18	14.5	20
TGA250	3.5		6	5.5	34	24	18.5	24.5
TGA350	3.5		6	6.6	44	28	22.5	31

Installation

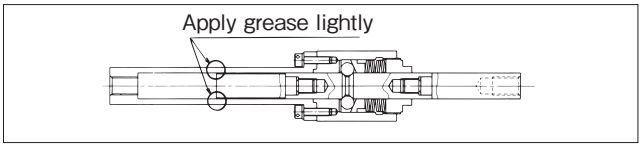
1. Installing to the machine

(1) Before installing the Axial Guard to the machine, completely wipe off any dust or dirt from the slide shaft, the spigot facing of the case and taps.

(2) Next, connect the slide shaft and the case tap portion. TEM recommends an adhesive for metals be applied to the tap portion or the bolt outer diameter to prevent any loosening. (Loctite 262 recommended)

(3) Make sure not to fix both the Axial Guard slide shaft side and the case side when installing the Axial Guard. The Axial Guard has no coupling function, so if it is installed too rigidly it will not properly function, potentially causing a malfunction or machine damage.

(4) When the guide sleeve and guide shaft are connected to the Axial Guard there is a possibility that the inner diameter of the guide sleeve and the outer diameter of the guide shaft end face may interfere. Just in case, apply grease to the portion on the diagram below. (Refer to the maintenance section on page 106 for information about grease brands.)



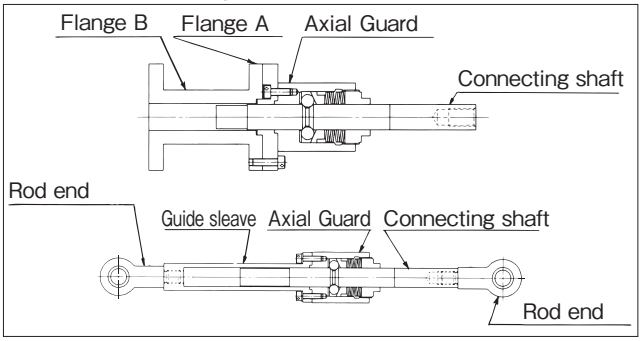
* When the Axial Guard is installed vertically, (lengthwise direction) grease may leak through the gap between the slide shaft and case or the adjustable screw. To avoid any problems, make sure to replenish grease at frequent intervals. (Refer to page 106 for maintenance information)

* Do not use the Axial Guard if there is a possibility that a falling accident of the drive or load side may occur when tripping. Such an accident may lead to serious injury or machine damage.

2. Overload detection

When using the Axial Guard, make sure to combine it with the sensor mechanism to ensure that overload can be properly detected. (Refer to page 105 for overload detection information)

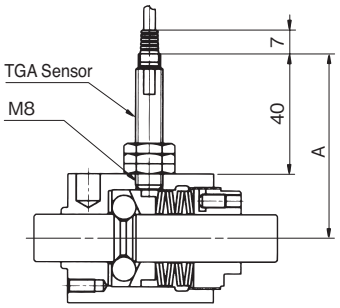
Installation example



Overload detection

When using the Axial Guard make sure to use the TGA Sensor to detect trip during overload.

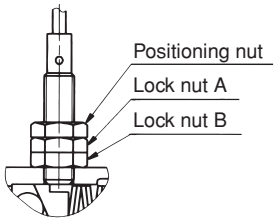
TGA Sensor installation example



Unit : mm

Model No.	A	Thread depth
TGA65	52	4.5
TGA150	54.5	
TGA250	58	
TGA350	63.5	

* This tap hole is plugged by plug bolt before shipment. Remove the plug when installing the sensor.



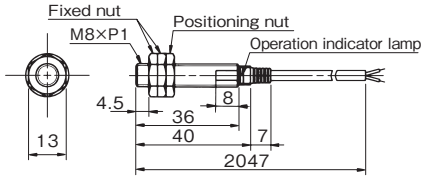
Fix the TGA Sensor to the case by screwing it into the tap holes. After fixing the sensor to the case, screw on lock nut A last to make it lock in place (double nut).
(The positioning nut is glued with an adhesive, so do not forcibly rotate it.)

■ TGA Sensor Specifications

		AC type	DC type
Model No.		TGA − S8	TGA − S8D
Power supply voltage	Rating	AC24 to 240V	DC12 to 24V
	Possible use range	AC20 to 264V(50/60Hz)	DC10 to 30V
Current consumption		Less than 1.7mA(at AC200V)	Less than 13mA
Control output (open, close capacity)		5 to 100mA	Max. 200mA
Indicator lamp		Operation indicator	
Ambient operating temperature		− 5 to + 70℃ (no condensation)	
Ambient operating humidity		35 to 95% RH	
Output form		NC (Output open/close condition when not detecting sensor plate)	
Operation form		—	NPN
Insulation resistance		More than 50MΩ (at DC500V mega) Charge portion - Case	
Mass		Approx. 45g (with 2m cord)	
Residual voltage		Refer to characteristic data	Less than 2.0V (Load current 200mA, 2m cord length)

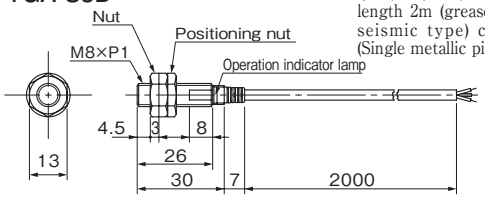
■ Measurement Diagram

●AC type TGA-S8



* Plastic insulation circle type cord φ4 (60/φ0.08) 2 cores, standard length 2m (grease resistant, anti-seismic type) cord extension (Single metallic piping) max. 200m

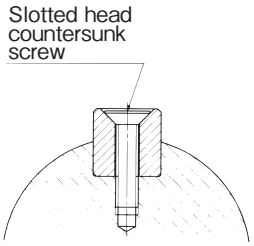
●TGA-S8D



* Plastic insulation circle type cord φ4 (60/φ0.08) 3 cores, standard length 2m (grease resistant, anti-seismic type) cord extension (Single metallic piping) max. 200m

When using the TGA Sensor it is necessary to stop the slide shaft side and case side rotation. As in the diagram below, stop rotation by putting the slide key (JIS1303 - 1916) between the guide sleeve and the guide shaft. For other methods, contact TEM for more information.

Reference drawing



Like the diagram on the left, fix the slide key to the shaft with a slotted head countersunk screw (JISB1101). Screw sizes are listed below.

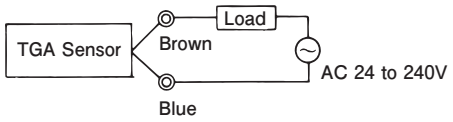
Model No.	Screw size
TGA65	M2
TGA150	M2
TGA250	M2
TGA350	M3

■ TGA Sensor handling

Refrain from striking, swinging or putting excessive force on the detecting portion.

AC type TGA-S8

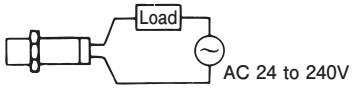
■ Circuit diagram



Not necessary to consider TGA Sensor's polarity (brown, blue)

■ Precautions for wiring

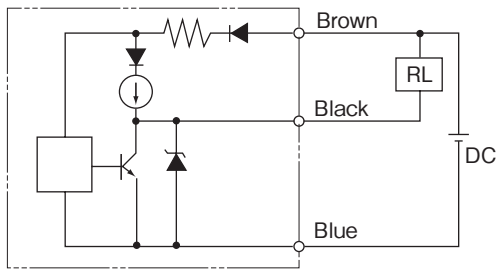
- Make sure to connect the load at first, then turn on the power. If the power is turned on without connecting the load, it will be damaged.



- In order to prevent malfunction or damage due to surge or noise, insert the TGA sensor code in a individual piping when it runs close to the power cable.

DC type TGA-S8D

■ Circuit diagram



■ About choosing load and wiring

• Connecting to the power source

Make sure to connect to the power source through load. A direct connection will break the elements inside.

• Metal piping

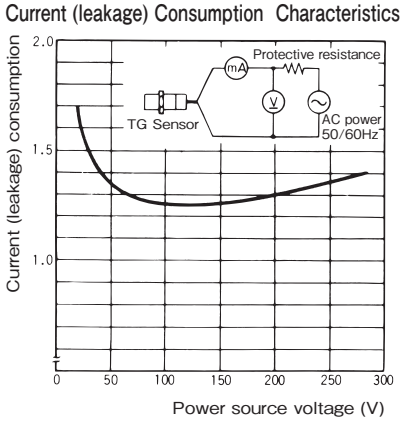
In order to prevent malfunction or damage, insert the proximity switch code inside a metal pipe when it runs close to the power cable.

• Surge protection

In the case where the TGA Sensor is near a device that generates a large surge (motor, welding machine, etc.), the TG Sensor contains a surge absorption circuit, but also insert a varistor to the source.

• The effect of current consumption (leakage)

Even when the TGA Sensor is OFF a small amount of current continues to flow to keep the circuit running. (Refer to the "Current Consumption (leakage) Graph".) Because of this, a small voltage occurs in the load that can sometimes lead to reset malfunction. Therefore, confirm that the voltage of the load is less than the reset voltage before use. As well, if using the relay as load, depending on the construction of the relay, a resonance may occur due to the current leaks when the sensor is OFF.



• When power voltage is low

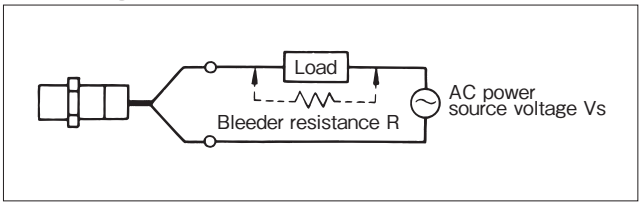
When power source voltage is lower than AC48V and load current is less than 10mA, the output residual voltage when the TGA Sensor is ON becomes large. When it is OFF, the residual voltage of load becomes large. (Refer to "Residual Voltage Characteristics of Load".) Take caution when using the load such as a relay operated by voltage.

• When load current is small

When load current is smaller than 5mA, residual voltage of load becomes large in the TGA Sensor. (Refer to "Residual Voltage Characteristics of Load".) In this case, connect the breeder resistance with load parallel, apply load current at more than 5mA, and set the residual voltage less than return voltage of load. Calculate the breeder resistance and allowable power using the following calculations. TEM recommends to use 20kΩ at AC100V and more than 1.5W (3W), and 39kΩ at AC200V and more than 3W (5W) for safe. (If heat generation becomes a problem, use the Wattage shown in ( ).

$$R \leqq \frac{V}{5-i}\ (k\Omega) \qquad P \geqq \frac{V^2 s}{5-i}\ (mW)$$

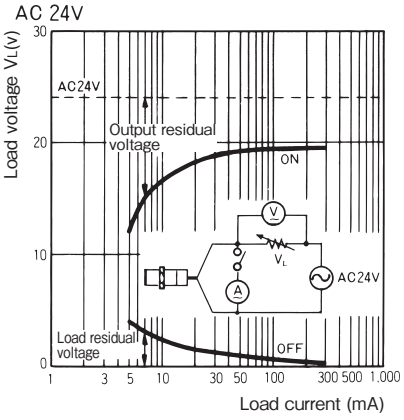
P : Wattage of breeder resistance
i : Current applied to the load (mA)

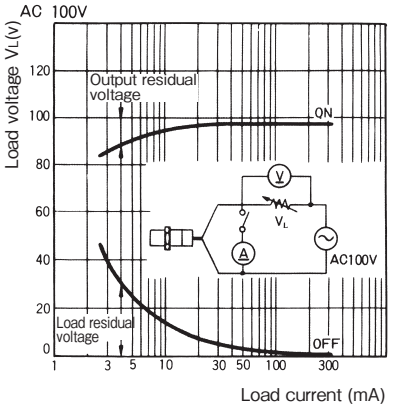


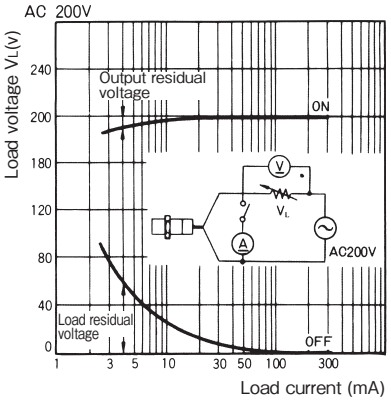
• Load with large inrush current

As for the load with large inrush current (1.8A and above) such as a lamp or motor, the opening and closing element can be deteriorated or be broken. In this case, use along with a relay.

Load Residual Voltage Characteristics







Maintenance

The Axial Guard is packed in grease for shipment. Add the grease shown in the right table once a year or every 100 trips.

Kyodo Oil	Sumitomo Lubricant	Dow Corning Toray	STT
Grease HD	Low temp grease	Molykote 44MA Grease	Solvest 832

MEMO

Safety Devices

SAFCON

Electronic
Shock Relay

Shock Relay

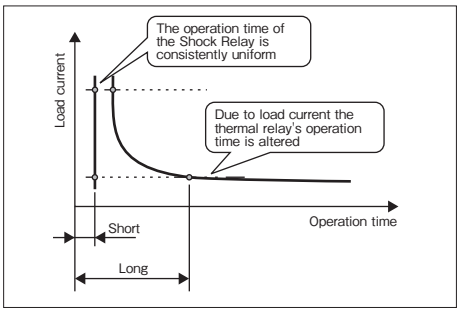
Swiftly detects equipment overload!

The Shock Relay is a current monitoring device that quickly detects motor overload, thus protecting your equipment from costly damage.

Features

1. Instantly detects overcurrent

When the motor current exceeds the predetermined current value, the relay contact signal can be output after a preset time.
For example, when a foreign object gets caught up in the conveyor, the Shock Relay sends a signal causing an emergency stop, thus minimizing equipment damage.



It's not a thermal relay

The purpose of the thermal relay is to protect the motor from burnout.
When the motor current continually exceeds the rated value for a certain period of time, an abnormal signal is sent to protect the motor from burnout.
Generally, it takes a long time for operation to begin, so it is not suitable for equipment/machine protection.

	Operation time	Protected object
Shock Relay	Short	Equipment
Thermal Relay	*Long	Motor

*If the motor current slightly exceeds the preset value, the thermal relay will not work. Even if it does work, it will do so slowly.

2. Easy to install on existing equipment

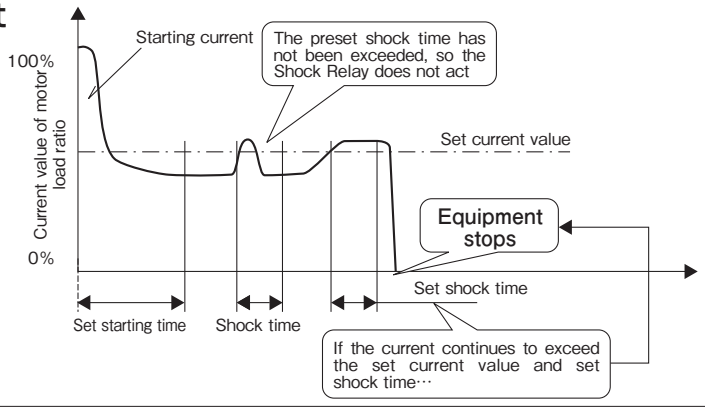
The Shock Relay is an electrical protection device.
In the case that the Shock Relay is added to existing equipment, it is not necessary to make major modifications to the device as in the case of the mechanical type.
Because the Shock Relay is installed inside the control panel, it can function outdoors or in harsh environments.

	Existing equipment	Environment
Electrical	Easy to install later	Built inside the panel
Mechanical	Difficult to install later	Necessary environmental precautions

3. The abnormal signal is only output under abnormal conditions

The Shock Relay sends an abnormal signal when overcurrent continues to exceed the preset period of time.
Sometimes during normal operation conveyors will experience insignificant short time current overloads due to reasons such as the current pulsation of the equipment, or when packages are put on the conveyor.
By using the shock time function these small overloads will not be recognized as overloads, therefore avoiding nuisance stoppages.

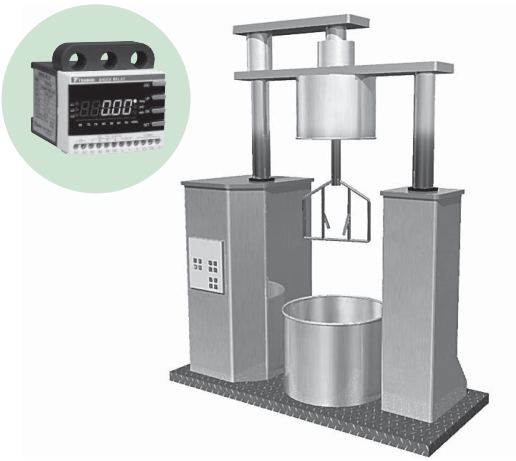
Operation Time Chart



Applications

SC Series

Mixer



Operation

1. When mixing has just started and the load is heavy, the mixer operates at a low speed.
2. When the load becomes lighter after some time of mixing, an output signal of 4 to 20mA is sent to a sequencer to switch the mixing to a higher speed.

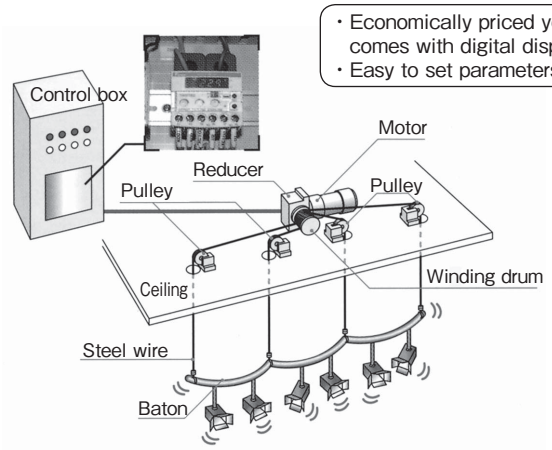
Key Points

Output of 4 to 20mA which enables actions according to the actual load.

ED Series

Lifting device for illumination and screens

- Economically priced yet comes with digital display
- Easy to set parameters



Operation

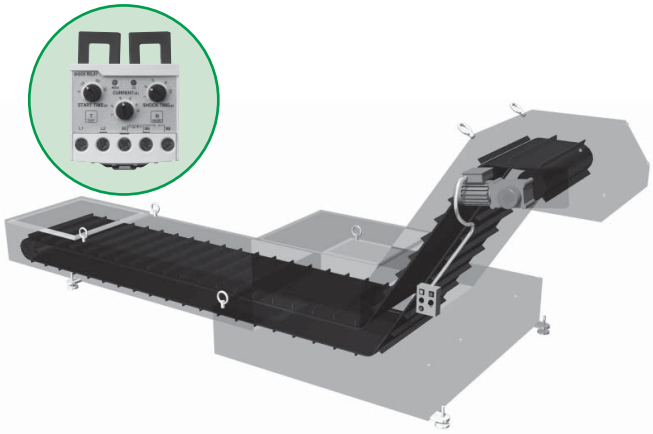
1. Due to over-installation of the lighting system, when the total weight of the baton exceeds the permissible load, the lifting device will be automatically shut down.
2. When the lifting device becomes overloaded during operation it automatically shuts down.

Key Points

During operation the motor current is displayed digitally, and allowable load and stopping due to overload can be set as a digital numeric value.

SS Series

Chip Conveyor



Operation

Protects the conveyor from damage when a tool gets caught in its belt.

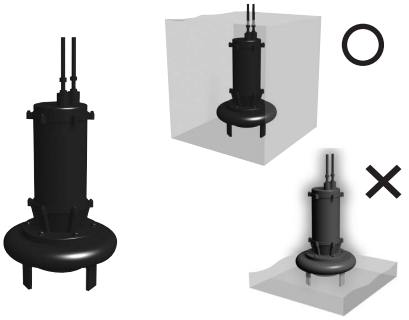
Key Points

The driver has been made more compact and less expensive.
*A built-in Shock Relay in the motor terminal box type is available.

- Ideal for the hollow type reducer (for applications where it is difficult to install a mechanical safety device)
- Easy to change settings
- Even with large torque the SS Series retains its compact size

SU Series

Pump



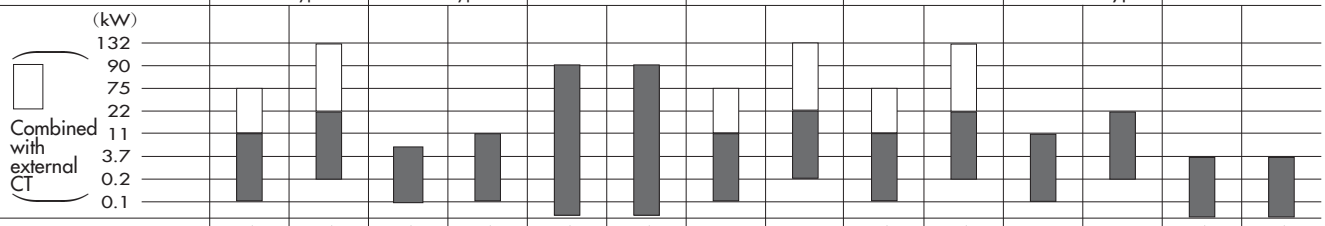
Operation

Prevent the pump motor from burnout due to water shortage.

Key Points

Compact body, economical, and test function

Series reference chart

Series name		SC Series	ED Series	150 Series	SS Series	SA Series	SU Series	50 Series
Model No.		TSBSCB/S06 to TSBSCB/S60	TSB020ED-1, -2 to TSB550ED-1, -2	TSB151, 152	TSBSS05 to 300	TSBSA05 to 300	TSBSU05-2 to TSBSU60-2	TSB50
Features		Digital display, communication function selectable self-holding/automatic reset type	Digital display, economical, selectable self-holding/automatic reset type	Analog display, self-holding type	Economical, self-holding type	Economical, automatic reset type	Economical, self-holding type under-load detection Type	Economical, automatic reset type
Motor	Combined with external CT (kW) 132 / 90 / 75 / 22 / 11 / 3.7 / 0.2 / 0.1							
	Power source (V)	200/220 / 400/440	200/220 / 400/440	200/220 / 400/440	200/220 / 400/440	200/220 / 400/440	200/220 / 400/440	200/220 / 400/440
Operation setting level		Ampere (A)	Ampere (A)	The ratio of motor-rated current value (%)	Ampere (A)	Ampere (A)	Ampere (A)	The ratio of motor-rated current value (%)
Start time setting range		0.2 to 12.0s adjustable	0.2 to 10.0s adjustable	0.2 to 20s adjustable	0.2 to 30s adjustable	0.2 to 10s adjustable	No	3s (fixed)
Shock time setting range		0.2 to 5.0s adjustable	0.2 to 5.0s adjustable	0.2 to 3s adjustable	0.2 to 10s adjustable	0.2 to 5s adjustable	0.2 to 30s	0.3 to 3s adjustable
Operation power source		AC100 to 240V	100 to 120V or 200 to 240V	AC100/110V or AC200/220V 50/60Hz	AC100 to 240V	AC100 to 240V	AC200 to 240V	AC100/110V or AC200/220V 50/60Hz
Condition of output relay after activation		Selectable; self-holding or automatic reset	Selectable; self-holding or automatic reset	Self-holding	Self-holding	Automatic reset	Self-holding	Automatic reset
Test function		○	○	○	○	○	○	×
Operation display		LED digital display	LED digital display	LED light	LED light	LED light	LED light	×
*2 Open phase、reverse phase、phase unbalance detection		○	×	×	×	×	×	×
Alarm output		○	×	△	×	×	×	×
DIN rail installed		○	○	×	○	○	○	×
Display meter		Digital meter current value display	Digital meter current value display	Analog meter % display	×	×	×	×
CT (current transformer)		Built-in (for large capcity motors, external CT is used together.)	Built-in	External CT separate	Built-in (for large capcity motors, external CT is used together.)	Built-in (for large capcity motors, external CT is used together.)	Built-in	External CT separate
*4 Special models	Impact load detection	×	×	△	×	×	×	×
	1A input	×	×	△	×	×	×	×
	Lower and upper limit detection	○	×	△	×	×	×	×
*4 Additional specifications	Conforms to UL/cUL standards	×	○	×	△	×	×	×
	CE marking	○	○	×	○	×	×	×
	Conforms to CCC standards	×	○	×	△	△	×	×
	Subtropical specifications	×	×	△	×	×	×	△
	Support for abnormal voltage of control power supply	*3 ×	*3 ×	△	*3 ×	*3 ×	*3 ×	△
	Panel installation	*5 ○	×	△	×	×	×	×
	Start time modification	×	×	△	×	×	×	△
	Shock time modification	×	×	△	×	×	×	△
	Automatic reset	○	○	△	×	○	×	○

○…Standard specs △…Special MTO ×…Not available

Notes: *1. This is the added voltage fluctuation range of use in regard to nominal voltage.

*2. Open phase ····· the motor lacks 1 phase.
Phase reversal ····· the phase of the power supply to the motor becomes inverted.
Phase unbalance ····· the phase current becomes unbalanced. The maximum value of the phase current is detected when it is greater than or equal to 2 x the minimum value.

*3. Even the voltage for operation is not standard, it is possible to use the standard units if the voltage fluctuation is taken into consideration and the voltage is within the above range.

*4. For more information, refer to page 112.

*5. Panel mounting type must be selected.

Notes when selecting

1. When used with human transportation equipment or lifting devices, install a suitable protection device on that equipment/ device for safety purposes. Otherwise an accident resulting in death, serious injury or damage to equipment may occur.

2. CT (current transformer)

The CT is essential for current detection (150 Series, 50 Series only). For more information about the appropriate CT, refer to the page of each series.

3. Model Selection for Special Capacity and/or Motor Voltage.

Normally a Shock Relay can be selected by motor capacity, but when the motor capacity and/or motor voltage is special (a standard Shock Relay can be used up to a maximum of 600V), select a Shock Relay based on the rated motor current value (set current range).

4. Operation Power Source

The operation power source described in the chart is the standard. For operation power voltages other than the standard, the SS, SA and SC Series have flexible power supplies. The 150 Series with a special operation power source is available as a special MTO product.

5. Output Relay Operation

The output relay operation consists of two modes: The activation type and the reverting type when overcurrent is detected.
In the event of a power outage, make sure to switch off the machine as the sudden activation of the output relay may cause an accident or equipment damage.

1) Activation type when overcurrent is detected

The output relay is activated (contact inverts) only when overcurrent is detected.

Corresponding Models ED Series, SA Series, 150 Series, 50 Series

2) Reverting type when overcurrent is detected

When the power source for the Shock Relay is ON, the output relay is activated (contact inverts). When overcurrent is detected, the output relay reverts to its original state.

Corresponding Model SS Series

3) Activation type/ Reverting type

It is possible to switch between these two modes.

Corresponding Model SC Series

6. Self-holding and Automatic Reset

The methods used for output relay resetting are the self-holding and automatic reset types.

1) Self-holding type

Even after overcurrent has stopped, the self-holding mode continues to function. In order to return it to normal operation, push the RESET button or cut the operation power supply.

Corresponding Models SS Series, 150 Series

2) Automatic Reset Type

The output relay automatically resets after overcurrent is gone.

Corresponding Models SA Series, 50 Series

3) Self-holding Type/ Automatic Reset Type

It is possible to switch between the above two modes.

Corresponding Models ED Series, SC Series

7. Inverter Drive Applicability

1) Detection accuracy decreases but generally if it is within the 30 - 60Hz range, it should be insignificant.
2) Even within the 30 - 60Hz range, when the inverter accelerates and decelerates, and the current increases or decreases, the Shock Relay can sometimes cause an unnecessary trip. Slowly accelerate and decelerate or set it so that there is some leeway in load current within the allowable range.
3) Connect the CT to the secondary side of the inverter, but make sure to connect the Shock Relay operation power source to a commercial power source (never connect it to the secondary side of the inverter).

8. Note

When the inertia of the equipment/ machine is large or the speed reduction ratio from the motor is large, the Shock Relay may sometimes not work.
Conduct a trial test first before putting it into regular use.

⚠ Refer to the manual for further details.

Outline of Special Models and Additional Specifications (Special models are available based on the 150 or 50 Series.)

Special models	Outline of specifications	Special unit model
Impact load detection	Separately from the usual overload, abnormally large current is instantly detected and outputted. Impact load settings can be set from 30%-300%. Impact load shock time is within 0.05s. Other functions and outline dimensions conform to product standards.	TSB151M TSB152M
1A input	When the secondary side of CT is 1A, it can input directly to the Shock Relay. (It's not necessary to consider motor capacity.) Other specifications and outline dimensions conform to product standards.	TSB152C
Upper-lower limit detection	Detects both overload and under-loads; however, because there is 1 output relay, it cannot distinguish between upper and lower limits.	TSB151W TSB152W

Additional specifications	Outline of specifications	Order symbol
Subtropical specifications	Can be used when ambient humidity is 90% RH and below. Other specifications conform to standard products.	S
Support for abnormal voltage of control power supply	Power source voltage: AC230V, AC240V, AC115V, AC120V (please contact us for more information on other voltages)	V
Panel installation	It can be mounted on the control panel surface and operated.	P
Start time modification	The integral multiple can be extended for a maximum of 60 seconds. The front panel scale becomes an integral multiple (x2, x3 ···). Other specifications conform to standard products.	T1
Shock time modification	The integral multiple can be extended for a maximum of 60 seconds. The front panel scale becomes an integral multiple (x2, x3 ···). Other specifications conform to standard products.	T2
Automatic reset	For the 150 Series only, the self-holding output relay can be changed to automatic reset.	H

Shock Relay SC Series

Features

Communication function which makes central monitoring of load in process possible

It is possible to check the condition of the Shock Relay at each process and perform setting changes remotely by using monitoring software (PCON).

4 to 20mA output

It is possible to check /analyze the load by performing an action adjusted to the actual load, or recording into the recorder.

Face mount (Panel type)

Panel type face mounting is available. The display portion can be separated from main unit, and can be installed at the control box panel.

Under current detection

Either alarm output or undercurrent detection output contact can be selected.

Maintenance indicator

Set the operational time until the next maintenance, and a notification will be given when the time is reached.

Thermal Energy (Inverse time characteristic)

Switch to electrical thermal energy to protect the motor from burnout.

CE marking

Conformed RoHS

Works with an inverter*

It is possible to detect current during inverter driving at frequencies of 20 to 200 Hz with high accuracy.

* To prevent unnecessary operation of the shock relay due to the increase in current during acceleration/deceleration, accelerate or decelerate slowly or allow a margin in the preset current.

All-in-one type

TSBSCB06
TSBSCB34
TSBSCB60

Panel type

TSBSCS06 + TSBSCD + TSBSCC05 to 30
TSBSCS34 + TSBSCD + TSBSCC05 to 30
TSBSCS60 + TSBSCD + TSBSCC05 to 30

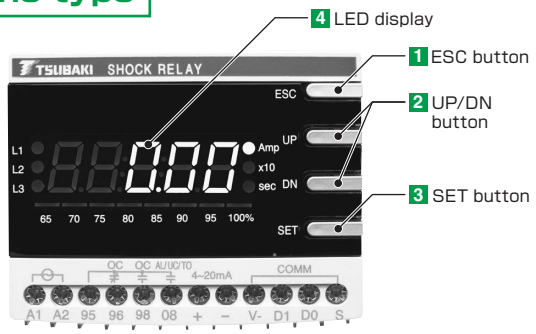
Standard specifications

					TSBSCB06	TSBSCB34	TSBSCB60
Model No.			All-in-one type		TSBSCB06	TSBSCB34	TSBSCB60
			Panel type		TSBSCS06	TSBSCS34	TSBSCS60
Motor	200V class	Number of wires pass through the CT hole		4t	0.1kW	—	—
				2t	0.2, 0.4kW	1.5, 2.2kW	—
				1t	0.75kW	3.7, 5.5kW	7.5, 11kW
	400V class			4t	0.2kW	—	—
				2t	0.4, 0.75kW	2.2, 3.7, 5.5kW	—
				1t	1.5kW	7.5, 11kW	15, 18.5, 22kW
Frequency of detect current					20 to 200Hz		
Maximum voltage of motor circuit					AC690V 50/60Hz		
Operational power source					100 to 240VAC±10%, 50/60Hz		
Protection function	Overcurrent setting	Number of wires pass through the CT hole		4t	0.15 to 1.60A (0.01A)	—	( ): Increment
				2t	0.30 to 3.20A (0.02A)	3.00 to 17.0A (0.1A)	—
				1t	0.60 to 6.40A (0.04A)	6.00 to 34.0A (0.2A)	10.00 to 60.0A (0.4A)
	Start time				0 to 12.0s (0.2s and larger: Increment 0.1s)		
	Shock time				0.2 to 5.0s (Increment 0.1s)		
	Accuracy	Current detection accuracy			±5% (In case of commercial power source)		
		Time detection accuracy			±5%		
	Under current				Trip at 0.2 to 5s (OFF: No action)		
	Lock when starting up				Set at 2 to 8 times of overcurrent setting value (OFF: No action) Trip after Start time + 0.2s when starting up.		
	Lock when operating				Set at 1.5 to 8 times of overcurrent setting value (OFF: No action), trip at 0.2 to 5s.		
	Phase-reversal				Trip within 0.15s, (OFF: No action)		
	Phase loss				Trip at 0.5 to 5s (OFF: No action)		
	Imbalance				Trip at 1 to 10s (OFF: No action) when setting at 10 to 50%		
	Alarm				Output when A, F and H are set (OFF: No action)		
	Running hour				Trip when 10 to 9990hr is set (OFF: No action)		
	Fail-safe				Activated when setting ON (Conducting normally: Excited, Trip: Non-excited)		
Output relay	Rated load				3A,250VAC (cosϕ = 1)		
	Minimum allowable load *1				DC24V, 4mA		
	Life				Activation 100,000times at rated load		
	Contact arrangement				OC:1c,AL/UC/TO:1a		
	Reset	Self-holding			E-r: Manual release or reset of power source, H-r: Only manual release		
		Auto-reset			A-r: Auto-reset and set the return time at 0.2s to 20min		
Analog output					Analog output 4 to 20mA DC Output (OFF: No action) Allowable load resistance: 100Ω and below		
Communication output					RS485/Modbus		
Insulation resistance (Between housing-circuit)					DC500V 10MΩ		
Dielectric strength voltage	Between housing-circuit				2000VAC 60Hz 1min.		
	Between relay contacts				1000VAC 60Hz 1min.		
Use environment	Place				Indoors, where it will not get wet		
	Ambient temperature				− 20 to + 60 °C		
	Ambient humidity				30 to 85%RH (No dew condensation)		
	Altitude				2000m and below		
	Atmosphere				No corrosive gas, oil-mist or dust		
	Vibration				5.9m/s^2 and below		
Power consumption					7VA and below		
Approx. mass					0.3kg and below		

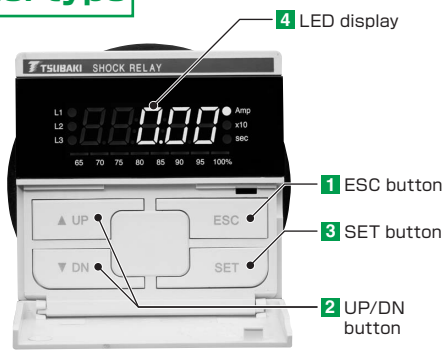
*1: In case inputting the output relay contact to programmable controller (PLC) directly, input through the relay for minute current, because contact failure may happen due to minute current.

Part names and Functions

All-in-one type



Panel type



1 ESC button (reset)

Releases the trip or returns back to the initial setting display.
Pushing the reset button after completing parameter settings to return back to initial screen.

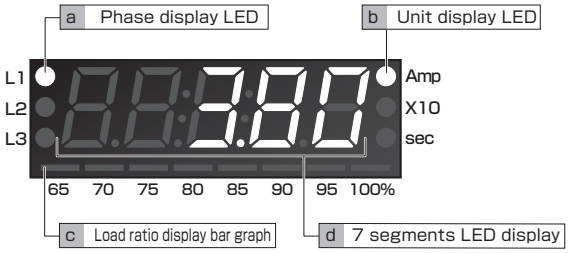
2 UP/DN button (UP/DOWN)

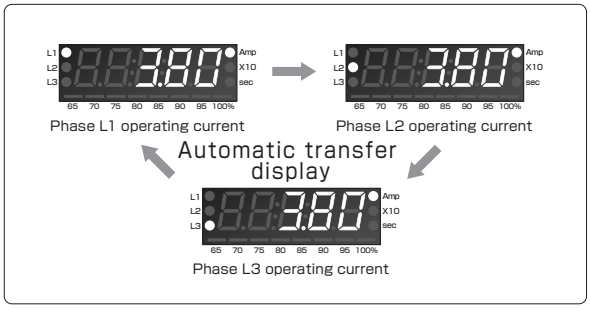
Switch to parameter mode and change data settings.

3 SET button (set)

Confirm and register parameter setting data.

4 LED display





a. Phase display LED
Displays the phase (L1(R)→L2(S)→L3(T)) which shows the current, changes every 2 seconds.

b. Unit display LED
LED which Indicates the unit.

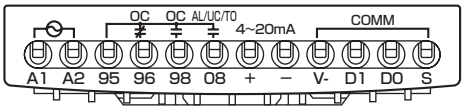
c. Load ratio display bar graph
Can be utilized as a guide when setting OC (Overcurrent setting value).
Displays the ratio as a percentage (%); Operational load current/OC current setting value

d. 7 segment LED
Displays operation current, parameter setting value, cause of trip, etc.

● Digital ammeter functions

1) While in normal operation, it is possible to change the displayed phase, and set it by pushing the SET button. Release by pushing the ESC button.
2) Trip record (3 most recent) can be viewed by pushing and holding the ESC button 5 sec. or longer. Push the UP/DN buttons to cycle through and confirm current values (cycles L1 →L2→L3→L1→...) . The order of the trip record appears on a bar graph in the order of 100%, 95%, and 90% for easy confirmation. Release by pushing the ESC button.

5 Terminal arrangement



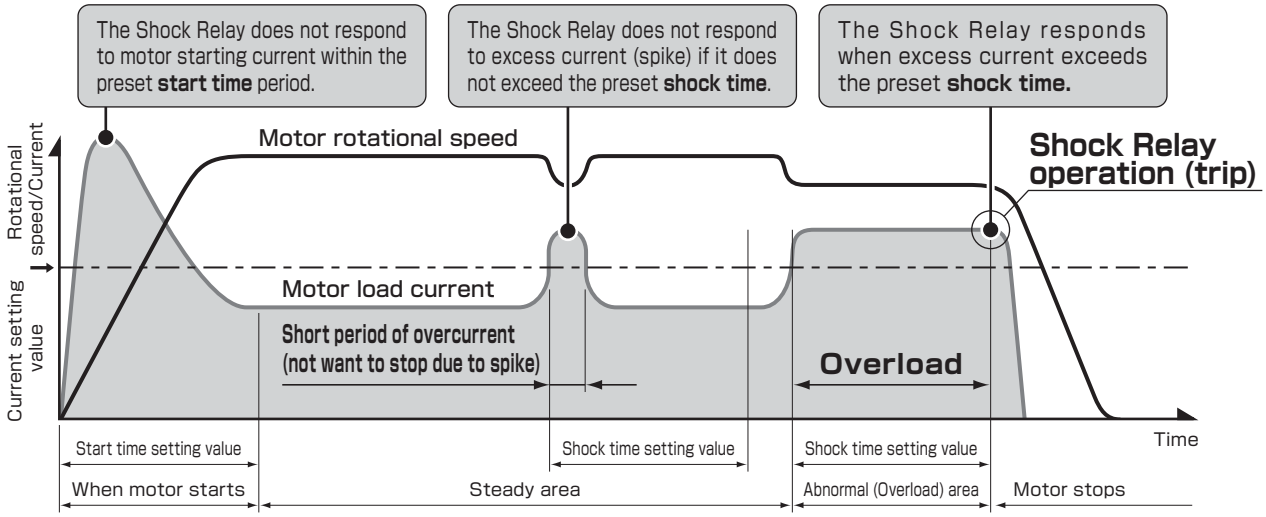
Applicable wire

Wire: ISO 1 to 25mm², AWG#18 to 1475℃ copper wire
Strip length: 8mm
No. of connectable wires: Up to 2 for one terminal
Tightening torque: 0.8 to 1.2N・m

Terminal symbol	Function	Explanation
A1, A2	Operational power source	Connect AC100 to 240V, commercial power source
95	Common terminal	Terminal 96, 98, 08 common
96	OC output	b contact: Normal-close, Overcurrent-open (In case FS:OFF)
98		a contact: Normal-open, Overcurrent-close (In case FS:OFF)
08	AL/TO/UL output	Alarm output/Running hour output/Undercurrent output
+	Analog output	Output analog current DC4 to 20mA
−		
V-, D1, D0, S	Terminal for communication	Connect when using communication function.

Operating mode

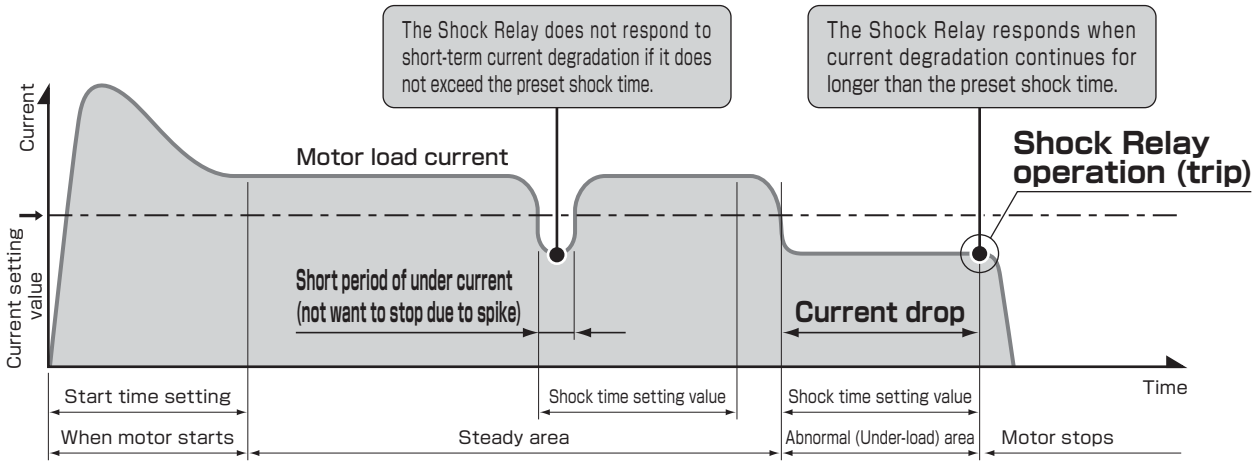
Overload operating mode



Light load operation (Under-load detection) mode

Once the motor current falls below the preset level, under-load is detected and a signal is sent to stop the motor.

*However, in case of the under-load detection, the output contact becomes choice either alarm output.



Model No.

All-in-one type

Main unit

TSBSCB06

- TSB: Shock Relay
- SC: SC Series
- B: Type B: All-in-one type
- 06: Load current (Maximum setting current value) 06 : 6A, 34 : 34A, 60 : 60A

External CT (for SC Series only)

In case current setting range is over 60A, use with TSBSCB/S06 as a set.

TSB3CTC100

- TSB: Shock Relay
- 3CT: 3 Phase CT
- C: For SC Series
- 100: Rated primary current 100 : 100A, 200 : 200A, 300 : 300A

Panel type

Main unit (special for Panel type)

TSBSCS06

- TSB: Shock Relay
- SC: SC Series
- S: Type S: Panel type
- 06: Load current (Maximum setting current value) 06 : 6A, 34 : 34A, 60 : 60A

Panel unit (special for Panel type)

TSBSCD

- TSB: Shock Relay
- SC: SC Series
- D: Panel

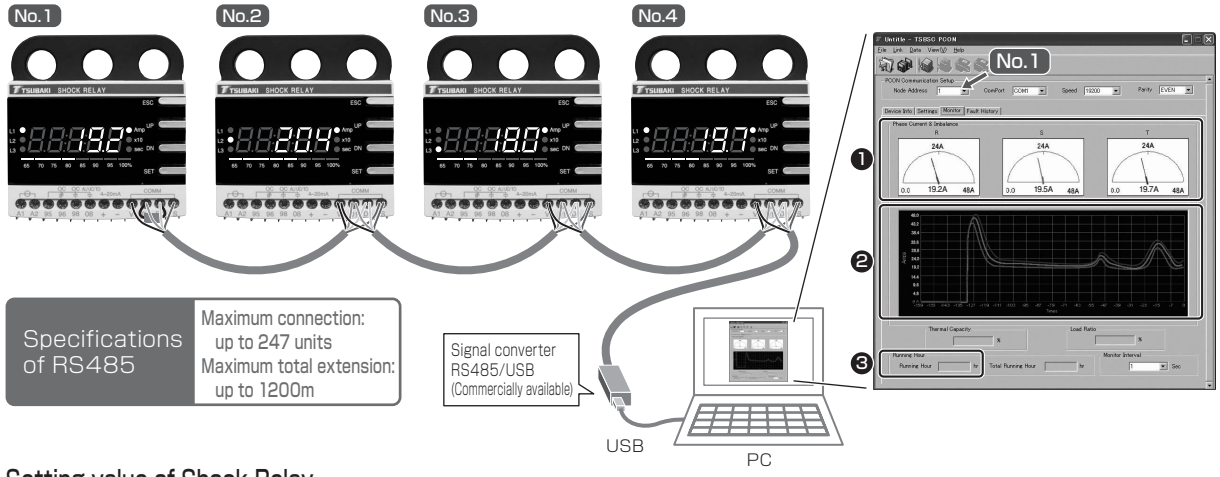
Cable (special for Panel type)

TSBSCC05

- TSB: Shock Relay
- SC: SC Series
- C: Cable
- 05: Cable length 05 : 0.5m, 10 : 1.0m, 15 : 1.5m, 20 : 2.0m, 30 : 3.0m

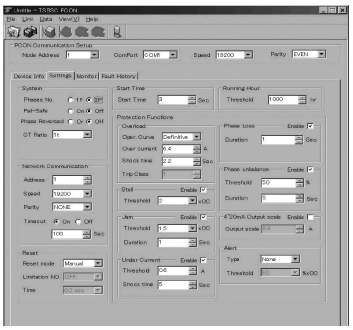
Specific function of SC Series

Communication function



Specifications of RS485	Maximum connection: up to 247 units Maximum total extension: up to 1200m

Setting value of Shock Relay



1) "Read-in setting values"
Read-in the setting values from a specified Shock Relay address and display them on the PC screen.

2) "Writing setting values"
Setting values edited on the PC can be written to a specified Shock Relay address.

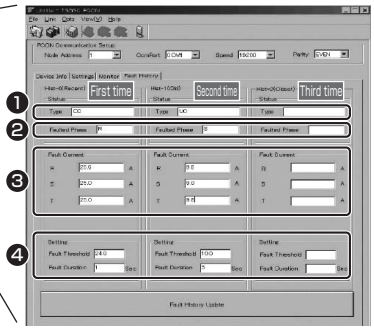
3) "Back up of setting values"
Setting values edited on the PC can be backed up to a text file.

❶ **"Remote control"** — Display the current of each phase L1, L2 and L3 on the PC screen by reading them from specified Shock Relay address.

❷ "Display current change" — Plot the current value of each phase at specified intervals. Data for the last 159 times can be displayed.

❸ "Display accumulated operation time" — Can be utilized for equipment maintenance such as oil filling, filter cleaning etc.

Record of trip



"Trip record on last 3 times"

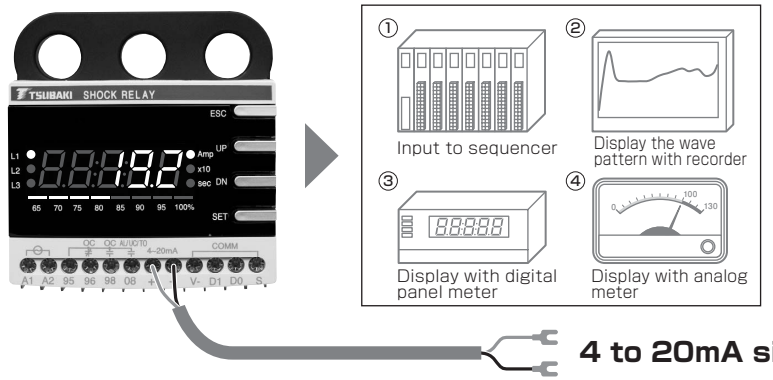
Trip record on last 3 times of Shock Relay of designed address is displayed on the screen monitor

❶ "Cause of the trouble" ❸ "Current value when trouble happened"
❷ "Phase caused trouble" ❹ "Setting value when trouble happened"

4 to 20mA analog signal

"What is a 4 to 20mA analog signal?"

A 4 to 20 mA analog signal is a standard instrumentation signal used around the world.
Instrumentation signal:
・Voltage signal: DC 0 to 5 V, DC 0 to 10 V, etc.
・Current signal: DC 4 to 20 mA, DC 0 to 20 mA, etc.
Current signals are less susceptible to influence from noise than voltage signals.
In addition, DC 4 to 20 mA, when compared to DC 0 to 20 mA, is more precise in the event of wire disruption or breaks. Therefore, DC 4 to 20 mA is used frequently, specifically in the case of long transmission distances (several tens of meters) or in answer to requests for reducing noise influence..



<Example of application>
①Automatic control of the input and viscosity depending on the load by inputting the load current of a crusher or mixer to the sequencer.
②Figuring out the operation and loading conditions for the equipment by recording the load current of a trial unit, and using it as the basis for an optimal equipment design.
③, ④Activation of a digital and analog meter with DC 4 to 20 mA signal for remote centralized monitoring of pumps, etc.

In the case of TSBSCB60 (Max. 60A), it is possible to transmit DC 0 to 60 A as a DC 4 to 20 mA signal. In addition, output value correction is available due to the scaling adjustment function of the DC 4 to 20mA output of the TSBSC Series.

Setup steps

Item	Operation button	Operation instruction
1. Selection of parameter	UP/DN	Select the setting parameter by pushing the UP/DN button.
2. Preparation for setting	SET	The setting value begins blinking when the SET button is pushed after selecting a parameter.
3. Selection of setting	UP/DN	Push the UP/DN button until the desired setting value is shown.
4. Register of setting	SET	Press the SET button after selecting the setting value, the blinking value indication returns to normal and the setting value is registered.
5. Initial indication	ESC	Push the ESC button to return to the initial indication after completing the settings. In the case that no button is pushed, returns to initial indication automatically after 50 seconds.

Parameter

No.	Menu	Parameter		Explanation of function
		Initial Value	Setting Value	
1	Parameter lock	PE: 0	0	All parameter settings are possible.
			1	To lock parameter settings, input "1" for every parameter set. To unlock the setting, input "1", then "0". When PE:--- is displayed, the setting is completed.
2	Selection of phase No.	Ph:3Ph	3Ph	Monitoring 3 phase motor
			1Ph	Monitoring single phase motor.
3	Operation curve	tcc:dE	dE	Operates with definite time characteristic.
			th	Operates with inverse time characteristic and is cumulative as in the case of thermal characteristic. (Refer to Thermal characteristic chart on page 120.)
			In	Operates with inverse time characteristic. (Refer to Inverse characteristic chart on page 120.)
			no	Setting for disabling the upper limit detection.
4	CT ratio	ct: 1t	1t,2t,4t	Setting the number of motor wires that pass through the CT (1t: 1time, 2t: 2 times, 4t: 4 times) Type 34; only 1t and 2t, Type 60; only 1t
			100,200,300	Select when using External CT (Type 06 only)
5	Fail Safe	FS:oFF	oFF	Normal mode When a trip occurs, the relay turns ON (95-96: Open, 95-98: Closed).
			on	Fail safe mode After the power is turned on, the relay turns ON (95-96: Open, 95-98: Closed); and when a trip occurs, the relay turns OFF (95-96: Closed, 95-98: Open). * This setting becomes effective after a power reset.
6	Reverse phase detection	rP:oFF	oFF	Set to "on" when detecting phase-reversal.
			on	
7	Over current threshold	oc:5.40	See the right	Set the current value for overcurrent. For type 34 and 60, the current value cannot be set over 32A for inverse time characteristics "th" and "In" . ● Current setting table Unit: (A)

CT Ratio	06 type		34 type		60 type	
	Setting range	Increments	Setting range	Increments	Setting range	Increments
1t	0.60 to 6.40	0.04	6.00 to 34.0	0.2	10.0 to 60.0	0.4
2t	0.30 to 3.20	0.02	3.00 to 17.0	0.1		
4t	0.15 to 1.60	0.01				
100	12.0 to 128	1				
200	24.0 to 256	1				
300	36.0 to 384	1				

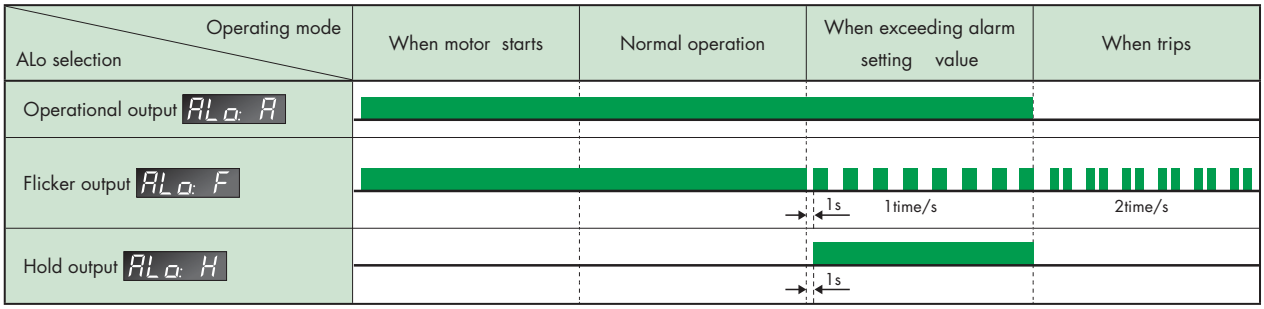
Parameter

No.	Menu	Parameter		Explanation of function
		Initial Value	Setting Value	
8	Start time	dt: 02.	0	When setting the inverse time characteristic "In", be aware that it operates in Cold characteristic from the starting of the motor until the current becomes lower than OC setting, and then operates in Hot characteristic after that.
			0.2 to 12.0s	The relay does not output within the time setting, so as to not operate when the motor starts. When inverse time characteristic "In" is set, it operates in Hot characteristic after Start time.
9	Over current Shock time	ot: 02.	0.2 to 5.0s	Set continuous overloading time of the overcurrent setting.
		cLS: 1.	1 to 30	Select the operation characteristic when inverse time characteristic "th", "In" are set. (Refer to Thermal and inverse characteristic charts)
10	Under current threshold	uc:oFF	oFF	Set current value when detecting undercurrent. This cannot be set higher than the overcurrent value. Relay output for undercurrent is as follows: Alarm ALo is set to "except uc": outputs at OC terminal Alarm ALo is set to "uc": outputs at AL/UC/TO terminals
			See the right	
11	Under current Shock time	ut: 02.	0.2 to 5.0s	Set continuous under-loading time of under-current setting.
12	Phase loss	PL:oFF	oFF	Set to "on" in the case that phase loss is detected.
			on	
13	Phase loss time	PLt:05.	0.5 to 5s	Set operation time in the case that phase loss is detected. When phase loss detection is set to oFF, it does not display.
14	Imbalance threshold	Ub:oFF	oFF	Set to 10 to 50% in case imbalance is detected. Imbalance ratio (%) = $\frac{\text{(Max.Current-Min.Current)}}{\text{Max.Current}} \times 100$
			10 to 50%	
15	Imbalance duration	Ubt: 1	1 to 10s	Set operation time in the case that an imbalance is detected. When imbalance detection is set to oFF, this does not display.
16	Stall threshold	Sc:oFF	oFF	Set the ratio against overcurrent setting in the case of detecting the lock when starting. Setting range; Sc setting value ×OC ≦ 250A. This parameter is not displayed when the start time is set to 0s.
			2 to 8 times	
17	Jam threshold	JA:oFF	oFF	Set the ratio against overcurrent setting in the case of detecting the lock when running. Setting range; JA setting value ×OC ≦ 250A.
			1.5 to 8 times	
18	Jam fault duration	Jt: 02.	0.2 to 5s	Set the operating time in the case of detecting the lock when running. When lock JA is set to oFF, it is not displayed.
19	Analog Output range	r4.20	See the right	Set the current value as analog current output scale for 20mA output. Refer to page 117 Current setting chart for setting range.
			oFF	Set when disabling analog current output.
20	Alert	ALono	no	Set when disabling alarm output.
			A	Set when enabling alarm output. Refer to the table on page 119.
			F	
			H	
			to	Set to trigger an output when the running hour is set.
			uc	Set in the case of detecting under-load.
		ALoFF	oFF	Set the ratio against the OC current when alarm outputting.
			50 to 100%	

Parameter

No.	Menu	Parameter		Explanation of function
		Initial Value	Setting Value	
21	Reset	rtE-r	E-r	Self-holding after trip, back in when power is reset or ESC button is pushed.
			H-r	Self-holding after trip, back in when ESC button is pushed.
			A-r	Automatic reset after trip.
		Ar: 05.	0.2s to 20min	Set automatic reset time
22	Reset limitation	rnoFF	oFF	There is no limit to the number of resets
			1 to 5	Set the number of reset operations (within 30 minutes).
23	Total running hour	-trh-		Display total running hours
24	Running hour	-rh-		Display operational time since inputting running hours setting time.
25	Running hour setting	rhoFF	oFF	To output the running hours, set the number of hours. The running hours will be counted from the point when the input is completed.
			10 to 99990hr	
26	Communication setting	Ad: 1	1 to 247	Set the communication address
		bP:19.2	See the right	Set the communication speed 1.2, 2.4, 4.8, 9.6, 19.2, 38.4kbps
		PrEun	odd, Evn, non	Set the parity
		LtoFF	oFF, 1 to 999s	Set the waiting time until an error is displayed when there is communication trouble.
27	Test mode	tESt		In the case that the set button is pushed when this is displayed, after 3 sec. + Shock Time, -End- is shown and relay is output.

Alarm

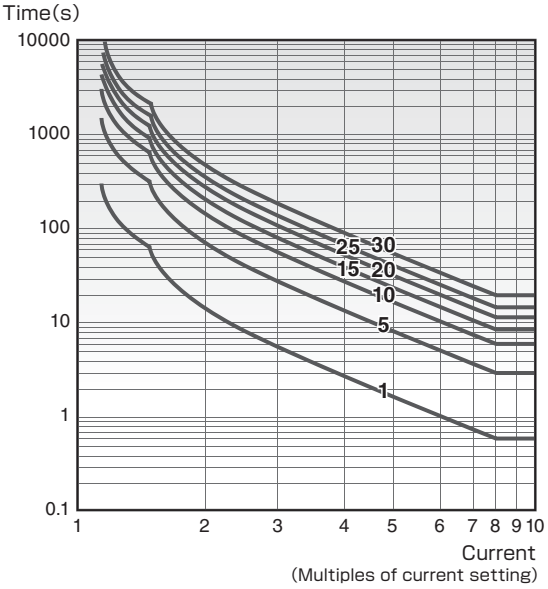


Trip display

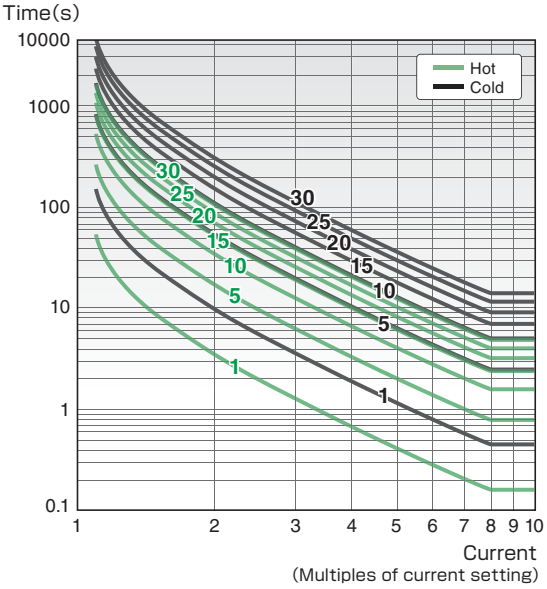
Trip function	Indication	Contents of trip	Solution
Over current	oc: 3.6	After the preset Start time period, the current exceeds the upper setting value and continues to flow longer than the preset Shock time. Trip current is 3.6A.	Check the abnormality of machine
Phase loss	PL -r	Trip due to phase loss of R(L1) phase	Check the abnormality of machine
Phase reversal	-rP-	Trip due to phase reversal	Check phase sequence with phase sequence meter
Stall (Lock when starting)	Sc:350	When the motor starts, the current exceeds Sc setting value and continues to flow longer than the preset Start time.	Check the abnormality of machine
Jam (Lock when operating)	JA:158	When motor is operating, the current exceeds Ja setting value and continues to flow longer than Jt setting time.	Check the abnormality of machine
Imbalance	Ub: 42	Current of each phase becomes imbalanced larger than the Ub setting value, and continues to remain imbalanced longer than the Ubt setting time.	Check the power source, motor and motor wiring
Under current	uc: 1.6	After the preset Start time period, the current under-runs the lower setting value and continues to flow longer than the preset Shock time. Trip current is 1.6A.	Check the abnormality of machine
Limitation of the number of auto-reset	rnFuL	Number of auto-resets after trip exceeds the setting value within 30 minutes.	Check the abnormality of machine

Inverse time characteristic charts

Thermal characteristic



Inverse characteristic



Number of motor wires that pass through the CT (current transformer) hole

Refer to the table below for the number of motor wires that pass through the CT.
The values in this table are just a guide for when the motor is used at load ratio of 80 to 100%.
In case that motor load ratio is low, increase the number of motor wires to pass through to improve the setting accuracy.
In addition, in case of motors not in the table below (small size, single phase, different voltage, etc.), select and set an appropriate model and number of motor wires that pass through the CT based on the setting current values.

3 phase AC 200V class motor		
kW	Applicable Shock Relay Model No.	Number of motor wires that pass through the CT
0.1	TSBSCB/S06	4
0.2	TSBSCB/S06	2
0.4	TSBSCB/S06	2
0.75	TSBSCB/S06	1
1.5	TSBSCB/S34	2
2.2	TSBSCB/S34	2
3.7	TSBSCB/S34	1
5.5	TSBSCB/S34	1
7.5	TSBSCB/S60	1
11	TSBSCB/S60	1
–	–	–
–	–	–
–	–	–

3 phase AC 400V class motor		
kW	Applicable Shock Relay Model No.	Number of motor wires that pass through the CT
–	–	–
0.2	TSBSCB/S06	4
0.4	TSBSCB/S06	2
0.75	TSBSCB/S06	2
1.5	TSBSCB/S06	1
2.2	TSBSCB/S34	2
3.7	TSBSCB/S34	2
5.5	TSBSCB/S34	2
7.5	TSBSCB/S34	1
11	TSBSCB/S34	1
15	TSBSCB/S60	1
18.5	TSBSCB/S60	1
22	TSBSCB/S60	1

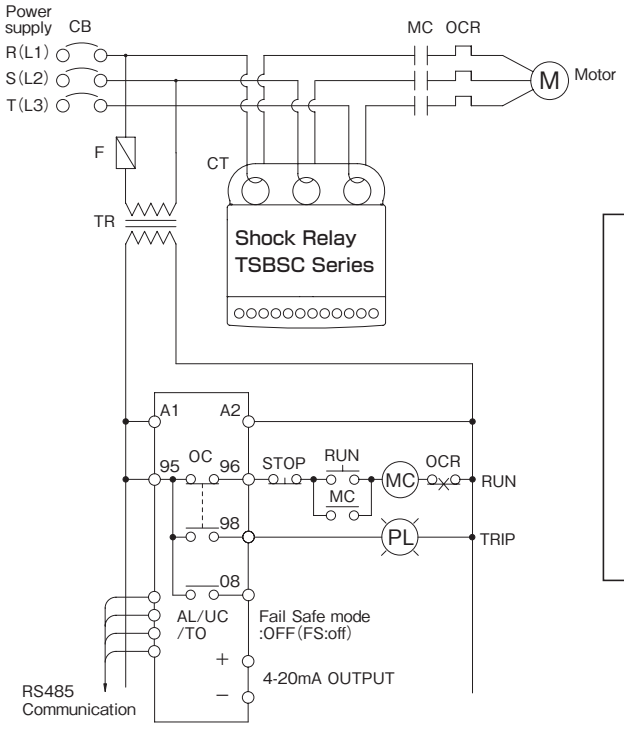
Note 1) Set the parameter "CT ratio" based on the number of motor wires that pass through the CT.
2) In case that the motor kW exceeds the above table, use external CT.

Specification of External CT

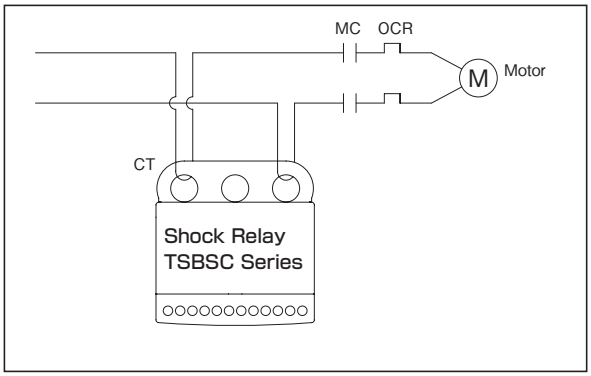
	Model No.		TSB3CTC100	TSB3CTC200	TSB3CTC300
External CT	Class		Grade 3		
	Rated primary current		100A	200A	300A
	Rated secondary current		5A		
	Rated burden		5VA		
	Rated frequency		50/60Hz		
	Approx. mass		0.9kg		
For ref.	Applicable main unit model No.		TSBSCB/S06		
	Adapted motor	200V class	15 to 18.5kW	22 to 37kW	45 to 75kW
		400V class	30 to 45kW	55 to 90kW	110 to 132kW

Connection diagram

Basic connection diagram



Single-phase motor



Note) 1. If necessary, set transformer (Tr) depending on the voltage on the Shock Relay and electromagnetic contactor (MC). Install an isolating transformer if there is any harmonic noise generating device, such as an inverter.
2. Output relay; Normal condition: not excited, Trip condition: excited
3. Coil capacity of MC connected with output relay of Shock Relay is;
Throw: less than 200VA, Hold: less than 20VA
As a guide, in case of TSBSCB60/TSBSCS60, set auxiliary relay, and activate auxiliary relay with output relay of the Shock Relay, and open/close MC with the contactor of the auxiliary relay.

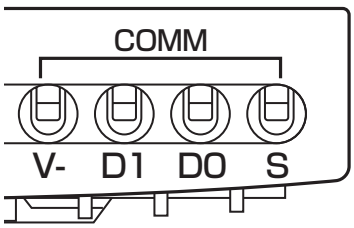
Communication function

Communication specification

Item	Content
Transmittance standards	RS-485
Max. transmittance distance	1200m (Depends on transmittance speed)
Transmittance system	Half-duplex system Protocol: modbus
Transmittance speed	1.2k to 38.4kbps

Connection with signal converter

1) Prepare a signal converter to use the monitoring software (PCON) of TSBSC.
2) Use twist cables and connect as follows.



Terminal	Signal	RS485 Terminal
V-	GND	GND
D1	Data (B)	Tx+
D0	Data (A)	Tx-
S	Shield	Shield

Communication function

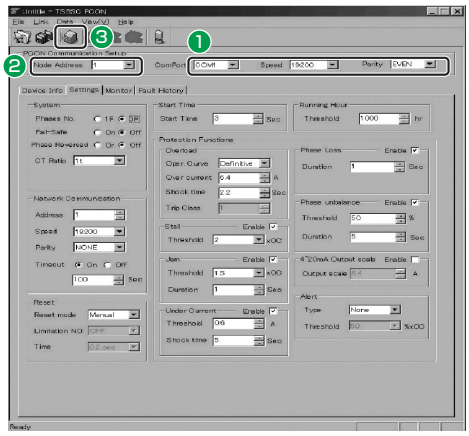
Monitoring software (PCON)

Monitoring software for PC is available.
It is possible to communicate between PC and Shock Relay through a signal converter (RS485/USB; commercially available).

Main function

The following can be performed on the PC screen;

◇ setting of the parameters for the Shock Relay
◇ monitoring of the changes in the motor current
◇ confirmation of the trip record



❶ Communication setting at PCON side
❷ Selection of the other communication party
❸ Starting of the communication

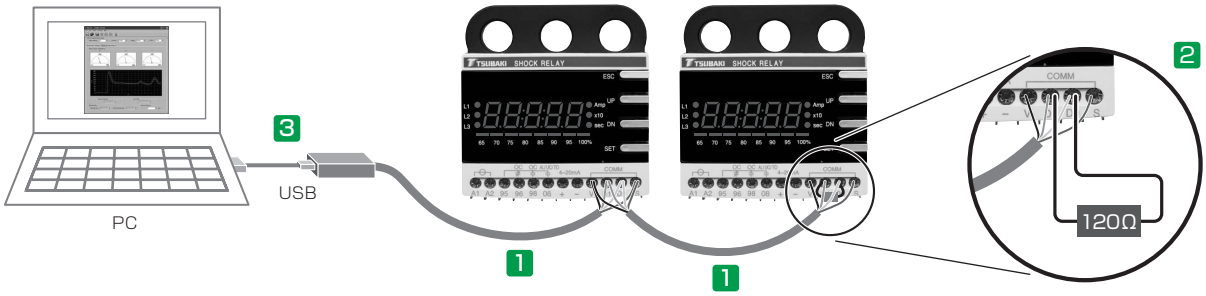
Things to prepare

① RS485/USB signal converter (commercially available)
② USB cable (commercially available; which fits the size of slot of ①)
③ Twist pair cable with shield (commercially available)
④ Terminating resistor (120Ω, 1/4W and larger)
⑤ Special monitoring software "TSBSC PCON" CD-ROM

* For ④ and ⑤, contact TEM.

Connection method

1 Connect the terminal V-, D1, D0 and S with the cable.
2 Connect the terminating resistor 120Ω between terminating terminal D1 and D0.
3 Connect the PC and the signal converter with a USB cable.



Setting the address of the main unit

Set the address and the communication method to each Shock Relay main unit in advance, before starting communication.
Set the following item by calling up parameter 26 communications setting.
Address (1 to 247), Communication speed (1.2 to 38.4kbps), Parity (EVEN, ODD, non), Communication loss time (off, 1 to 999s)

Setting of the special software "TSBSC PCON"

First, install the special monitoring software and signal converter software to the PC.

1 When the desktop icon is clicked, the software is activated, and the PCON operating display appears on screen. Set the communication settings for the PCON side to be the same as the communication method for the Shock Relay main unit. In addition, select the PC port number in which the USB cable is connected, as [ComPort].
2 Select the address of the Shock Relay of the other communication party.
3 Click the link icon to begin communication.

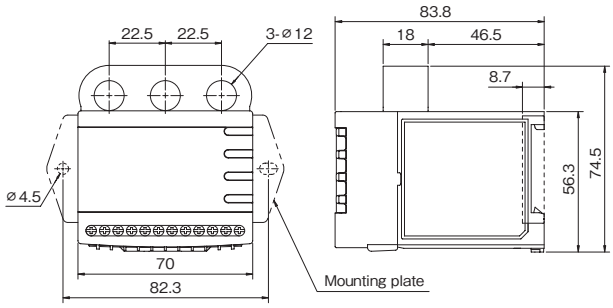
*In the case that communication with a PLC (sequencer) is necessary without using PC monitoring software, consult TEM.

Getting method of the monitoring software (PCON)

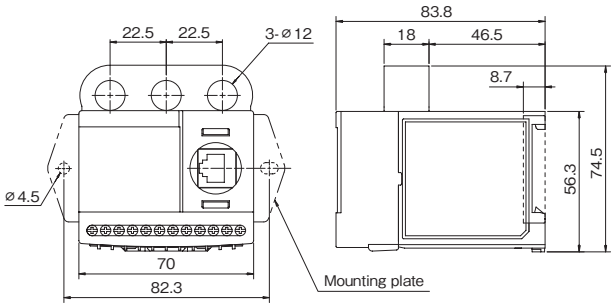
Consult TEM.

Outline dimensions

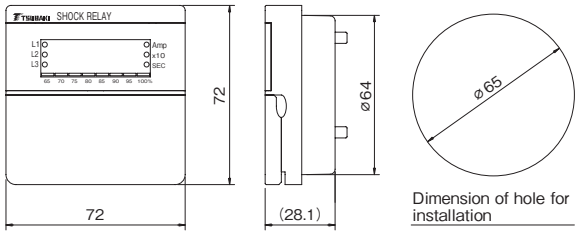
ALL-in-one type main unit
TSBSCB06, TSBSCB34, TSBSCB60



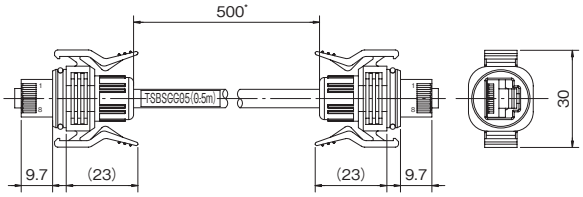
Panel type main unit
TSBSCS06, TSBSCS34, TSBSCS60



Panel unit (special for Panel type)
TSBSCD

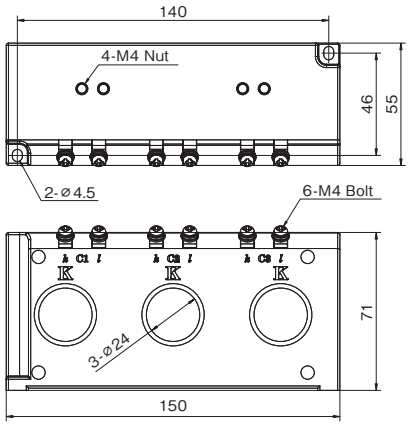


Cable (special for Panel type)
TSBSCC05, TSBSCC10, TSBSCC15, TSBSCC20, TSBSCC30



*In case of TSBSCC05 (0.5m specification)

External CT
TSB3CTC100, TSB3CTC200, TSB3CTC300



Shock Relay ED Series

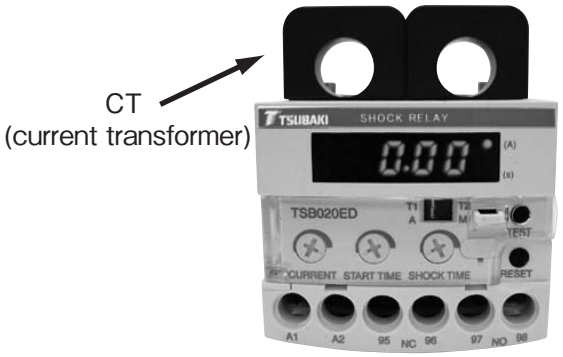
Features

- Displays both the motor current and each setting value digitally
- Economically priced
- CT included in one compact unit
- Works with inverter*

  Current can be precisely detected when inverter is operating between 20 - 200Hz.
- Choose between self-holding output relay and automatic reset
- CE marking
- UL・cUL certification
- CCC certification

*To prevent an unnecessary trip due to an increase of amperage when accelerating and decelerating, slowly accelerate and decelerate or allow some leeway for set current.

CT all-in-one model



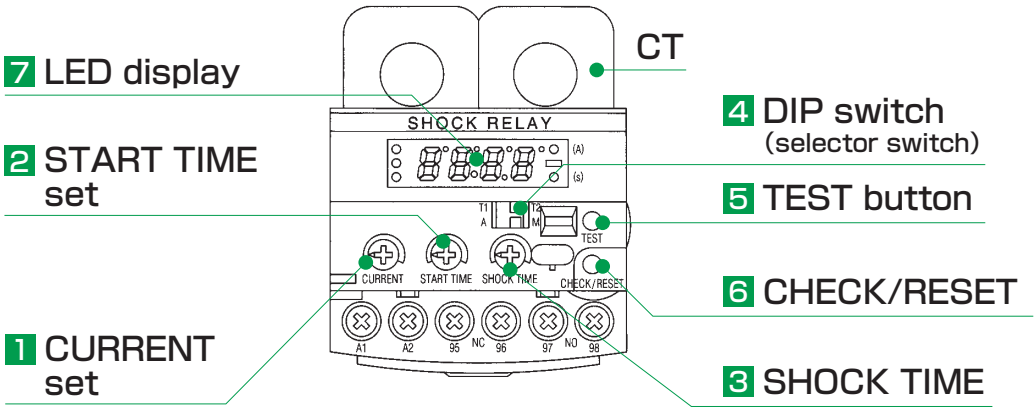
TSB020ED-1 TSB220ED-1
TSB020ED-2 TSB220ED-2
TSB075ED-1 TSB550ED-1
TSB075ED-2 TSB550ED-2

Standard Specifications

Model				Control power supply voltage 100 to 120V	TSB020ED–1	TSB075ED–1	TSB220ED–1	TSB550ED–1
				Control power supply voltage 200 to 240V	TSB020ED–2	TSB075ED–2	TSB220ED–2	TSB550ED–2
Motor	Applicable motors *1	200V class	No. of wires that pass through the CT hole, DIP switch *4	T2	0.1kW	0.4kW	1.5kW	3.7kW
				T1	0.2kW	0.75kW	2.2kW	5.5kW
		400V class	No. of wires that pass through the CT hole, DIP switch *4	T2	0.1, 0.2kW	—	2.2, 3.7kW	7.5kW
				T1	0.4, 0.75kW	1.5kW	5.5kW	11kW
	Frequency of motor current				20 to 200Hz			
	Maximum motor circuit voltage				AC600V 50/60Hz			
Operating power supply				1	100 to 120VAC±10%, 50/60Hz			
				2	200 to 240VAC±10%, 50/60Hz			
Protection functions	Overload	Current setting range *3	No. of wires that pass through the CT hole, DIP switch	T2	0.20 to 1.20A (0.01A increments)	1.20 to 3.20A (0.02A increments)	3.00 to 10.0A (0.1A increments)	6.00 to 26.0A (0.2A increments)
				T1	0.40 to 2.40A (0.02A increments)	1.80 to 5.80A (0.04A increments)	4.00 to 14.0A (0.1A increments)	9.00 to 34.0A (0.25A increments)*2
		Start time*3			0.2 to 10.0s (0.2s increments)			
		Shock time*3			0.2 to 5.0s (0.2s increments)			
	Accuracy	Current detection accuracy			±5% ±1 digit or less (except, when combined with the inverter, ±10% ±1 digit or less)			
		Temporal accuracy			±5% ±1 digit or less			
	Locked rotor start				It will trip if the set current value exceeds 200% when starting, after the set start time +0.2s has elapsed			
Output relay	Rated load				3A, 250VAC (cosϕ=1)			
	Minimum allowable load				DC24V, 4mA			
	Life span				100,000 times at rated load			
	Contact constitution				1a1b			
	Operation				Energization/normal operation: no excitation; at the time of trip: excitation			
	Reset		Trip reset, DIP switch	A	After resetting to normal current value, it takes 1s to automatically reset			
				M	Can be manually reset by pressing the "RESET" button			
Insulation	Between case and circuit				DC500V, 10MΩ			
Withstand voltage	Between case and circuit				2000VAC 60Hz: 1 minute			
	Relay contact electrodes				1000VAC 60Hz: 1 minute			
Work environment	Location				Indoors, where it will not get wet			
	Ambient temperature				−20 to +50°C			
	Ambient humidity				30 to 85%RH (no condensation)			
	Altitude				2000m or less			
Power consumption					2.0W or less			
Mass					0.25kg or less			

*1. The applicable motors are just a rough indication for reference. Make your selection based upon actual electrical current value. Select by electrical current value for single-phase motors as well.
*2. Set values 10A and higher are displayed as described on the right due to a maximum number of display digits. 10.0A→10.2A→10.5A→10.7A→11.0A
*3. A ±1 digit error can occur with the current and the set time in the range indicated.
*4. Be sure to make one turn when selecting T1 and two turns when selecting T2.

Part Names and Functions



1 Current Setting (CURRENT)
Sets current at the value at which trip occurs.

2 Start Time Setting (START TIME)
Sets start time (start compensating time). When the motor starts, there is a possibility that the motor current will exceed the set current value, but during the start time period it will not trip.

3 Shock Time Setting (SHOCK TIME)
Sets shock time (output delay time). When the motor current exceeds the set current value the count begins, and when shock time has elapsed, it will trip.

4 DIP Switch (selector switch)

Setting	Purpose	■		□	
No. of motor wires that pass through the CT T1/ T2	Current value set range selection	T1	No. of passes through the CT:1	T2	No. of passes through the CT:2
Trip reset A / M	Output relay reset selection	A	It automatically returns from the trip state 1 second after current value returns below the current setting value.	M	Trip state is maintained until the check/ reset button is pressed. It then resets.

5 TEST Button (TEST)
When the LED displays current value, pressing the TEST button will carry out an operation test.

6 CHECK/RESET Button (CHECK/RESET)
[During normal operation]
By pressing the CHECK/RESET button when the LED displays current value, it switches to the setting screen.
[During trip]
When the CHECK/RESET button is pressed, trip is cleared and the display switches to the current value.
[During set-up]
When the LED display is at the setting screen, pressing the CHECK/RESET button will switch between the current, start time, and shock time settings, in this order.

7 LED Display
Current value and set current are displayed when (A) is indicated on the display screen (to the left of the A). (A = ampere)

Current value

Current set up

Start time and shock time set up are displayed when (s) is indicated on the display screen (to the left of the s). (s = second)

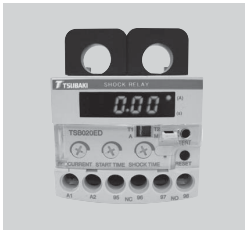
Start time set up

Shock time set up

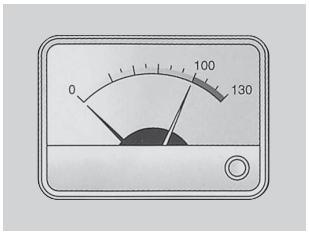
Shock Relay

The ED Series has the following features, which the Meter Relay (analog type) does not include:

- ■ Start time (starting compensation) function
- ■ Shock time (output delay) function
- ■ Compact design, includes CT
- ■ Works with inverter driving
- ■ Choose between self-holding output relay and automatic resetting
- ■ Includes test function
- ■ Detection of locked rotor start

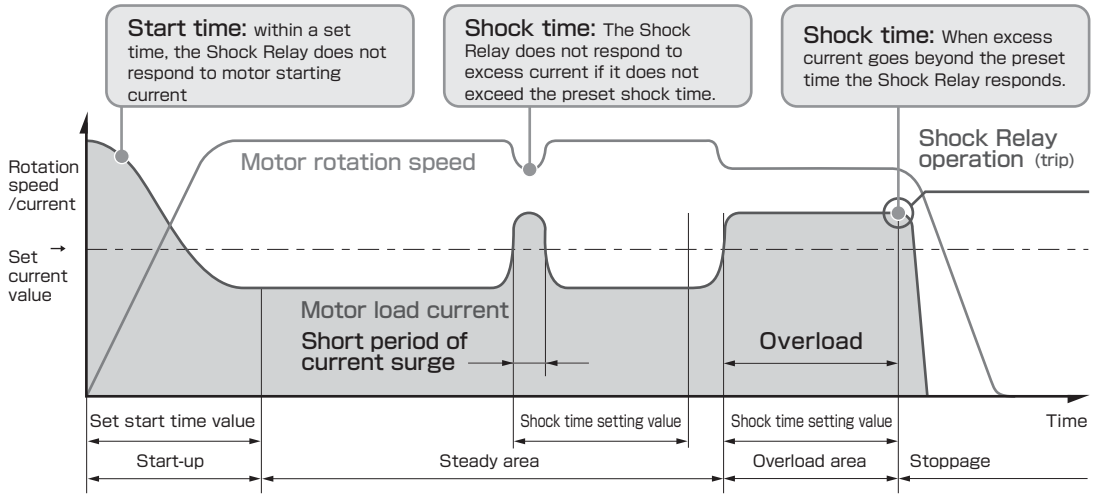


ED Series

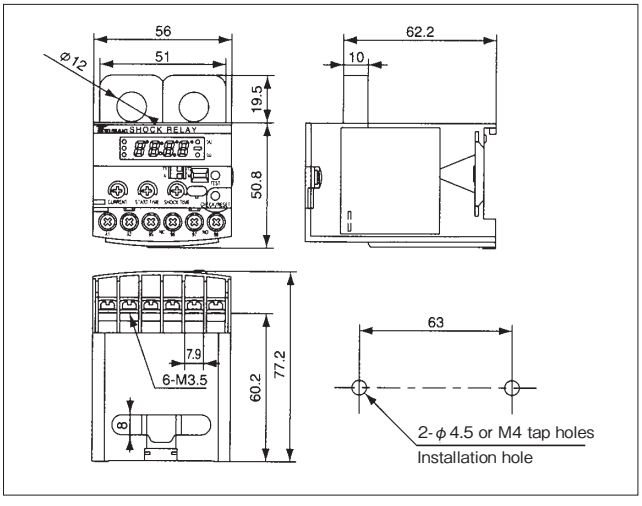


Meter Relay (analog type)

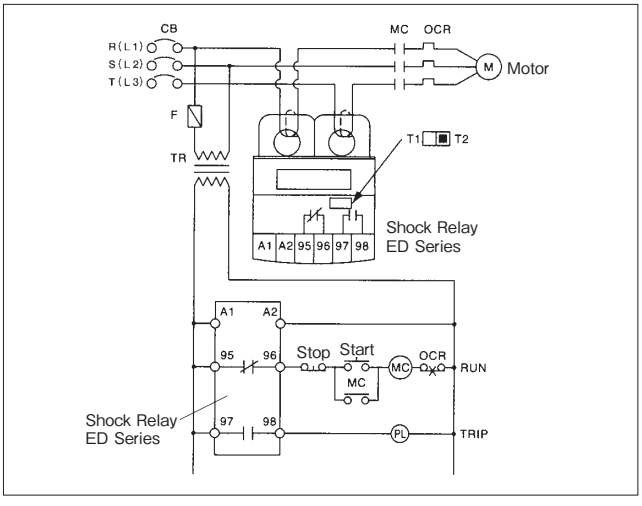
Operating Mode



Outline dimensions



Basic connection diagram



Model No.

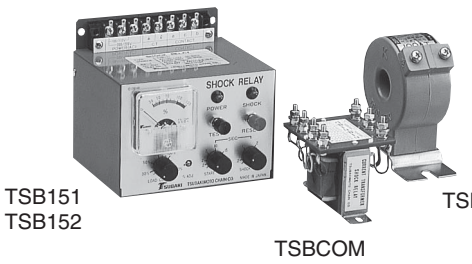
TSB020ED－1

- SHOCK RELAY
- Maximum applicable motor capacity (200V class)
  020…0.2kW　075…0.75kW
  220…2.2kW　550…5.5kW
- ED Series
- Control power supply voltage
  1…AC100V to 120V　2…AC200V to 240V

Shock Relay 150 Series

Features

1. Analog meter
2. Self-holding type
3. Special MTO models and additional specifications are available



Standard Specifications

Function \ Model			TSB151-COM	TSB152, TSB□AT*2
Common	Motor	200V class	0.2 to 3.7kW*1	5.5 to 90kW
		400V class	0.2 to 3.7kW	5.5 to 90kW
	Work environment	Ambient temperature	−10°C to 50°C	
		Relative humidity	45 to 85% RH; there is no condensation	
		Vibration	Less than 5.9m/s²	
		Height	Less than 1000m	
		Ambient atmosphere	No corrosive gas, dust	
Main Unit	Main unit model		TSB151	TSB152
	Load current (current range)*4		30 to 130% (100%=5mA)	30 to 130% (100%=5A)
	Current accuracy setting		±10% (full-scale)	
	Time setting range	Start time*4	0.2 to 20s	
		Shock time*4	0.2 to 3s	
	Control power supply voltage		AC100/110V or AC200/220V 50/60Hz ±10%	
	Max. motor circuit voltage		AC600V, 50/60Hz	
	Current detecting system		1 phase CT system	
	Output relay	Self-holding	Self-holding available	
		Normal state	Output relay not excited	
		Abnormal case	Output relay excited	
		Contact rating	1c contact, AC250V 0.2A (inductive load cosϕ=0.4)	
		Minimum applicable load*3	DC24V, 4mA	
	Output relay life-span	Mechanical	10,000,000 times	
		Electric	100,000 times	
	Test function		Included	
	Withstand voltage	Gap between circuit and housing	AC1500V, 60Hz, 1 minute (power supply circuit and contact circuit)	
		Contact gap	AC700V, 60Hz, 1 minute	
		Circuit gap	AC1500V, 60Hz, 1 minute (power supply circuit and contact circuit)	
	Mass		1.0kg	1.2kg
	Consumed power		1.2VA	
External CT	External accessory CT model		TSB COM	TSB□AT(□…Rated input current value)
	Rated input current		0.75A, 1.5A, 1.75A, 2.0A, 2.5A, 3.3A, 4.0A, 5.3A, 7.0A, 9.0A, 10.0A, 16.0A	100A, 120A, 150A, 200A, 250A, 300A
	Rated output current		5mA	5A
	Rated load		0.5VA	5VA
	Mass		0.5kg	0.6kg

Notes: *1. If the TSBCOM-A (small capacity type CT) is used, it is possible to use a less than 0.1kW motor.
*2. TSB152 and TSB□AT (CT) have different model numbers.
*3. When directly inputting output relay contact into the programmable controller (PLC), be aware that a minute electric current can cause contact failure.
As for the input to PLC, it is recommended to drive the relay coil for minute current by relay signal of Shock Relay at first, then input this relay contact to PLC.
*4. Current and time setting ranges can be set within the warranty range, but not the upper or lower level of setting volume.

Part Names and Functions

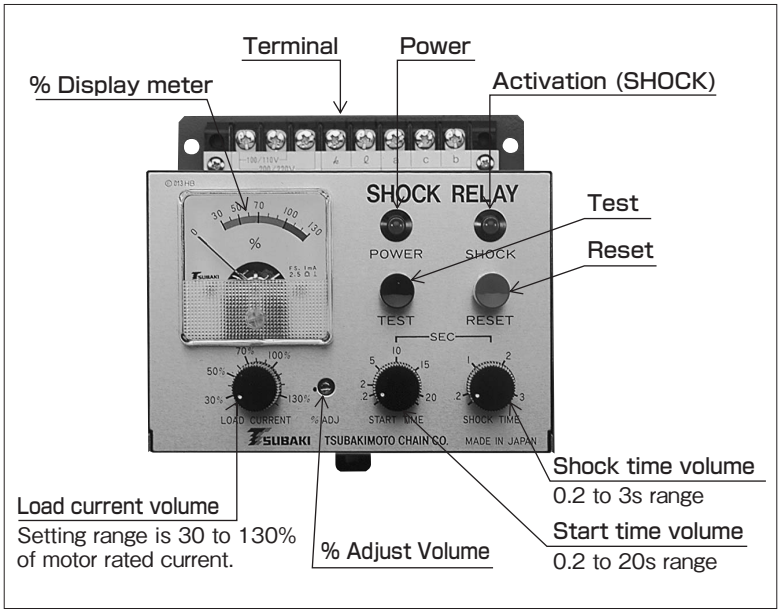
% Display Meter
The meter displays the percentage of the motor rated current vs. the motor current in operation. (The rated current here is based upon the Motor Rated Current CT selection table on page 100.)

LOAD CURRENT volume
Can be set to stop the motor at the desired level when overload occurs. When the motor current exceeds the preset CURRENT value (at the same time, overload time continues to exceed the preset SHOCK TIME), the Shock Relay activates and stops the motor.

% Adjust Volume
If the input from CT is 5mA (TSB151) or 5A (TSB152), the meter can be modified in the 95 to 130% range. Also, after adjusting the % adjuster, the meter scale indicator and load current set scale are the same.

START TIME volume
When the motor starts there is a possibility that the motor current will exceed the set current value.
To prevent the Shock Relay from tripping due to the spike in start current, start time is set a little bit longer than the period of motor start up to ignore the spike.

Terminal
The terminal is located on the upper portion of the Shock Relay, making wiring easy.



POWER indicator
The POWER indicator lights when Shock Relay is turned on.

Activation (SHOCK) indicator
The activation (SHOCK) indicator lights when the Shock Relay operates.

TEST button
Shock Relay operation can be tested stand-alone or during motor operation.

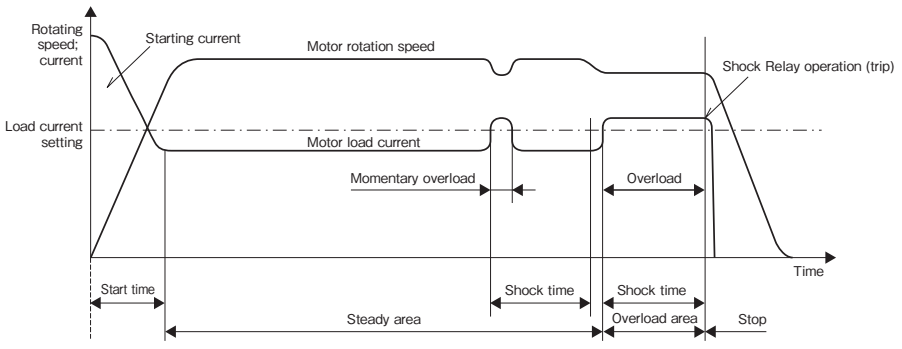
(When testing the Shock Relay, continue to press and hold the TEST button longer than the set START TIME or SHOCK TIME, whichever is longer.)

RESET button
After the Shock Relay activates, the RESET button is used to cancel the self-holding of the output contact.

SHOCK TIME volume
Shock time is the amount of time set until the Shock Relay will activate when overload occurs. Within the set time, the Shock Relay will not activate, even if it is overloaded.

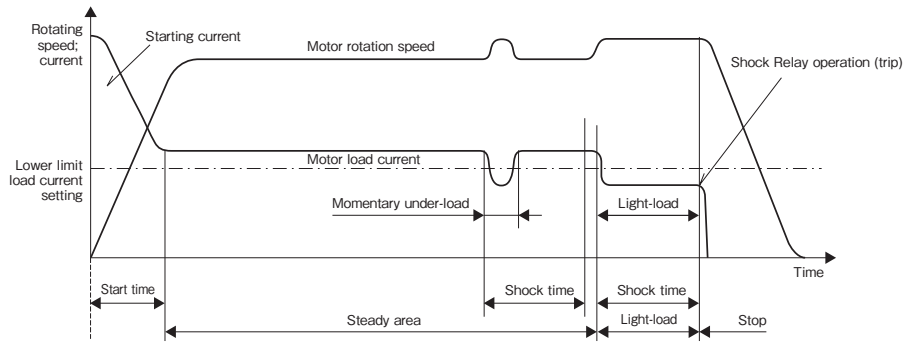
Operating mode

■ Overload operating mode



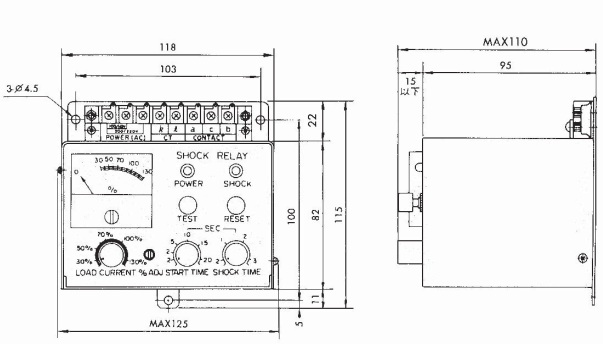
■ Light-load operating mode
TSB151W, 152W
(Lower/upper limit detector specifications)

Note: Because there is only one output relay, it is not possible to distinguish between overload operation and light-load operation.



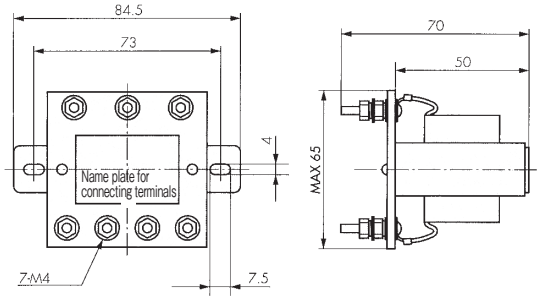
Outline dimensions

Main unit TSB151/TSB152

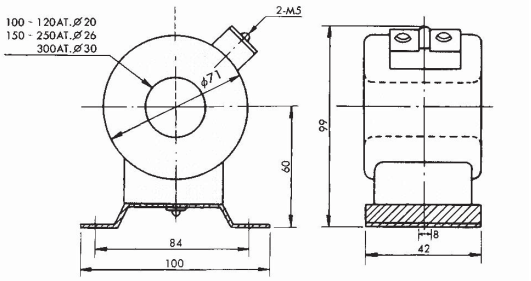


CT (current transformer)

■ Common CT TSB151
TSB COM/TSB COM-A



■ Through hole CT TSB152
TSB ☐ AT



The hatching mounting bracket's mounting location can be changed 90 degrees, so match up the holes when you change it.

Model No.

■ Motor for 3.7kW and less

TSB151 ☐ - ☐

- ☐ : Additional specifications: S, V, P, T1, T2, H
- 150 Series
  - Standard model …151
  - Special model …151M, 151W
- Shock Relay
- ☐ : Common type CT (current transformer)
  - COM…for 0.2 to 3.7kW
  - COM-A…for 0.1kW and less

■ Motor for more than 5.5kW

Main unit

TSB152 ☐

- ☐ : Additional specifications: S, V, P, T1, T2, H
- 150 Series
  - Standard model …152
  - Special model …152M, 152C, 152W
- Shock Relay

Note: Use the main unit and CT as a set.

Through hole CT

TSB ☐ AT

- ☐ : CT size

Standard model and special model additional specifications chart

Model \ Additional specifications		Subtropical spec.	Control power supply voltage modification	Panel mounting	Start time modification	Shock time modification	Auto-reset
		S	V	P	T1	T2	H
Standard	151/152	◎	◎	◎	◎	◎	◎
Impact load detection	151M/152M	◎	◎	◎	◎	◎	◎
1A input (motor capacity is not necessary to consider)	152C	◎	◎	◎	◎	◎	◎
Upper/lower limit detection	151W	◎	◎	◎	◎	◎	◎
	152W	◎	◎	◎	◎	◎	◎

Notes: 1. Refer to page 112 for detailed specifications
2. For additional specifications V, specify operation power source
3. For additional specifications T1 and T2, indicate the start time and shock time modification time.

◎ : Multiple specifications available

CT (current transformer)

■ Common CT: for motors up to and including 3.7kw

- TSB COM (standard type) can be used with 0.2 to 3.7kW motors.
- TSB COM-A (small capacity type) can be used with motors up to and including 0.1kW.

■ TSB COM (standard type)

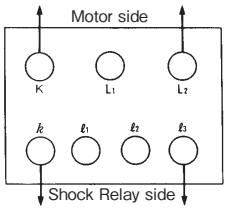
Motors (kW)	Power supply: AC200/ 220V			Power supply: AC400/ 440V		
	Motor rated current (A)	Connecting terminal		Motor rated current (A)	Connecting terminal	
		Motor side	Shock Relay side		Motor side	Shock Relay side
0.2	1.75	K-L_2	k-ℓ_1	0.75	K-L_2	ℓ_1-ℓ_2
0.4	2.5	K-L_2	k-ℓ_2	1.5	K-L_2	ℓ_2-ℓ_3
0.75	4.0	K-L_2	k-ℓ_3	2.0	L_1-L_2	ℓ_2-ℓ_3
1.5	7.0	K-L_1	k-ℓ_1	3.3	L_1-L_2	k-ℓ_2
2.2	10.0	K-L_1	k-ℓ_2	5.3	L_1-L_2	k-ℓ_3
3.7	16.0	K-L_1	k-ℓ_3	9.0	K-L_1	ℓ_1-ℓ_3

Note: Common type CT, motor side L1-L2; Shock Relay side ℓ1-ℓ2 combination, 1A output CT can be combined.

■ TSB COM-A (small capacity type)

Motor rated current (A)	Connecting terminal	
	Motor side	Shock Relay side
0.15	K-L_2	k-ℓ
0.25	K-L_2	k-ℓ
0.4	K-L_2	k-ℓ
0.6	K-L_1	k-ℓ
1.0	K-L_1	k-ℓ
1.6	K-L_1	k-ℓ

Note: Select by current value



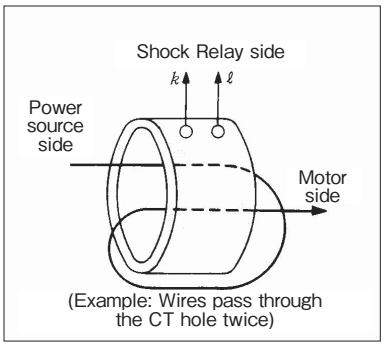
■ Through-type CT for motors 5.5kW and above

- Select a CT size applicable to motor capacity.

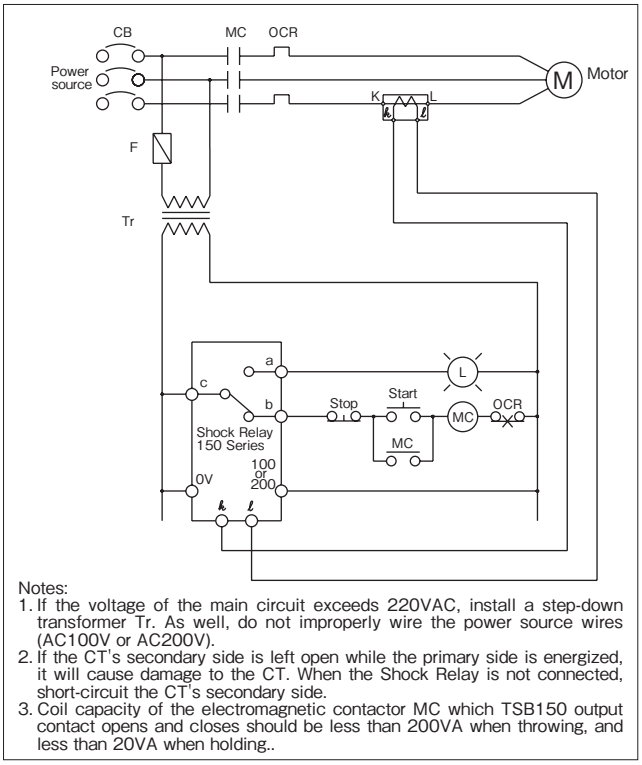
Motor (kW)	Power supply: AC200/ 220V			Power supply: AC400/ 440V		
	Motor rated current (A)	CT size	Number of wires that pass through the CT hole (T)	Motor rated current (A)	CT size	Number of wires that pass through the CT hole (T)
5.5	25	100AT	4	14	100AT	7
7.5	30	120AT	4	20	100AT	5
11	50	100AT	2	25	100AT	4
15	60	120AT	2	30	120AT	4
19	75	150AT	2	37	150AT	4
22	100	100AT	1	50	100AT	2
30	120	120AT	1	60	120AT	2
37	150	150AT	1	75	150AT	2
45	170	200AT	1	85	100AT	1
55	200	200AT	1	100	100AT	1
75	250	250AT	1	130	150AT	1
90	300	300AT	1	150	150AT	1

In the case the single-phase motor or motor capacity is not on the selection chart, use the following calculation to make your selection:

CT size ≧ motor rated current x number of wire(s) passing through the CT hole



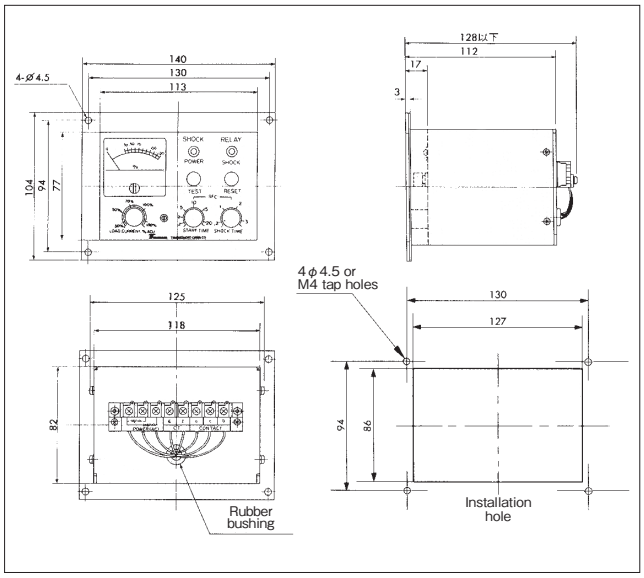
Basic connection diagram



Notes:
1. If the voltage of the main circuit exceeds 220VAC, install a step-down transformer Tr. As well, do not improperly wire the power source wires (AC100V or AC200V).
2. If the CT's secondary side is left open while the primary side is energized, it will cause damage to the CT. When the Shock Relay is not connected, short-circuit the CT's secondary side.
3. Coil capacity of the electromagnetic contactor MC which TSB150 output contact opens and closes should be less than 200VA when throwing, and less than 20VA when holding..

Special models and additional specifications

■ TSB151P, TSB152P (panel mounted type) outline dimensions



■ Notes on CT (current transformer) selection

The load current meter of the Shock Relay shows 100% at the time of the motor rated current value in the chart.
When the actual motor rated current value is not on the chart, use a CT on which the load current meter shows an 80 to 100% range when rated current flows.

Shock Relay SS Series

Features

- Output relay self-holding type
- Output relay return type when detecting over-current (fail-safe)
- Economically priced
- Broad current setting range
- High repeating accuracy
- Includes TEST/ RESET buttons
- All-in-one unit with CT (current transformer)
- Special model for the conformance to UL/cUL standards
- CE marking
- DIN rail (35mm) mountable
- Can be used with a single-phase motor
- Special model for the conformance to CCC standards

All-in-one unit with CT

CT
(current transformer)

TSBSS05
TSBSS30
TSBSS60

Externally mounted CT type

External CT
(current transformer)

TSBSS100 (TSBSS05+TSB2CT100)
TSBSS200 (TSBSS05+TSB2CT200)
TSBSS300 (TSBSS05+TSB2CT300)

Standard Specifications

Items / Model No.			TSBSS05	TSBSS30	TSBSS60	TSBSS100	TSBSS200	TSBSS300
Common	Load current (current setting range)*3		0.5 to 5A	3 to 30A	5 to 60A	10 to 100A	20 to 200A	30 to 300A
	Applicable motor capacity	200V class	0.1 to 0.75kW	1.5 to 5.5kW	7.5 to 11kW	15 to 18.5kW	22 to 37kW	45 to 75kW
		400V class	0.2 to 2.2kW	3.7 to 11kW	15 to 22kW	30 to 45kW	55 to 90kW	110 to 132kW
	Work environment	Ambient temperature	−20℃ to 60℃					
		Ambient humidity	45 to 85%RH; no condensation					
		Vibration	Less than 5.9m/s²					
		Altitude	Less than 2000m					
		Ambient atmosphere	No corrosive gas, dust					
	Unit model No.		TSBSS05	TSBSS30	TSBSS60	TSBSS05	TSBSS05	TSBSS05
	Current setting accuracy		±10% (full scale)					
Main unit	Set time range	Start time*3	*4 0.2 to 30s					
		Shock time*3	*5 0.2 to 10s					
	Control power supply voltage (L1 - L2)		AC100 to 240V, 50/60Hz					
	Maximum motor circuit voltage		AC600V, 50/60Hz					
	Current detection system		Two-phase CT system					
	Output relay *1	Self-holding	Includes self-holding					
		Normal state	At start up there is a 0.5s delay, then the output relay excites					
		Abnormal case	When it trips or the power is shut off, the output relay is not excited					
		Contact capacity	1c contact, AC240V 3A (in the case of a resistance load)					
		Minimum applicable load*2	DC10V, 10mA					
		Reset method	Press the RESET button or cut the operation power					
	Output relay life-span	Mechanical	10,000,000 times					
		Electrical	100,000 times					
	Test functions		Internal circuit and output relay operation check					
	Withstand voltage	Between the circuit and case	AC2000V, 60Hz, 1 minute (power supply circuit and contact circuit)					
		Between contacts	AC1000V, 60Hz, 1 minute					
		Between circuit	AC2000V, 60Hz, 1 minute (power supply circuit and contact circuit)					
	Gross mass		0.2kg (not including external CT)					
	Power consumption	When AC110V	2.7VA (0.35W)					
		When AC200V	11.0VA (1.2W)					
	DIN rail mounting		○			×		
	UL•cUL		*6 ×			×		
	CE		○			×		
External CT	External CT Model No.		Not needed			TSB2CT100	TSB2CT200	TSB2CT300
	Rated primary current		—			100A	200A	300A
	Rated secondary current		—			5A		
	Rated load		—			5VA		
	Mass		—			0.5kg		

Notes: *1. During normal operation the output relay is ON, and when the Shock Relay operates it is OFF (refer to page 112).
*2. When directly inputting output relay contact into the programmable controller (PLC), be aware that a minute electric current can cause contact failure. As for the input to PLC, it is recommended to drive the relay coil for minute current by relay signal of Shock Relay at first, then input this relay contact to PLC.
*3. Current and time setting ranges can be set within the warranty range, but not the upper or lower level of setting volume.
*4. Although the minimum value on the display is 5s, values smaller than 5s can be set with the dial.
*5. Although the minimum value on the display is 1s, values smaller than 1s can be set with the dial.
*6. Special model is available for the conformance to cUL and CCC standards.

Part Names and Functions

LOAD CURRENT volume (A)

Load current can be set to stop the motor at the desired level when overload occurs. When the motor current exceeds the preset CURRENT value (at the same time, overload time continues to exceed the preset SHOCK TIME), the Shock Relay activates and stops the motor.

START TIME volume (s)

When the motor starts there is a possibility that the motor current will exceed the set current value. To prevent the Shock Relay from tripping due to the spike in start current, start time is set a little bit longer than the period of motor start up to ignore the spike.

TEST button

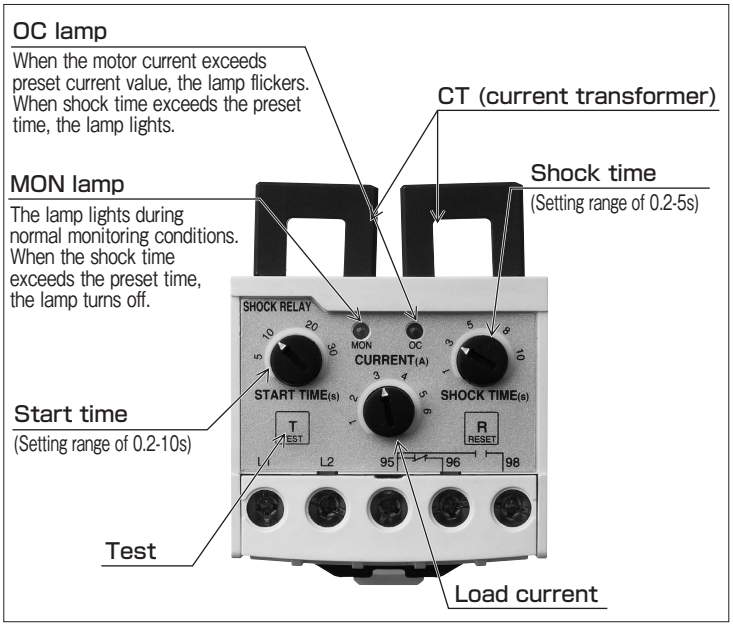
Shock Relay operation can be tested stand-alone or during motor operation.
(When testing the Shock Relay, continue to press and hold the TEST button longer than the set START TIME or SHOCK TIME, whichever is longer.)

RESET button

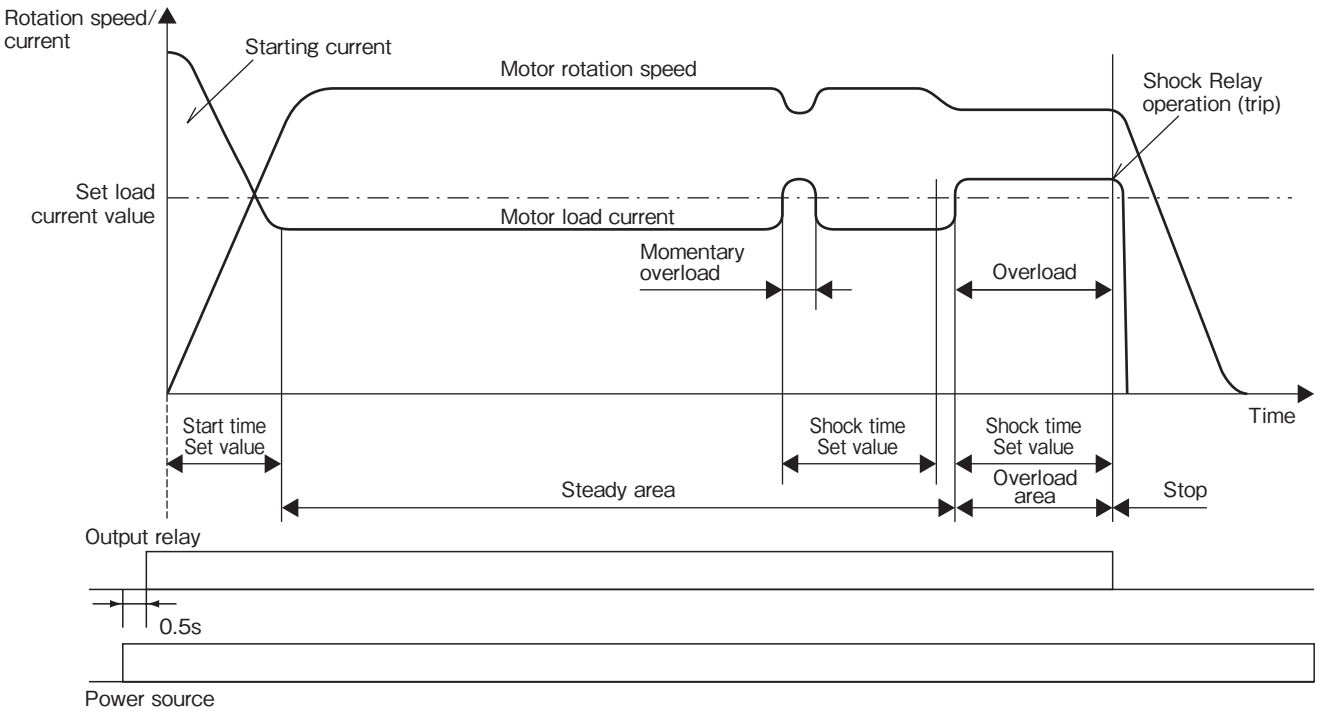
After the Shock Relay activates, the RESET button is used to cancel the self-holding of the output contact.

SHOCK TIME volume (s)

Shock time is the amount of time set until the Shock Relay will activate when overload occurs. Within the set time, the Shock Relay will not activate, even if it is overloaded.

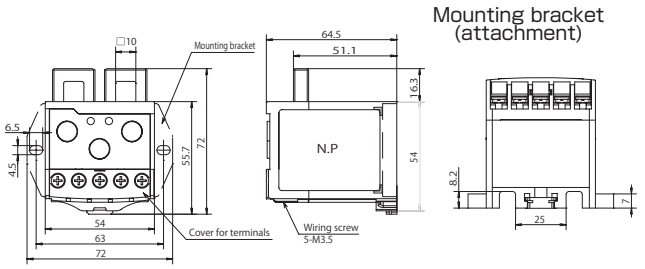


Operating Mode



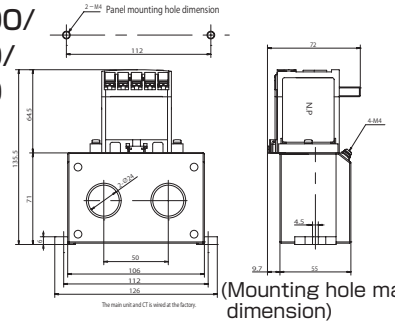
Outline dimensions

CT unit TSBSS05/TSBSS30/TSBSS60



Mass: 0.2kg

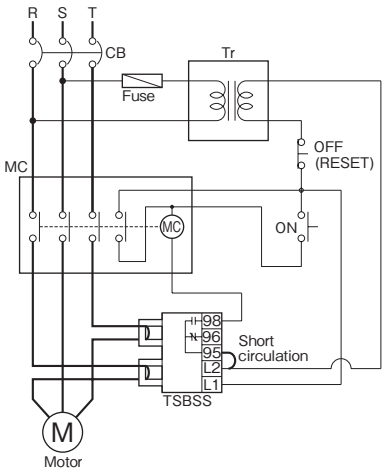
CT externally mounted type TSBBSS100/ TSBSS200/ TSBSS300



The external CT (current transformer) is wired before delivery.

Mass: 0.7kg

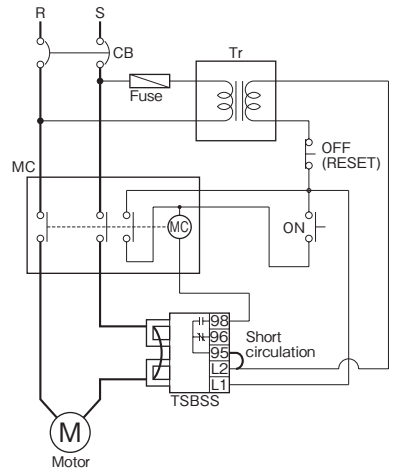
Basic connection diagram



CB : Circuit breaker
MC : Magnetic contactor
ON : Start switch
OFF : Stop switch
Fuse : Fuse
Tr : Transformer

Notes:
1. Set the transformer depending on the voltage of the Shock Relay and MC. Set the insulation transformer if there is a high-harmonic noise generator such as an inverter.
2. When it's running normally, the contact points 95-98 of the TSBSS are "closed" (95-96 are "open"), and when tripping, 95-98 are "open" (95-96 are "closed"). Coil capacity of the electromagnetic contactor MC which output contact opens and closes should be less than 200VA when throwing, and less than 20VA when holding.
3. Pass two wires out of three phases of the motor through the Shock Relay's CT in the same direction.

Single-phase motor reference schematic for when using the motor



Notes:
1. Set the transformer depending on the voltage of the Shock Relay and MC. Set the insulation transformer if there is a high-harmonic noise generator such as an inverter.
2. When it's running normally, the contact points 95-98 of the TSBSS are "closed" (95-96 are "open"), and when tripping, 95-98 are "open" (95-96 are "closed"). Coil capacity of the electromagnetic contactor MC which output contact opens and closes should be less than 200VA when throwing, and less than 20VA when holding.
3. Pass one phase through the Shock Relay's CT in the same direction.

As for the split-phase start and capacitor run motor, connect CT to the main coil side.

Notes on usage

1. During normal operation, the output relay is excited (ON). When overload is detected and the Shock Relay activates or the power supply is cut, the output relay is de-excited (OFF).
2. Pass the motor wire(s) through the CT hole the number of times referenced in the chart below. In order to increase the current setting accuracy, the number of wires that pass through the CT hole is 2 times or more for small motor currents.
   When the motor load factor is low, increase the number of wires that pass through the CT hole as necessary.
   Furthermore, when the number of the wires that pass through the CT hole is more than 2, it is necessary to convert the current scale value of current volume.
   (Ex.) When a wire passes two times through the CT, the value on the current scale should be at half value.

AC200V class motor			AC400V class motor		
Capacity (kW)	Shock Relay Model No.	No. of wires that pass through the CT hole	Capacity (kW)	Shock Relay Model No.	No. of wires that pass through the CT hole
0.1	TSBSS05	4	—	—	—
0.2	TSBSS05	3	0.2	TSBSS05	4
0.4	TSBSS05	2	0.4	TSBSS05	3
0.75	TSBSS05	1	0.75	TSBSS05	2
1.5	TSBSS30	3	1.5	TSBSS05	1
2.2	TSBSS30	2	2.2	TSBSS05	1
3.7	TSBSS30	1	3.7	TSBSS30	3
5.5	TSBSS30	1	5.5	TSBSS30	2
7.5	TSBSS60	1	7.5	TSBSS30	1
11	TSBSS60	1	11	TSBSS30	1
—	—	—	15	TSBSS60	1
—	—	—	18.5	TSBSS60	1
—	—	—	22	TSBSS60	1

3. Because products conforming to CE markings have been electro-magnetically tested for compatibility based on industrial environmental standards, they are not for household, commercial or light industrial use.

Model No.

CT Unit Type - External Mounted CT Type

TSBSS05

- TSBSS: Shock Relay
- SS Series
- 05: Load current (maximum current setting) 5A
- 30: 30A
- 60: 60A
- 100: 100A
- 200: 200A
- 300: 300A

Shock Relay SA Series

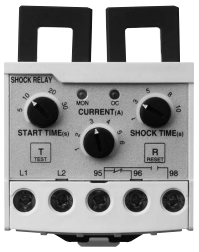
Features

- Output relay automatic return type
- Output relay activating type when detecting over-current
- Economically priced
- Accurate current setting
- High repeating accuracy
- Test function
- All-in-one unit with CT (current transformer)
- DIN rail (35mm) mountable
- Can be used with a single-phase motor
- Special model for the conformance to CCC standards

All-in-one unit with CT

CT
(current transformer)

TSBSA05
TSBSA10
TSBSA30
TSBSA60



Externally mounted CT type

External CT
(current transformer)

TSBSA100 (TSBSA05+TSB2CT100)
TSBSA200 (TSBSA05+TSB2CT200)
TSBSA300 (TSBSA05+TSB2CT300)

Standard specifications

Function / Model			TSBSA05	TSBSA10	TSBSA30	TSBSA60	TSBSA100	TSBSA200	TSBSA300
Common	Load current (current setting range)*3		0.5 to 5A	1 to 10A	3 to 30A	5 to 60A	10 to 100A	20 to 200A	30 to 300A
	Motor capacity	200V class	0.1 to 0.75kW	1.5 to 2.2kW	3.7 to 5.5kW	7.5 to 11kW	15 to 18.5kW	22 to 37kW	45 to 75kW
		400V class	0.2 to 2.2kW	3.7kW	5.5 to 11kW	15 to 22kW	30 to 45kW	55 to 90kW	110 to 132kW
	Work environment	Ambient temperature	−20°C to 60°C						
		Ambient humidity	45 to 85%RH: no condensation						
		Vibration	Less than 5.9m/s²						
		Altitude	Less than 2000m						
		Atmosphere	No corrosive gas or dust						
Main Unit	Unit model		TSBSA05	TSBSA10	TSBSA30	TSBSA60	TSBSA05	TSBSA05	TSBSA05
	Current setting accuracy		±10% (full-scale)						
	Time setting range	Start time*3	*4 0.2 to 10s						
		Shock time*3	*4 0.2 to 5s						
	Operation power source (A1−A2)		AC100 to 240V, 50/60Hz						
	Maximum motor circuit voltage		AC600V, 50/60Hz						
	Current detection system		2 phase CT system						
	Output relay *1	Self-holding	No self-holding (automatically returns after 1s)						
		Normal state	Output relay is not excited						
		Abnormal case	Output relay is excited						
		Contact capacity	0.2A AC250V cos ϕ =0.4						
		Minimum applicable load*2	DC10V, 10mA						
	Output relay life span	Mechanical	10,000,000 times						
		Electrical	100,000 times						
	Test functions		Internal circuit and output relay operation verification						
	Withstand voltage	Between the circuit and case	AC2000V, 60Hz, 1 minute (power supply circuit and contact circuit)						
		Between contacts	AC 1000V, 60Hz, 1 minute						
		Between circuits	AC2000V, 60Hz, 1 minute (power supply circuit and contact circuit)						
	Mass		0.2kg (excluding external CT)						
	Power consumption	When AC110V	2.7VA (0.35W)						
		When AC200V	11.0VA (1.2W)						
	DIN rail mounting		○				×		
External CT	External CT Model No.		Not needed				TSB2CT100	TSB2CT200	TSB2CT300
	Rated primary current		—				100A	200A	300A
	Rated secondary current		—				5A		
	Rated load		—				5VA		
	Mass		—				0.5kg		

Notes: *1. The operation of the TSBSA Series is the complete opposite of the TSBSS Series.
*2. When directly inputting output relay contact into the programmable controller (PLC), be aware that a minute electric current can cause contact failure.
As for the input to PLC, it is recommended to drive the relay coil for minute current by relay signal of Shock Relay at first, then input this relay contact to PLC.
*3. Current and time setting ranges can be set within the warranty range, but not the upper or lower level of setting volume.
*4. Although the minimum value on the display is 1s, values smaller than 1s can be set with the dial.
*5. Special model is available for the conformance to CCC standards.

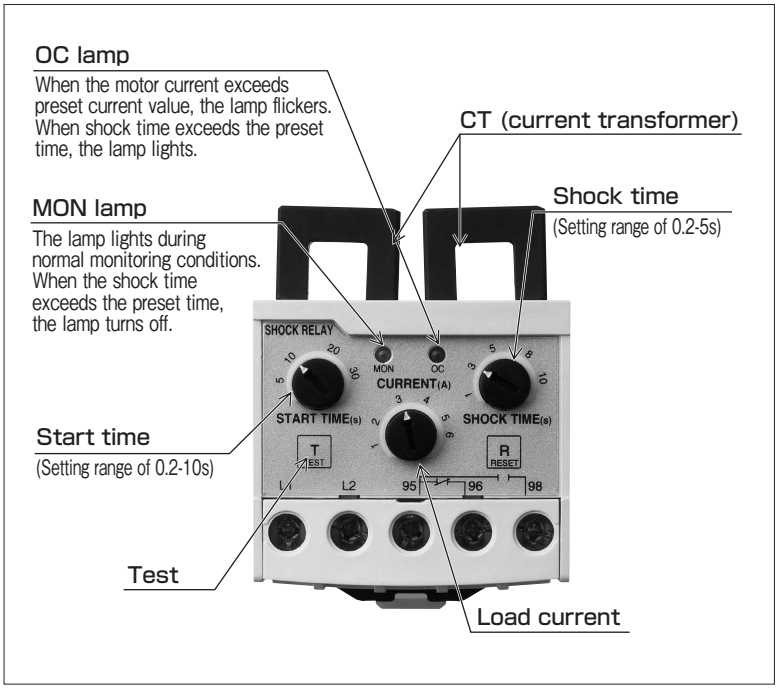
Part Names and Functions

LOAD CURRENT setting
Load current can be set to stop the motor at the desired level when overload occurs. When the motor current exceeds the preset CURRENT value (at the same time, overload time continues to exceed the preset SHOCK TIME), the Shock Relay activates and stops the motor.

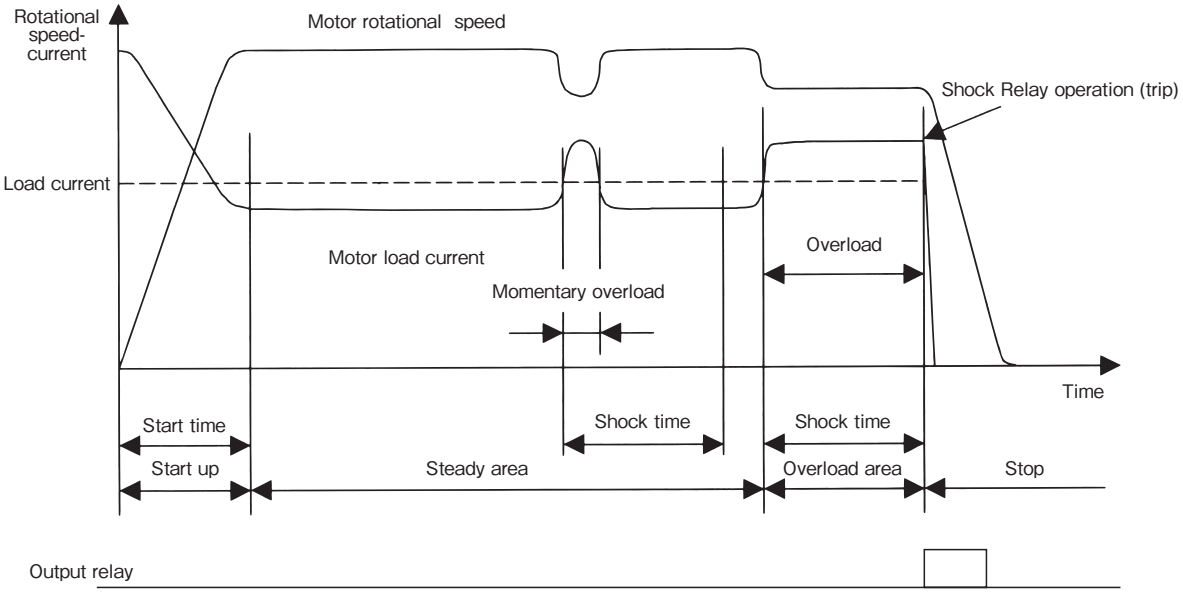
START TIME setting
When the motor starts there is a possibility that the motor current will exceed the set current value. To prevent the Shock Relay from tripping due to the spike in start current, start time is set a little bit longer than the period of motor start up to ignore the spike.

TEST function
Shock Relay operation can be tested stand-alone or during motor operation.
(When testing the Shock Relay, continue to press and hold the TEST button longer than the set START TIME or SHOCK TIME, whichever is longer.)

SHOCK TIME setting
Shock time is the amount of time set until the Shock Relay will activate when overload occurs. Within the set time, the Shock Relay will not activate, even if it is overloaded.

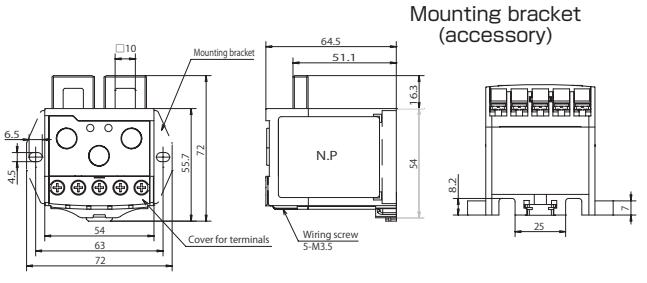


Operating Mode



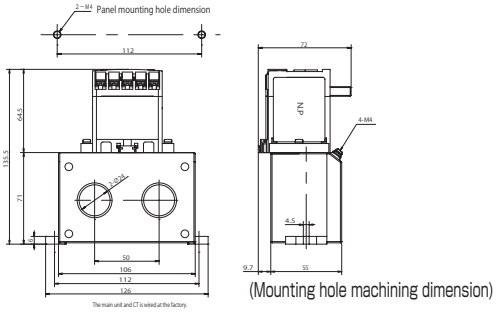
Outline dimensions

CT unit type TSBSA05/TSBSA10/TSBSA30/TSBSA60



Mass: 0.2kg

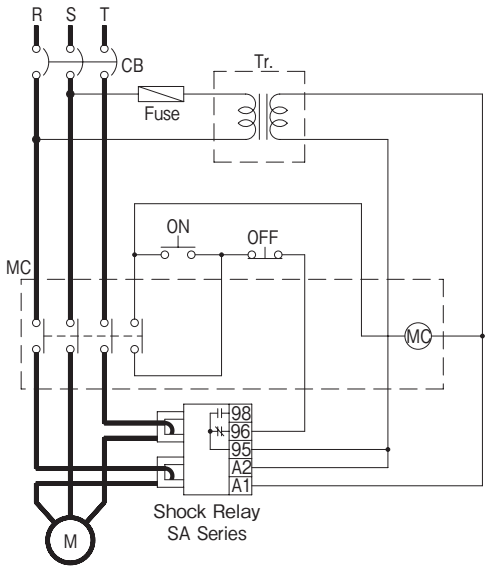
CT external mounting type TSBSA100/ TSBSA200/ TSBSA300



The external CT (current transformer) is wired before shipment.

Mass: 0.7kg

Basic connection diagram



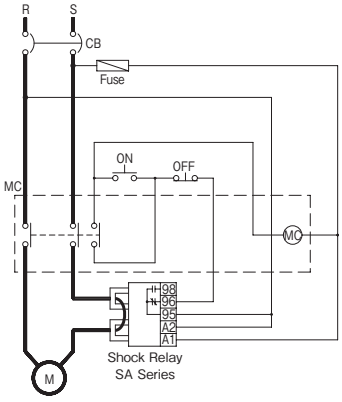
CB : Circuit breaker
MC : Magnetic contactor
ON : Start switch
OFF : Stop switch
Fuse : Fuse
Tr : Step-down transformer/ Insulation transformer

Notes:
1. Set the transformer depending on the voltage of the Shock Relay and MC. Set the insulation transformer if there is a high-harmonic noise generator such as an inverter.

2. The TSBSA contact output 95-98 are "open" during normal state (95-96 are "closed"), when tripping 95-98 are "closed" (95-96 are "open"). Coil capacity of the electromagnetic contactor MC which output contact opens and closes should be less than 200VA when throwing, and less than 20VA when holding.

3. Two wires out of three phases of the motor are passed through the Shock Relay's CT in the same direction.

Single-phase reference connection diagram



Notes:
1. Set the transformer depending on the voltage of the Shock Relay and MC. Set the insulation transformer if there is a high-harmonic noise generator such as an inverter.

2. The TSBSA contact output 95-98 are "open" during normal state (95-96 are "closed"), when tripping 95-98 are "closed" (95-96 are "open"). Coil capacity of the electromagnetic contactor MC which output contact opens and closes should be less than 200VA when throwing, and less than 20VA when holding.

3. 1 phase of the motor is passed through the Shock Relay's CT in the same direction. For when the split-phase or condensor start, connect the CT to the phase of the main coil side.

Model No.

TSBSA05

- TSBSA: Shock Relay
- SA: SA Series
- 05: Load current

Maximum preset current value
05···5A
10···10A
30···30A
60···60A
100···100A
200···200A
300···300A

Number of wire(s) that pass through the CT hole

Depending on motor capacity, use the chart on the right to select the applicable Shock Relay model and number of wire(s) to pass through the CT hole.
In order to increase the current setting accuracy, the number of wires that pass through the CT hole is 2 times or more for small motor currents.
When the motor load factor is low, increase the number of wires that pass through the CT hole as necessary.
Furthermore, when the number of the wires that pass through the CT hole is more than 2, it is necessary to convert the current scale value of current volume.
(Ex.) When a wire passes two times through the CT, the value on the current scale should be at half value.

AC200V class motor			AC400V class motor		
Capacity (kW)	Shock Relay Model No.	No. of wires that pass through the CT hole	Capacity (kW)	Shock Relay Model No.	No. of wires that pass through the CT hole
0.1	TSBSA05	4	—	—	—
0.2	TSBSA05	3	0.2	TSBSA05	4
0.4	TSBSA05	2	0.4	TSBSA05	3
0.75	TSBSA05	1	0.75	TSBSA05	2
1.5	TSBSA10	1	1.5	TSBSA05	1
2.2	TSBSA10	1	2.2	TSBSA05	1
3.7	TSBSA30	1	3.7	TSBSA10	1
5.5	TSBSA30	1	5.5	TSBSA30	1
7.5	TSBSA60	1	7.5	TSBSA30	1
11	TSBSA60	1	11	TSBSA30	1
—	—	—	15	TSBSA60	1
—	—	—	18.5	TSBSA60	1
—	—	—	22	TSBSA60	1

Shock Relay SU Series

Features

Under-load Detection Type

Once the motor current falls below the preset level, it can detect an under-load and send a signal to stop the motor.

Compact all-in-one CT (Current Transformer)

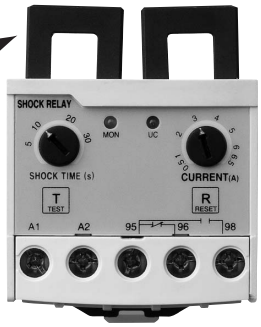
Includes Test and Reset buttons

DIN rail (35mm) mountable

Can also be used with a single phase motor

CT all-in-one model

CT
(Current Transformer)



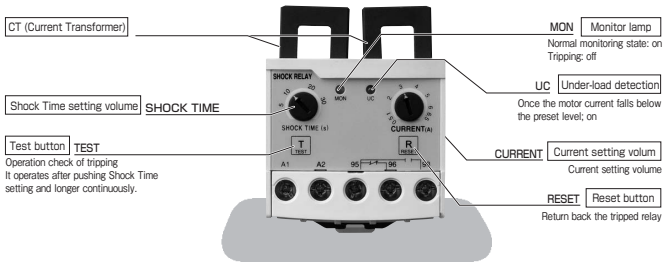
TSBSU05-2
TSBSU30-2
TSBSU60-2

Standard specifications

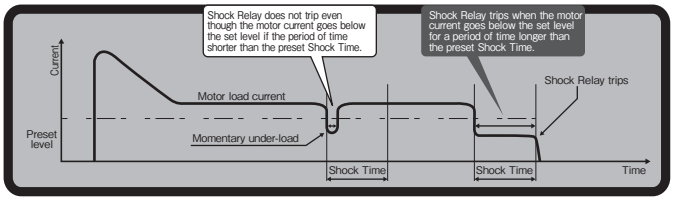
Model No.		TSBSU05-2	TSBSU30-2	TSBSU60-2
Current setting range *1,*2		0.5 to 5A	3 to 30A	5 to 60A
Shock Time setting range *1		0.2 to 30s		
Current setting accuracy		±10% (full scale)		
Control power supply voltage (A1 – A2)		AC 200 to 240V±10% 50/60Hz		
Maximum motor circuit voltage		AC 600V 50/60Hz *3		
Current detection system		2 phase CT system		
Display	MON lamp	Normal monitoring state: MON lamp (green) is on		
	UC lamp	Detection of under current: UC lamp (red) is on		
Output relay	Contact arrangement	1c		
	Contact rating	3A AC250V $\cos\phi$=1		
	Recommended amperes (in case of frequent operation)	0.2A and below AC250V $\cos\phi$=0.4		
	Minimum application load *4	DC10V, 10mA		
	Operation	Relay is excited when tripping		
	Self-holding	Yes (refer to the diagram shown in the next page)		
	Life	100,000 times at contact rating load		
Reset method		RESET button: ON or Power source: off		
Work environment	Ambient temperature	−20 to 60°C		
	Storage temperature	−30 to 70°C		
	Humidity	45 to 85%RH; no condensation		
	Altitude	2000m and below		
	Atmosphere	No corrosive gas nor dust; Pollution degree 3 and below; in the control box		
	Vibration	5.9m/s^2 and below		
Insulation resistance	Between case and circuit	10MΩ and above (DC500V megger)		
Withstand voltage	Between case and circuit	AC2000V 60Hz 1 min.		
	Between contacts	AC1000V 60Hz 1 min.		
	Between circuits	AC2000V 60Hz 1 min.		
Materials	Case	Polycarbonate, UL94V0		
	Cover for terminals	Nylon 6		
Power consumption		2VA and below		
Mounting		35mm DIN rail or attached bracket		
Dimensions	Main unit (including CT)	Length 62 x width 54 x height 66mm		
Mass	Main unit (including CT)	0.2kg		

*1.Current and Shock Time setting ranges are those which can be set, but do not show the upper or lower limits of the setting volume.
*2.In the case that the current, at normal state, exceeds the setting range, each model can allow up to 100A respectively.
*3.In the case of an inverter drive, there is a possibility of malfunction due to the distortion of the current waveform. If the frequency is within the range of 30 to 60Hz, it can be used because the influence is minor.
*4.Be sure to input minute electric currents through the relay when inputting an output relay contact directly into the PLC (Programmable logic controller), because there is a risk of contact failure due to minute electric current.

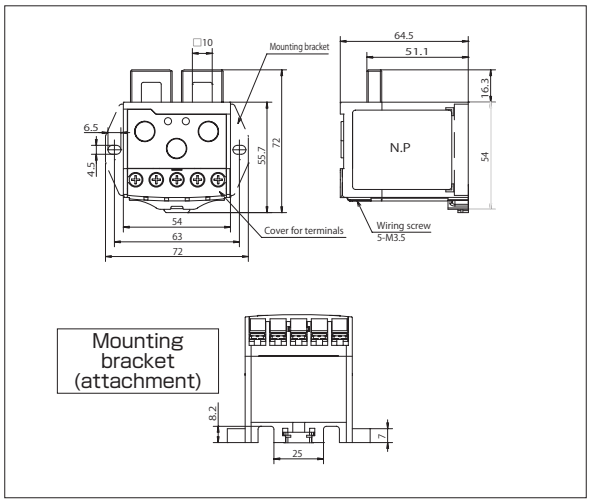
Part Names and Functions



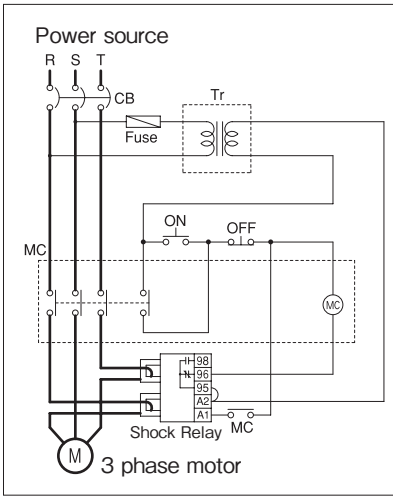
Operating mode



Outline dimensions

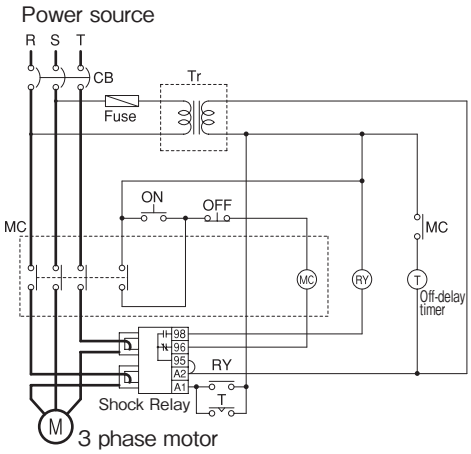


Basic connection diagram



1. If necessary, set transformer (Tr) depending on the voltage on the Shock Relay and electromagnetic contactor (MC). Install an isolating transformer if there is any harmonic noise generating device, such as an inverter.
2. Output relay; Normal condition: not excited, Trip condition: excited
3. Turn on or off the power source of the Shock Relay simultaneously as the motor starts/stops. In case the Shock Time setting is 1.5 sec. or shorter, the output relay may activate when the motor stops.
4. Coil capacity of MC connected with output relay of Shock Relay is; Throw: less than 200VA, Hold: less than 20VA
   As a guide, in case of TSBSU60, set auxiliary relay, and activate auxiliary relay with output relay of the Shock Relay, and open/close MC with the contactor of the auxiliary relay.
5. This basic connection diagram is not for self-holding. If a self-holding circuit is necessary, refer to the special diagram for self-holding.

Self-holding diagram for reference



Setting of Shock Time should be 1.5 sec. and longer, while that of the off-delay timer should be 1.5 sec. and shorter.

Model No.

TSBSU05-2

- TSBSU05-2
  - Shock Relay
  - SU Series
  - Setting current range (Max. setting current value)
    - 05···0.5 to 5A
    - 30···3 to 30A
    - 60···5 to 60A
  - Operational power source

Number of wire(s) that pass through the CT (Current Transformer) hole

Pass the motor wire(s) through the CT hole the number of times referenced in the chart below. These numbers are rough indication of when the motor load factor is 80 to 100%. In case the motor load factor is low, increase the number of wires that pass through the CT hole as necessary to improve the setting accuracy. In case the motor is not listed below (small capacity, single phase, different voltage, etc.), select the model and number of wire(s) passing through the CT hole depending on the setting current.

AC 200V class 3 phase motor			AC 400V class 3 phase motor		
Capacity (kW)	Applicable Shock Relay Model No.	Number of wires that pass through the CT hole	Capacity (kW)	Applicable Shock Relay Model No.	Number of wires that pass through the CT hole
0.1	TSBSU05-2	4	—	—	—
0.2	TSBSU05-2	3	0.2	TSBSU05-2	4
0.4	TSBSU05-2	2	0.4	TSBSU05-2	3
0.75	TSBSU05-2	1	0.75	TSBSU05-2	2
1.5	TSBSU30-2	3	1.5	TSBSU05-2	1
2.2	TSBSU30-2	2	2.2	TSBSU05-2	1
3.7	TSBSU30-2	1	3.7	TSBSU30-2	3
5.5	TSBSU30-2	1	5.5	TSBSU30-2	2
7.5	TSBSU60-2	1	7.5	TSBSU30-2	1
11	TSBSU60-2	1	11	TSBSU30-2	1
—	—	—	15	TSBSU60-2	1
—	—	—	18.5	TSBSU60-2	1
—	—	—	22	TSBSU60-2	1

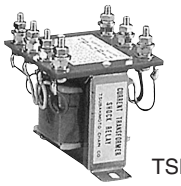
Note 1) In case the number of the wires that pass through the CT hole is more than 2 times, it is necessary to convert the current scale value of CURRENT volume.
(Ex.) When a wire passes two times through the CT, the value on the CURRENT scale should be at half value.
2) In case the motor capacity exceeds the above motor capacity, use the external CT.

Shock Relay 50 Series

Features

1. Economically priced
2. Automatic reset
3. Additional specifications available

TSB50



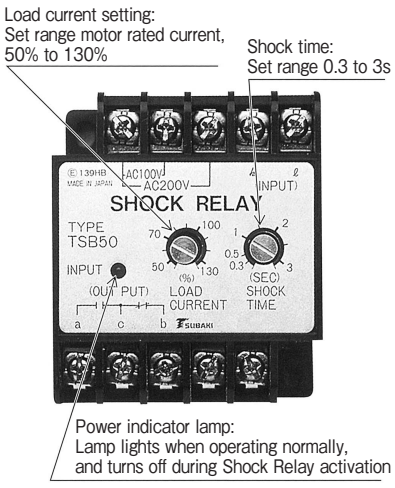
TSBCOM
current transformes

Standard specifications

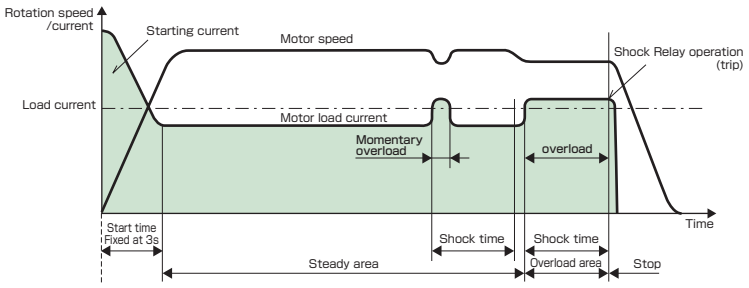
Function		Model	TSB50-COM
Common	Motor	200V class	0.2 to 3.7kW*1
		400V class	0.2 to 3.7kW
	Work environment	Ambient temperature	−10°C to 50°C
		Ambient humidity	45 to 85%RH: no condensation
		Vibration	Less than 5.9m/s²
		Altitude	Less than 1000m
		Atmosphere	No corrosive gas, dust
Main Unit	Unit Model No.		TSB50
	Load current (current setting range)*3		50 to 130% (100%=5mA)
	Current setting accuracy		±10% (full-scale)
	Time setting range	Start time	Fixed at 3s
		Shock time	0.3 to 3s
	Control power supply voltage		AC100/110V or AC200/220V 50/60Hz ±10%
	Maximum motor circuit voltage		AC600V, 50/60Hz
	Current detecting system		Single-phase CT system
	Output relay	Self-holding	No self-holding (automatic return)
		Normal operation	Output relay is not excited
		Abnormal case	Output relay is excited
		Contact capacity	1s contact, AC250V 0.1A (inductive load cosϕ=0.4)
		Minimum applicable load*2	DC10V, 10mA
	Output relay life span	Mechanical	10,000,000 times
		Electrical	100,000 times
	Test functions		Not available
	Withstand voltage	Space between circuit and housing	AC1500V, 60Hz, 1minute (power supply circuit and contact circuit)
		Contact spacing	AC500V, 60Hz, 1minute
		Circuit spacing	AC1500V, 60Hz, 1minute (power supply circuit and contact circuit)
	Mass		0.3kg (not including external CT)
	Electricity consumption		0.5VA
External CT	Attached External CT		TSB COM
	Rated primary current		0.75A, 1.5A, 1.75A, 2.0A, 2.5A, 3.3A, 4.0A, 5.3A, 7.0A, 9.0A, 10.0A, 16.0A
	Rated secondary current		5mA
	Rated load		0.5VA
	Mass		0.5kg

Notes:
1. If TSBCOM-A (small capacity type CT) is used, it can be used for less than 0.1kW motors.
2. When directly inputting output relay contact into the programmable controller (PLC), be aware that a minute electric current can cause contact failure.
   As for the input to PLC, it is recommended to drive the relay coil for minute current by relay signal of Shock Relay at first, then input this relay contact to PLC.
3. Current and time setting ranges can be set within the warranty range, but not the upper or lower level of setting volume.

Part Names and Functions

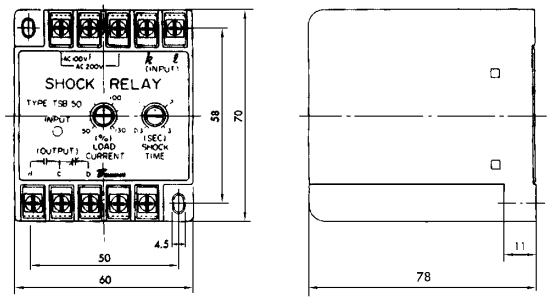


Operating Mode

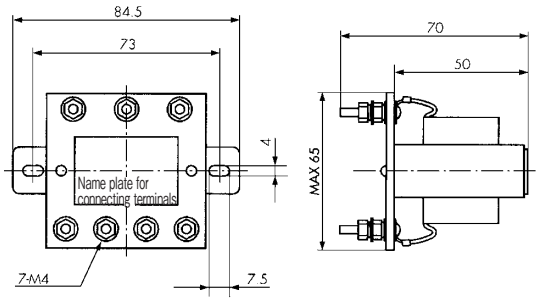


Outline dimensions

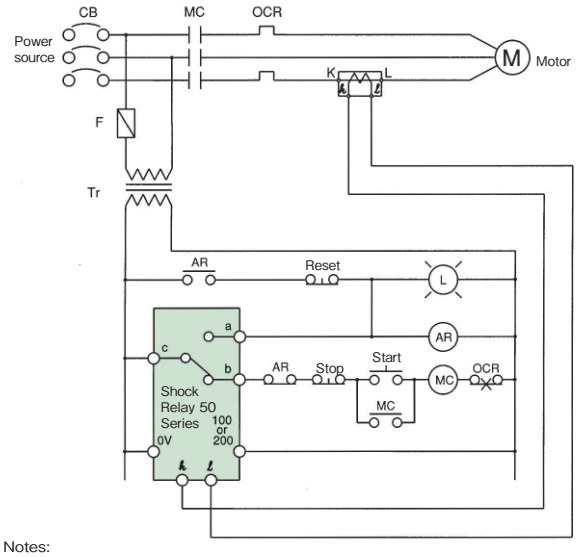
Main unit TSB50



Common type CT (current transformer) TSB COM/TSB COM-A



Basic connection diagram



Notes:
1. When the main circuit's voltage exceeds 220VAC, install a step down transformer Tr. As well, take care not to make a mistake with the power source (AC100V or AC200V) wiring.
2. If the CT's secondary side is left open while the primary side is energized, it will cause damage to the CT.
   When the Shock Relay is not connected, short-circuit the CT's secondary side.
3. Coil capacity of the electromagnetic contactor MC which output contact opens and closes should be less than 200VA when throwing, and less than 20VA when holding.

Common CT (current transformer)

- TSB COM (standard type) can be used with a 0.2 to 3.7kW motor.
- TSB COM-A (small capacity type) can be used with a 0.1kW and smaller motor.

Model No.

Additional specifications S, V, T1, T2

TSB 50 □ -COM & COM-A

- TSB — Shock Relay
- 50 — 50 Series
- -COM & COM-A — Common type CT (current transformer)
  - COM···for 0.2 to 3.7kW
  - COM-A···for 0.1kW and less

Note) Use main unit with CT as a set.

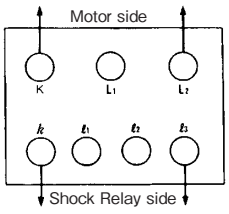
■TSB COM (standard type)

Motor (kW)	Motor voltage AC200/220V			Motor voltage AC400/440V		
	Motor rated current (A)	Connecting terminal		Motor rated current (A)	Connecting terminal	
		Motor side	Shock Relay side		Motor side	Shock Relay side
0.2	1.75	K-L_2	k-ℓ_1	0.75	K-L_2	ℓ_1-ℓ_2
0.4	2.5	K-L_2	k-ℓ_2	1.5	K-L_2	ℓ_2-ℓ_3
0.75	4.0	K-L_2	k-ℓ_3	2.0	L_1-L_2	ℓ_2-ℓ_3
1.5	7.0	K-L_1	k-ℓ_1	3.3	L_1-L_2	k-ℓ_2
2.2	10.0	K-L_1	k-ℓ_2	5.3	L_1-L_2	k-ℓ_3
3.7	16.0	K-L_1	k-ℓ_3	9.0	K-L_1	ℓ_1-ℓ_3

Note:
Common type CT, motor side L_1-L_2; Shock Relay side ℓ_1-ℓ_2 combination, 1A output CT can be combined.

■TSB COM-A (small capacity type)

Motor rated current (A)	Connecting terminal	
	Motor side	Shock Relay side
0.15	K-L_2	k-ℓ_1
0.25	K-L_2	k-ℓ_2
0.4	K-L_2	k-ℓ_3
0.6	K-L_1	k-ℓ_1
1.0	K-L_1	k-ℓ_2
1.6	K-L_1	k-ℓ_3



Note:
Select by current value

■ CT (current transformer) Selection Notes

The load current meter of the Shock Relay shows 100% at the time of the motor rated current value in the chart.

When the actual motor rated current value is not on the chart, use a CT on which the load current meter shows 80% to 100% range when rated current flows.

Additional specifications chart

Additional specs. / Model	Subtropical specifications	Control power supply voltage modification	Start time modification	Shock time modification
	S	V	T1	T2
TSB50	◎	◎	◎	◎

◎: Multiple specifications available

Notes:
1. Refer to page 112 for detailed specifications.
2. Specify operational power source voltage for the Shock Relay in the case of additional specification V.
3. Specify required start time and shock time in the case of additional specifications T1 and T2.

MEMO

SAFCON

Control Devices

Mechanical

Torque Keeper, MINI-KEEPER

Torque Keeper

Features

The friction facings of the slipping clutch and brake are made with special fine chemical fibers.

Long life

Special fine chemicals are used for friction facings, so much longer life can be expected when compared to other types of brake lining.

Slipping torque stability

Torque fluctuation is very small, so stable torque can be transmitted.

Constant torque repeatability

Even with high frequent repeated slippage, stable torque is transmitted consistently.

Light weight

Due to the aluminum AF flange, the Torque Keeper is light in weight.

Compact

Its special design makes for significant space savings. The Torque Keeper is more compact than other braking devices.

Wide torque range

Each size has a wide torque range.

Easy torque setting

Torque indicators make torque setting easy.

Ease of operation

Operation is easy due to the easy to use adjusting nut.

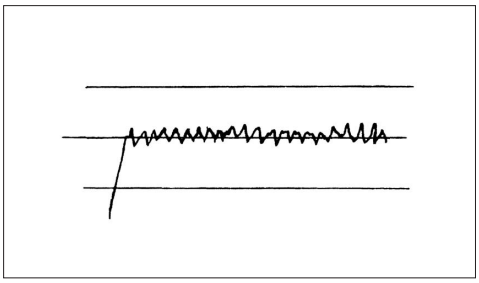
Greasing unnecessary

Grease and cooling are not needed.

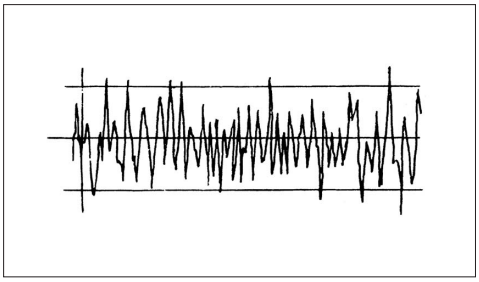
Quick finished bore delivery

Finished bores can be made for quick delivery.
(Refer to page 159 for details)

Torque Keeper

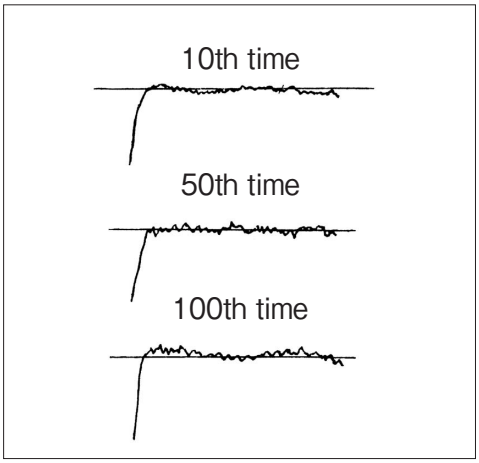


Standard brake



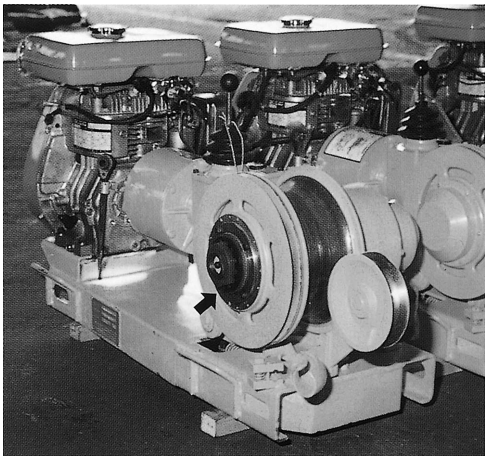
Compared to our ordinary products

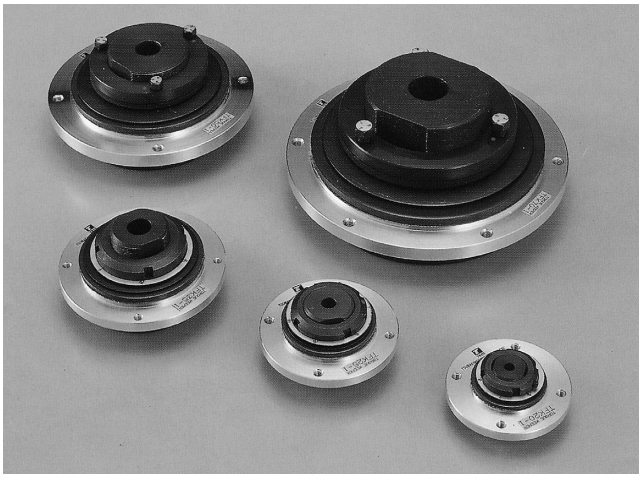
Intermittent slip

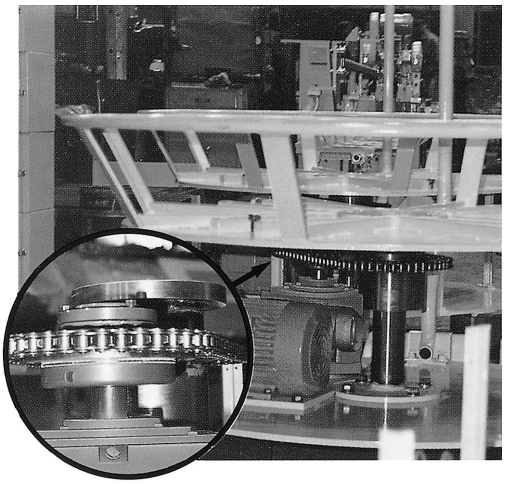


Long life/ Stable/ Easy to operate!

Our brakes have embarked on a new era of the fine chemical fiber. By using these fine chemical fibers, the TSUBAKI Torque Keeper can achieve a longer product life than that of the conventional type of brake lining. This brand new type of Torque Keeper brake has been designed with an abrasion resistance, the use of a torque indicator, weight savings and other aspects that make it easy to use. For the driving of each conveyor's accumulation and brakes for automatic machineries as well as others, we recommend TSUBAKI Torque Keeper for all industrial equipment brake mechanisms.

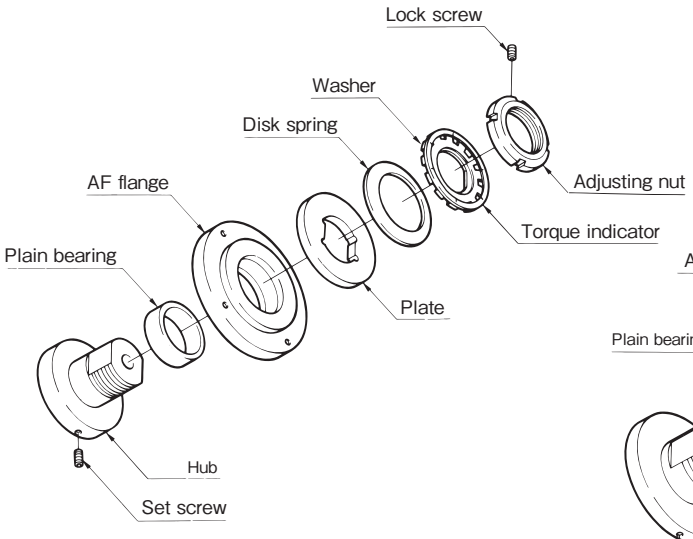




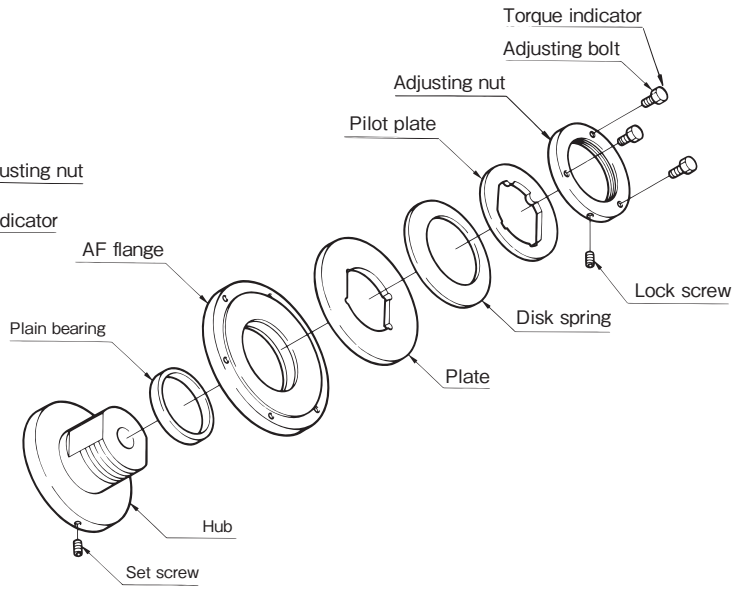


Construction

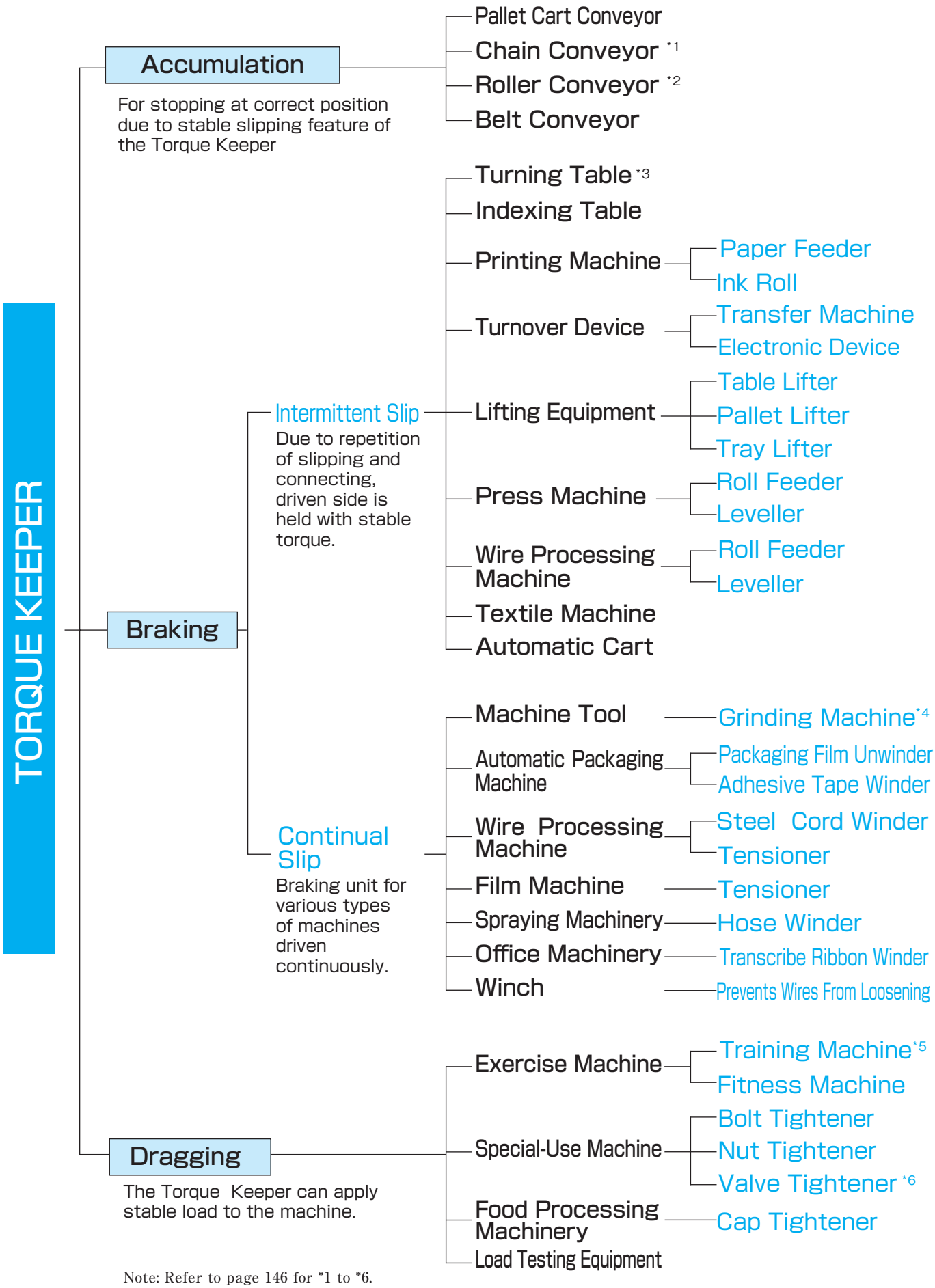
TFK20 • 25 • 35



TFK50 • 70



Purpose and Machine Type

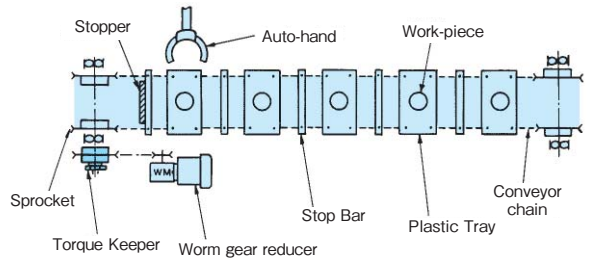


Note: Refer to page 146 for *1 to *6.

Applications

—Accumulation—

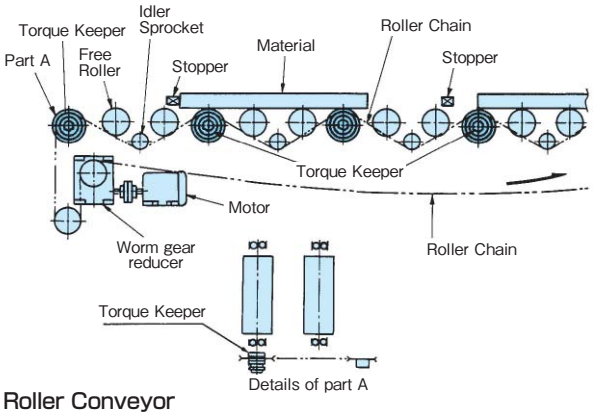
(FOR LOADING/UNLOADING) *1



Chain Conveyor

When the stop bar contacts the stopper, the Torque Keeper slips and the conveyor stops.
When the stopper is unset, the Torque Keeper connects and the conveyor resumes operation.

(FOR INTERMITTENT SLIP) *2

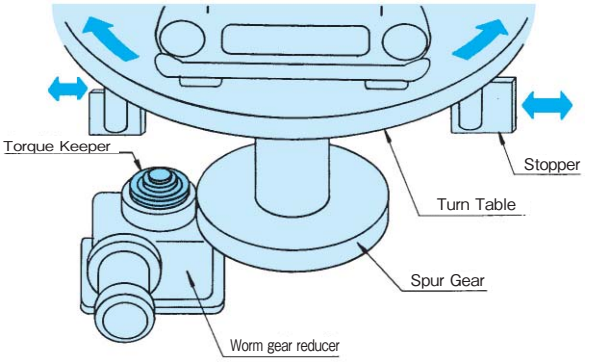


Roller Conveyor

When the roller chain is moving, if the material contacts the stopper, the nearby Torque Keeper slips and the material will be stopped. After releasing the stopper, the Torque Keeper will be connected and the material will continue moving.

—Braking—

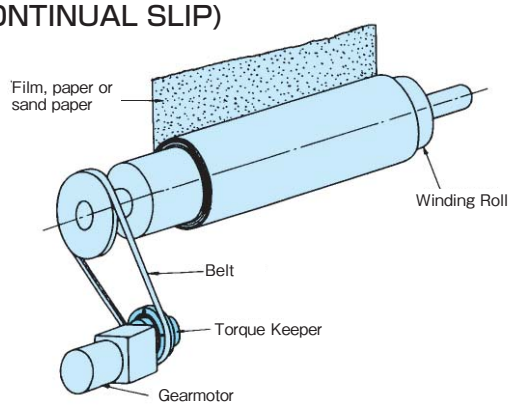
(INTERMITTENT SLIP) *3



Turn Table for Parking System

At the parking station the car is rotated in the exit direction on the turn table. When the turn table comes to the correct position, it will be stopped by the stopper. The slipping of the Torque Keeper protects the drive unit from damage.

(CONTINUAL SLIP) *4

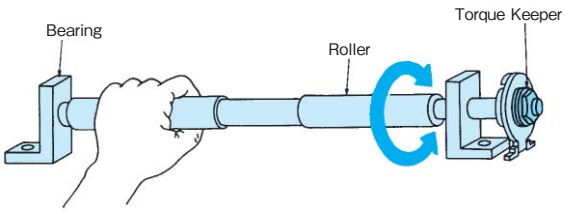


Winding of Film, Paper or Sandpaper

The gear motor winds the film, paper or sand paper through the Torque Keeper. In this case, the Torque Keeper is slipping under low rpm, so it can apply stable tension.

—Dragging—

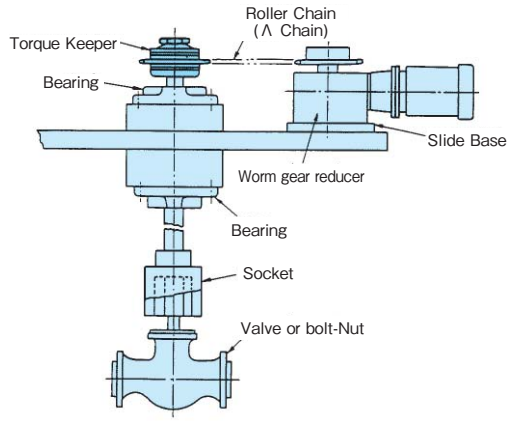
(FOR LOAD) *5



Wrist Exerciser

The wrist can be exercised by the rotating roller. The Torque Keeper applies the load to the roller through the stable slipping torque.

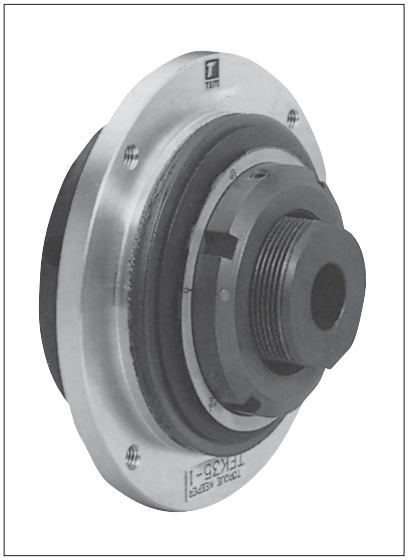
(FOR TIGHTENING) *6

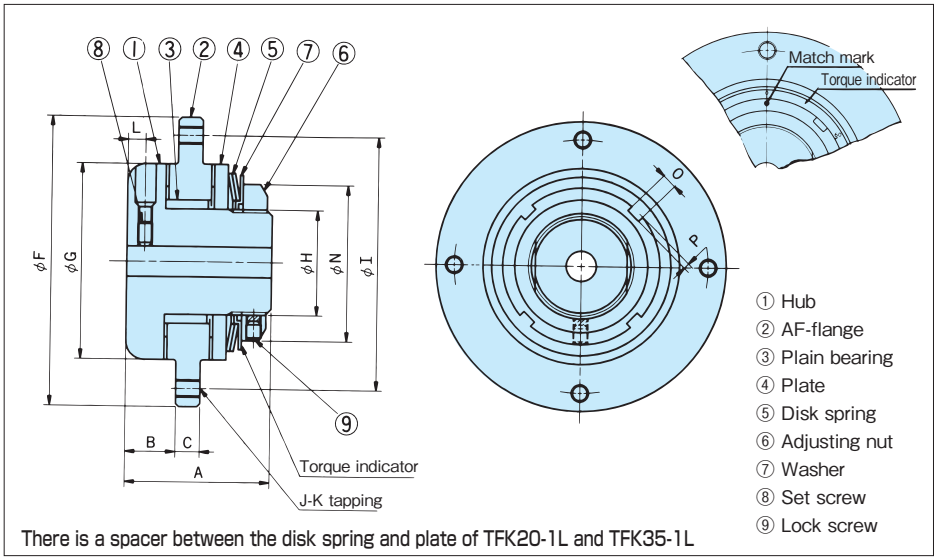


Tightening Machine

The bolt, nut and valve are tightened by the stable torque of the Torque Keeper.

TFK20·25·35





There is a spacer between the disk spring and plate of TFK20-1L and TFK35-1L

Unit : mm

Model No.	Setting torque range N·m {kgf·m}	Rough bore dia.	Min. bore dia.	Max. bore dia.	Dimensions														Weight
					A	B	C	F (h7)	G	H	I PCD	J-K No.-dia.	L	N	O	P	Adjusting nut dia. × pitch	Set screw	kg
TFK20-1L	0.59 to 1.18 {0.06 to 0.12}	7	9	14	37	13.3	7	84	50	24	70	4-M6	5	38	5	2	M24 × 1.0	M5 x 8	0.56
TFK20-1	1.76 to 5.88 {0.18 to 0.6}																		
TFK20-2	3.92 to 11.8 {0.4 to 1.2}																		
TFK25-1L	1.76 to 4.12 {0.18 to 0.42}	10	14	22	48	16.8	8	96	65	35	84	4-M6	6	52	5	2	M35 × 1.5	M5 x 8	0.76
TFK25-1	3.92 to 16.7 {0.4 to 1.7}																		
TFK25-2	7.84 to 32.3 {0.8 to 3.3}																		
TFK35-1L	5.88 to 11.8 {0.6 to 1.2}	17	19	25	62	19.8	8	120	89	42	108	4-M6	7	65	6	2.5	M42 × 1.5	M6 x 12	1.5
TFK35-1	11.8 to 44.1 {1.2 to 4.5}																		
TFK35-2	20.6 to 89.2 {2.1 to 9.1}																		

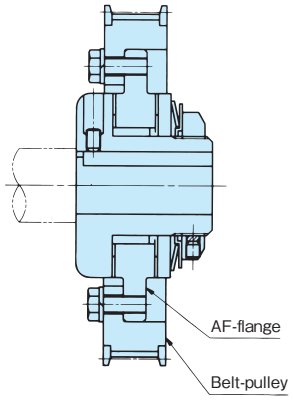
Note: 1. All rough bore types are in stock.
2. An M5 lock screw is included.
3. The weight are those of a product with the maximum shaft hole diameter.

Installation

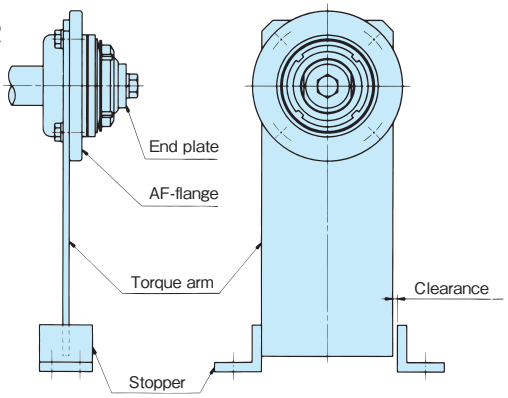
1. When installing the belt-pulley, sprockets etc, fix the outside diameter (dimension F) of the AF-flange and spigot facing with a bolt tightly. (Example 1)
The sprocket minimum number of teeth to be shown is on page 148.
The recommended tolerance of the spigot facing is H7 or H8.

2. When installing the torque arm, fix it to the AF flange with bolts tightly.
Also, the tip of the torque arm should be supported in the rotational direction only.
There should be sufficient free movement for axial direction. (Example 2)

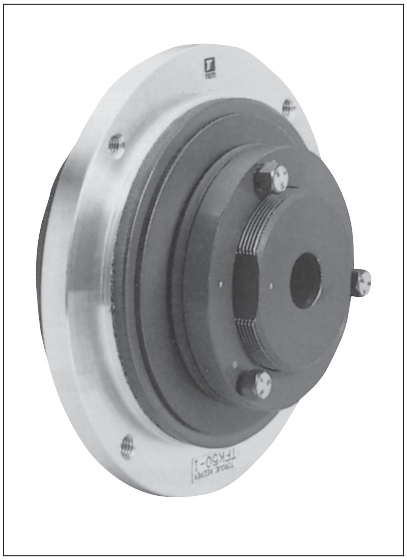
Example 1

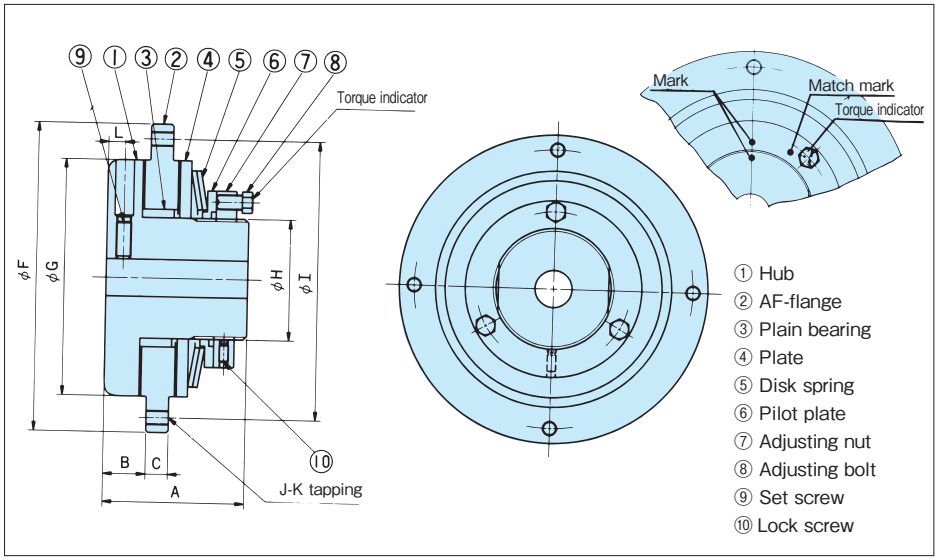


Example 2



TFK50·70





Unit : mm

Model No.	Setting torque range N·m {kgf·m}	Rough-bore dia.	Min. bore dia.	Max. bore dia.	Dimensions												Weight
					A	B	C	F (h7)	G	H	I PCD	J-K No.-dia.	L	Adjusting nut dia. × pitch	Adjusting bolt dia. X pitch	Set screw	kg
TFK50-1L	11.8 to 29.4 {1.2 to 3.0}	20	22	42	76	22.8	12	166	127	65	150	4-M8	9	M65 × 1.5	M8 × 1	M8 x 20	4.0
TFK50-1	28.4 to 125 {2.9 to 12.8}																
TFK50-2	52.9 to 252 {5.4 to 25.7}																
TFK70-1L	29.4 to 70.6 {3.0 to 7.2}	30	32	64	98	24.8	12	216	178	95	200	6-M8	10	M95 × 1.5	M10 × 1.25	M10 x 20	9.4
TFK70-1	69.6 to 341 {7.1 to 34.8}																
TFK70-2	134 to 650 {13.7 to 66.3}																

Note: 1. All rough bore types are in stock.
2. An M5 lock screw is included.
3. The weight is that of one with the maximum bore diameter.

Minimum number of sprocket teeth

Model.No	Sprocket						
	RS35	RS40	RS50	RS60	RS80	RS100	RS120
TFK20	32	25					
TFK25	35	28	23	20	16		
TFK35		△ 33 (34)	28	24	19	16	14
TFK50		45	△ 37 (38)	△ 31 (32)	24	20	18
TFK70			△ 47 (48)	△ 39 (40)	△ 31 (32)	25	22

Note: 1.The roller chain which does not require lubricating oil is recommended.
2. △ denotes non-standard A-type sprocket needs a space.In case of using standard sprockets, please use the sprocket in ( ).

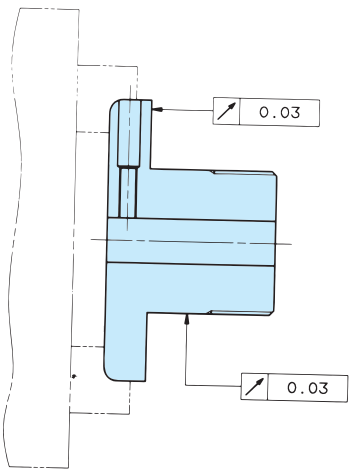
Model No.

TFK35-1-25J-2.5

- Size
- No. of disk springs
  - 1…1pc
  - 2…2pcs
  - 1L…weak spring
- Bore diameter (No symbol if there is no finished bore)
- Keyway type (J: New JIS normal type, E: Old JIS 2nd grade , No symbol: special keyway)
- Set torque (Unit: kgf·m, No symbol if there is no torque setting)

Bore Finishing

When bore finishing, chuck the outside diameter of the hub as per the following instructions and align the centering.
If the centering is bad, there is a possibility of not stable slipping torque due to abnormal run out of friction facing.



The finished bore Torque Keeper TFK

Finished bore products can be made for quick delivery

■ Finished bore and keyway

The finished bores of TFK20 to TFK70 have been standardized

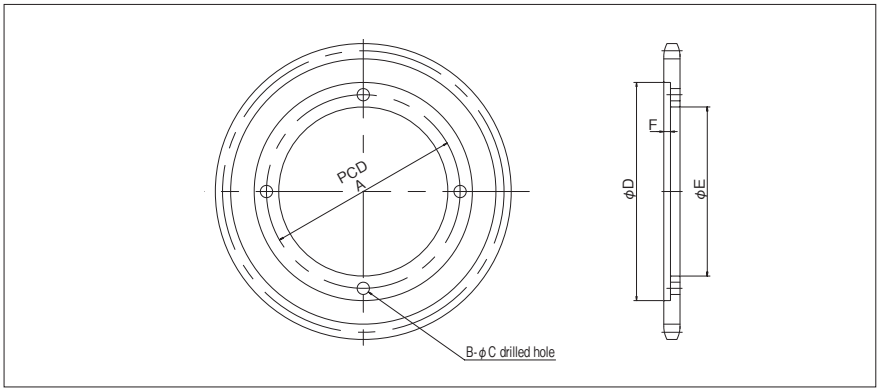
■ Finished bore sizes chart

Unit : mm

Torque Keeper Model No.	Finished bore size
TFK20-1L	9,10,11,12,14
TFK20-1	
TFK20-2	
TFK25-1L	14,15,16,17,18,19,20,22
TFK25-1	
TFK25-2	
TFK35-1L	19,20,22,24,25
TFK35-1	
TFK35-2	
TFK50-1L	22,24,25,28,29,30,32,33, 35,36,38,40,42
TFK50-1	
TFK50-2	
TFK70-1L	32,33,35,36,38,40,42,43,45,46, 48,50,52,55,56,57,60,63
TFK70-1	
TFK70-2	
Delivery	Ex.-Japan 4weeks by sea

■ Recommended dimensions for drive member processing

When manufacturing a drive member, refer to the drawing below.



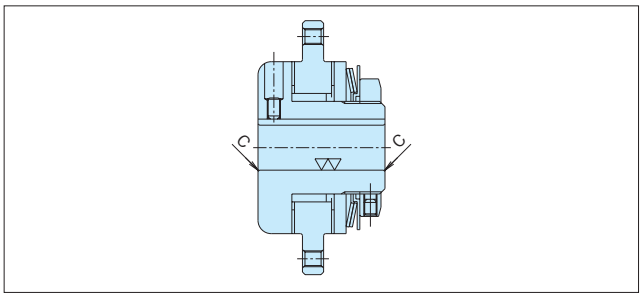
Series name	Recommended sprocket finishing dimensions					
	A	B	C	D (H7)	E	F
TFK20	70	4	6.6	84	52	*3
TFK25	84	4	6.6	96	68	*3
TFK35	108	4	6.6	120	92	4
TFK50	150	4	9.0	166	130	5
TFK70	200	6	9.0	216	182	5

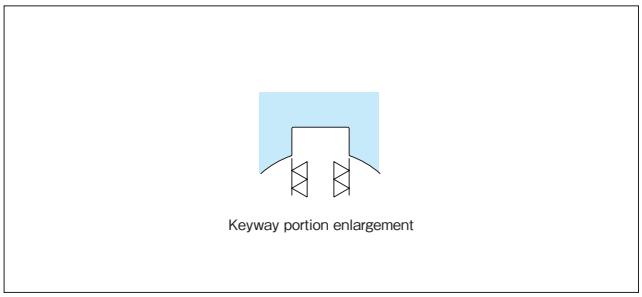
*F = 2 when using RS35.

Model No.

TFK35 - 1 - 25J

- TFK35 — Size
- 1 — No. of disk springs
  - 1…1pc
  - 2…2pcs
  - 1L…weak spring
- 25 — Shaft bore
- J — New JIS keyway normal type





■ Chamfer and finish

Shaft bore diameter	Chamfering size
φ25 and less	C0.5
φ50 and less	C1
Above φ51	C1.5

■ Shaft bore diameter and keyway specifications

- Shaft bore diameter tolerance is H7
- The keyway is new JIS (JIS B 1301-1996) "normal type"
- Set screws come delivered with the product

Selection

When using the Torque Keeper with a human transport device or a lifting device, install a suitable protection device on that equipment for safety purposes.
Otherwise an accident resulting in death, serious injury or damage to the equipment may occur due to a falling accident.

1. Decide the conditions from the table below in accordance with your application (see page145). Determine the size from the T-N curve graphs on the next page.

Application	Conditions	Size
Accumulation	Determine the following for the Torque Keeper of each conveyor: ① Slip torque ② Slip rpm ③ Slip time (conveyor stop time) ④ Connection time (conveyor drive time) ⑤ Operating time per day	Determine a size for which the slip torque and rpm is within the allowable range (below the curve) on the T-N curve graph. When the slip time is longer than the connection time, and the operating time per day exceeds eight hours, we recommend that it be operated within the ▭ area of the T-N curve graph.
Braking	Determine the following for the Torque Keeper of each machine: ① Brake torque ② Rpm ③ Slip time (brake operating time) ④ Connection time (time when brake not operated) ⑤ Operating time per day Note: Items ③ and ④ are not necessary in case of continual slipping.	Determine a size for which the brake torque and rpm is within the allowable range (below the curve) on the T-N curve graph. When the slip time is longer than the connection time, and the operating time per day exceeds eight hours, we recommend that it be operated within the ▭ area of the T-N curve graph.
Dragging	Determine the following for the Torque Keeper of each machine: ① Slip torque ② Slip rpm ③ Slip time ④ Connection time ⑤ Operating time per day	Determine a size for which the slip torque and rpm is within the allowable range (below the curve) on the T-N curve graph. When the slip time is longer than the connection time, and the operating time per day exceeds eight hours, we recommend that it be operated within the ▭ area of the T-N curve graph.

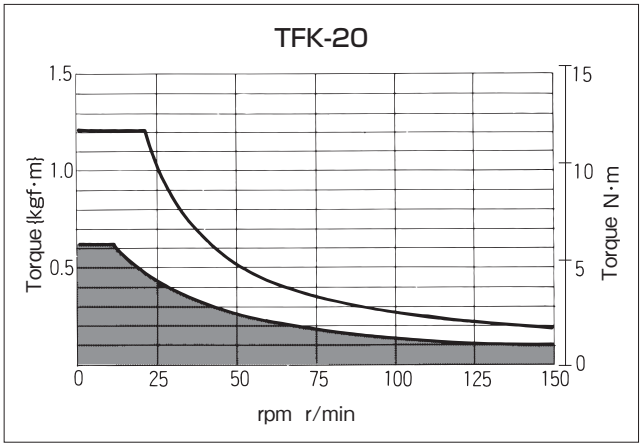
2. Verify that the shaft bore range of the chosen Torque Keeper conforms with the shaft diameter to be installed.
3. Setting the slip torque:
   Each Torque Keeper is set at a value that is 50% of the maximum set torque range (see pages 147, 148). The torque curve will be included with the unit when it is delivered. This 50% torque is called the "zero point" and it is the basis for setting the slip torque.
   For details, see the section, "Handling Part 2" on page 152.

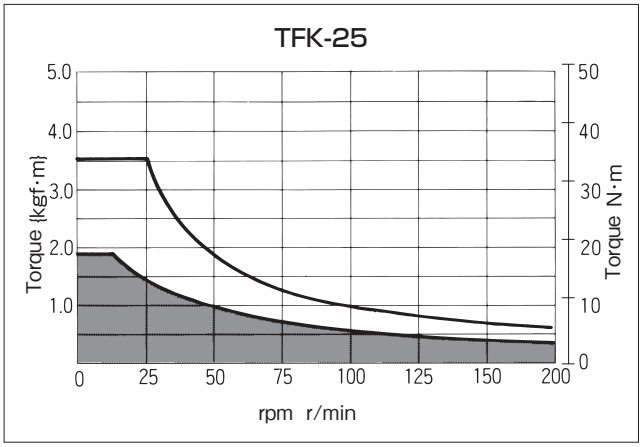
Points of caution regarding selection

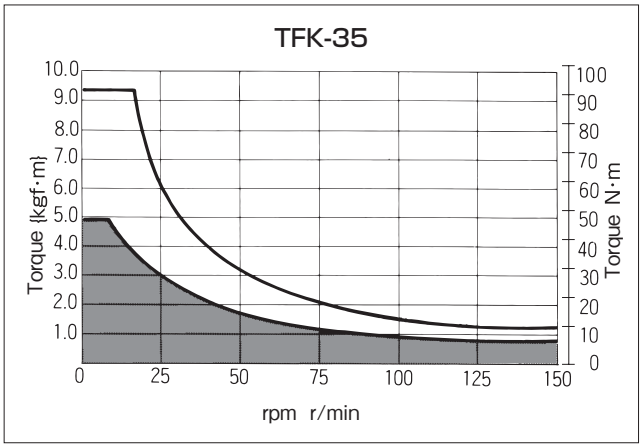
1. Do not allow water or oil to get onto the friction surface. This will cause the torque to drop and unstable slip torque will result.
2. The T-N curve graph is intended for use when the ambient temperature is below 40℃ . Please contact TEM when the ambient temperature is higher than this.
3. Please contact TEM when the slip torque for the shaft diameter to be used is smaller than the setting torque range of the Torque Keeper.
4. Reversing the direction of rotation will cause backlash. Torque Keeper cannot be used with machines that do not allow backlash.

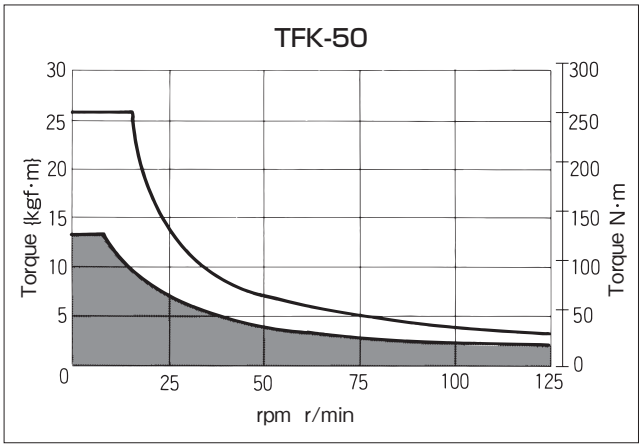
T-N Curve

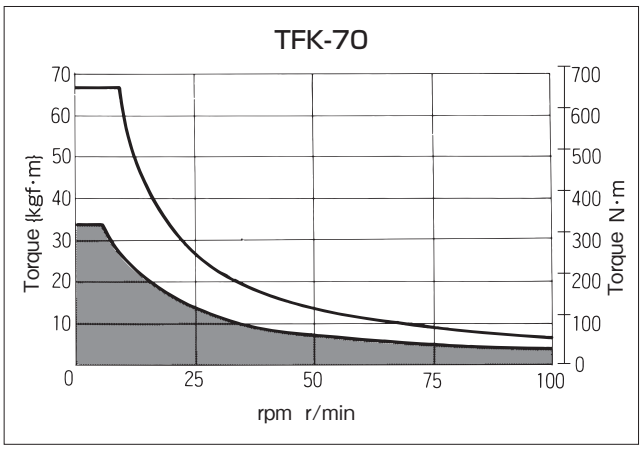
{ } for reference











Note: The T-N curve graph is based on the allowable temperature range of the Torque Keeper.
If a more stable slipping torque is necessary, we recommend that it be operated within the ▭ area.
However, be aware that when the speed is 30 r/min or less, a stick-slip phenomenon may occur, which will cause unstable torque. A stick-slip phenomenon is a phenomenon in which a friction surface slips and stops repeatedly.

Handling Part 1

1. All Torque Keeper units are shipped with rough bores.
   Finish a shaft bore in the hub after disassembly.
   Refer to page 148 regarding shaft bore finish.
2. Be careful not to mix up parts when disassembling two or more Torque Keepers. When assembling, be sure to use the original parts. If parts are mixed up, the slip torque will not match the torque curve delivered with the unit.
3. Be sure that any toothed belts or roller chains, etc., are not over-tensioned when using the Torque Keeper. Unstable slip torque will result if more than the required tension is applied.

Handling Part 2

Each Torque Keeper is set at a value that is 50% of the maximum set torque range (see pages 147, 148). The torque curve will be included with the unit when it is delivered. This 50% torque is called the "zero point" and it is the basis for setting the slip torque.

To set the slip torque of TFK 20, 25 and 35, tighten the adjustment nut with a hook spanner wrench. To set the slip torque of TFK 50 and 70, tighten the three adjustment bolts with a wrench. Refer to page 153 to determine the zero point.

Setting the slip torque

TFK 20, 25 and 35

(1)When the required slip torque is over the zero point, tighten the adjustment nut to the angle required in accordance with the attached torque curve. This operation is facilitated by the torque indicator (which shows the angle) and match marks.

(2)When the required slip torque is below the zero point, loosen the adjustment nut beyond the point required and then tighten it to the desired angle, in accordance with the attached torque curve.

Example: Set to a slip torque − 30° from the zero point.

① Loosen the adjustment nut to − 60° from the zero point.

② Tighten the adjustment nut from − 60° to − 30°

TFK 50 and 70

(1)When the required slip torque is over the zero point, tighten the three adjustment bolts to the angle required in accordance with the attached torque curve. This operation is facilitated by the torque indicator (which shows the angle) and match marks.

(2)When the required slip torque is below the zero point, loosen the three adjustment bolts beyond the point required and then tighten them to the desired angle, in accordance with the attached torque curve.

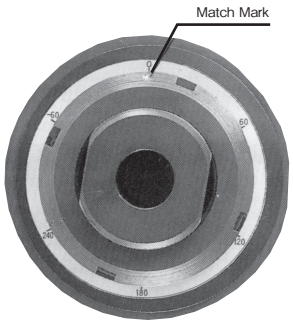
Example: Set to a slip torque − 60° from the zero point.

① Loosen the adjustment bolts to − 90° from the zero point.

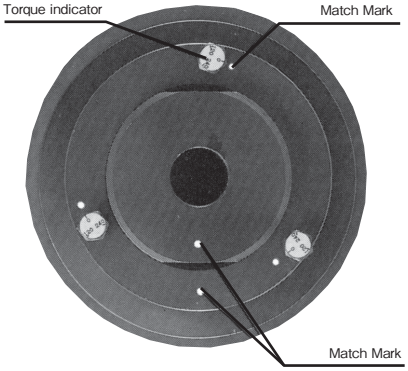
② Tighten the adjustment bolts from − 90° to − 60°

(Caution) When initially setting the Torque Keeper or when changing the setting during operation, we recommend running the machine for two or three minutes to run in before normal operation. This will allow you to obtain a more stable slip torque. Break-in as follows in accordance with the slip torque setting.

TFK20·25·35 Torque indicator



TFK50·70 Torque indicator



(1)When the slip torque is below the zero point:

① Run in the machine at zero point torque for two to three minutes.

② Set the slip torque as explained above and then enter normal operation.

(2)When the slip torque is above the zero point:

① Set the slip torque as explained above.

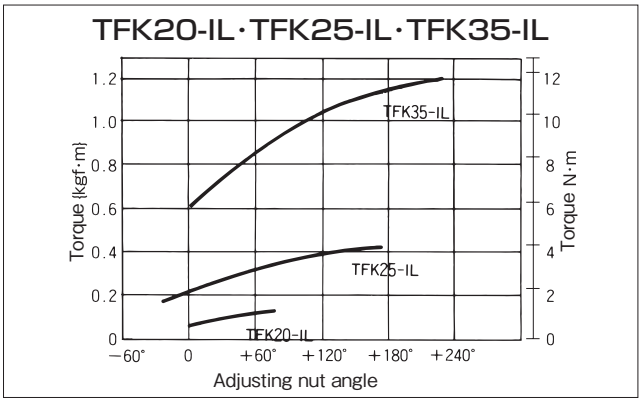
② Run in the machine for two to three minutes.

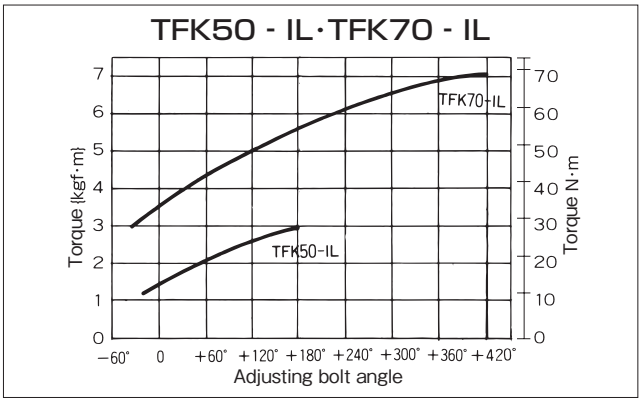
③ Return the adjustment nut or bolts to the zero point.

④ Set the slip torque again and then begin normal operation.

Torque Curve

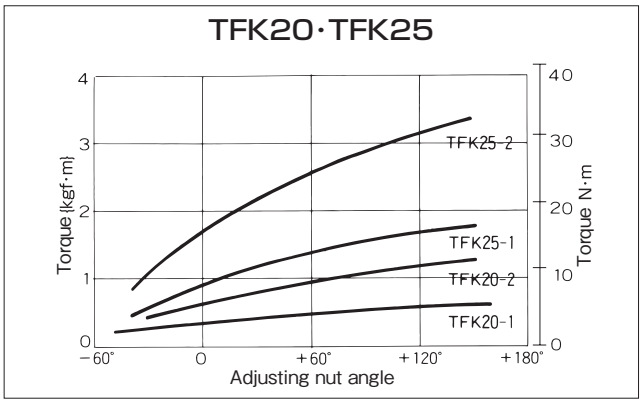
Weak Spring Type

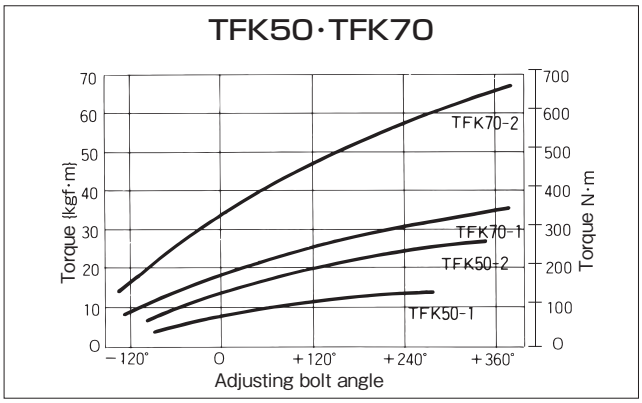


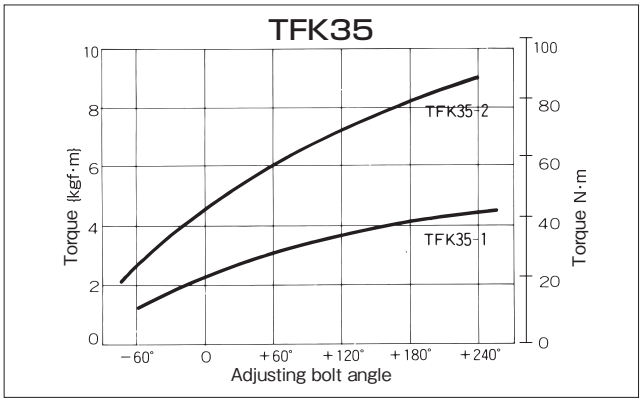


Torque Curve

Standard Spring Type { } for reference







Note: 1. Indicator 0 on torque curve shows 50% of maximum torque.
2. Each torque curve is an example. Refer to the attached torque curve of the actual unit.

Finding the zero point

After finishing the shaft bore and re-assembling the unit, determine the zero point as explained below:

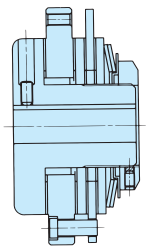
TFK 20, 25 and 35

1. During re-assembly, match the"0" on the torque indicator with the position of the set screw on the hub (part ⑧ on page 147). (Do not allow it to be positioned 180° in the opposite direction.)
2. Hand-tighten the adjustment nut and then use a hook spanner wrench to further tighten it until the match mark reaches the "0" position on the torque indicator.

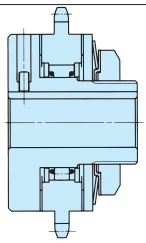
TFK 50 and 70

1. Tighten the adjustment nut and align it with the match mark on the hub.
2. Hand-tighten the bolts and then use a wrench to further tighten them until the "0"position on the indicators align with the match marks.

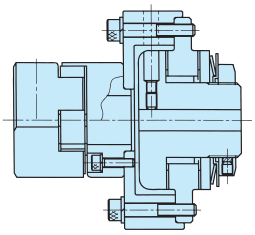
Special Type Torque Keeper



Model: TFK35W-2
(multiple disc type Torque Keeper)
Specifications: Bore dia. Φ25
Setting torque range 45 to 196N·m
{4.6 to 20kgf·m}



Model: TFK35LD-1
(Built-in Cam Clutch type Torque Keeper)
Specifications: Max. bore dia. Φ25
Setting torque range
11 to 43N·m{1.1kgf·m to 4.4kgf·m}
Main applications: Machines in which it is necessary to loosen bolts, nuts, or valves, etc., after tightening them with a fixed torque.



Model: TFK25-1C
(coupling type Torque Keeper)
Specifications: Max. bore dia. Torque Keeper side Φ22
Coupling side Φ29
Setting torque range 3.92 to 16.7N·m
{0.4 to 1.7kgf·m}

Note: contact TEM for more information on the special type.

Lock screw/tightening torque

Hexagon socket head screw	Tightening torque N·m{kgf·cm}
M5	3.8 {38.7}
M8	16 {163}

Precautions:

When re-tightening the lock screws that are once removed, make sure to take the following precautions:

1. Confirm that the plug tip has not been removed. If a lock screw is used with a tipless plug, the hub's thread may be damaged or the hub's pocket may get jammed.
2. Confirm that the plug's tip has not been heavily damaged. If a lock screw is used with a heavily damaged plug tip, the hub's thread may be damaged.

*If 1. or 2. is found to be the case, exchange the damaged parts with new ones.

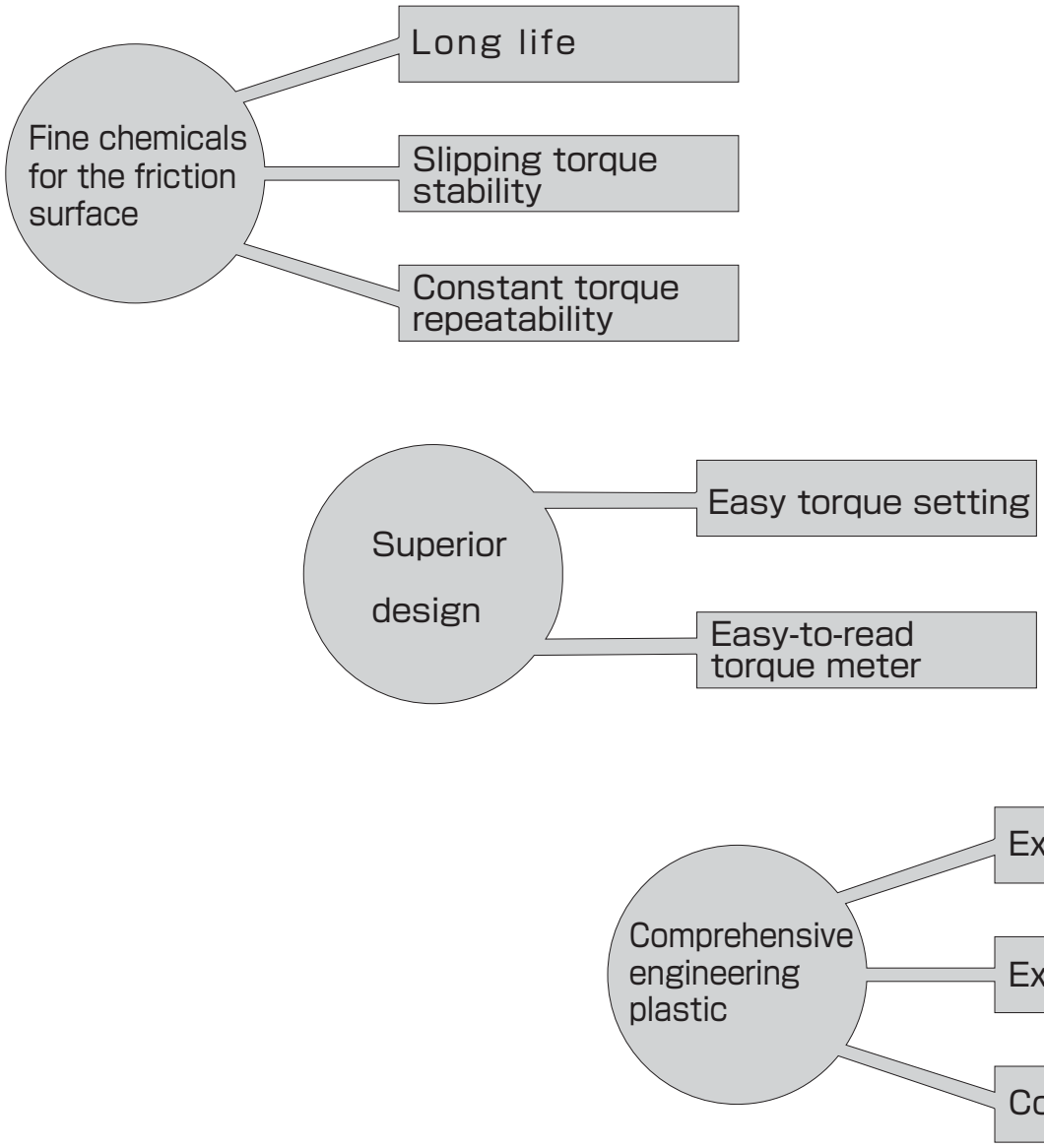
MEMO

MINI-KEEPER

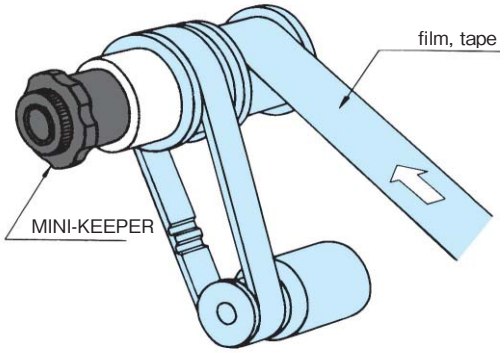
Features

Highly accurate, light and super-compact slipping clutch and brake

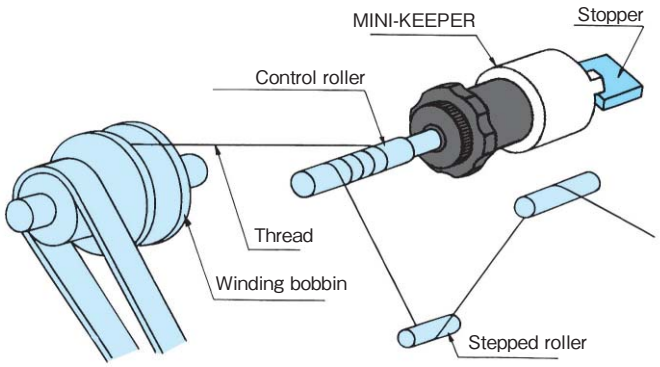
The TSUBAKI MINI-KEEPER is a super-compact slipping clutch and brake, constructed from fine chemicals and engineering plastic. With the MINI-KEEPER we have achieved supreme levels of lightness, compactness, and accuracy among similar devices. The MINI-KEEPER is ideal for braking, accumulating, and dragging applications in OA equipment and precision machinery.



Applications



The MINI-KEEPER slips and maintains constant tension on the tape (or film, etc.).
It is ideal for braking in the winding and unwinding.



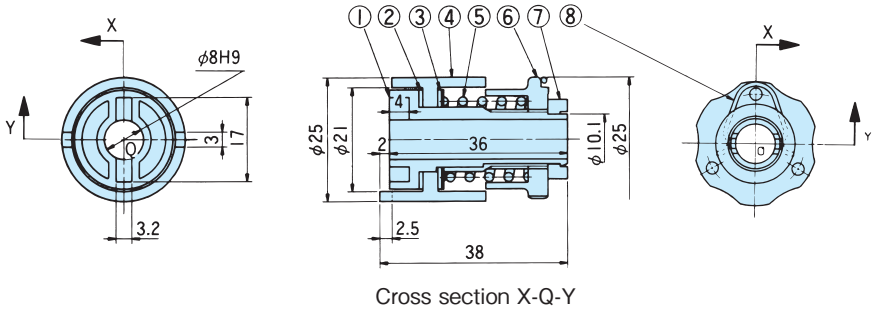
The MINI-KEEPER is installed on the tension controller in previous stage of the winding roll.
It provides stable slip torque and maintains stable tension on the thread.

<Other potential applications>

Thermal printer
Paper feeder
Plotter
Copier
Textile machine
Wire cutter
Film processing equipment
Accumulation conveyor
Automatic packaging machine
Coil winding machine
Labeler
Barcode printer
Electronic device manufacturing equipment
Various robots
Ribbon printer
Facsimile

Dimensions

MK08

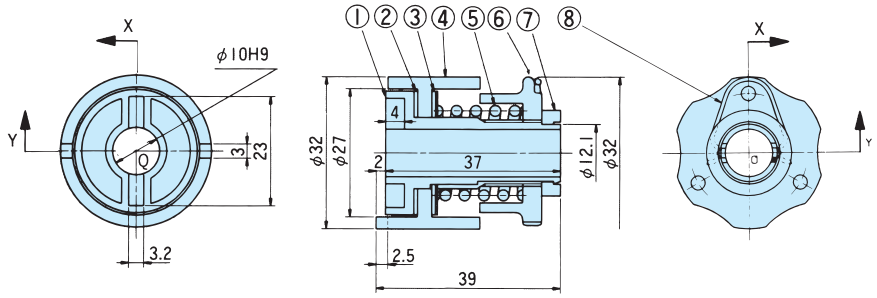


Cross section X-Q-Y

Setting torque range
1.96 to 9.80N·cm
{0.2 to 1.0kgf·cm}
Maximum slip rpm
Refer to "T-N Curve" on the next page
Mass: 18 g

① Hub
② Friction facing A
③ Friction facing B
④ Flange
⑤ Coil spring
⑥ Adjustment nut
⑦ Stop collar
⑧ Anti-rotation clip

MK10

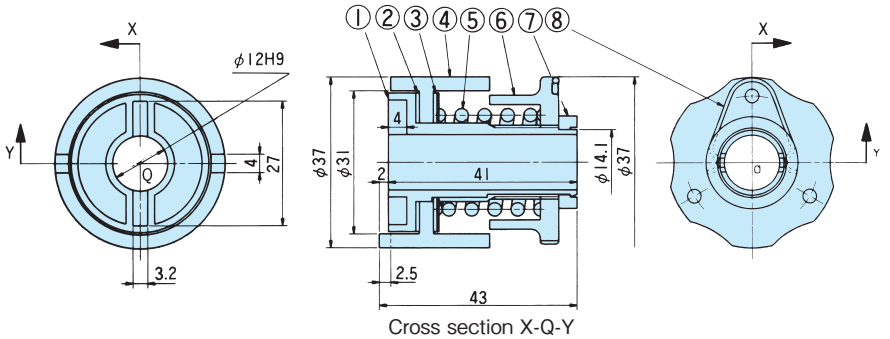


Cross section X-Q-Y

Setting torque range
4.90 to 19.6N·cm
{0.5 to 2.0kgf·cm}
Maximum slip rpm
Refer to "T-N Curve" on the next page
Mass: 30 g

① Hub
② Friction facing A
③ Friction facing B
④ Flange
⑤ Coil spring
⑥ Adjustment nut
⑦ Stop collar
⑧ Anti-rotation clip

MK12



Cross section X-Q-Y

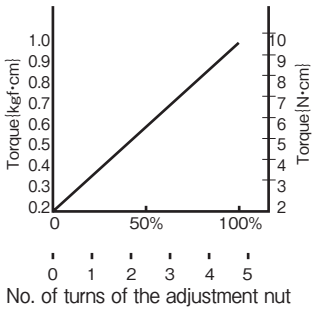
Note: All models are in stock.

Setting torque range
10.8 to 39.2N·cm
{1.1 to 4.0kgf·cm}
Maximum slip rpm
Refer to "T-N Curve" on the next page
Mass: 46 g

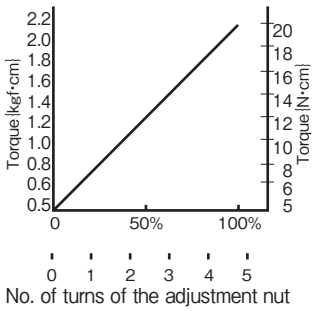
① Hub
② Friction facing A
③ Friction facing B
④ Flange
⑤ Coil spring
⑥ Adjustment nut
⑦ Stop collar
⑧ Anti-rotation clip

Torque Curves

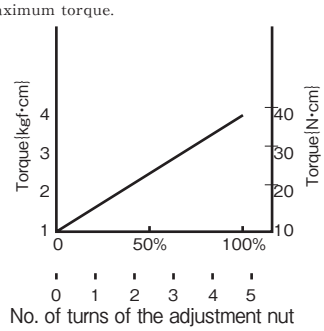
The percentage axis indicates the percentage of maximum torque.



The percentage axis indicates the percentage of maximum torque.



The percentage axis indicates the percentage of maximum torque.



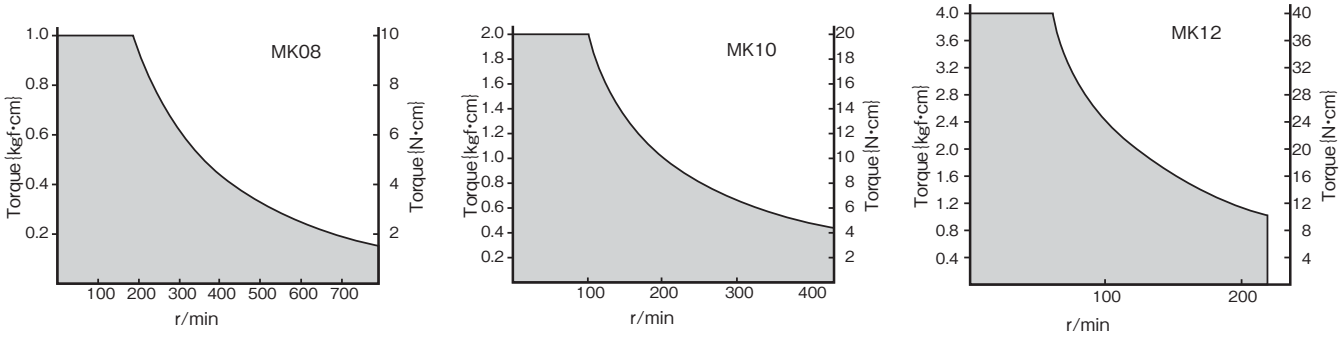
Selection

When using the MINI-KEEPER with a human transport device or a lifting device, install a suitable protection device on that equipment for safety purposes. Otherwise an accident resulting in death, serious injury or damage to the equipment may occur due to human disaster and an accidental falling.

Choose set torque and slip rpm from the ▭ part of the T-N curve graphs below.

* The T-N curve graph displays the limit value reached by heat generation during continual slip. When the slip time per one operation is short and the interval is long, it is possible to use the MINI-KEEPER in excess of the T-N value. In this case, please contact TEM for a consultation.
* Contact TEM for non-standard specifications.
* However, be aware that when the speed is 30 r/min or less, a stick-slip phenomenon may occur, which will cause unstable torque. A stick-slip phenomenon is a phenomenon in which a friction surface slips and stops repeatedly.

T-N Curve



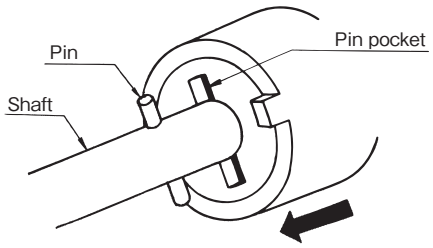
The T-N curve is applied when the ambient temperature is 40℃ or lower.

Contact us for other cases.

Handling

Installation onto a shaft

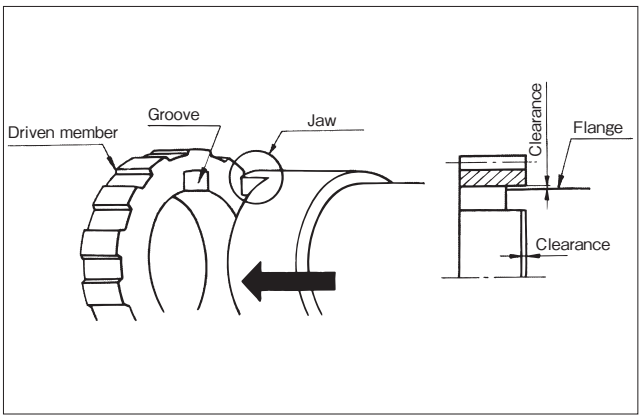
1. The MINI-KEEPER's shaft bore is already finished. We recommend a tolerance for the installation shaft dia. of h7 or h8.
2. Use the pin pocket (groove) on the end face of the hub to connect the MINI-KEEPER to the shaft. Insert the pin into the shaft, and then set them to the pin pocket as shown in the diagram below. The clearance should be about 0.5mm.



Make sure to set a clearance between pin end face, side and pin pocket.
Pin bore machining is different depending on the sort of pin.

Installation onto a driven member

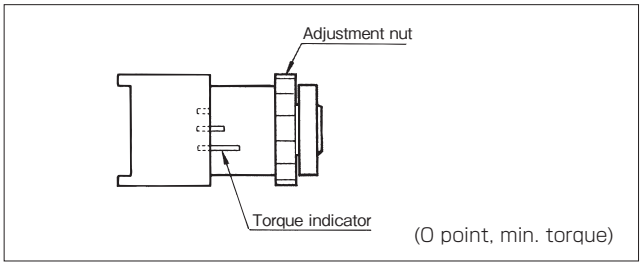
1. Use a jaw at flange to install the MINI-KEEPER onto a driven member (gear, pulley, etc.).



Cut a groove into the end face of the driven member, and slide the jaw into it. At this time, be sure to allow a clearance so that thrust and radial loads do not act on the flange end face including the jaw. The clearance should be about 0.5mm.

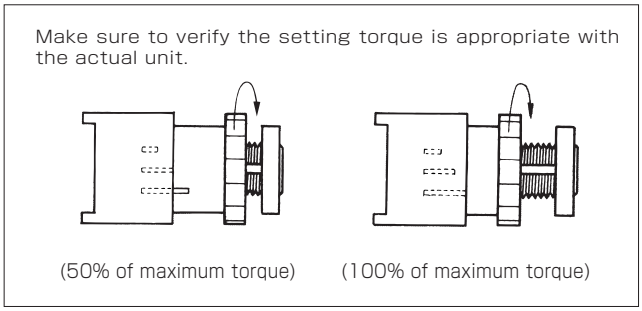
Torque setting

1. All MINI-KEEPERs are set at the zero point (minimum torque) before shipment. When in this condition, the scale above the periphery of the adjustment nut is as shown in the diagram below. Verify this.

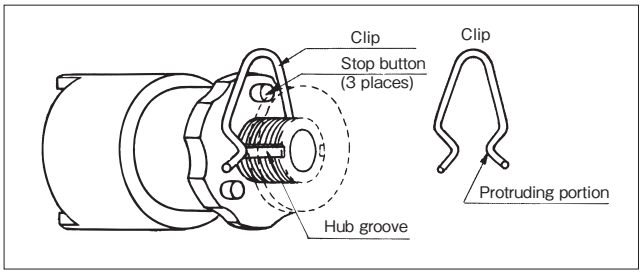


2. Set the torque by tightening the adjustment nut. Refer to the torque curve on page 157. Use the torque indicator as a guide for the torque setting illustrated below.

Make sure to verify the setting torque is appropriate with the actual unit.

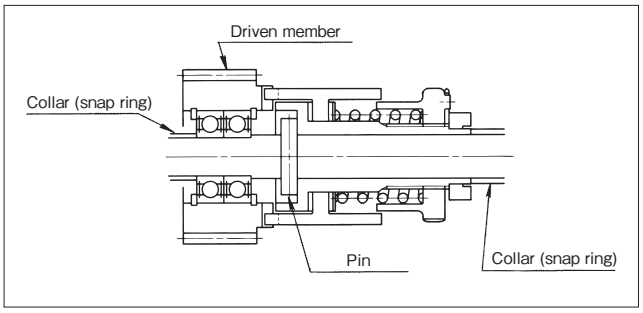


3. After setting the torque, fix the adjustment nut to stop it from rotating. Do this by inserting the accessory clip for anti-rotating between the adjustment nut and the stop collar as shown below. Make sure to verify the protruding portion of the clip for anti-rotating is inserted at the hub groove (both sides). Anti-rotation is made by the clip for anti-rotating hitting the stop button (convex portion) of the adjustment nut.



Note: 1. If oil or water gets into the friction facings, it will result in abnormal torque and unstable slipping torque.
2. The standard highest operating ambient temperature for the MINI-KEEPER is 40℃ If this will be exceeded, contact TEM.

Installation example



SAFCON

Control Devices

Electrical

Shock Monitor

Shock Monitor

(Industrial Property Right Patent No. 2796775 and others)

Features

The Shock Monitor is a power monitoring safety and control device that can detect even the minimal variations in load by monitoring input power.

1. Ideal for monitoring light loads

For a standard motor there are only minute current variations in the light load zone. For load monitoring of the device used in the light load zone, monitoring electric power variations in the proportional load is ideal.

2. Almost completely unaffected by source voltage variation

Even with a constant load, if the power supply fluctuates then current will fluctuate largely, thus making accurate load detection impossible. While the Shock Monitor is monitoring machine power it is almost completely unaffected by voltage fluctuation, so stable load detection is possible.

3. Can be used with a wide range of frequencies (5-120Hz)

Can be used with an inverter and a servomotor drive. (The inverter's electronic thermal is for burnout protection. Not suitable for device protection.)

* If the power source frequency exceeds 120Hz such as servo motor for machine tool main spindle, consult TEM.

4. Quick response

Input power is measured every 0.02s. Right after trouble happens, the signal is output in a minimum of 0.05s.

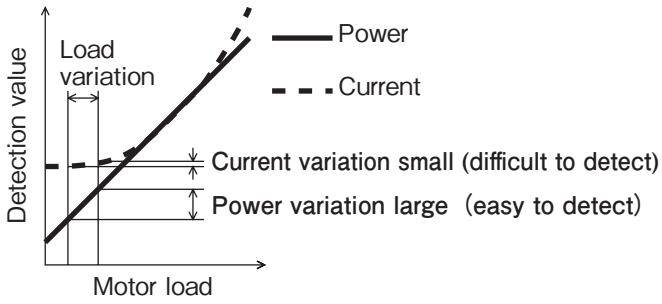
5. Load condition recording

The direct current voltage that is proportionate to motor input power is output, so the load condition can be recorded on the recorder.

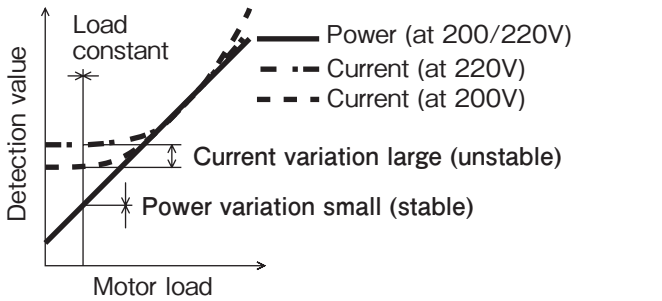
TSM4000 Series
converted into 0 to 10V (basic type)
converted into 0 to 5V (optional)
converted into 4 to 20mA (optional)

6. CE compliancy possible

For details, contact TEM.



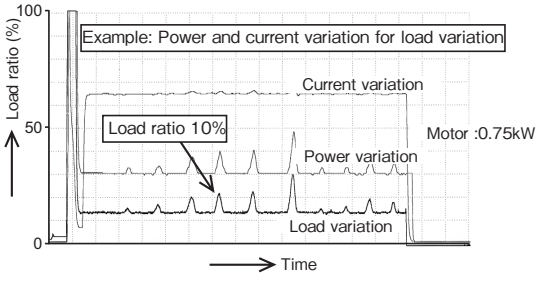
Variation at light load zone



Influence of power source voltage fluctuation

Example: Power and current variation for load variation

(1) The power variation that is proportional to load variation is emerged.
(2) From the chart below we can see that with a load variation of about 10%, there is almost no change in current, while power makes remarkable change.



Model reference chart

Item \ Model No.			TSM4000 *1 *2 Basic type	TSM4000H1 *2 Economy type	TSM4000H2 Load following type	TSM4000M1 Contact detection type	TSM4000M2 Integral power type	TSM4000C1 Built-in forward/reverse sequencer type
Applied motor	Capacity		0.1 to 110kW					
	*3 Power source voltage		AC200/220V, AC400/440V					
	Frequency		5 to 120Hz					
Control power supply voltage			AC90 to 250V50/60Hz, DC90 to 250V Nonpolar					
Input	*3 Motor voltage		AC250V, MAX					
	Current sensor		DC2.5V					
	Control input		X1, X2, X3, IH, RST	X1, X2, RST	X1, RST	X1, X2, X3, X4, X5	X1, X2, X3, X4, X5	X1, X2
Output	No. of contact		3c	2c	2c	3c	3c	2a, 1b, 1c
	Relay contact output		AC250V, 0.5A (Inductive load cos ϕ = 0.4) DC30V, 0.4A (Inductive load) DC110V, 0.2A (Inductive load) Minimum load applicable DC24V, 4mA					
	Output relay life	Mechanical	10,000,000 activations					
		Electrical	100,000 activations					
	Analog output relay		DC0 to 10V					
Setting	Load setting level	Output 1	High1 – 200 to 200%	HIGH1 5 to 200%	HIGH1 1 to 99%	OUT1 1 to 99%	OUT1 0 to 99%	Overload 5 to 200%
		Output 2	High2 – 200 to 200%	HIGH2 5 to 200%	HIGH2 5 to 200%	OUT2 1 to 99%	OUT2 5 to 200%	No load 5 to 200%
		Output 3	Low – 99 to 99%	———	———	OUT3 5 to 200%	OUT3 5 to 200%	———
	Start time setting range		0.1 to 20.0s					1 to 300s
	Shock time setting range		"MIN" or 0.1 to 10.0s In case motor power souce frequency is 50Hz and higher, shock time at "MIN" is approximately 50ms.					
	Reponse		Set by number of moving average	QUICK (Average no. 1 time), NORMAL (Average no. 5 times), SLOW (Average no. 20 times)				
Function	*4 Inhibit function		Manual/auto switching	Autoinhibit		Manual/auto switching		———
	Relay self-holding		Self-hold/auto reset selectable				Only OUT3 is selectable	Sequencer function
	Switching detection level		8 steps	4 steps	None	8 steps		None
	Test function		Relay output test					
	Peak-hold function		When the load ratio exceeds the pre-set level (or falls below it), shows the maximum value within shock time. Only when the output is set as self-hold, it is peak hold.					
Display	% Power display range		– 200 to 200%	0 to 200%				
	Voltage display range		0 to 500V					
	Current display range		0.01 to 999A					
	Frequency display range		5 to 120Hz					
Power consumption			10VA (Inrush current 5A within 5ms)					
Approximate mass			1.0kg					
Work environment	Ambient temperature		0 to 50℃					
	Reative humidity		45 to 85% RH; there is no condensation					
	Altitude		1000m and less					
	Ambient atomosphere		No corrosive gas, dust					

Note: *1. Basic type can monitor not only positive (plus) torque but also negative (minus) torque.
*2. Basic type and Economy type can monitor power or torque.(Negative torque can not be monitored by the Economy type.)
In case of torque monitoring, torque is calculated by the monitored power, and displayed. In this case, rated torque (100%) is that at 60Hz.
In case the frequency is 20Hz and below, errors become larger due to motor efficiency. In this case, use for power monitoring.
*3. In case Shock Monitor is used at AC400/440V, a 400V class resister "TSM4-PR1" is necessary.
*4. This is the function to stop the power monitoring of Shock Monitor. Basic, M1 and M2 types can inhibit manually, and between inhibit input terminal and CM are ON within setting time, or during ON, load ratio "0%" flashing and do not monitor power.
In addition, if the frequency changes 4Hz/1s of motor voltage, monitoring is automatically stopped. (Auto inhibit)

⚠ Warning

When using the Shock Monitor with a human transport device or a lifting device, install a suitable protection device on that equipment for safety purposes.
Otherwise an accident resulting in death, serious injury or damage to the equipment may occur due to a falling accident.

Quickly detects small load changes

Shock Monitor TSM4000

Contributes to "visualization" in factories (option)

Combining a commercially available touch panel display and a shock monitor having an optional communication function makes it possible to display the current readout of the shock monitor and a trend graph of the readout on a remote display.

Also, you can change the parameters of the shock monitor through remote touch panel operations.

* For the details of the optional communication function, contact our customer service center listed on the back cover.

Features

Safety Design

The terminal block is equipped with a cover.

This structure prevents dust from entering the main unit.

Analog output

A 0 to 10 V analog output is available as a standard feature (also, 0 to 5 V and 4 to 20 mA outputs are available as options), which enables actions and monitoring according to the load.

Environmental Consideration

The backlight automatically turns off, which contributes to the saving of energy.

This product does not contain any RoHS restricted substances, so it is environmentally friendly.

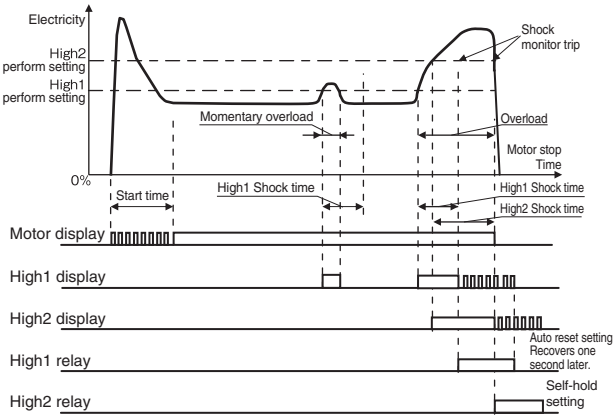
Improved Handleability

The panel-mount style is standardized to make connection to the terminal block easy when mounting this product on a panel.

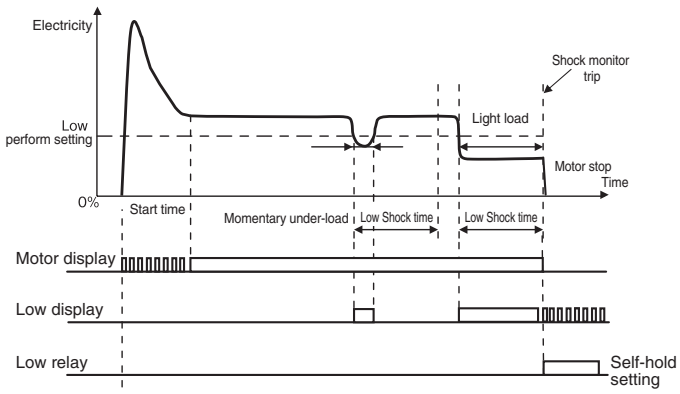
Also, this product can be mounted on DIN rails.

Basic operations of TSM4000

■ Overload operating mode



■ Light load operation mode



* The counting of both the start time and the shock time begins when the motor starts. Therefore, the one set to a longer time is valid.

1) The TSM4000 compares the load with the preset overload detection level, and presents an external notification of load abnormality when an overload state (or a light load state) continues for a certain period of time (the shock time).

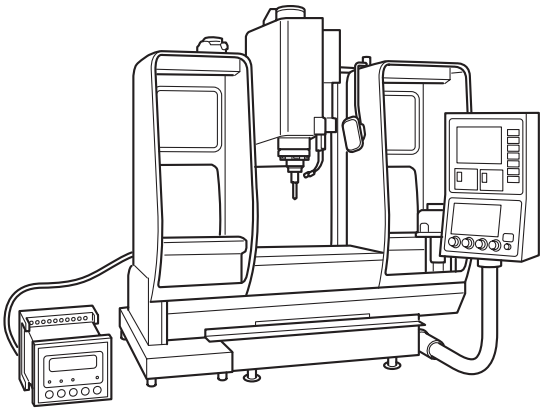
2) Two upper limit abnormality signals and one lower limit abnormality signal are available and can be used as prediction signals or motor stop signals.

3) To prevent false output due to acceleration, the load detection is canceled for a preset time (the start time) when starting the motor.

4) A torque monitoring function (20 to 120 Hz) is available, which is effective when an inverter is used. See Note) *2 on page 162.

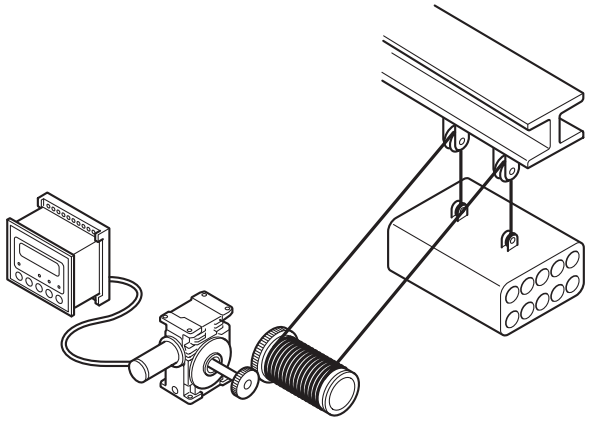
● Usage examples

Overload protection for machine tool/detection of drill breakage
Ideal for realizing a Dantotsu line



In a drilling process using a machine tool, the Shock Monitor reliably detects not only overload but also any breakage of the drill, preventing defective products from being produced during unattended operation.
Additionally, using a model which calculates integral power values enables detection of wear in the drill with high accuracy. Replacing the drill before breakage can prevent yield decreases.

Overload protection for a suspension/hoisting device

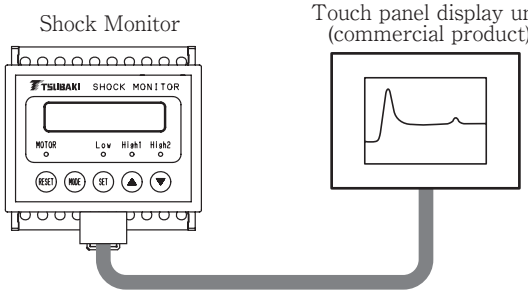


The Shock Monitor can be used with a hoisting device on a staging set or in a factory. When the load on the device exceeds the design load (allowable load), the drive system is stopped automatically to prevent accidents such as dropping.
The power detection method ensures highly accurate load detection even for high-reduction operation using a worm gear reducer in the drive unit.

● Application examples of the optional communication function

The optionally available communication function enables the combination of the Shock Monitor and a commercially-available touch panel display unit to be used in the following ways:

<Functions available with the display unit>
- Displaying of electrical power, current, and voltage data in graph form
- Saving of the above data and transferring the data into memory
- Reading/writing of setting values for a specified parameter



Communication specifications

item	Brief specifications
Transmission standard	RS485
Communication method	Half-duplex, bidirectional, Modbus protocol
Transmission speed	Selectable from 2.4, 4.8, 9.6, 19.2, and 38.4kbps

<Usage>
- The production process can be monitored using real-time displays of power and current waveforms.
- Checking the waveform of abnormal events is effective in preventive measures or making improvements to guard against device damage.

For details, contact TEM.

● Model No.

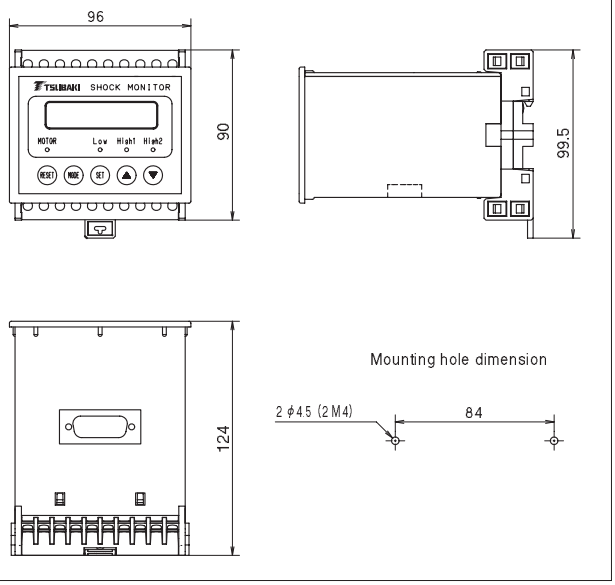
TSM4000 P – □□□□ – A1

- Shock Monitor main unit
- Current sensor (Example: U010)

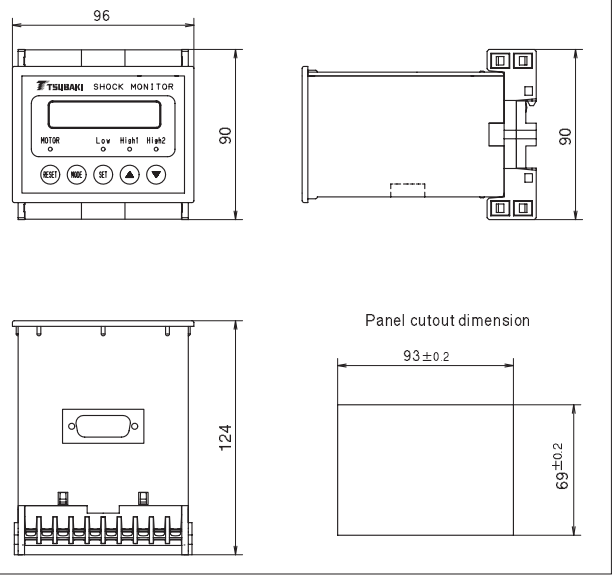
Type
- Blank : Basic type
- P : Panel mounting type
- H1 : Economy type
- H2 : Load following type
- M1 : Contact detection type
- M2 : Integral power type
- C1 : Built-in forward/reverse sequencer type

Option code
- Blank : Standard specification
- T1 : With communication function (consultation required)
- A1 : Analog output 4 to 20mA
- A2 : Analog output 0 to 5V

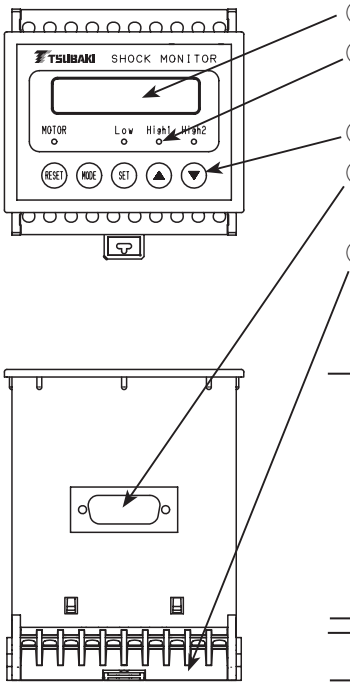
● Outline dimensions (Basic type)



● Outline dimensions (Panel mounting type)



● Part names and functions



① Liquid crystal display…… Displays load ratio, setting value, or parameter data.

② LED indicators …… Indicates the status where the motor is running and the output relay is activated.

③ Operation keys …… Keys used to toggle the display mode or change parameters.

④ Connector CN1 …… Connects a device to use signals for control input or analog output.

⑤ Terminal block for wiring Terminals for connecting control power supply, motor voltage, relay output, current sensor cable, etc.

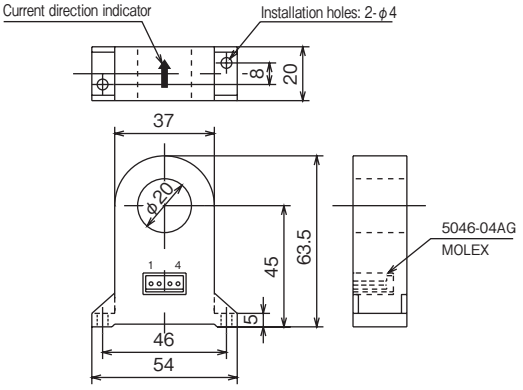
Option

■ Current sensor (attachment)

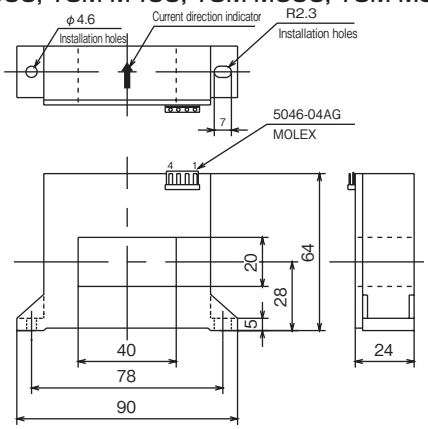
The current sensor brings motor current into the Shock Monitor unit.
Select a model from the chart below depending on the motor capacity and voltage.

	AC 200/220V motor		AC 400/440V motor	
Motor capacity (kW)	Sensor Model No.	Number of wires that pass through the CT hole	Sensor Model No.	Number of wires that pass through the CT hole
0.1	TSM-U010	6	TSM-U010	12
0.2	TSM-U010	3	TSM-U010	6
0.4	TSM-U010	2	TSM-U010	3
0.75	TSM-U050	6	TSM-U010	2
1.5	TSM-U050	3	TSM-U050	6
2.2	TSM-U050	2	TSM-U050	5
3.7	TSM-U050	1	TSM-U050	3
5.5	TSM-U050	1	TSM-U050	2
7.5	TSM-U100	1	TSM-U050	1
11	TSM-U100	1	TSM-U050	1
15	TSM-U150	1	TSM-U100	1
18.5	TSM-U150	1	TSM-U100	1
22	TSM-U200	1	TSM-U100	1
30	TSM-M300	1	TSM-U150	1
37	TSM-M300	1	TSM-U150	1
45	TSM-M400	1	TSM-U200	1
55	TSM-M600	1	TSM-M300	1
75	TSM-M600	1	TSM-M300	1
90	TSM-M800	1	TSM-M400	1
110	TSM-M800	1	TSM-M400	1

Sensor Model No.
TSM-U010, TSM-U050, TSM-U100, TSM-U150, TSM-U200



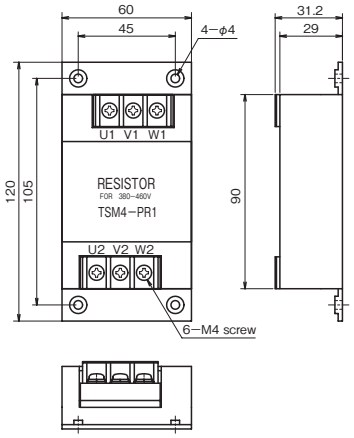
Sensor Model No.
TSM-M300, TSM-M400, TSM-M600, TSM-M800



■ 400V class resister

It is necessary in case the motor voltage is 400/ 440V. Please order separately.

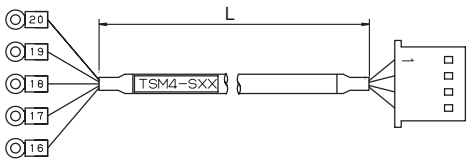
TSM4-PR1



■ Sensor cable

A 1 m length sensor cable (TSM4-S01) comes standard to connect the Shock Monitor and the current sensor.
In case a different cable is required, order the cable with the connector below separately.

Model No.	Cable length (L)
TSM4-S01 (attached)	1m
TSM4-S03	3m
TSM4-S05	5m
TSM4-S10	10m
TSM4-S20	20m
TSM4-S30	30m

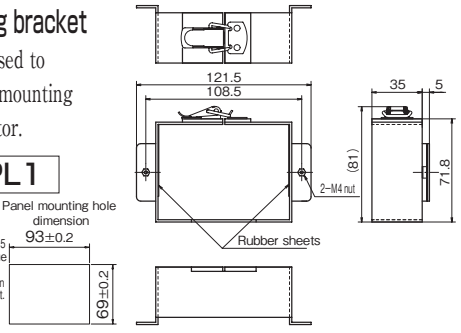


■ Panel mounting bracket

This bracket is used to secure the panel mounting type Shock Monitor.

TSM4-PL1

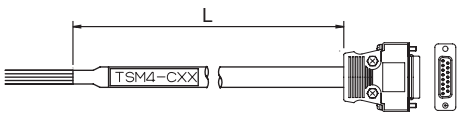
Note
1. Included
: M4 3-point SEMS screw x 15
2. Screw tightening torque
: 0.12 to 0.16N·m
3. Panel mounting hole dimension
: See the figure on the right.



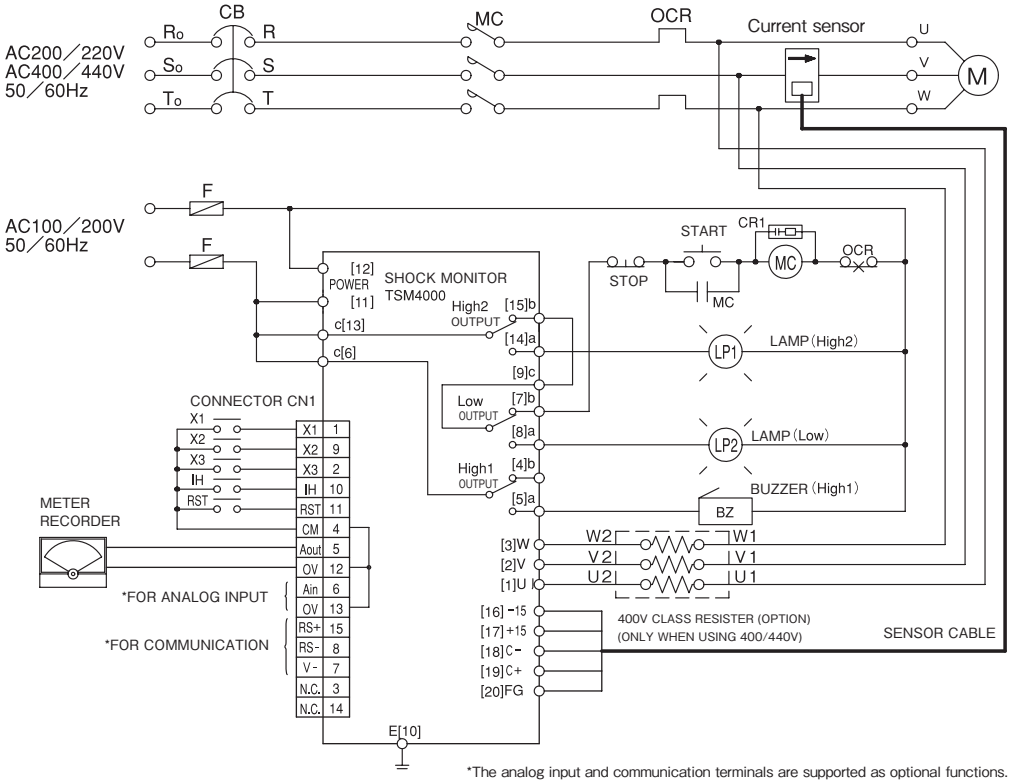
■ I/O cable

This cable is necessary when you want to perform process changeover from the outside, when resetting the shock monitor, and when connecting an external meter. It should be ordered separately when necessary.

Model No.	Cable length (L)
TSM4-C01	1m
TSM4-C03	3m



■ External connection



*The analog input and communication terminals are supported as optional functions.

CB : Circuit breaker
F : Fuse
MC : Electromagnetic contactor for motor
OCR : Over current relay
CR1 : CR filter
START : Start button
STOP : Stop button

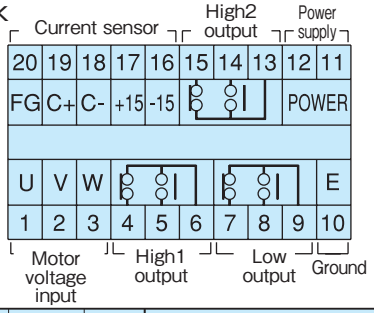
Operating electromagnetic coil capacity (magnetic capacity) of the electromagnetic contactor [MC] for motor should be less than 100VA when throwing, and less than 10VA when holding.

Note:
1. Select the current sensor from the Current Sensor table based on motor capacity and voltage. Use the specified number of pass through and current direction.
2. Make sure to insert the current sensor into the "phase V", and use sensor cable TSM-SXXN to connect with Shock Monitor.
3. If using a 400/440V motor, use 400V class resister shown in dashed line.
4. Connect motor voltage terminal of Shock Monitor U[1], V[2], W[3] with the phase of [U], [V], [W] respectively.
5. Use relay for minute electric current for [X1], [X2], [X3], [IH], [RST].

◎ In case of a wrong connection, load can not be detected correctly and the Shock Monitor will not work properly.

■ Terminal functions

・Terminal block



Name	Symbol	IN/ OUT	Pin No.	Explanation
Control power supply	POWER	IN	11	Connection of control power supply
			12	
Ground	E	—	10	Ground terminal
Current sensor	− 15	OUT	16	Sensor cable
	+15	OUT	17	
	C −	IN	18	
	C+	IN	19	
	FG	—	20	
Motor voltage	U	IN	1	Motor voltage input terminal
	V	IN	2	
	W	IN	3	
Low output	b	OUT	7	Relay contact output when the lower limit output is activated
	a	OUT	8	
	c	OUT	9	
High1 output	b	OUT	4	Relay contact output when the higher limit 1 output is activated
	a	OUT	5	
	c	OUT	6	
High2 output	c	OUT	13	Relay contact output when the higher limit 2 output is activated
	a	OUT	14	
	b	OUT	15	

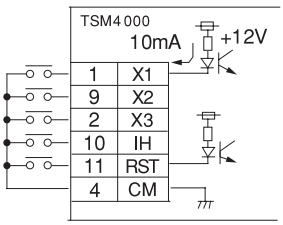
・Connector CN1

X1	X3	N.C.	CM	Aout	Ain	V-	RS-
1	2	3	4	5	6	7	8
9	10	11	12	13	14	15	
X2	IH	RST	OV	OV	N.C.	RS+	

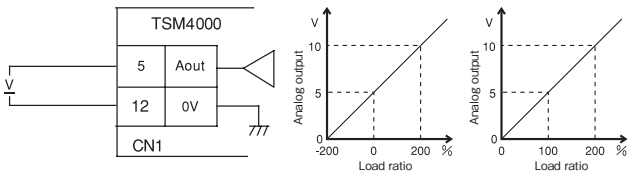
Note) Connection to pins No. 3 and 14 is prohibited.

Name	Symbol	IN/ OUT	Pin No.	Explanation
Process switch	X1	IN	1	Power process terminal
	X2	IN	9	
	X3	IN	2	
Inhibit	IH	IN	10	Inhibit terminal
Common	CM	IN	4	X1,X2,X3,IH,RST common terminal
Reset	RST	IN	11	Resetting self-hold status

■ Control input



■ Analog output



When the model supports the terminal function as standard, the analog output characteristic can be selected with Parameter 21: OUTPUT SELECT.

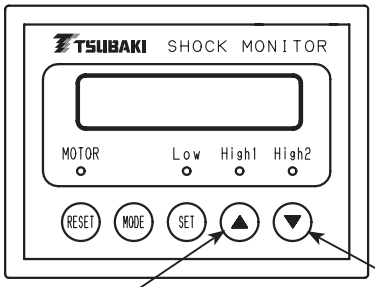
■ Parameter setting

No.	Parameter	Data	Data when shipment	Contents
1	Parameter Lock	(1)Unlocked	(1)	All parameters can be changed.
		(2)Locked		Parameters other than this parameter cannot be changed.
2	Motor Voltage	(1)200-230V	(1)	Motor voltage 3 phase 200V class
		(2)380-460V		Motor voltage 3 phase 400V class
3	Motor kW	0.1 to 110kW	0.75	Setting motor capacity
4	Start Time	0.1 to 20.0s	3.0s	Setting the start time
5	Process	1 to 8	1	Number of process
6	High2 Level Process[1]	-200 to -5% 5 to 200%	100%	Higher limit 2 level of process 1
7	Shock Time H2	MIN,0.1 to 10s	1.0s	Higher limit 2 shock time
8	Output Relay H2	(1)Self-Hold	(1)	Selecting the higher limit 2 output operation mode.
		(2)Auto-Reset		
9	High1 Level Process[1]	-200 to -5% 5 to 200%	80%	Higher limit 1 level of process 1
10	Shock Time H1	MIN,0.1 to 10s	1.0s	Higher limit 1 shock time
11	Output Relay H1	(1)Self-Hold	(2)	Selecting the higher limit 1 output operation mode.
		(2)Auto-Reset		
12	Low Level Process[1]	-99 to 0 to 99%	0%	Lower limit level of process 1
13	Shock Time L	MIN,0.1 to 10s	1.0s	Lower limit shock time
14	Output Relay L	(1)Self-Hold	(1)	Selecting the lower limit output operation mode.
		(2)Auto-Reset		
15	Motor Efficiency	10 to 100%	100%	Motor efficiency.
16	Response	1 to 50times	5times	Number of moving average sampling operations
17	Inhibit Time	IH,0.1 to 10s	IH	Inhibit time*
18	Auto Inhibit	(1)On	(2)	Setting the auto inhibit function.
		(2)Off		
19	Power/Torque	(1)Power	(1)	Monitor with motor input power
		(2)Torque		Monitor with the torque calculated by the power
20	H2Relay Logic	(1)Fail Safe	(2)	Selecting the fail-safe operation.
		(2)Nomal Logic		
21	Output Select	(1)-200 to 200%	(2)	Selecting the analog output.
		(2)0 to 200%		
22	LCD Backlight	(1)Always	(1)	Keeping the backlight on at all times.
		(2)2min		Turning the backlight off two minutes after key operation.
23	Trip Test	(1)Motor on/off	(1)	Selecton of test mode during motor operation
		(2)Motor off		

* Inhibit time: Time for which the power detection is temporarily stopped.

■ LCD contrast adjustment

When the LCD display is illegible, hold down the SET key and press ▲ or ▼ key to adjust it.
(Note that excessively high contrast will shorten the LCD service life.)



Hold down the SET key and press ▲ to make the display darker.

Hold down the SET key and press ▼ to make the display lighter.

New and unique applications for the Shock Monitor

Various application-specific types based on the "Basic type" of TSM4000!!

Our line-up of Shock Monitors fits perfectly with all kinds of applications.

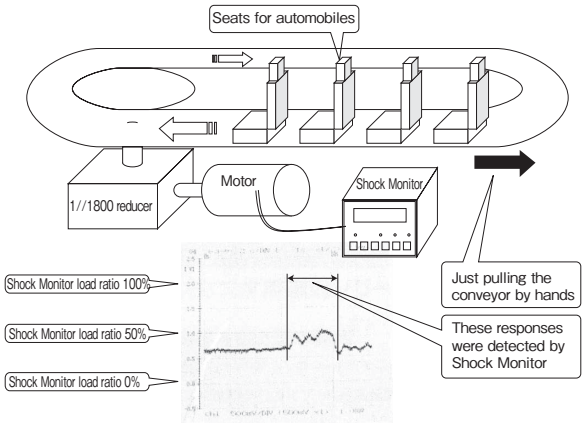
Application examples and basic operations of each type

1. [Basic type] TSM4000 type
   [Economy type] TSM4000H1 type ····For general industrial machines

The economy type has fewer functions than the basic type.
Refer to the below charts for a comparison of Shock Monitor functions.

■ Damage prevention

Low speed conveyor overload protection



Key point

There is little current variation due to a high gear ratio, making it difficult for the Shock Relay to detect the overload, so a power detecting type Shock Monitor is the best option.

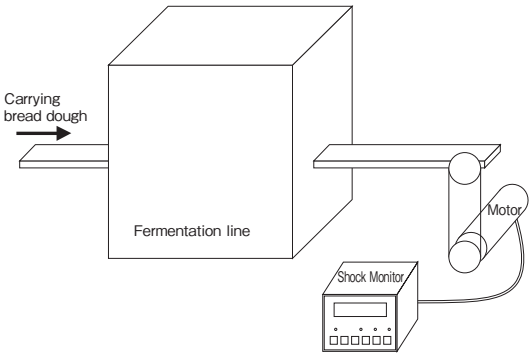
Applications

Assembly conveyor, water and sewage treatment, garbage disposal equipment conveyors, etc.

Note) Overload may be difficult to be detected depending on the characteristics of the machine. So, check your use conditions and contact us if you are considering detecting overloads.

■ Preventive maintenance

Bread making line lubrication maintenance



Key point

Shock Monitor detects even minute load rise due to the lack of lubrication for the chain. It then sends an alarm signal to operate the automatic lubricator.

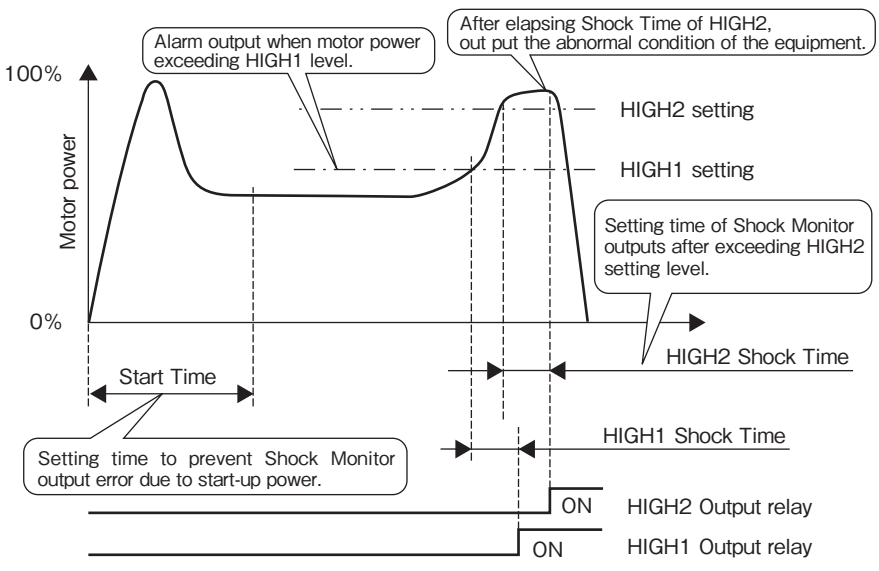
Applications

Food processing machines that operate 24 hours a day, etc.

Basic operations of TSM4000H1

● Minute load detection is possible by electric power: Economy type

Simplified setting type with fewer functions



[Features]

1) Simplified functions means easy setting.
2) Relay output has two outputs. It can be used as an alarm signal (HIGH1) and an abnormal level output (HIGH2).
3) As a set, HIGH1 and HIGH2 can be switched from the external for a maximum of 4 types. It is useful to change the setting depending on the work-piece being carried.
4) It comes with an efficient torque* monitoring function (20 to 120Hz) for when using the inverter.

*Refer to page 172, Note: *2

Comparison on function [Basic model] and Economy model]

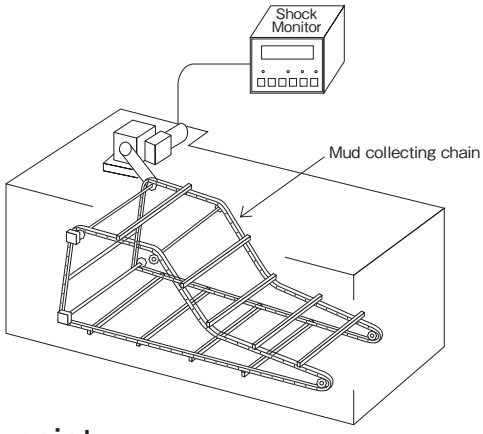
Function		Basic model	Economy model
Load detection	HIGH1	○	○
	HIGH2	○	○
	LOW	○	×
Torque monitoring function		○	○
No. of selection of detection level (No. of process to monitor)		8	4
Monitoring negative torque		○	×

Application examples and basic operations of each type

2.[Load following type] TSM4000H2 Type···For general industrial machines

■ Protection for equipment which varies in efficiency

● Equipment driven by worm reducer



Key point

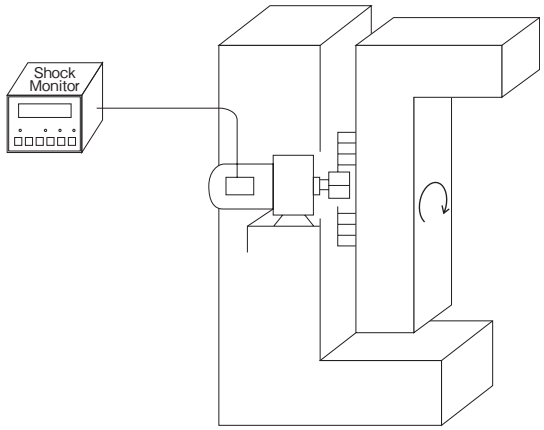
The efficiency of the reducer varies together with operating time. As well, even for equipment where the load ratio varies, it is possible to detect abnormal condition due to the load following function.

Applications

Water treatment equipment, etc.

■ Protection for equipment which periodically varies in load.

● Swivel



Key point

Even if the load of the equipment varies during 1 rotation, it is possible to detect abnormal conditions due to the load following function.

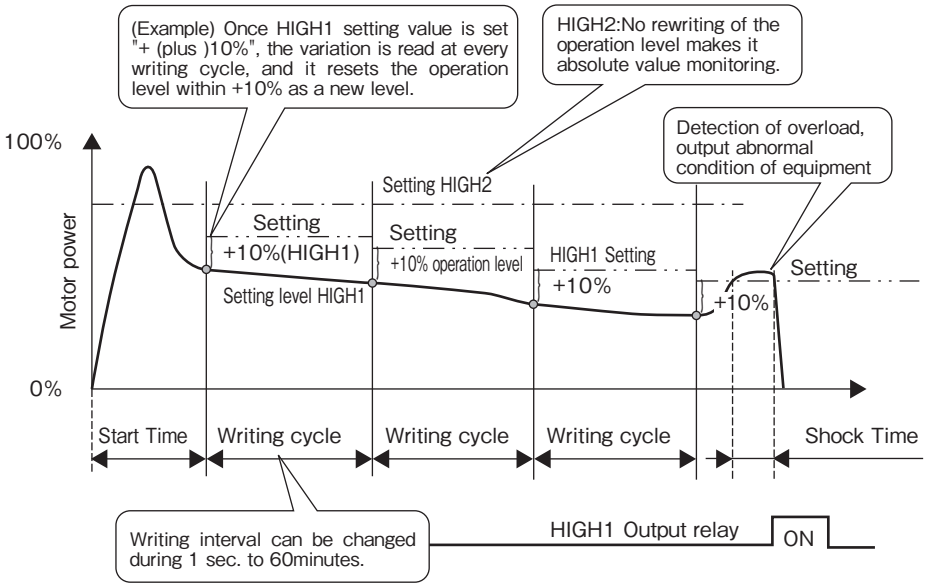
Applications

Medical equipment, etc.

Basic operations of TSM4000H2

● The set value automatically varies and follows the variation of load: load following

Because variation in machine efficiency does not affect the Shock Monitor, it makes the ideal overload protection device.



[Features]

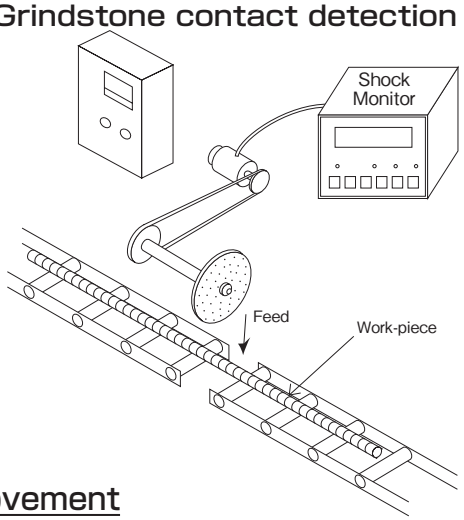
1) For equipment where mechanical efficiency varies by periodically following the operational level and minimizing the efficiency variation effect, the practical overload state can be detected.
2) The writing cycle can be changed to meet the fluctuations of the efficiency change.
3) While the operational level of HIGH2 is constant and has no variation, absolute value monitoring can be done by HIGH2.

Application examples and basic operations of each type

3.[Contact detection type] TSM4000M1 Type····For machine tools (Industrial Property Right Patent No.: 3108798)

■ Tool and work-piece contact detection (Feed speed control, etc.)

● Grindstone contact detection



Movement

Until the grindstone makes contact with the work-piece the feed speed is high. After the Shock Monitor has detected contact with the work-piece, the TSM4000M1 immediately switches to a low feed speed. (shortening the working time)

Key point

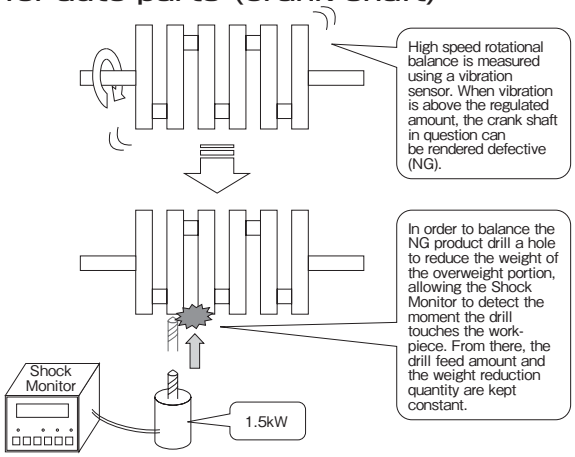
A minute load at an instant when the grindstone contacts with the work-piece is quickly and accurately detected. Consequently, a substantial decrease in the finishing cycle time is realized.

Applications

Metalworking, machine tools, etc.

■ Tool and work piece contact detection

● Rotational balance corrector for auto parts (crank shaft)



Movement

When drilling the hole, if the drill touches the work-piece, it will be detected and the Shock Monitor will immediately output. From there, by keeping feed time constant, the drilled quantity is managed uniformly.

Key point

The Shock Monitor ignores common changes to idling power. Because it can only detect work volume, it can securely judge the moment contact is made with the drill (0.03s).

Applications

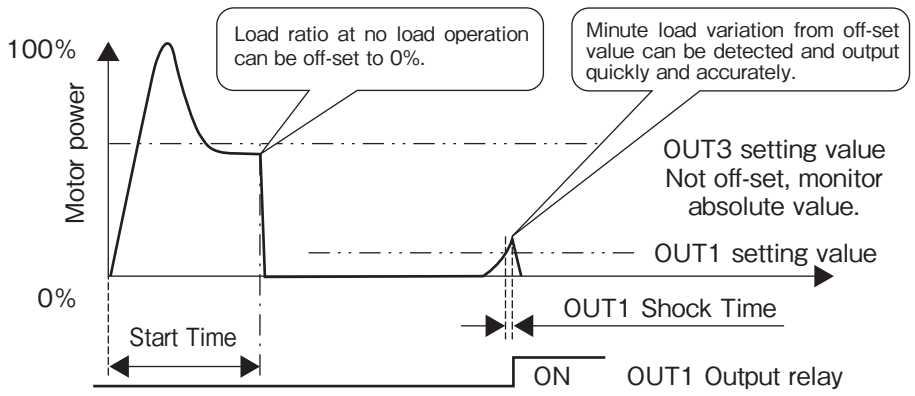
Machine tools (drilling machine, grinding machine, etc.)

Note: If the power source frequency exceeds 120Hz, such as a servo motor for a machine tool's main spindle, consult TEM.

Basic operations of TSM4000M1

● Rapidly detects work-piece contact: contact detection

The idling position is automatically offset to a 0% load ratio, and the Shock Monitor can only detect work volume.



[Features]

1) Because the TSM4000M1 automatically offsets power during idling to 0%, the minute power change during tool and work-piece contact can be detected with high precision. (There are two types of output: OUT1 and OUT2.)
2) OUT3 is not an off set value, and absolute value can be monitored.
3) In regard to a detection level, as a set, OUT1, OUT2 and OUT3 can be switched from the external for a maximum of 8 types, it can deal with the change of grindstone and work-piece.

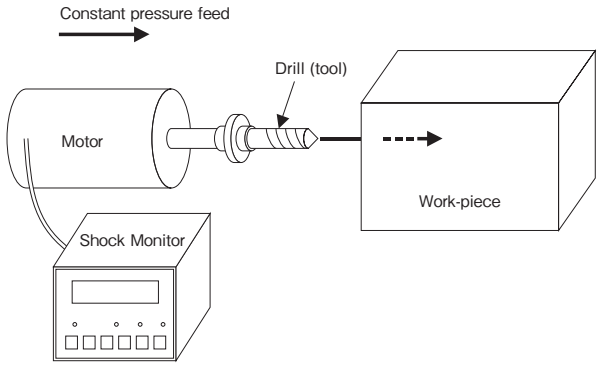
Application examples and basic operations of each type

4.[Integral power type] TSM4000M2 Type···· For machine tools

By integrating 1 cycle of power from the manufacturing process, tool wear condition and breakage, as well as overload can be detected.

■ Estimated tool service life

● Drill piece wear detection



Key point

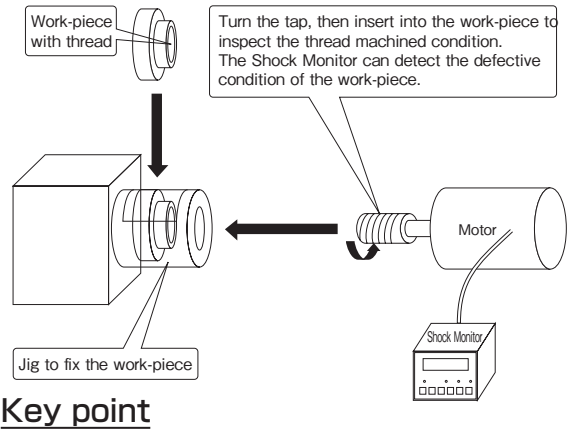
In regard to a constant pressure finishing machine, even the tool wears but the load variation is small. By taking advantage of the increase in machining time, high precision wear detection with the integral power type model is attained.

Applications

Machine tools, etc.

■ Check the product quality

● Screw thread quality inspection



Key point

Like when checking the quality of a tap hole, instantaneous power is unstable and the integral power type is ideal for applications where setting the detection level is difficult.

Applications

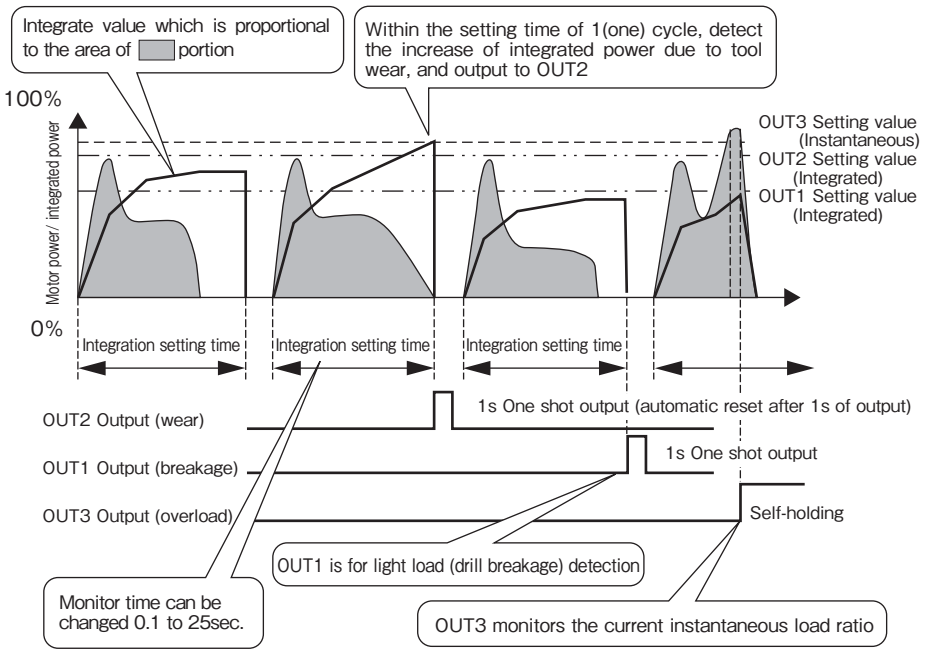
Inspection equipment etc.

Note: If the power source frequency exceeds 120Hz such as a servo motor for a machine tool main spindle, consult TEM.

Basic operations of TSM4000M2

● With the total power consumption of 1 cycle, machine tool wear, breakage and overload can be detected: integral power

Machine tool wear can be detected by integrated power, and outputting the abnormal condition.



[Features]

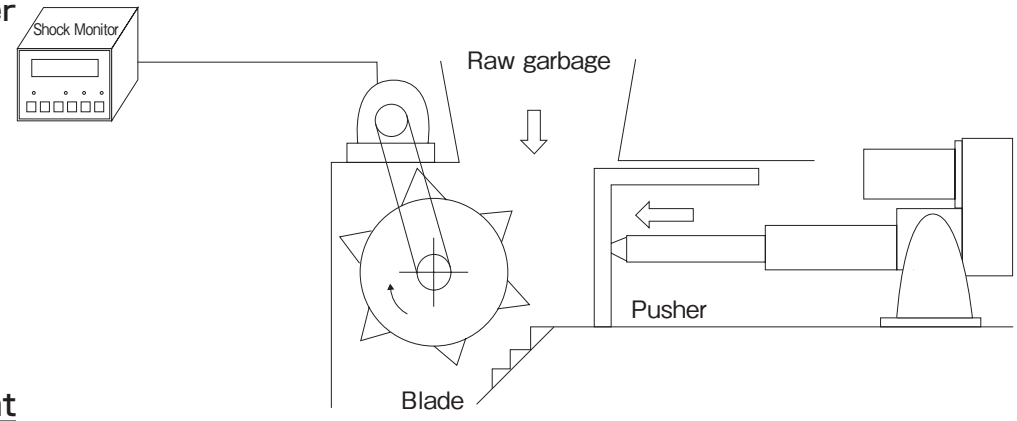
1) In regard to a constant pressure finishing machine, even the tool wears but the load ratio does not increase while the machining time increases. For this application it is monitored by power consumption (area).
2) After machining is completed, the drill wear is detected by the upper limit of power integration (OUT2), while the drill breakage can be detected by the lower limit (OUT1).
3) With the instantaneous value of OUT3, overload due to jam is monitored with absolute value.
4) As a set, there are a maximum of 8 types that OUT1, OUT2 and OUT3 can be switched between from the external. It works with the change of tools and work-pieces.
5) The elapsed time setting can be changed easily.

Application examples and basic operations of each type

5. For built-in forward and reverse sequence type: TSM4000C1 Type……For crushers

■ Crusher blade protection and forward/reverse control

● Crusher



Movement

Precisely detects load on crusher blades. When a jam occurs, the machine automatically detects overload → the machine stops → moves into reverse → stops → moves forward repeatedly until the machine becomes un-jammed.

Key point

Blade life span increases significantly. The sequence program necessary for forward and reverse movement is built-in, so it is easy to control the crusher.

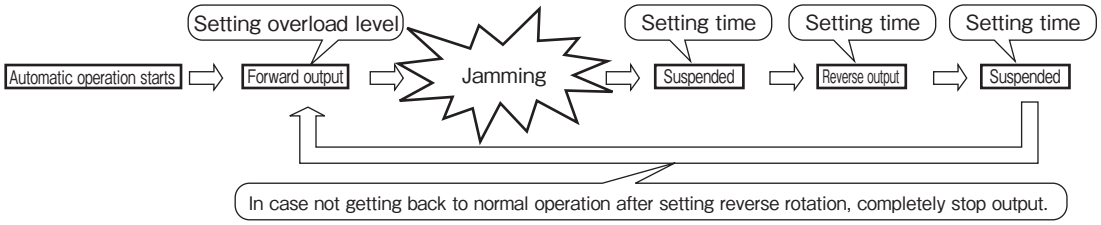
Applications

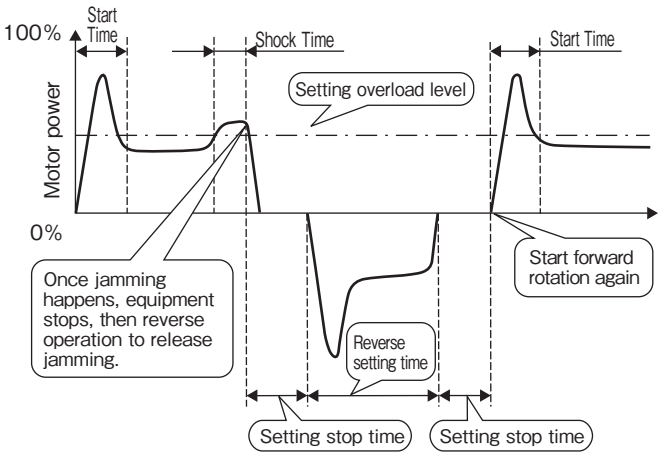
Crusher for waste disposal, reducer, screw conveyor, etc.

Basic operations of TSM4000C1

● When overload occurs the machine is automatically run in reverse: The sequence program for forward and reverse rotation is built-in.

The sequence control program for the crusher is built-in.





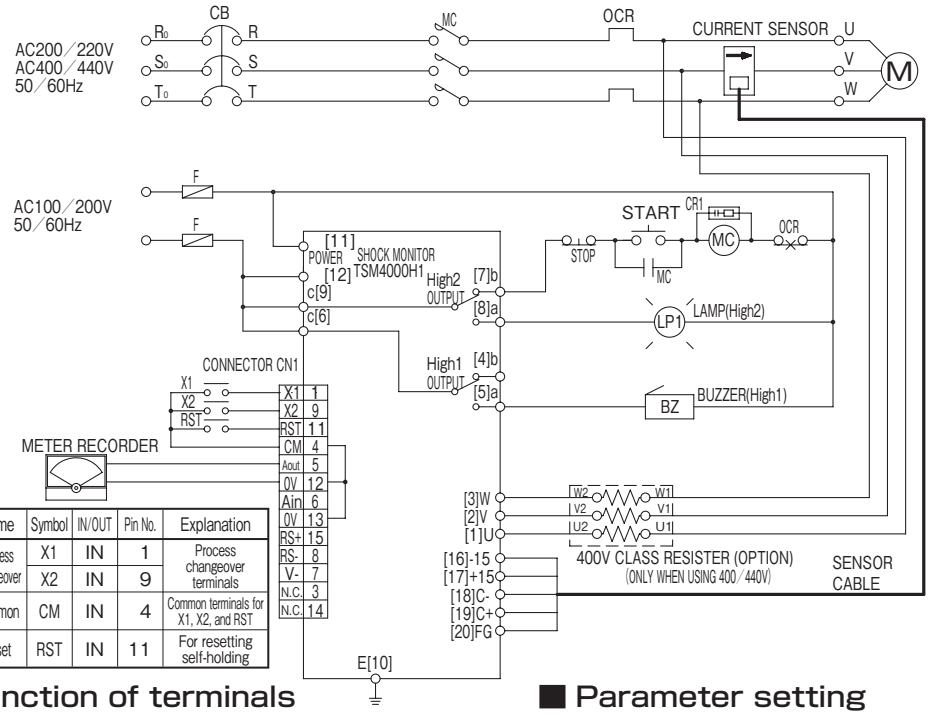
[Features]

1) Just by inputting the starting (forward movement) signal, stopping, reverse movement and restarting during overload can be controlled without an external sequencing program.
2) Even if the preset reverse setting time has past, when the machine does not return to normal operation, the stop signal is output and the device can be completely stopped.
3) The setting of overload level, stop time, and reverse running time can be easily done in the field.
4) To save energy it is possible to automatically stop when there is no load.

External connection/ parameter settings/ terminal functions

2. Economy type TSM4000H1 ····· For general industrial machinery

■ External connection



Name	Symbol	IN/OUT	Pin No.	Explanation
Process changeover	X1	IN	1	Process changeover terminals
	X2	IN	9	
Common	CM	IN	4	Common terminals for X1, X2, and RST
Reset	RST	IN	11	For resetting self-holding

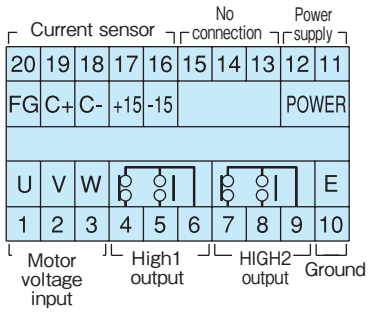
CB : Circuit breaker
F : Fuse
MC : Electromagnetic contactor for motor
OCR : Over current relay
CR1 : CR filter
START : Start button
STOP : Stop button

Operating electromagnetic coil capacity (magnetic capacity) of the electromagnetic contactor [MC] for motor should be less than 100VA when throwing, and less than 10VA when holding.

Note:
1. Select the current sensor from the Current Sensor table based on motor capacity and voltage. Use the specified number of passes through and current direction.
2. Make sure to insert the current sensor into the "phase V", and use the sensor cable TSM-SXX to connect with the Shock Monitor.
3. If using a 400/440V motor, use the 400V class resister shown in dashed line.
4. Connect the motor voltage terminal of the Shock Monitor U[1] ,V[2] ,W[3] with the phase of [U], [V], [W] respectively.
5. Use relay for minute electric current for [X1], [X2], [RST].

◎ In case of a wrong connection, load can not be detected correctly and the Shock Monitor will not work properly.

■ Function of terminals



Name	Symbol	IN/OUT	Pin No.	Explanation
Control power supply voltage	POWER	IN	11	Connection of control power supply
			12	
Ground	E	–	10	Ground terminal
Current sensor	-15	OUT	16	Sensor cable
	15	OUT	17	
	C-	IN	18	
	C+	IN	19	
	FG	–	20	
Motor voltage	U	IN	1	Motor voltage input terminal
	V	IN	2	
	W	IN	3	
HIGH 1 output	b	OUT	4	Relay contact output when the higher limit 1 output is activated
	a	OUT	5	
	c	OUT	6	
HIGH 2 output	b	OUT	7	Relay contact output when the higher limit 2 output is activated
	a	OUT	8	
	c	OUT	9	
No connection	–	N.C	13	Do not connect anything
		N.C	14	
		N.C	15	

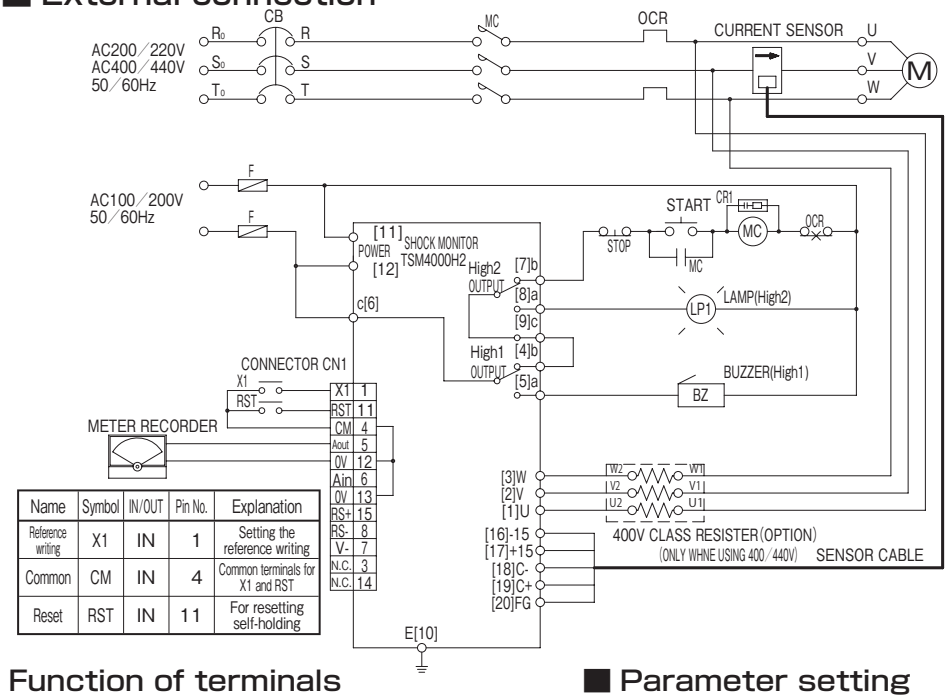
■ Parameter setting

No.	Parameter	Data		Data when shipment	Contents
1	Motor Voltage	(1)200-230V		(1)	Motor voltage 3 phase 200v class
		(2)380-460V			Motor voltage 3 phase 400v class
2	Motor kW	(1)0.1kW	(11)15kW	0.75kW	Setting motor capacity
		(2)0.2kW	(12)18.5kW		
		(3)0.4kW	(13)22kW		
		(4)0.75kW	(14)30kW		
		(5)1.5kW	(15)37kW		
		(6)2.2kW	(16)45kW		
		(7)3.7kW	(17)55kW		
		(8)5.5kW	(18)75kW		
		(9)7.5kW	(19)90kW		
		(10)11kW	(20)110kW		
3	Start Time	0.1 to 20.0s		3.0	Setting the start time
4	Process	1 to 4		1	Number of process
5	High1 Level	5 to 200%		80	Higher limit 1 level of process 1
6	Shock Time H1	MIN 0.1 to 10.0s		1.0	Higher limit 1 shock time
7	Output Relay H1	(1)Self-Hold		(2)	Selecting the output operation mode. (High1)
		(2)Auto-Reset			
8	High2 Level	5 to 200%		100	Higher limit 2 level of process 1
9	Shock Time H2	MIN 0.1 to 10.0s		1.0	Higher limit 2 shock time
10	Output Relay H2	(1)Self-Hold		(1)	Selecting the output operation mode. (High2)
		(2)Auto-Reset			
11	Response	(1)QUICK		(2)	Number of moving average operations
		(2)NORMAL			
		(3)SLOW			
12	Auto Inhibit	(1)On		(2)	Setting the auto inhibit function.
		(2)Off			
13	Power/Torque	(1)Power		(1)	Monitor with motor input power
		(2)Torque			Monitor with the torque calculated by the power
14	LCD Backlight	(1)Always		(1)	Setting the backlight illumination time.
		(2)2min			

External connection/ parameter settings/ terminal functions

3. Load following type TSM4000H2……For general industrial machinery

■ External connection



Name	Symbol	IN/OUT	Pin No.	Explanation
Reference writing	X1	IN	1	Setting the reference writing
Common	CM	IN	4	Common terminals for X1 and RST
Reset	RST	IN	11	For resetting self-holding

CB : Circuit breaker
F : Fuse
MC : Electromagnetic contactor for motor
OCR : Over current relay
CR1 : CR filter
START : Start button
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Operating electromagnetic coil capacity (magnetic capacity) of the electromagnetic contactor [MC] for motor should be less than 100VA when throwing, and less than 10VA when holding.

Note:
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2. Make sure to insert the current sensor into the "phase V", and use the sensor cable TSM-SXX to connect with the Shock Monitor.
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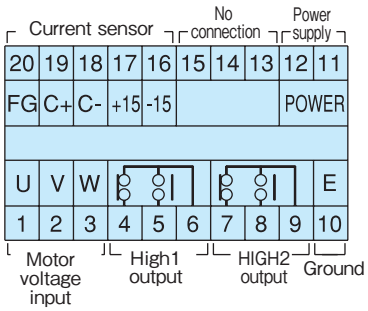
■ Function of terminals



Name	Symbol	IN/OUT	Pin No.	Explanation
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Current sensor	-15	OUT	16	Sensor cable
	15	OUT	17	
	C-	IN	18	
	C+	IN	19	
	FG	–	20	
Motor voltage	U	IN	1	Motor voltage input terminal
	V	IN	2	
	W	IN	3	
HIGH 1 output	b	OUT	4	Relative value higher limit output 1
	a	OUT	5	
	c	OUT	6	
HIGH 2 output	b	OUT	7	Absolute value higher limit output 2
	a	OUT	8	
	c	OUT	9	
No connection	–	N.C	13	Do not connect anything
		N.C	14	
		N.C	15	

■ Parameter setting

No.	Parameter	Data		Data when shipment	Contents
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		(2)380-460V			Motor voltage 3 phase 400v class
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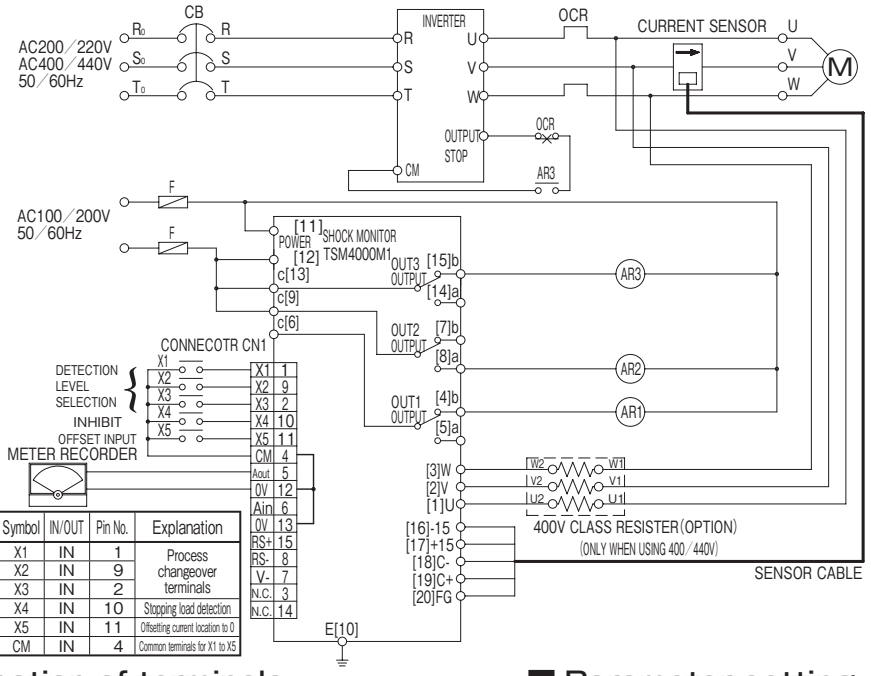
		(2)0.2kW	(12)18.5kW		
		(3)0.4kW	(13)22kW		
		(4)0.75kW	(14)30kW		
		(5)1.5kW	(15)37kW		
		(6)2.2kW	(16)45kW		
		(7)3.7kW	(17)55kW		
		(8)5.5kW	(18)75kW		
		(9)7.5kW	(19)90kW		
		(10)11kW	(20)110kW		
3	Start Time	0.1 to 20.0s		3.0	Setting the start time
4	High1 Level	1 to 99%		10	Value of higher limit 1
5	Shock Time H1	MIN		1.0	Setting HIGH 1 shock time
		0.1 to 10.0s			
6	Output Relay H1	(1)Self-Hold		(2)	Setting the output operation mode (High 1)
		(2)Auto-Reset			
7	High2 Level	5 to 200%		100	Value of higher limit 2
8	Shock Time H2	MIN		1.0	Setting HIGH 2 shock time
		0.1 to 10.0s			
9	Output Relay H2	(1)Self-Hold		(1)	Selecting the output operation mode (High 2)
		(2)Auto-Reset			
10	Response	(1)QUICK		(2)	Number of moving average operations
		(2)NORMAL			
		(3)SLOW			
11	Auto Inhibit	(1)On		(2)	Setting the auto inhibit function
		(2)Off			
12	Offset Mode	(1)Interval		(2)	Setting the reference writing
		(2)X1			
13	Interval Time	1 to 60s 1.1 to 60.0min		50s	Writing cycle
14	LCD Backlight	(1)Always		(1)	Setting the backlight illumination time.
		(2)2min			

External connection/ parameter settings/ terminal functions

4. Contact detection typeTSM4000M1 ····· For machine tools

■ External connection



Name	Symbol	IN/OUT	Pin No.	Explanation
Process changeover	X1	IN	1	Process changeover terminals
	X2	IN	9	
	X3	IN	2	
Inhibit	X4	IN	10	Stopping load detection
Offset	X5	IN	11	Offsetting current location to 0
Common	CM	IN	4	Common terminals for X1 to X5

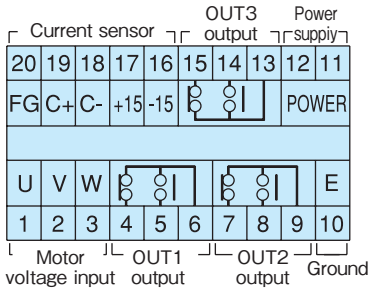
CB : Circuit breaker
F : Fuse
MC : Electromagnetic contactor for motor
OCR : Over current relay
CR1 : CR filter
START : Start button
STOP : Stop button

Operating electromagnetic coil capacity (magnetic capacity) of the electromagnetic contactor [MC] for motor should be less than 100VA when throwing, and less than 10VA when holding.

Note:
1. Select the current sensor from the Current Sensor table based on motor capacity and voltage. Use the specified number of passes through and current direction.
2. Make sure to insert the current sensor into the "phase V", and use the sensor cable TSM-SXX to connect with the Shock Monitor.
3. If using a 400/440V motor, use the 400V class resister shown in dashed line.
4. Connect the motor voltage terminal of the Shock Monitor U[1], V[2], W[3] with the phase of [U], [V], [W] respectively.
5. Use relay for minute electric current for [X1], [X2], [X3], [X4], [X5].

◎ In case of a wrong connection, load can not be detected correctly and the Shock Monitor will not work properly.

■ Function of terminals



Name	Symbol	IN/ OUT	Pin No.	Explanation
Control power supply voltage	POWER	IN	11	Connection of control power supply
			12	
Ground	E	–	10	Ground terminal
Current Sensor	-15	OUT	16	Sensor cable
	15	OUT	17	
	C-	IN	18	
	C+	IN	19	
	FG	–	20	
Motor voltage	U	IN	1	Motor voltage input terminal
	V	IN	2	
	W	IN	3	
OUT 1 output	b	OUT	4	Relative value higher limit output 1 after offset
	a	OUT	5	
	c	OUT	6	
OUT 2 output	b	OUT	7	Relative value higher limit output 2 after offset
	a	OUT	8	
	c	OUT	9	
OUT 3 output	c	OUT	13	Non-offset absolute value higher limit output.
	a	OUT	14	
	b	OUT	15	

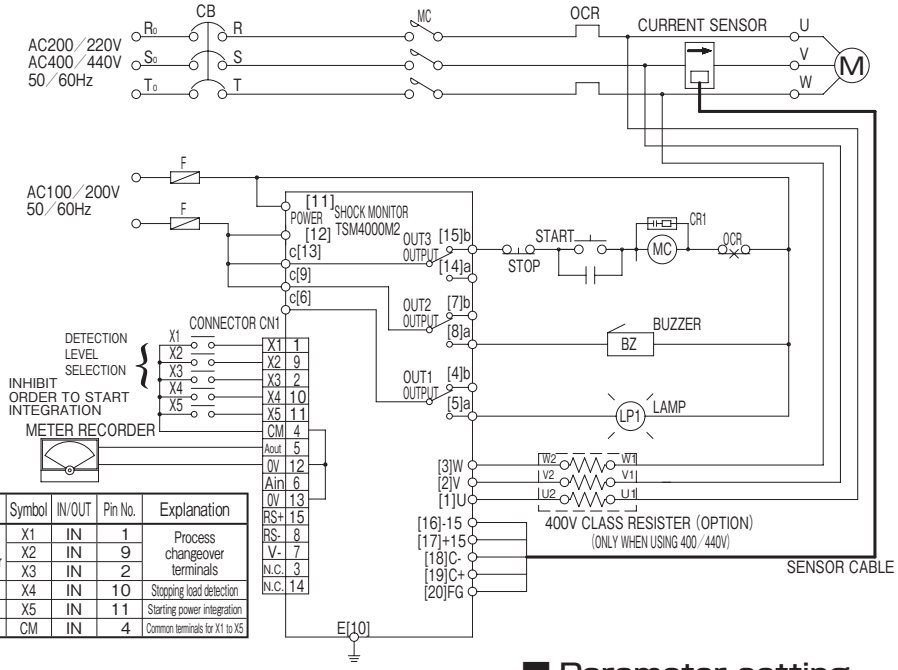
■ Parameter setting

No.	Parameter	Data	Data when shipment	Contents
1	Parameter Lock	(1)Unlocked	(1)	Can change parameter setting
		(2)Locked		Can not change parameter setting unless in an unlocked condition
2	Motor Voltage	(1)200-230V	(1)	Motor voltage 3 phase 200v class
		(2)380-460V		Motor voltage 3 phase 400v class
3	Motor kW	(1)0.1kW (11)15kW	0.75kW	Setting motor capacity
		(2)0.2kW (12)18.5kW		
		(3)0.4kW (13)22kW		
		(4)0.75kW (14)30kW		
		(5)1.5kW (15)37kW		
		(6)2.2kW (16)45kW		
		(7)3.7kW (17)55kW		
		(8)5.5kW (18)75kW		
		(9)7.5kW (19)90kW		
		(10)11kW (20)110kW		
4	Start Time	0.1 to 20.0s	3.0	Setting the start time
5	Process	1 to 8	1	Number of process
6	OUT1 Level	1 to 99%	10	OUT1 value
7	Shock Time OUT1	MIN 0.1 to 10.0s	1.0	OUT1 shock time
8	Output Relay OUT1	(1)Self-Hold (2)Auto-Reset	(2)	Selecting the output operation mode. (OUT1)
9	OUT2 Level	1 to 99%	15	OUT2 value
10	Shock Time OUT2	MIN 0.1 to 10.0s	1.0	OUT2 shock time
11	Output Relay OUT2	(1)Self-Hold (2)Auto-Reset	(2)	Selecting the output operation mode. (OUT2)
12	OUT3 Level	5 to 200%	80	OUT3 value
13	Shock Time OUT3	MIN 0.1 to 10.0s	1.0	OUT3 shock time
14	Output Relay OUT3	(1)Self-Hold (2)Auto-Reset	(1)	Selecting the output operation mode.(OUT3)
15	Response	(1)QUICK (2)NORMAL (3)SLOW	(2)	Number of moving average operations
16	Inhibit Time	IH 0.1 to 10.0s	IH	Setting the inhibit time
17	Auto Inhibit	(1)On (2)Off	(2)	Setting the auto inhibit function
18	LCD Backlight	(1)Always (2)2min	(1)	Setting the backlight illumination time

External connection/ parameter settings/ terminal functions

5. Integral power typeTSM4000M2····· For machine tools

■ External connection



Name	Symbol	IN/OUT	Pin No.	Explanation
Process changeover	X1	IN	1	Process changeover terminals
	X2	IN	9	
	X3	IN	2	
Inhibit	X4	IN	10	Stopping load detection
Start integration	X5	IN	11	Starting power integration
Common	CM	IN	4	Common terminals for X1 to X5

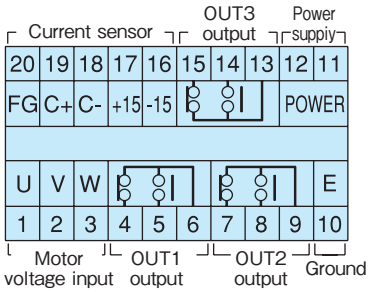
CB : Circuit breaker
F : Fuse
MC : Electromagnetic contactor for motor
OCR : Over current relay
CR1 : CR filter
START : Start button
STOP : Stop button

Operating electromagnetic coil capacity (magnetic capacity) of the electromagnetic contactor [MC] for motor should be less than 100VA when throwing, and less than 10VA when holding.

Note:
1. Select the current sensor from the Current Sensor table based on motor capacity and voltage. Use the specified number of passes through and current direction.
2. Make sure to insert the current sensor into the "phase V", and use the sensor cable TSM-SXX to connect with the Shock Monitor.
3. If using a 400/440V motor, use the 400V class resister shown in dashed line.
4. Connect the motor voltage terminal of the Shock Monitor U[1], V[2], W[3] with the phase of [U], [V], [W] respectively.
5. Use relay for minute electric current for [X1], [X2], [X3], [X4], [X5].

◎ In case of a wrong connection, load can not be detected correctly and the Shock Monitor will not work properly.

■ Function of terminals



Name	Symbol	IN/ OUT	Pin No.	Explanation
Control power supply voltage	POWER	IN	11	Connection of power source
			12	
Ground	E	–	10	Ground terminal
Current Sensor	-15	OUT	16	Sensor cable
	15	OUT	17	
	C-	IN	18	
	C+	IN	19	
	FG	–	20	
Motor voltage	U	IN	1	Motor voltage input terminal
	V	IN	2	
	W	IN	3	
OUT 1 output	b	OUT	4	Lower limit output after integration
	a	OUT	5	
	c	OUT	6	
OUT 2 output	b	OUT	7	Higher limit output after integration
	a	OUT	8	
	c	OUT	9	
OUT 3 output	c	OUT	13	Higher limit output at instantaneous electric power
	a	OUT	14	
	b	OUT	15	

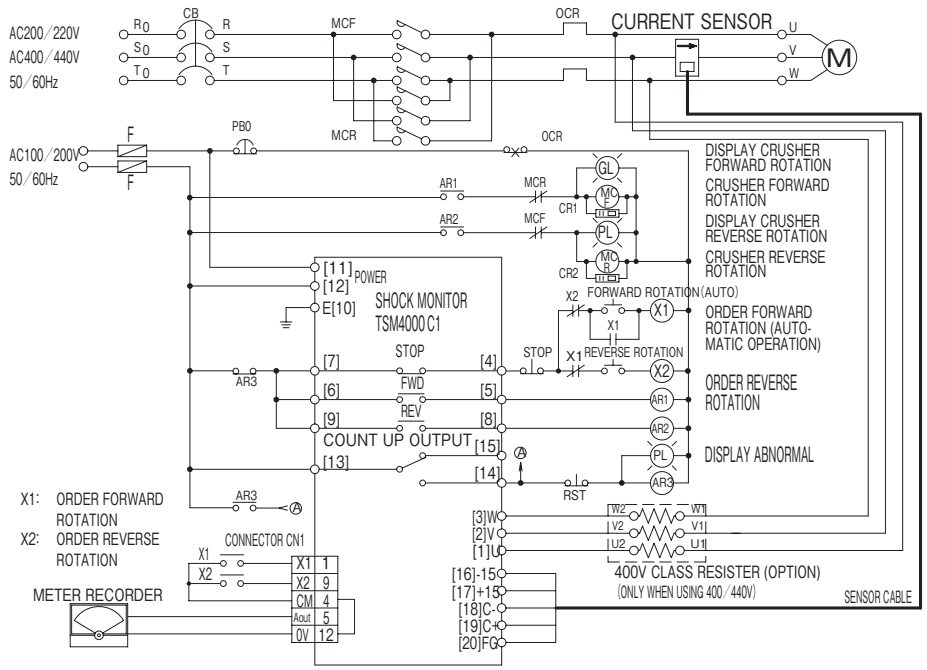
■ Parameter setting

No.	Parameter	Data		Data when shipment	Contents
1	Parameter Lock	(1)Unlocked		(1)	Can change parameter setting
		(2)Locked			Can not change parameter setting unless in an unlocked condition
2	Base Time	0.1 to 25s		2.5	Setting the time for the rated value of integrated power
3	Integration Time	X5,0.1 to 25s		5.0	Setting the time for power value integration
4	Motor Voltage	(1)200-230V		(1)	Motor voltage 3 phase 200V class
		(2)380-460V			Motor voltage 3 phase 400V class
5	Motor kW	(1)0.1kW	(11)15kW	0.75kW	Setting motor capacity
		(2)0.2kW	(12)18.5kW		
		(3)0.4kW	(13)22kW		
		(4)0.75kW	(14)30kW		
		(5)1.5kW	(15)37kW		
		(6)2.2kW	(16)45kW		
		(7)3.7kW	(17)55kW		
		(8)5.5kW	(18)75kW		
		(9)7.5kW	(19)90kW		
		(10)11kW	(20)110kW		
6	Start Time	0.1 to 20.0s		3.0	Setting the start time
7	Process	1 to 8		1	Number of process
8	OUT1 Level	0 to 99%		0	Value of OUT1 integrated power lower limit
9	OUT2 Level	5 to 200%		80	Value of OUT2 integrated power upper limit
10	OUT3 Level	5 to 200%		100	Value of OUT3 instantaneous power upper limit
11	Shock Time OUT3	MIN		1.0	Setting shock time OUT 3
		0.1 to 10.0s			
12	Output Relay OUT3	(1)Self-Hold		(1)	Selecting the output operation mode (OUT3)
		(2)Auto-Reset			
13	Response	(1)QUICK		(2)	Number of moving average operations
		(2)NORMAL			
		(3)SLOW			
14	Inhibit Time	IH		IH	Setting inhibit time
		0.1 to 10.0s			
15	Auto Inhibit	(1)On		(2)	Setting the auto inhibit function
		(2)Off			
16	LCD Backlight	(1)Always		(1)	Setting the backlight illumination time
		(2)2min			

External connection/ parameter settings/ terminal functions

6. Built-in forward/reverse sequencer type TSM4000C1……For crushers

■ External connection



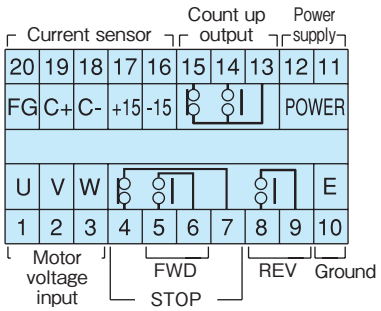
CB : Circuit breaker
F : Fuse
MCF : Electromagnetic contactor for motor to forward rotation
MCR : Electromagnetic contactor for motor to reverse rotation
OCR : Over current relay
AR1 : Auxiliary relay for forward output
AR2 : Auxiliary relay for reverse output
AR3 : Auxiliary relay to light alarm lamp
CR1, 2: CR absorber
PB0 : Emergency stop button
RST : Alarm display reset

Note:
1. Select the current sensor from the Current Sensor table based on motor capacity and voltage. Use the specified number of passes through and current direction.
2. Make sure to insert the current sensor into the "phase V", and use the sensor cable TSM-SXX to connect with the Shock Monitor.
3. If using a 400/440V motor, use the 400V class resister shown in dashed line.
4. Connect the motor voltage terminal of the Shock Monitor U[1], V[2], W[3] with the phase of [U], [V], [W] respectively.
5. Use relay for minute electric current for [X1], [X2].

◎ In case of a wrong connection, load can not be detected correctly and the Shock Monitor will not work properly.

Name	Symbol	IN/OUT	Pin No.	Explanation
Auto operation input Manual reverse order	X1	IN	1	Auto operation Manual reverse operation
	X2	IN	9	
Common	CM	IN	4	Common terminals for X1 and X2

■ Function of terminals



Name	Symbol	IN/OUT	Pin No.	Explanation
Control pwer supply voltage	POWER	IN	11	Connection of control power supply
			12	
Ground	E	–	10	Ground terminal
Current sensor	-15	OUT	16	Sensor cable
	15	OUT	17	
	C–	IN	18	
	C+	IN	19	
	FG	–	20	
Motor voltage	U	IN	1	Motor voltage input terminal
	V	IN	2	
	W	IN	3	
FWD	a	OUT	5	Order of forward rotation
	c	OUT	6	
STOP	b	OUT	4	Order of stop (1s shot)
	c	OUT	7	
REV	a	OUT	8	Order of reverse rotation
	c	OUT	9	
Count up output	c	OUT	13	Count-up output (1s shot)
	a	OUT	14	
	b	OUT	15	

■ Parameter setting

No.	Parameter	Data		Data when shipment	Contents
1	Parameter lock	(1)Unlock		(1)	Can change parameter setting
		(2)Lock			Can not change parameter setting unless in an unlocked condition
2	Motor voltage	(1)200-230V		(1)	Motor voltage 3 phase 200V class
		(2)380-460V			Motor voltage 3 phase 400V class
3	Motor kW	(1)0.1kW	(13)22kW	0.75kW	Setting motor capacity. * Parameter (21)132kW to (23)200kWcan be set only for a 400Vclass motor.
		(2)0.2kW	(14)30kW		
		(3)0.4kW	(15)37kW		
		(4)0.75kW	(16)45kW		
		(5)1.5kW	(17)55kW		
		(6)2.2kW	(18)75kW		
		(7)3.7kW	(19)90kW		
		(8)5.5kW	(20)110kW		
		(9)7.5kW	(21)132kW*		
		(10)11kW	(22)150kW*		
		(11)15kW	(23)200kW*		
		(12)18.5kW			
4	No load level	Unused		Unused	Prevention of idle running
		5 to 200%			
5	Overload level	5 to 200%		100	Overload detection level
6	Start time	1 to 300s		5	Setting the start time
7	No load continuing level	0.1 to 60min		15.0	Time between after under-running no load level until COUNTUP output
8	Overload duration time (Overload time)	MIN		1.0	Shock time when overload occurs
		0.1 to 10.0s			
9	Pause time (1)	1 to 600s		10	Pause time during switching from forward to reverse rotation
10	Reverse time	1 to 600s		5	Reverse running time
11	Pause time (2)	1 to 600s		10	Pause time during switching from reverse to forward rotation
12	No. of reverse rotation	1 to 10 times		5	No. of reverse rotation until COUNTUP output
13	Reverse rotation	Plus		10	Time to count the no. of reverse rotation.
		1 to 600s			Add to 1 cycle time
14	Response	(1)QUICK		(2)	Number of moving average operations
		(2)NORMAL			
		(3)SLOW			
15	LCD Backlight	(1)Always		(1)	Setting the backlight illumination time
		(2)2min			

MEMO

Safety Guide and Warranty

⚠ WARNING Death or serious injury may result from product misuse due to not following the instructions.

"Mechanical type Safety and Control devices"
- Begin inspection and maintenance after verifying that no load or rotational force is being applied to the equipment.
- Check the operation of the device periodically so that it can be sure to function properly when overload occurs.

"Electrical type Safety and Control devices"
- When carrying out an operation test or making a periodic inspection, make sure to verify that it functions properly as a protection device.
- Follow the instruction manual when carrying out megger testing because most electrical devices have certain requirements for megger testing.
- Check the operation of the device periodically so that it can be sure to function properly when overloaded occurs.

"Common"
- Comply with the 2-1-1 General Standard of "Ordinance on Labor Safety and Hygiene".
- When performing maintenance or inspections:
  1) Wear proper work clothes and protective equipment (safety devices, gloves, shoes, etc.). To avoid an accident, make sure to perform maintenance and inspections in an appropriate environment.
  2) Make sure the power is switched off, and the machine has stopped completely before carrying out maintenance and inspections. Take the necessary measures to ensure the power is not turned back on.
  3) Follow the instruction manual.
  4) Wire according to the technical standards of Electrical Installation and company regulations. Take note of the cautions in this manual which explain installation direction, clearance and environmental conditions. Make sure to ground the device to prevent electrical shock and to improve noise resistance.
- When using with lifting equipment, install a suitable protection device for safety purposes, otherwise an accident resulting in death, serious injury or damage to the equipment may occur due to a falling accident.

⚠ CAUTION Minor or moderate injury, as well as damage to the product may result from product misuse due to not following the instructions.

"Mechanical type Safety and Control devices"
- The strength of the equipment should be designed to withstand the load or rotational force when the device is activated due to overload.
- Wear damage may occur depending on the number and frequency of activations. Following the manual, check the functions and operations periodically. If something is not functioning properly, contact the distributor for repair.

"Electrical type Safety and Control devices"
- Consumable parts (tantalum electrolytic capacitors, relays, etc.) are built-in the products. Using the manual, periodically check the functions and operation of the device. If it is not functioning properly, contact the distributor for repair.
- Do not use the device in a corrosive gas environment. Sulphidizing gases (SO_2, H_2S) can especially corrode the copper and copper alloy used on PCBs and parts, and cause a malfunction.

"Common"
- Read the instruction manual carefully, and use the product properly. In case the instruction manual is not available, request one from the distributor where you purchased the product, or our sales office with the product name and model number.
- Deliver this instruction manual to the final customer who uses the Tsubaki E&M product.
- Do not reset the main unit or shaft of the shock guard by turning it by hand. Doing so is dangerous.

Warranty: Tsubaki E&M Co.: hereinafter referred to as "Seller" Customer: hereinafter referred to as "Buyer" Goods sold or supplied by Seller to Buyer: hereinafter referred to as "Goods"

1. Warranty period without charge
Effective 18 months from the date of shipment or 12 months from the first use of Goods, including the installation of the Goods to the Buyer's equipment or machine - whichever comes first.

2. Warranty coverage
Should any damage or problem with the Goods arise within the warranty period, given that the Goods were operated and maintained according to the instructions provided in the manual, the Seller will repair and replace at no charge once the Goods are returned to the Seller.
This warranty does not include the following:
1) Any costs related to removal of Goods from the Buyer's equipment or machine to repair or replace parts.
2) Cost to transport Buyer's equipment or machines to the Buyer's repair shop.
3) Costs to reimburse any profit loss due to any repair or damage and consequential losses caused by the Buyer.

3. Warranty with charge
Seller will charge for any investigation and repair of Goods caused by:
1) Improper installation by failing to follow the instruction manual.
2) Insufficient maintenance or improper operation by the Buyer.
3) Incorrect installation of the Goods to other equipment or machines.
4) Any modifications or alterations of Goods by the Buyer.
5) Any repair by engineers other than the Seller or those designated by the Seller.
6) Operation in an environment not specified in the manual
7) Force Majeure or forces beyond the Seller's control such as natural disasters and injustices inflicted by a third party.
8) Secondary damage or problems incurred by the Buyer's equipment or machines.
9) Defective parts supplied or specified by the Buyer.
10) Incorrect wiring or parameter settings by the Buyer.
11) The end of life cycle of the Goods under normal usage.
12) Losses or damages not liable to the Seller.

4. Dispatch service
The service to dispatch a Seller's engineer to investigate, adjust or trial test the Seller's Goods is at the Buyer's expense.

⚠ CAUTION
The contents of this catalog are mainly to aid in product selection.
Read the instruction manual thoroughly before using the product in order to use it properly.

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